

**ECE 250 - Project 5**  
**Shortest Path using Dijkstra's Algorithm**  
**Design Document**  
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## **1. Overview**

### **Class 1: Node**

#### **Description:**

Helped in creating a linked list for the vector.

#### **Member Variables:**

1. String City
2. Node type pointer next
3. Double edgeWeight

### **Class 2: linkedList**

It implements the linked list data structure to implement the undirected graph.

#### **Member Variables:**

1. Node type pointer head
2. Node type pointer tail

### **Class 3: undirectedGraph**

#### **Description:**

It is the implementation of undirected graph which has implements all the command functions for the project and also builds a vector of type linked list to store city information.

#### **Member Variables:**

1. Vector of type linked list cityList
2. Node type pointer info
3. Integer vertex
4. Integer edge

#### **Member Functions (operations):**

1. insert: for the command i to insert the name of the city as a node in the linked list
2. assignEdge: Updates or add the distance of the road if the conditions of the input are valid
3. search: Searches the city name and return the index if it exists
4. degree: returns the number of vertices a node is connected to.
5. graphNodes: returns the total number of nodes i.e. the variable vertex.
6. graphEdges: returns the number of edges i.e. the variable edge.
7. distance: returns the edge weight between two vertices from the adjacency matrix.
8. clear: it clears the whole linked list

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## 2. Constructors/Destructors

### Class Node (Constructor and Destructor):

This class has a constructor to create an object for the vector.

All other classes do not need a constructor or a destructor as they have different functions and the memory is deallocated in the functions.

## 3. Test Cases

Test 1: Add a lot of cities and connect edges between them check for exceptions, search for existing and non-existing cities

Test 2: Check the other functions like graph\_nodes and graph\_edges , clear, find the shortest distance and the distance between the cities.

### Test File Example 1:

```
i Toronto
i Markham
i Oshawa
i Belleville
i Kingston
i Cornwall
i Ottawa
i Montreal
setd
Toronto;Markham;31.3
setd Toronto;Oshawa;59.9
setd
Ottawa;Montreal;199.0
setd
Cornwall;Montreal;114.0
setd
Markham;Ottawa;374.0
graph_nodes
graph_edges
s Belleville
s Cornwall
degree Oshawa
degree Cornwall
degree Toronto
d Oshawa;Ottawa
d Belleville;Kingston
d Toronto;Montreal
shortest_d
Toronto;Montreal
print_path
Toronto;Montreal
clear
graph_nodes
```

### Test File Example 2:

```
i City0
i City1
i City2
i City3
i City4
setd City0;City1;10.0
setd City0;City2;5.0
setd City1;City2;3.0
setd City2;City3;9.0
setd City2;City4;2.0
setd City4;City3;6.0
setd City1;City3;1.0
graph_nodes
graph_edges
s City3
s City5
s City4
degree City2
degree City4
degree City0
d City0;City2
d City2;City3
d City2;City4
shortest_d City0;City4
clear
graph_nodes
```

#### 4. Performance

For class undirectedGraph:

The insert function's time complexity is  $O(V)$  as we are inserting a node in the linked list and its linear time.

The assignEdge function runs in linear time  $O(V)$  as it has for loops and conditional statements.

The search function also runs in linear time  $O(V)$  because it uses a for loop to search for the city.

The degree function consists of a for loop, so it has a time complexity of  $O(V)$ .

The graphNodes runs in constant time as it returns a single variable vertex.

The graphEdges runs in constant time as it returns a single variable edge

The Distance function just returns the value of that edge from the matrix so it is also implemented in constant time  $O(1)$ .

The clear function runs a for loop in  $O(V)$  times.