```cpp
#define trigPin 13
#define echoPin 12
int counter = 0;
int currentState = 0;
int previousState = 0;
void setup()
{
 Serial.begin(9600);
 pinMode(trigPin, OUTPUT);
 pinMode(echoPin, INPUT);
}

void loop()
{
 long duration, distance;
 digitalWrite(trigPin, LOW);
 delayMicroseconds(2);
 digitalWrite(trigPin, HIGH);
 delayMicroseconds(10);
 digitalWrite(trigPin, LOW);
 duration = pulseIn(echoPin, HIGH);
 distance = (duration/2) / 29.1;
 if (distance <= 60)
 {
 currentState = 1;
 }
 else
 {
 currentState = 0;
 }
 delay(100);
 if(currentState != previousState)
 {
if(currentState == 1)
{
counter = counter + 1;
Serial.println(counter);
    }
  }
}
```