

High Performance Computing and Big Data Assignment 3: MPI and OpenMP

High Performance Computing and Big Data 2024

Group: 5

Team members: Iason Christofilakis, Lars Meijer

Email: iason.christofilakis@student.uva.nl, lars.meijer@student.uva.nl

February 2, 2024

1 Implementation

In this section, we present the implementation details of the parallelized Game of Life simulation using MPI and OpenMP. The implementation focuses on distributing the computational workload among multiple MPI processes and leveraging OpenMP for parallelism within each process.

The chosen implementation path leverages a parallelized approach to simulate Conway's Game of Life using a combination of MPI (Message Passing Interface) and OpenMP (Open Multi-Processing) for distributed and shared-memory parallelism, respectively. The code begins by initializing MPI and determining the rank and size of each process within the MPI communicator. The board is divided horizontally into blocks, with each process responsible for a distinct segment. The parallelization is achieved by employing OpenMP directives, specifically in the computation of cell states during each iteration. Notably, the implementation demonstrates efficient communication between neighboring processes using MPI, ensuring synchronization and exchange of boundary data. Additionally, the code incorporates verification checks at specified iterations, comparing the population of a predefined pattern against expected values. The implementation not only achieves the parallelization of the Game of Life algorithm but also includes robust error handling and execution time measurements. The choice of this implementation path aligns with the goal of harnessing both MPI and OpenMP to attain a high-performance parallel simulation of the Game of Life across multiple processes and threads.

1.1 Header and Library Inclusions

```
1 #include <stdio.h>
2 #include <stdint.h>
3 #include <stdlib.h>
4 #include <mpi.h>
5 #include <omp.h>
6 #include <stdbool.h>
```

Listing 1: Header and Library Inclusions

These lines include the necessary standard C libraries and MPI (Message Passing Interface) library for parallel processing.

1.2 Constants and Definitions

```
// Debug printing controls

#define DEBUG_PRINT_RANK_INFO O

#define DEBUG_PRINT_REGION O

#define DEBUG_RUN_VERIFICATION_CHECKS O

#define DEBUG_PRINT_TOTAL_POPULATION O

#define DEBUG_PRINT_EXECUTION_TIME 1
```

Listing 2: Constants and Definitions

Here, we define constants for the board size, maximum iterations, starting positions of patterns, and debug controls.

1.3 Pattern Definitions

```
// Include patterns
#include "grower.h"

#include "glider.h"

#include "beehive.h"
```

Listing 3: Pattern Definitions

Imports the patterns (grower, glider, beehive) that will be placed on the board.

1.4 Utility Macros and Functions

```
_{
m 38} // Macro to convert 2D indices to a 1D index for a flattened array
39 #define INDEX(row, col) ((row) * BOARD_SIZE + (col))
40
_{
m 41} // Function to convert local coordinates to global coordinates
42 void local_coords_to_global(int *global_row, int *global_col, int row, int col, int
      startRow, int startCol) {
      *global_row = row + startRow;
      *global_col = col + startCol;
44
45 }
46
47 // Function to print a region of the board
  void print_region(uint8_t *board, int startRow, int startCol, int height, int width)
      for (int i = startRow; i < startRow + height; ++i) {</pre>
49
50
           for (int j = startCol; j < startCol + width; ++j) {</pre>
               printf("%c", board[INDEX(i, j)] ? '#' : '^');
51
          7
52
           printf("\n");
53
      }
54
55 }
```

Listing 4: Utility Macros and Functions

Defines a macro for converting 2D indices to a 1D index and functions for converting local coordinates to global coordinates and printing a region of the board.

1.5 Initialization and Population Counting

```
// Function to initialize the local board with a specific pattern
void initialize_local_board(uint8_t *board, int block_start, int block_size) {
    // Fill the local board with the grower pattern
    // Only the part of the pattern that is within the local board boundaries will be copied
for (int i = 0; i < block_size + 2; ++i) {</pre>
```

```
for (int j = 0; j < BOARD_SIZE; ++j) {
   if (i == 0 || i == block_size + 1) {</pre>
62
63
                      // Set boundary rows to 0
64
65
                      board[INDEX(i, j)] = 0;
                      continue;
66
                 }
67
                 int row_global, col_global;
68
                 local_coords_to_global(&row_global, &col_global, i, j, block_start, 0);
if (row_global >= GROWER_START_ROW && row_global < GROWER_START_ROW +
69
70
       GROWER_HEIGHT &&
                      col_global >= GROWER_START_COL && col_global < GROWER_START_COL +
71
       GROWER_WIDTH) {
72
                      // Copy the grower pattern to the local board
                      board[INDEX(i, j)] = grower[row_global - GROWER_START_ROW][col_global
73
         - GROWER_START_COL];
                } else
74
                      // Set cells outside the grower pattern to 0
75
                      board[INDEX(i, j)] = 0;
76
            }
77
78
       }
79 }
80
_{81} // Function to calculate the population of the local board
82 int local_board_population(uint8_t *board, int block_size) {
83
       int population = 0;
       for (int i = 1; i <= block_size; ++i) {</pre>
84
            for (int j = 0; j < BOARD_SIZE; ++j) {</pre>
85
                 population += board[INDEX(i, j)];
86
87
88
       }
       return population;
89
90 }
```

Listing 5: Initialization and Population Counting

Functions for initializing the local board with the grower pattern and counting the population of the local board.

1.6 Game of Life Rules

```
_{92} // Function to apply the Game of Life rules to a cell
93 uint8_t apply_rules(int current_state, int neighbors) {
       if (current_state == 1) {
94
95
            // Cell is alive
           if (neighbors < 2 || neighbors > 3) {
96
97
                // Rule 1 and 3: Cell dies
                return 0;
98
           } else {
99
100
                // Rule 2: Cell survives
                return 1;
101
           }
       } else {
103
           // Cell is dead
104
            if (neighbors == 3) {
105
                // Rule 4: Cell becomes alive
106
                return 1;
107
           } else {
108
               // Cell remains dead
                return 0;
```

```
112 }
113 }
```

Listing 6: Game of Life Rules

Defines the rules for the Game of Life, determining whether a cell survives, dies, or becomes alive (as described here).

1.7 Game of Life Iterations

```
_{115} // Function to run one iteration of the Game of Life for the local region of the
void run_game_of_life(uint8_t *current, uint8_t *next, int block_size) {
#pragma omp parallel for collapse(2)
        for (int i = 1; i <= block_size; ++i) {
    for (int j = 0; j < BOARD_SIZE; ++j) {</pre>
118
                 // Count neighbors for each cell
120
                 int neighbors = 0;
for (int ni = -1; ni <= 1; ++ni) {</pre>
121
122
                      for (int nj = -1; nj <= 1; ++nj) {</pre>
123
                           if (ni == 0 && nj == 0) continue;
124
125
                           int ni_ = i + ni;
126
127
128
                           // Check if the neighbor is within the local board boundaries
                           int nj_ = j + nj;
129
130
                           // Check if the neighbor is within the board boundaries
131
                           if (nj_ >= 0 \&\& nj_ < BOARD_SIZE) {
132
                               neighbors += current[INDEX(ni_, nj_)];
                      }
135
                 }
136
137
                 // Apply Game of Life rules
138
139
                 next[INDEX(i, j)] = apply_rules(current[INDEX(i, j)], neighbors);
            }
140
141
        }
142 }
```

Listing 7: Game of Life Iterations

Includes the parallelized code for running one iteration of the Game of Life for the local region of the board using OpenMP.

1.8 Global Population Calculation

```
_{144} // Function to calculate the population of the entire board across all processes
  int total_board_population(uint8_t *local_board, int block_size) {
145
146
       int local_population = local_board_population(local_board, block_size);
147
       // Use MPI_Allreduce to perform a reduction operation across all processes
148
149
       int total_population;
       if (MPI_Allreduce(&local_population, &total_population, 1, MPI_INT, MPI_SUM,
150
       MPI_COMM_WORLD) != MPI_SUCCESS) {
           fprintf(stderr, "Error in MPI_Allreduce operation.\n");
151
           exit(EXIT_FAILURE);
       }
```

```
return total_population;
156 }
```

Listing 8: Global Population Calculation

Calculates the population of the entire board across all processes using MPI_Allreduce.

1.9 Verification Checks

```
158 // Function to perform verification checks at specific iterations
void run_verification(uint8_t *local_board, int iter, int block_size) {
       // Check total population for specific iterations
160
       if (iter == 10) {
161
           int total_population = total_board_population(local_board, block_size);
162
           printf("Generation 10: Grower pattern population = %d\n", total_population);
163
           if (total_population != GROWER_POPULATION_GEN10) {
164
               printf("ERROR: Incorrect population for generation 10\n");
165
               exit(1);
166
           }
167
       }
168
169
       if (iter == 100) {
170
171
           int total_population = total_board_population(local_board, block_size);
           printf("Generation 100: Grower pattern population = %d\n", total_population);
172
           if (total_population != GROWER_POPULATION_GEN100) {
173
174
               printf("ERROR: Incorrect population for generation 100\n");
               exit(1);
           }
176
177
       }
178 }
```

Listing 9: Verification Checks

Includes checks for total population at specific iterations and terminates with an error if the population is incorrect.

1.10 Main Function and MPI Initialization

```
int main(int argc, char *argv[]) {
       int rank, size;
181
182
183
       // Start up MPI
       if (MPI_Init(&argc, &argv) != MPI_SUCCESS) {
184
           fprintf(stderr, "Error initializing MPI.\n");
185
           exit(EXIT_FAILURE);
187
       if (MPI_Comm_rank(MPI_COMM_WORLD, &rank) != MPI_SUCCESS) {
188
           fprintf(stderr, "Error in MPI_Comm_rank.\n");
189
           exit(EXIT_FAILURE);
190
191
       }
       if (MPI_Comm_size(MPI_COMM_WORLD, &size) != MPI_SUCCESS) {
192
           fprintf(stderr, "Error in MPI_Comm_size.\n");
193
           exit(EXIT_FAILURE);
194
195
196
       const bool am_master = 0 == rank;
197
198
       // Divide the board into blocks for parallel processing (horizontal segments)
199
       int block_size = BOARD_SIZE / size;
200
       int block_start = rank * block_size;
201
```

```
int block_end = block_start + block_size;
202
        if (DEBUG_PRINT_RANK_INFO) {
203
            // Print the block start and end indices for each process
204
            printf("Rank %d: Block start = %d, Block end = %d\n", rank, block_start,
205
       block_end);
206
207
       // Allocate memory for the local and next generation boards
208
       uint8_t *local_board = (uint8_t *) malloc(BOARD_SIZE * (block_size + 2) * sizeof(
209
       uint8_t));
       uint8_t *next_gen_board = (uint8_t *) malloc(BOARD_SIZE * (block_size + 2) *
       sizeof(uint8_t));
211
       if (local_board == NULL || next_gen_board == NULL) {
212
213
            fprintf(stderr, "Error allocating memory.\n");
            exit(EXIT_FAILURE);
214
215
216
       // Initialize the local board with the grower pattern
217
218
       initialize_local_board(local_board, block_start, block_size);
219
       // Record the start time for measuring execution time
220
       double start_time = MPI_Wtime();
221
222
       for (int iter = 0; iter < MAX_ITERATIONS; ++iter) {</pre>
223
            if (DEBUG_PRINT_RANK_INFO) {
224
                // Print the population of the local board for each iteration printf("Rank %d: Iteration %d, Population = %d\n", rank, iter,
226
                        local_board_population(local_board, block_size));
227
228
           }
229
            if (DEBUG_PRINT_REGION) {
230
                print_region(local_board, GROWER_START_ROW, GROWER_START_COL,
231
       GROWER_HEIGHT, GROWER_WIDTH);
           }
232
233
            if (DEBUG_RUN_VERIFICATION_CHECKS) {
234
                // \ensuremath{\mathsf{Verification}} checks for specific iterations
235
236
                run_verification(local_board, iter, block_size);
237
238
            if (DEBUG_PRINT_TOTAL_POPULATION && am_master) {
239
                // Calculate and print the total population of the entire board
240
                int total_population = total_board_population(local_board, block_size);
241
                printf("Total population after iteration %d: %d\n", iter,
242
       total_population);
243
244
245
            // Communication between neighboring processes using MPI
            // Identify left and right neighbors, set MPI_PROC_NULL if at the boundary
246
            int left_neighbour = (rank == 0) ? MPI_PROC_NULL : (rank - 1);
247
            int right_neighbour = (rank == size - 1) ? MPI_PROC_NULL : (rank + 1);
248
249
            // Define MPI request objects for non-blocking communication
250
            {\tt MPI\_Request\ left\_send\_request\ ,\ right\_send\_request\ ;}
251
           MPI_Request left_recv_request, right_recv_request;
252
253
            // Initiate non-blocking send operations to left and right neighbors
            if (block_start > 0) {
255
                // Communication with the left neighbor
256
```

```
if (MPI_Isend(&local_board[INDEX(1, 0)], BOARD_SIZE, MPI_UINT8_T,
257
       left_neighbour, 0, MPI_COMM_WORLD,
                              &left_send_request) != MPI_SUCCESS) {
258
                    fprintf(stderr, "Error in MPI_Isend to left neighbor.\n");
259
                    exit(EXIT_FAILURE);
260
261
                if (MPI_Irecv(&local_board[INDEX(0, 0)], BOARD_SIZE, MPI_UINT8_T,
       left_neighbour, 0, MPI_COMM_WORLD,
                              &left_recv_request) != MPI_SUCCESS) {
263
                    fprintf(stderr, "Error in MPI_Irecv from left neighbor.\n");
264
                    exit(EXIT_FAILURE);
265
               }
266
           }
267
268
           if (block_end < BOARD_SIZE) {</pre>
               // Communication with the right neighbor
270
                if (MPI_Isend(&local_board[INDEX(block_size, 0)], BOARD_SIZE, MPI_UINT8_T
271
       , right_neighbour, 0,
                              MPI COMM WORLD.
272
                              &right_send_request) != MPI_SUCCESS) {
273
274
                    fprintf(stderr, "Error in MPI_Isend to right neighbor.\n");
                    exit(EXIT_FAILURE);
275
276
                if (MPI_Irecv(&local_board[INDEX(block_size + 1, 0)], BOARD_SIZE,
277
       MPI_UINT8_T, right_neighbour, 0,
                              MPI_COMM_WORLD, &right_recv_request) != MPI_SUCCESS) {
278
                    fprintf(stderr, "Error in MPI_Irecv from right neighbor.\n");
279
280
                    exit(EXIT_FAILURE);
               }
281
           }
282
284
           // Wait for completion of all non-blocking communication operations
285
           if (block_start > 0) {
286
                if (MPI_Wait(&left_send_request, MPI_STATUS_IGNORE) != MPI_SUCCESS) {
                    fprintf(stderr, "Error in MPI_Wait for left_send_request.\n");
287
288
                    exit(EXIT_FAILURE);
289
                if (MPI_Wait(&left_recv_request, MPI_STATUS_IGNORE) != MPI_SUCCESS) {
290
291
                    fprintf(stderr, "Error in MPI_Wait for left_recv_request.\n");
                    exit(EXIT_FAILURE);
292
293
294
           if (block end < BOARD SIZE) {
295
                if (MPI_Wait(&right_send_request, MPI_STATUS_IGNORE) != MPI_SUCCESS) {
296
                   fprintf(stderr, "Error in MPI_Wait for right_send_request.\n");
297
                    exit(EXIT_FAILURE);
298
299
                if (MPI_Wait(&right_recv_request, MPI_STATUS_IGNORE) != MPI_SUCCESS) {
300
                    fprintf(stderr, "Error in MPI_Wait for right_recv_request.\n");
301
                    exit(EXIT_FAILURE);
302
               }
303
           }
304
305
           // Run one iteration of the Game of Life for the local region
306
           run_game_of_life(local_board, next_gen_board, block_size);
307
308
           // Swap pointers to update the local board for the next iteration
309
           uint8_t *temp = local_board;
           local_board = next_gen_board;
311
312
           next_gen_board = temp;
```

```
313
314
       // Record the end time for measuring execution time
315
       double end_time = MPI_Wtime();
316
317
       // Print total execution time
318
       if (DEBUG_PRINT_EXECUTION_TIME && am_master) {
319
           printf("Total execution time: %f seconds\n", end_time - start_time);
320
321
322
       // Print the final time : the time taken by the slowest process to complete the
323
       execution
       double max_time;
324
       if (MPI_Reduce(&end_time, &max_time, 1, MPI_DOUBLE, MPI_MAX, 0, MPI_COMM_WORLD)
325
       != MPI_SUCCESS) {
                            "Error in MPI_Reduce operation.\n");
           fprintf(stderr,
326
            exit(EXIT_FAILURE);
327
328
       printf("Max execution time: %f seconds\n", max_time - start_time);
329
330
331
       // Free allocated memory
332
       free(local_board);
333
       free(next_gen_board);
334
335
336
       // Finalize MPI
       if (MPI_Finalize() != MPI_SUCCESS) {
337
            fprintf(stderr, "Error finalizing MPI.\n");
338
            exit(EXIT_FAILURE);
339
340
341
       return 0;
342
343 }
```

Listing 10: Main Function and MPI Initialization

The main function initializes MPI, divides the board into blocks for parallel processing, allocates memory, runs iterations, performs MPI communication, and finalizes MPI.

2 Data distribution and communication method

In the provided code, the data distribution strategy involves dividing the Game of Life board into horizontal segments, creating a strip-like decomposition. Each MPI process is assigned a specific segment of the board, responsible for computing the Game of Life rules within that local region. The primary communication occurs between neighboring processes to exchange boundary information necessary for the computation of the next generation. For each process, the left and right neighbors are identified, and non-blocking MPI send and receive operations are employed to facilitate data exchange.

Specifically, communication involves sending and receiving entire rows of cells between neighboring processes. The left neighbor sends its rightmost row to the current process, and the right neighbor sends its leftmost row. This horizontal exchange of boundary data ensures that each process has the required information to apply the Game of Life rules accurately within its local segment. The MPI_Wait function is utilized to synchronize these non-blocking communication operations, ensuring proper coordination and data consistency throughout the parallel simulation. This communication strategy effectively balances computation and communication, contributing to the scalability of the simulation across multiple MPI processes.

3 Speedup

Table 1 summarizes the execution times of the parallel Game of Life implementation across various process configurations that were run on the Snellius cluster, using one node. Each row corresponds to a specific total number of processes/threads (specifically the product of the two), and the columns represent different configurations within that total. The "Max Execution Time" column indicates the highest execution time observed for a given configuration. The table provides insights into the scalability of the parallel implementation, demonstrating improved performance as the number of processes increases.

The speedup (S) is calculated using the formula:

$$S = \frac{T_{\text{serial}}}{T_{\text{parallel}}}$$

where T_{serial} is the execution time in a serial (non-parallel) setting, and T_{parallel} is the (maximum) execution time in a parallel setting.

Total Processes*Threads	#Processes	#Threads per process	Execution Time (s)	Max Exec Time (s)	Speedup
1	1	1	206.133195	206.133195	-
2	1	2	103.484263	103.491485	1.99
	2	1	103.491485		
4	1	4	51.930277	51.930277	3.97
	2	2	51.929517		
	4	1	51.907608		
8	1	8	26.050067	26.050067	7.91
	2	4	26.005198		
	4	2	26.036027		
	8	1	25.957004		
16	1	16	13.020182	13.020182	15.83
	2	8	13.044554		
	4	4	13.068875		
	8	2	13.057330		
	16	1	13.000273		
32	1	32	6.519567	6.519567	31.62
	2	16	6.532024		
	4	8	6.513430		
	8	4	6.515856		
	16	2	6.492571		
	32	1	6.438125		
64	1	64	3.341772	3.341772	61.68
	2	32	3.307247		
	4	16	3.267373		
	8	8	3.318634		
	16	4	3.294378		
	32	2	3.262157		
	64	1	3.162100		
128	1	128	9.926397		
	2	64	2.182159		
	4	32	6.728790	9.926397	20.77
	8	16	7.027649		
	16	8	7.674845		
	32	4	2.285173		
	64	2	1.958015		
	128	1	7.117786		

Table 1: Benchmark Results for Parallel Game of Life

The speedup analysis is visualized in Figure 1, where the speedup (last column of Table 1) is plotted against the total number of processes/threads (first column of Table 1). The rounded speedup values are annotated on the data points for clarity.

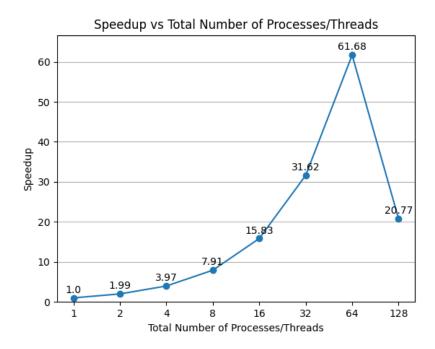


Figure 1: Speedup vs Total Number of Processes/Threads

4 Population Growth

In the context of the provided Game of Life simulation, it is noteworthy that after 5000 generations, the final population is at 3647 living cells.

The growth chart (Figure 2), visually encapsulates this evolution, showcasing the population fluctuations until reaching the state of 3647 cells after the specified number of iterations.

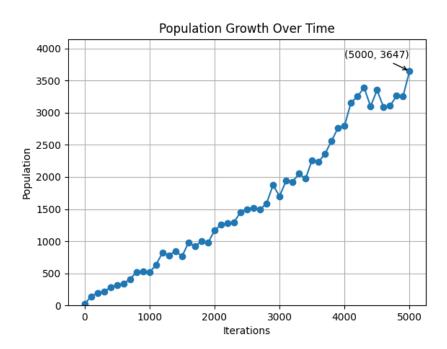


Figure 2: Population Growth Over 5000 Generations