Functional Analysis

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July 24, 2021

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1 Introduction

We have thus far looked at abstract vector spaces in linear algebra and (metric) topological spaces in topology. In this course, we will combine these concepts and study linear metric space. In particular, we will study vector spaces equipped with a topology such that certain properties are satisfies.

In this course, we will often study the space of functions and hence the name of the course. As we have seen before, given that the codomain space possesses a certain structure, it is possible to define point-wise addition and scalar multiplications on functions, and thus, possible to equip the space with a vector space structure.

Let us recall some definitions.

Definition 1.1 (Metric). A metric ρ on a non-empty set X is a function with type signature $X \times X \to \mathbb{R}^+$ such that for all $x, y, z \in X$

- $\rho(x,y) = 0 \iff x = y;$
- $\rho(x,y) = \rho(y,x)$;
- $\rho(x,y) \le \rho(x,z) + \rho(z,y)$.

Definition 1.2 (Translation Invariant). A metric space (V, ρ) where V is equipped with the binary operation $(+): V \times V \to V$ is translational invariant if for all $w, z, v \in V$,

$$\rho(w+v,z+v) = \rho(w,z).$$

Definition 1.3 (Norm). A norm $\|\cdot\|$ on the vector space V (over the field \mathbb{K} equipped with a modulus $|\cdot|$) is a function with type signature $X \to \mathbb{R}^+$ such that for all $x, y \in V, k \in \mathbb{K}$,

- $||x|| = 0 \iff x = 0;$
- $||k \cdot x|| = |k|||x||$;
- $||x + y|| \le ||x|| + ||y||$.

We recall that a norm induces a metric by defining $\rho(x,y) = ||x-y||$. In this case, it is possible to show that (+) and (\cdot) are continuous with respect to this metric and ρ is translational invariant.

Definition 1.4 (Banach Space). A normed space is said to be a Banach space if it is complete, i.e. every Cauchy sequence converge.

Definition 1.5 (Separable). A topological space is said to be separable if there exists a dense countable subset.

As we shall see, for $0 < 0 < \infty$, ℓ_p is separable while ℓ_{∞} is not.

Definition 1.6 (Compact). A topological space is said to be compact if every open cover has a finite sub-cover.

Unlike what we have seen before, as we consider infinite dimensional spaces, we will see that the Heine-Borel property will no longer hold, i.e. closed and bounded is no longer equivalent to compact.

2 Linear Spaces

Definition 2.1 (Equivalent Norms and Metrics). Two norms $\|\cdot\|_k$ for k=1,2 are said to be equivalent if there exists some M>0 such that for all x,

$$\frac{1}{M} \|x\|_1 \le \|x\|_2 \le M \|x\|_1.$$

Similarly, two metrics ρ_k are said to be equivalent if there exists some M>0 such that for all x,y,

$$\frac{1}{M}\rho_1(x,y) \leq \rho_2(x,y) \leq M\rho_1(x,y).$$

It is clear that equivalent is a symmetric relation and as we have seen before, all norms on a finite dimensional space are equivalent.

Definition 2.2 (Concave and Convex Function). A function $f: V \to \mathbb{R}$ is

• concave if for all $s \in [0,1], x, y \in V$, we have

$$sf(x) + (1-s)f(y) \le f(sx + (1-s)y);$$

• convex if for all $s \in [0,1], x, y \in V$, we have

$$sf(x) + (1-s)f(y) \ge f(sx + (1-s)y).$$

Proposition 2.1. If $f: \mathbb{R}^+ \to \mathbb{R}^+$ is concave and f(0) = 0. Then

$$f(x+y) < f(x) + f(y).$$

Proof. Clear by taking $s = \frac{y}{x+y}$, we have

$$(1-s)f(x+y) = sf(0) + (1-s)f(x+y) < f(s \cdot 0 + (1-s)(x+y)) = f(x),$$

and

$$sf(x+y) = sf(x+y) + (1-s)f(0) < f(s(x+y) + (1-s) \cdot 0) = f(y).$$

Adding the two equations, we have

$$f(x+y) = (1-s)f(x+y) + sf(x+y) < f(x) + f(y).$$

Corollary 2.1. If ρ is a metric and $\eta: \mathbb{R}^+ \to \mathbb{R}^+$ is a concave and vanishing at 0, then $\rho \circ \eta$ is also a metric.

Definition 2.3 (Linear Metric Space). A vector space V over the field \mathbb{K} equipped with a metric ρ on V and a metric $|\cdot - \cdot|$ on \mathbb{K} is a linear metric space if $(+): V \times V \to V$ and $(\cdot): \mathbb{K} \times V \to V$ are continuous with respect to the induced metric.

Proposition 2.2. Any normed space is a linear metric space.

Proof. Let $(x_n, y_n) \to (x, y)$ in V^2 , then we have

$$\|(x_n + y_n) - (x + y)\| \le \|x_n - x\| + \|y_n - y\| \to 0.$$

Thus, (+) is continuous.

Similarly, if $(\lambda_n, x_n) \to (\lambda, x)$ in $\mathbb{K} \times V$,

$$\begin{split} \|\lambda_n x_n - \lambda x\| &= \|\lambda_n x_n - \lambda_n x + \lambda_n x - \lambda x\| \\ &\leq \|\lambda_n x_n - \lambda_n x\| + \|\lambda_n x - \lambda x\| \\ &= |\lambda_n| \|x_n - x\| + |\lambda_n - \lambda| \|x\|. \end{split}$$

Now, since (λ_n) is convergent, it is bounded by some M > 0 and thus,

$$\|\lambda_n x_n - \lambda x\| \leq |\lambda_n| \|x_n - x\| + |\lambda_n - \lambda| \|x\| \leq M \|x_n - x\| + |\lambda_n - \lambda| \|x\| \to 0,$$

implying (\cdot) is continuous.

2.1 Classical Spaces

We recall the L_p spaces from second year measure theory, and in particular, when we consider the counting measure μ , we have the nice property that

$$\int f \mathrm{d}\mu = \sum_{n=0}^{\infty} f(n),$$

and we no longer require a quotient to define the linear space as the only null-set is the empty set (thus, two function are a.e equal if and only if they are equal). In this special case, we call the resulting space ℓ_p with the p-norm

$$\|f\|_p = \left(\int |f|^p \mathrm{d}\mu\right)^{\frac{1}{p}} = \left(\sum_{n=0}^{\infty} |f(n)|^p\right)^{\frac{1}{p}}.$$

We will use the sequence notation and write $a_n := a(n)$ for $a \in \ell_p$.

As this is simply a special case of the L_p space, the inequalities proved on the L_p space remains. We will recall them here for ℓ_p spaces.

Proposition 2.3 (Hölder's Inequality). Let $\frac{1}{p} + \frac{1}{q} = 1$ where $p, q \in (1, \infty)$. Then for $a = (a_i)_{i \in \mathbb{N}}, b = (b_i)_{i \in \mathbb{N}} \in \ell_p$, we have

$$|\langle a, b \rangle| \le ||a||_p ||b||_q,$$

where $\langle a, b \rangle := \sum_{i \in \mathbb{N}} a_i b_i$.

Proposition 2.4 (Minkowski's Inequality). Let $a,b\in \ell_p$ for some $1\leq p\leq \infty$. Then $a+b\in \ell_p$ and

$$||a+b||_p \le ||a||_p + ||b||_p.$$

Lemma 2.1. Let $I \subseteq \mathbb{R}$ be an interval and $\phi : I \to \mathbb{R}^+$ be a function. Then ϕ is convex if and only if for all $y \in I$, there exists a $\gamma \in \mathbb{R}$, such that for all $x \in I$,

$$\gamma(x-y) < \phi(x) - \phi(y)$$
.

Proposition 2.5 (Jensen's Inequality). let $\phi \geq 0$ be convex and suppose $\sum_{i \in \mathbb{N}} \eta_i = 1$, $|\langle \alpha \rangle| < \infty$ and $\langle \phi(\alpha) \rangle$ (where $\langle \beta \rangle = \sum_{i \in \mathbb{N}} \eta_i \beta_i$), then

$$\phi(\langle \alpha \rangle) \le \langle \phi(\alpha) \rangle.$$

Proof. By the above lemma, there exists some γ such that

$$\gamma(\alpha_j - \langle \alpha \rangle) \leq \phi(\alpha_j) - \phi(\langle \alpha \rangle).$$

Thus,

$$\begin{split} 0 &= \sum \eta_i \gamma(\alpha_j - \langle \alpha \rangle) \leq \sum \eta_i (\phi(\alpha_j) - \phi(\langle \alpha \rangle)) \\ &= \sum \eta_i \phi(\alpha_j) - \phi(\langle \alpha \rangle) \sum \eta_i \\ &= \langle \phi(\alpha_j) \rangle - \phi(\langle \alpha \rangle) \end{split}$$

where the first equality follows as γ is independent of the index i.

Proposition 2.6. For p < p', $\ell_p \subseteq \ell_{p'}$. On the other hand, if $\sum \eta_i = 1$, we have $\ell_p(\eta) \supseteq \ell_{p'}(\eta)$.

Definition 2.4. Let ϕ be a convex function such that $\phi(0) = 0$, $\phi(x) \to \infty$ as $x \to \infty$. If ϕ has the doubling property such that there exists some M > 0 such that for all $x \in \mathbb{R}$, $\phi(2|x|) \leq M\phi(|x|)$, then

$$V := \left\{a: \mathbb{N} \to \mathbb{R} \mid \sum \eta_i \phi(|a_i|) < \infty \right\}$$

where $\sum \eta_i = 1$ is a vector space with point-wise operations.

Proposition 2.7. Given a metric space (X, ρ) , there exists a complete metric space $(\tilde{X}, \tilde{\rho})$ and an isometric embedding $\iota: X \to \tilde{X}$ such that for all $x, x' \in X$, $\tilde{\rho}(\iota(x), \iota(x')) = \rho(x, x')$.

Proof. We have seen similar ideas in the completion of \mathbb{Q} though completing the space with equivalence classes of mutually Cauchy sequences as elements of \tilde{X} .

As we have seen last year, the L_p spaces are complete, and thus are Banach spaces. Thus, we have ℓ_p spaces are also complete and are Banach spaces. In fact, the proof that ℓ_p spaces are complete is easier, in that one may show completeness through showing the point-wise limit of the sequences indeed belong to ℓ_p .

Definition 2.5. We define

- $c_0 := \{ x \in \ell_{\infty} \mid \lim_{n \to \infty} x_n = 0 \},$
- $c := \{x \in \ell_{\infty} \mid \exists \lim_{n \to \infty} x_n\},\$

be subspaces of ℓ_{∞} .

Proposition 2.8. c_0 is complete.

Proof. Let $(x_i^n) \subseteq c_0$ be a Cauchy sequence and let $x_i = \lim_{n \to \infty} x_i^n$, then it suffices to show $\lim_{i \to \infty} x_i = 0$.

Since (x_i^n) is Cauchy, for all $\epsilon > 0$, there exists some $N \in \mathbb{N}$ such that for all $n \geq N$,

$$||x^n - x^N||_{\infty} < \frac{\epsilon}{2}.$$

Furthermore, as $x_i^N \to 0$ as $i \to \infty$, there exists some $I \in \mathbb{N}$ such that for all $i \geq I$, $|x_i^N| < \epsilon/2$. Thus, for all $i \geq I$, we have

$$\frac{\epsilon}{2} > \|x^n - x^N\|_{\infty} > |x_i^n - x_i^N| > |x_i^n| - \frac{\epsilon}{2} \implies \epsilon > |x_i^n|,$$

for all $n \geq N$. Hence, taking $n \to \infty$, we have

$$\epsilon > \lim_{n \to \infty} |x_i^n| = |x_i|,$$

implying $x_i \to 0$ as $i \to \infty$.

Proposition 2.9. c is complete.

Proof. Similar to above, let (x_i^n) be Cauchy and define (x^n) such that for all $n \in \mathbb{N}$, $x^n = \lim_{i \to \infty} x_i^n$ and (x_i) such that $(x_i^n) \to (x_i)$ in ℓ_{∞} . It is not difficult to see that (x^n) is Cauchy and thus converges to some x.

$$\begin{array}{ccc} (x_i^n) & \xrightarrow{n \to \infty} (x_i) \\ i \to \infty \! \! \! \! \! \! \! \! \! & & \downarrow_{i \to \infty} \\ (x^n) & \xrightarrow{n \to \infty} x \end{array}$$

Indeed, as (x_i^n) is Cauchy, for all $\epsilon > 0$, there exists some $N \in \mathbb{N}$ such that for all $p, q \ge N$, $\|x_i^p - x_i^q\|_{\infty} < \epsilon/3$. Furthermore, there exists some $I \in \mathbb{N}$ such that for all $j \ge I$, $|x_i^p - x^p|, |x_i^q - x^q| < \epsilon/3$. Thus,

$$|x^p - x^q| < |x_j^p - x^p| + |x_j^p - x_j^q| + |x_j^q - x^q| < \frac{\epsilon}{3} + \|x_i^p - x_i^q\|_{\infty} + \frac{\epsilon}{3} = \epsilon.$$

Hence, it remains to show $x_i \to x$ as $i \to \infty$. Fix $\epsilon > 0$, then there exists $N \in \mathbb{N}$ such that for all $n \geq N$, $|x^n - x| < \epsilon/3$. Furthermore, there exists $M \in \mathbb{N}$ such that for all $n \geq M$, $||x_i^n - x_i||_{\infty} < \epsilon/3$. Then, for all $p \geq \max\{N, M\}$, there exists $I \in \mathbb{N}$ such that for all $j \geq I$, $|x_j^p - x^p| < \epsilon/3$. Finally,

$$|x_j-x| \leq |x_j-x_j^p| + |x_j^p-x^p| + |x^p-x| \leq \|x_i-x_i^p\|_\infty + \frac{\epsilon}{3} + \frac{\epsilon}{3} < \epsilon,$$

implying $x_i \to x$ as $i \to \infty$ and $(x_i) \in c$.

2.1.1 Separability

In this section we will consider the separability of different classical spaces.

Proposition 2.10. The space ℓ_p is separable for all $p \geq 1$.

Proof. It is easy to see that the subspace of all finite sequences is dense in ℓ_p . Indeed, if $x \in \ell_p$ and x^n is the sequence such that $x_i^n = x_i$ for all $i \le n$ and $x_i^n = 0$ for all i > n, we have

$$\|x-x^n\|_p^p = \sum_{i=0}^\infty |x_i-x_i^n|^p = \sum_{i=n+1}^\infty |x_i|^p$$

which tends to 0 as $n \to \infty$. Now, by defining $\ell_{\mathbb{Q},n}$ as the set of rational sequences with length n, we have $d := \bigcup_{n \in \mathbb{N}} \ell_{\mathbb{Q},n}$ is dense in the space of all finite sequences. Now, since d is countable as it is a countable union of countable sets, we have found a countable dense set of ℓ_p .

Lemma 2.2. A metric space is X not separable if there exists an uncountable subset S such that for some some k > 0, d(x, y) > k for all $x, y \in S$.

Proof. As subset of a separable *metric* space is separable, S, must be separable. But as d(x,y) > k for all $x,y \in S$, no sequences of S but the constant sequence can converge. Thus, for all countable subsets of S, simply picking a point of S not in that subset suffices. \Box

Proposition 2.11. ℓ_{∞} is not separable.

Proof. Clearly the set containing all sequences of only 0 and 1s is a subset of ℓ_{∞} . Furthermore, this sequence is uncountable as it bijects \mathbb{R} be considering the binary representation of a real number. Thus, since all distinct elements in this set have distance 1 apart, the conclusion follows by the above lemma.

Proposition 2.12. $C^k([a,b])$ (the set of k-differentiable functions from the interval [a,b]) for all $k \in \mathbb{N}$ is separable.

Proof. Recalling the Weierstass approximation theorem, we have for all continuous function f, there exists a sequence of polynomials f_n such that $f_n \to f$ uniformly. Thus, as the set of polynomials with rational coefficients is countable, and dense in the space of all polynomials, we have found a countable dense set of $C^0([a,b])$. Now as $C^k([a,b]) \subseteq C^0([a,b])$ for all $k \in \mathbb{N}$, we have $C^k([a,b])$ is separable as required.

Definition 2.6 (Absolutely Convergent). Let X be a normed space and let (x_n) be a sequence of X, then a series $\sum_{n\in\mathbb{N}} x_n$ is said to be absolutely convergent if $\sum_{n\in\mathbb{N}} \|x_n\| < \infty$.

Proposition 2.13. A normed space X is complete if and only if for all sequences (x_n) of X such that $\sum x_n$ is absolutely convergent implies x_n converges. Thus, a normed space is Banach if and only if this property is satisfied.

Proof. See problem sheet. \Box

By recalling the proof of the completeness of L_p spaces, we note that this property was used extensively. As a consequence, we see that $L_p(\mu)$ is separable if the measure μ is separable. In particular, the spaces $L_p(\mathbb{R}^n,\lambda)$ are separable for all n. On the other hand, L_{∞} is in general not separable.

2.2 Hamel and Schauder Basis

In this small section we will introduce two new notions of basis for infinite dimensional spaces. In particular, we will introduce the Hamel basis which is a natural extension of the definition of basis for the finite dimensional case and the Schauder basis which is a notion of basis that incorporates the topological properties of the space.

Definition 2.7 (Linear Independent). A set $W \subseteq V$ is linear independent if for all $(\lambda_i)_{i=1}^m \subseteq \mathbb{K}$, $(w_i)_{i=1}^n \subseteq W$,

$$\sum \lambda_i w_i = 0 \implies \lambda_i = 0$$

for all $i = 1, \dots, n$.

Definition 2.8 (Hamel Basis). A set $W \subseteq V$ is a Hamel basis for a linear space V if W is linearly independent and for all $x \in V$, there exists a unique finite linear combination of vectors $(w_i)_{i=1}^n \subseteq W$, $(\lambda_i)_{i=1}^m \subseteq \mathbb{K}$ such that

$$x = \sum \lambda_i w_i.$$

Proposition 2.14. Every linear space has a Hamel basis.

We will come back to the proof of this proposition after discussing an important result known as the Hahn-Banach theorem.

Definition 2.9 (Schauder Basis). A set $W \subseteq V$ is a Schauder basis for a normed space V if W is countable, linearly independent, and for all $x \in V$, there exists a unique (possibly infinite)-sequence $(\lambda_i)_{i=1}^{\infty} \subseteq \mathbb{K}$ and $(w_i)_{i=1}^{\infty} \subseteq W$ such that

$$x = \sum_{i=1}^{\infty} \lambda_i w_i.$$

Proposition 2.15. If a Banach space X has a Schauder basis, then it is separable.

The proof of the above proposition is left as an exercise. It is notable that the reverse of the above is not true and was in fact a Scottish book problem which an counterexample was given by Per Enflo in 1972 who was awarded a live goose.

It is clear that for $p \ge 1$, the set $W := \{e_j \mid j \in \mathbb{N}\}$ where $(e_j)_i = \delta_{ij}$ is a Schauder basis of ℓ_p .

Recall that $c \subseteq \ell_{\infty}$ is the set of sequences which has a limit. By considering the sequence $x_n = 1$, we see that the set of standard basis vectors no longer form a basis of c as

$$\left\| x - \sum_{i=1}^{n} e_i \right\|_{\infty} = 1,$$

for all n. Defining $W:=\{e_0:=(1,1,\cdots)\}\cup\{e_j\mid j\in\mathbb{N}\},$ for all $(a_n)\in c,$ let $\lambda_0:=\lim_{n\to\infty}a_n$ and $\lambda_n=a_n-\lambda_0.$ Then, for all $\epsilon>0,$ there exists some $N\in\mathbb{N}$ such that for all $n\geq N,$ $|a_n-\lambda_0|\leq \epsilon.$ Thus,

$$\left\|\lambda_0e_0+\sum_{i=1}^n\lambda_ie_i-a\right\|_{\infty}=\|(0,\cdots,0,\lambda_0-a_n,\lambda_0-a_{n+1},\cdots)\|_{\infty}<\epsilon,$$

implying W is a Schauder basis of c.

Furthermore, one may show that C([0,1]) has a Schauder basis consisting of all the "spike" functions at the points $k2^{-n}$ for all $n \in \mathbb{N}$, $k = 1, \dots 2^{-n}$.

2.3 Hilbert Spaces

Recall the definition of sesquilinear forms over some vector space \mathbb{H} .

Definition 2.10 (Sesquilinear Form). A sesquilinear form $\langle \cdot, \cdot \rangle : \mathbb{H} \times \mathbb{H} \to \mathbb{K}$ on \mathbb{H} where \mathbb{K} is \mathbb{R} or \mathbb{C} is a function such that

- it is linear with respect to the second argument;
- and is conjugate symmetric.

We say $\langle \cdot, \cdot \rangle$ is nondegenerate if x = 0 if and only if $\langle x, y \rangle = 0$ for all $y \in \mathbb{H}$. Nondegenerate sesquilinear forms are called scalar products and a vector space equipped with a scalar product is called a unitary space (or a scalar product space).

We see that a scalar product induces a norm by defining $||f||^2 := \langle f, f \rangle$. In particular, we recall the ℓ_2 , C([a,b]) and L_2 are all scalar product spaces.

Proposition 2.16. Let \mathbb{H} be a unitary space, then

- $||f + g||^2 + ||f g||^2 = 2||f||^2 + 2||g||^2$ (parallelogram identity);
- $\langle f,g\rangle=\frac{1}{4}(\|f+g\|^2-|f-g\|^2)$ if $\mathbb{K}=\mathbb{R}$ and $\langle f,g\rangle=\frac{1}{4}\sum_{k=0,\cdots 3}i^k\|f+i^kg\|^2$ if $\mathbb{K}=\mathbb{C}$ (polarisation identity).

Definition 2.11 (Hilbert Space). A unitary space is a Hilbert space if it is complete with respect to its induced norm.

Definition 2.12 (Convex Set). A set S is said to be convex if for all $x, y \in S$, $(1-t)x+ty \in S$ for all $t \in [0,1]$.

Proposition 2.17 (Nearest Point Property). Every nonempty closed convex set \mathcal{K} in a Hilbert space \mathbb{H} contains a vector of the smallest norm. Moreover, if $h \in \mathbb{H}$, there exists a unique $h_0 \in \mathcal{K}$ such that

$$\|h-h_0\|=\operatorname{dist}(h,\mathcal{K}):=\inf_{k\in K}\|h-k\|.$$

Proof. By the definition of infimum, there exists a sequence $(k_n) \subseteq \mathcal{K}$ such that

$$\lim_{n \to \infty} \|k_n\| \to d := \inf_{k \in \mathbb{K}} \|k\|.$$

Consider, for all $n, m \in \mathbb{N}$, by the parallelogram identity,

$$\left\|\frac{1}{2}(k_n-k_m)\right\|^2 = \frac{1}{2}(\|k_n\|^2 + \|k_m\|^2) - \left\|\frac{1}{2}(k_n+k_m)\right\|^2.$$

Then, as $\mathbb K$ is convex, $\frac{1}{2}(k_n+k_m)\in\mathbb K$ and so $\|(k_n+k_m)/2\|^2\geq d^2$ and

$$\left\|\frac{1}{2}(k_n-k_m)\right\|^2 \leq \frac{1}{2}(\|k_n\|^2+\|k_m\|^2)-d^2.$$

Thus, taking $n, m \to \infty$, the right hand side tends to zero and so (k_n) is Cauchy and hence convergent. Now as \mathcal{K} is closed, the limit is in \mathcal{K} and hence the statement.

Definition 2.13 (Orthogonal Systems). Let $(\mathbb{H}, \langle \cdot, \cdot \rangle)$ be an unitary space. A set of vectors $\{e_j \in \mathbb{H} \mid j \in J\}$ for some index set J is called an orthogonal system if for all distinct $i, j \in J$,

$$\langle e_i, e_j \rangle = 0.$$

If furthermore, $\langle e_i, e_i \rangle = 1$ for all $i \in J$, then we say the system is orthonormal.

Proposition 2.18. Every orthogonal system is linearly independent.

Proof. Exercise.
$$\Box$$

Using Zorn's lemma, one can show that every unitary space contains an orthogonal basis.

Definition 2.14 (Fourier Coefficients). Let $(\mathbb{H}, \langle \cdot, \cdot \rangle)$ be an unitary space and let $\{e_j \in \mathbb{H} \mid j \in J\}$ be an orthogonal system. Then for each $f \in \mathbb{H}$, the Fourier coefficients with respect to the orthogonal system are

$$c_j := \frac{\langle e_j, f \rangle}{\|e_j\|^2}.$$

Proposition 2.19. If $f = \sum_{k \in \mathbb{N}} \alpha_k e_k$, then $a_j = c_j$.

Proof. Let n < m and $S_m := \sum_{k=1}^m \alpha_k e_k$. Then, $\langle S_m, e_n \rangle = \overline{\alpha_n} \|e_n\|^2$. Thus, we have

$$|\overline{\alpha_n}\|e_n\|^2 - \langle f, e_n \rangle| = |\langle S_m, e_n \rangle - \langle f, e_n \rangle| = |\langle S_m - f, e_n \rangle| \leq \|S_m - f\|\|e_n\| \to 0$$

as
$$m \to \infty$$
.

Proposition 2.20. Suppose $(e_j)_{j\in\mathbb{N}}$ is orthogonal and $g(a_1,\cdots,a_n):=\left\|f-\sum_{j=1}^n a_j e_j\right\|^2$. Then g attains its minimum at $a_j=c_j$. Furthermore, we have

$$\sum_{j=1}^{\infty} |c_j|^2 \|e_k\|^2 \le \|f\|^2.$$

This inequality is known as Bessel's inequality.

Proof. Exercise.
$$\Box$$

Definition 2.15. An orthogonal system $\{e_j \mid j \in J\}$ is called complete if for all $f \in \mathbb{H}$, if $\langle f, e_j \rangle = 0$ for all j, then f = 0.

Proposition 2.21. The following are equivalent

- 1. $(e_j)_{j\in\mathbb{N}}$ is complete;
- 2. $\|f \sum_{j=1}^{n} c_j e_j\| \to 0$ as $k \to \infty$ where c_j are the Fourier coefficients;
- 3. $||f||^2 = \sum_{j=1}^{\infty} |c_j|^2 ||e_k||^2$ for all $f \in \mathbb{H}$.

Proof. Exercise.
$$\Box$$

2.4 Finite Dimensional Spaces

Theorem 1. Let $(X, \|\cdot\|)$ be a finite dimensional normed space and let $\{e_i\}$ be a basis for X. Then, there exists some $M, m \in \mathbb{R}^+$ such that for all $x = \sum_{i=1}^n a_i e_i$,

$$m \sum_{i=1}^n |a_i| \le \|x\| \le M \sum_{i=1}^n |a_i|.$$

Proof. WLOG. assume $\sum_{i=1}^{n} |a_i| = 1$ since if otherwise, we may just scale x by $1/\sum |a_i|$. Then the function $f:(a_i) \mapsto \|\sum_i a_i e_i\|$ for all sequences (a_i) . Now, by checking that f is continuous, and by considering that the set $\{(a_i) \mid \sum \|a_i = 1\|\}$ is a closed subspace, f must attain a minimum m implying the left hand side inequality. On the other hand, consider the inequality

$$\left\|\sum_{i=1}a_ie_i\right\|\leq \sum|a_i|\|e_j\|\leq \max_k\|e_k\|\sum|a_i|=\max_k\|e_k\|.$$

Hence, it suffices to choose $M = \max ||e_k||$.

A direct corollary is that all norms on finite dimensional spaces are equivalent.

Definition 2.16 (Equivalent Norms). Two norms $\|\cdot\|_1$, $\|\cdot\|_2$ on X are said to be equivalent if there exists some $C \in \mathbb{R}^+$ such that

$$\frac{1}{C} \|x\|_1 \le \|x\|_2 \le C \|x\|_1,$$

for all $x \in X$.

Proposition 2.22. Equivalence of norms is an equivalence relation.

Proof. Easy check.

Corollary 2.2. Every norm on a finite dimensional space is equivalent.

Proof. If $\|\cdot\|_1, \|\cdot\|_2$ are two norms on X, then let $\{e_i\}$ be a basis of X. Thus, by simply defining the norm

$$||x|| = \left\| \sum_{i=1}^{n} a_i e_i \right\| := \sum_{i} |a_i|,$$

we have $\|\cdot\|_1$ is equivalent to $\|\cdot\|$ which is equivalent to $\|\cdot\|_2$. Hence, $\|\cdot\|_1$ is equivalent to $\|\cdot\|_2$ by transitivity.

Proposition 2.23. Every finite dimensional space over a complete field is complete.

Proof. Follows by considering the individual coefficients of a Cauchy sequence with respect to some basis is also Cauchy. \Box

Proposition 2.24. Every compact set of a normed space is closed and bounded.

Proof. As a normed space is a metric space, it suffices to consider sequential compactness. In particular, if a set is not closed, then it contains a sequence converging to a point not within the set. Then every sub-sequence of that sequence also converges to that point outside of the set, and so is not compact. On the other hand, if the set is not bounded, we can construct a sequence with norms tending to ∞ . It is then clear that the sequence does not contain any convergent subsequence.

We note that the converse of the above proposition is not true for infinite dimensional spaces. Indeed, we see that the canonical basis of ℓ_2 is closed and bounded but not complete.

Proposition 2.25. If $(X, \|\cdot\|)$ is a finite dimensional normed space, then every closed and bounded set is compact (this property is known as the Heine-Borel property).

Proof. Follows by choosing a subsequence for each coefficient by using Bolzano-Weierstrass.

In fact this property is sufficient to determine whether or not a normed space is finite dimensional.

Lemma 2.3 (Riesz's lemma). Let Y be a closed proper subspace of a subspace Z of X where $(X, \|\cdot\|)$ is a normed space. Then for any $\theta \in (0,1)$, there exists some $z \in Z$ such that

$$||z|| = 1$$
 and $||y - z|| \ge \theta$

for all $y \in Y$.

Proof. Let $v \in Z \setminus Y$, and define $a := \inf_{y \in Y} \|y - v\| > 0$. Then, as Y is closed, $\|y_0 - v\|$ attains a for some $y_0 \in Y$. Thus,

$$0 < a = \|v - y_0\| \le \frac{a}{\theta}.$$

Then, defining

$$z:=\frac{v-y_0}{\|v-y_0\|}=:c(v-y_0),$$

we have for all $y \in Y$,

$$||z - y|| = ||c(v - y_0) - y|| = c ||v - (y_0 + \frac{1}{c}y)||.$$

Since $y_0 + \frac{1}{c}y =: y_1 \in Y$, we have $||v - y_1|| \ge a$, and so

$$\|z - y\| = c\|v - y_1\| \ge ca = \frac{a}{\|v - y_0\|} \ge \frac{a}{a/\theta} = \theta.$$

Proposition 2.26. A normed space is finite dimensional if and only if $\{x \mid ||x|| = 1\}$ is compact.

Proof. Clearly, if X is finite dimensional, then as $\{x \mid \|x\| = 1\}$ is closed and bounded, it is compact.

Let $(X,\|\cdot\|)$ be an infinite dimensional normed space and suppose $\{e_i\}_{i=1}^{\infty}$ is a countable infinite linearly independent subset of X. Define $Z_n = \operatorname{span}\{e_i \mid i=1,\cdots,n\}$, and for each n, by Riesz's lemma, define $z_n \in Z_{n+1}$ such that $\|z_n\| = 1$ and $\|z_n - z_i\| \ge 1/2$ for all $i=1,\cdots,n$. Thus, we have defined a sequence in $\{x \mid \|x\| = 1\}$ which does not contain any convergent subsequence, and hence, $\{x \mid \|x\| = 1\}$ is not compact.

3 Linear Operators

3.1 Bounded Linear Operators

Definition 3.1 (Bounded Linear Operator). A linear map $T: X \to Y$ between normed spaces $(X, \|\cdot\|_X)$ and $(Y, \|\cdot\|_Y)$ is a bounded linear operator if there exists some $c \in \mathbb{R}^+$ such that,

$$||Tx||_Y \le C||x||_X$$

for all $x \in X$. In this case, one may define the operator norm by,

$$||T|| := \sup_{x \in X; x \neq 0} \frac{||Tx||_Y}{||x||_X}.$$

Proposition 3.1. Every linear map from a finite dimensional normed spaces is bounded.

Proof. Simply bound T by the maximum of the norm of the basis.

Proposition 3.2. Let X, Y be Banach spaces and let $T: X \to Y$ be a continuous linear map, then for all compact $\mathcal{K} \subseteq X$, $T(\mathcal{K}) \subseteq Y$ is also compact.

Proof. Follows by recalling that the continuous image of a compact space is compact (by pull-back of the open-cover). \Box

Proposition 3.3. If $T: X \to Y$ is a linear map between normed spaces $(X, \|\cdot\|_X)$ and $(Y, \|\cdot\|_Y)$, then the following are equivalent,

- 1. T is continuous;
- 2. T is Lipschitz continuous;
- 3. T is bounded;
- 4. T is continuous at some point $x_0 \in X$.

Proof. Clearly (3) \Longrightarrow (2) \Longrightarrow (1) \Longrightarrow (4), so let us first show (4) \Longrightarrow (1)). If T is continuous at x_0 , then for all $\epsilon > 0$, there exists some $\delta > 0$ such that for all $x \in B_{\delta}(x_0)$, $\epsilon > \|Tx - Tx_0\|$. Then, for all $\tilde{x} \in X$, we have

$$\epsilon > \|Tx - Tx_0\| = \|Tx + T(\tilde{x} - x_0) - Tx_0 - T(\tilde{x} - x_0)\| = \|T(\tilde{x} + (x - x_0)) - T\tilde{x}\|.$$

Thus, for all $x \in B_{\delta}(\tilde{x})$, we have $x - \tilde{x} + x_0 \in B_{\delta}(x_0)$ and hence,

$$\epsilon > \|T(\tilde{x} + (x - \tilde{x} + x_0 - x_0)) - T\tilde{x}\| = \|Tx - T\tilde{x}\|,$$

which implies T is continuous.

Now, it suffices to show that $(1) \implies (3)$. Since T is continuous at 0, there exists some $\delta > 0$ such that for all $x \in B_{\delta}(0)$, ||Tx|| < 1. Then for all $x \in X$, we have

$$\left\| \frac{\delta x}{2\|x\|} \right\| = \frac{\delta}{2} < \delta,$$

and so,

$$1 > \left\| T \left\| \frac{\delta x}{2\|x\|} \right\| \right\| = \frac{\delta}{2\|x\|} \|Tx\|,$$

implying $Tx < 2||x||/\delta$ for all x.

Definition 3.2. We denote the space of linear bounded operators between two normed spaces X, Y equipped with the operator norm by $\mathcal{L}(X, Y)$.

Proposition 3.4. Let $(X, \|\cdot\|_X)$ be a normed space and $(Y, \|\cdot\|_Y)$ be a Banach space. Then $\mathcal{L}(X,Y)$ is also a Banach space.

We will now recall the Banach contraction mapping theorem.

Definition 3.3 (Contraction). A map $T: X \to X$ on a metric space (X, ρ) is a contraction if there exists some α , $0 < \alpha \le 1$ such that for all $x, y \in X$,

$$\rho(Tx, Ty) \le \alpha \rho(x, y).$$

T is a strict contraction if a < 1.

Definition 3.4 (Fixed Point). A point $x \in X$ is a fixed point of the map $T: X \to X$ if Tx = x.

Theorem 2 (Banach Contraction Mapping). If X is a complete metric space and $T: X \to X$ is a strict contraction, then T has a unique fixed point.

Proof. Exercise/see second year analysis.

3.2 Dual Space and Dual Operators

3.2.1 Dual Space

Definition 3.5 (Dual Space). Given a normed space $(X, \|\cdot\|)$, its dual space is $X^* := \mathcal{L}(X, \mathbb{K})$. The elements of the dual spaces are called continuous functionals on X.

Proposition 3.5. $(\ell_p)^* = \{T: \ell_p : \to \mathbb{K} \mid T(x) = \sum_i y_i x_i, y \in \ell_q \}$ where 1/p + 1/q = 1 and $\mathbb{K} = \mathbb{R}$ or \mathbb{C} .

Proof. Let $T(x) = \sum_i y_i x_i$ for some $y \in \ell_q$, it is clear that T is linear. Consider, by Hölder's inequality

$$\|T(x)\| = \left|\sum_i y_i x_i\right| \leq \|x\|_p \|y\|_q.$$

Thus, $||T|| \le ||y||_q < \infty$, implying $T \in (\ell_p)^*$.

Now, let $\phi \in (\ell_p)^*$. Fixing $y_n = \phi(e_n)$, it suffices to show that $(y_n) \in \ell_q$ since it is clear that $\phi(x) = \sum x_i y_i$ by linearity. Setting $x_i = |y_i|^q/y_i$ for all $y_i \neq 0$ and $x_i = 0$ for $y_i = 0$, consider that $\phi(\sum x_i e_i) = \sum x_i y_i = \sum |y_i|^q$. On the other hand,

$$|\phi(x)| \leq \|\phi\| \|x\|_p = \|f\| \left(\sum |x_i|^p\right)^{1/p} = \|\phi\| \left(\sum \frac{|y_i|^{qp}}{|y_i|^p}\right)^{1/p}.$$

As 1/p + 1/q = 1, we have qp = p + q and so,

$$|\phi(x)| \leq \|\phi\| \left(\sum \frac{|y_i|^{qp}}{|y_i|^p} \right)^{1/p} = \|\phi\| \left(\sum |y_i|^q \right)^{1/p}.$$

Thus,

$$\sum |y_i|^q \le \|\phi\| \left(\sum |y_i|^q\right)^{1/p},$$

implying

$$\|y_i\|_q = \left(\sum |y_i|^q\right)^{1/q} = \left(\sum |y_i|^q\right)^{1-1/p} = \frac{\sum |y_i|^q}{\left(\sum |y_i|^q\right)^{1/p}} \leq \|\phi\| < \infty,$$

and $(y_i) \in \ell_q$.

Proposition 3.6. If X is a Hilbert space, then for all $y \in X$,

$$T_{n}(x) := \langle y, x \rangle$$

is a bounded linear functional on X.

Proof. Follows by the Cauchy-Schwarz inequality.

In year two linear algebra we saw that all linear functionals on a finite dimensional space are of the form as above. In fact, this is true for all Hilbert spaces.

Lemma 3.1. Let X be a Hilbert space and Y a closed subspace of X. Then $X = Y \oplus Y^{\perp}$.

Proof. Y is complete since it is a closed subspace of a complete space. As $Y \cap Y^{\perp} = \{0\}$, it suffices to show that $Y + Y^{\perp} = X$. Let $x \in X$, then as subspaces are convex, by the nearest point property, there exists some $y \in Y$ such that ||y - x|| = dist(x, Y). Defining y' = x - y, we have x = y + y' and it remains to show $y' \in Y^{\perp}$.

Suppose otherwise, there exists some $\tilde{y} \in Y$ such that $\langle \tilde{y}, y' \rangle > 0$ (we may assume the by simply multiplying by a scalar). Then, for t > 0,

$$\begin{split} \|(y+t\tilde{y})-x\|^2 &= \langle y+t\tilde{y}-x,y+t\tilde{y}-x\rangle \\ &= \langle y-x,y-x\rangle + \langle t\tilde{y},y-x\rangle + \langle y-x,t\tilde{y}\rangle + t^2\langle \tilde{y},\tilde{y}\rangle, \\ &= \mathrm{dist}(x,Y)^2 - 2t\langle \tilde{u},x\rangle + t^2\|\tilde{y}\|^2 \end{split}$$

were for small enough t, $2t\langle \tilde{y}, x \rangle > t^2 \|\tilde{y}\|^2$ and so, $\|(y + t\tilde{y}) - x\| < \text{dist}(x, Y)$, contradiction! **N.B. I am unclear about the last equality!**

Theorem 3 (Riesz Representation Theorem). Let X be a Hilbert space and $l \in X^*$. Then there exists a unique $z \in X$ such that for all $x \in X$, $l(x) = \langle z, x \rangle$.

Proof. Uniqueness is easy to check since, if $\langle z, \cdot \rangle = \langle z', \cdot \rangle$, then $\langle z - z', \cdot \rangle = 0$ implying z - z' = 0.

If l=0 then z=0 suffices so suppose otherwise, i.e. $N:=\ker l\neq X$. Then, as $N=l^{-1}(\{0\})$ where $\{0\}$ is closed, N is also closed, and thus, by the above lemma $N\oplus N^{\perp}=X$ and so, there exists some $z_0\in N^{\perp}$ $z_0\neq 0$. Define

$$v = l(x)z_0 - l(z_0)x.$$

We see that $l(v) = l(x)l(z_0) - l(z_0)l(x) = 0$ so $v \in N$, and hence $\langle z_0, v \rangle = 0$. Unfolding the definition, we have

$$0=\langle z_0,v\rangle=\langle z_0,l(x)z_0-l(z_0)x\rangle=l(x)\|z_0\|^2-l(z_0)\langle z_0,x\rangle,$$

implying

$$l(x) = \frac{l(z_0)\langle z_0, x\rangle}{\|z_0\|^2} = \left\langle \frac{l(z_0)}{\|z_0\|^2} z_0, x \right\rangle.$$

Hence, picking $z = (l(z_0)/\|z_0\|^2)z_0$ suffices.

With this, is easy to check that the map $\phi: X \to X^*: v \mapsto \langle \cdot, v \rangle$ is in fact a isometric anti-isomorphism.

Let us now consider the dual space of ℓ_p for $p \in [1, \infty]$. In the case that p = 2, we know that ℓ_2 is a Hibert space, and so the Riesz representation theorem provides an isomorphism $\ell_2 \cong (\ell_2)^*$. In the case that $p \in (1, \infty)$, as we have seen every linear functional of ℓ_p is of the form

$$T:\ell_p\to \mathbb{K}: x\mapsto \sum_i x_iy_i,$$

for some $y \in \ell_q$, 1/p + 1/q = 1, and thus, by checking linearity, we fine $(\ell_p)^* \cong \ell_q$.

In the case the p=1, for all $y\in \ell_{\infty},\ f_y:\ell_1\to \mathbb{K}$ defined to be $f_y(x)=\sum_i x_iy_i$ is a continuous linear functional since

$$|f_y(x)| = \left|\sum_i x_i y_i\right| \leq \|y\|_\infty \left|\sum_i x_i\right| = \|y\|_\infty \|x\|_1 < \infty.$$

In particular, this provides an injection $\ell_{\infty} \hookrightarrow (\ell_1)^*$. By the same argument, we can show $\ell_1 \hookrightarrow (\ell_{\infty})^*$.

3.2.2 Dual Operators

Definition 3.6 (Dual Operator). Given a Hilbert space X, and $L \in \mathcal{L}(X,X)$, we define the dual operator $L^*: X^* \to X^*$ by

$$L^* f := f \circ L.$$

We equip L^* with the operator norm

$$||L^*|| = \sup_{f \neq 0} \frac{||L^*f||}{||f||}.$$

Proposition 3.7. $||L^*|| = ||L||$ and the following properties hold,

- $(S+T)^* = S^* + T^*;$
- for all $\alpha \in \mathbb{K}, (\alpha T)^* = \overline{\alpha} T^*;$
- $(T^*)^* = T$;
- $(ST)^* = T^*S^*$.

Consider X a Hilbert space and let $T \in \mathcal{L}(X,X)$. Then by Riesz representation, for all $f \in X^*$, there exists some $z_{T^*f} \in X$ such that $T^*f(x) = \langle z_{T^*f}, x \rangle$. On the other hand, as $T^*f(x) = f(Tx)$, by Riesz, there exists some z_f such that $T^*f(x) = f(Tx) = \langle z_f, Tx \rangle$. Comparing both equations, we have

$$\langle z_{T*f}, x \rangle = \langle z_f, Tx \rangle = \langle T^{\dagger} z_f, x \rangle,$$

where T^{\dagger} is the adjoint of T. Thus, $T^{\dagger}z_f = z_{T^*f}$.

Definition 3.7 (Dual Operator again). If X_1, X_2 are Hilbert spaces and $T \in \mathcal{L}(X_1, X_2)$, the dual operator of T is

$$T^*: X_2^* \to X_1^*: f \mapsto f \circ T.$$

By Riesz representation, $X_i^*\cong X_i$, and we may view T^* as a linear operator on $X_2\to X_1$. In particular, for all $f\in X_2^*$, $T^*f\in X_1^*$ so there exists some $z_{T^*f}\in X_1$ such that $T^*f(x)=\langle z_{T^*f},x\rangle$. On the other hand, $T^*f(x)=f(Tx)$ and so, there exists some $z_f\in X_2$ such that $T^*f(x)=\langle z_f,Tx\rangle$. So,

$$\langle z_f, Tx \rangle = \langle z_{T^*f}, x \rangle.$$

Then, we may define $T^\dagger: X_2 \to X_1$ such that $T^\dagger z_f = z_{T^*f}.$

Consider $\nabla:D(\nabla)\to L^2$ where $D(\nabla)\subseteq L^2$. Suppose for now that $D(\nabla)=C_0^\infty$, i.e. smooth, compactly supported functions. As demonstrated above, one may find the dual operator ∇^* of ∇ such that

$$\langle g, \nabla \phi \rangle = \langle \nabla^* g, \phi \rangle$$

for all $g \in L^2$, $\phi \in C_0^{\infty}$. This operator is known as the weak derivative and we shall treat this topic properly later in this course

Proposition 3.8. Given a linear operator $T \in \mathcal{L}(X_2, X_1)$ where X_1, X_2 are normed spaces, the map

$$h: X_1 \times X_2 \to \mathbb{K}: (x,y) \in X_1 \times X_2 \mapsto \langle x, Ty \rangle$$

is a sesquilinear form.

Definition 3.8 (Bounded Sesquilinear Form). A sesquilinear form h on a normed space is bounded if

$$||h(\cdot,\cdot)|| := \sup_{x,y\neq 0} \frac{|h(x,y)|}{||x|||y||} < \infty.$$

Proposition 3.9. Let X_1, X_2 be Hilbert spaces and let h be a bounded sesquilinear form. Then h has the representation

$$h(x,y) = \langle Sx, y \rangle,$$

for some $S \in \mathcal{L}(X_1, X_2)$ such that ||S|| = ||h||.

Proof. For all $x \in X_1$, as $h(x,\cdot): X_2 \to \mathbb{K} \in X_2^*$, by Riesz, there exists some z_x such that $h(x,\cdot) = \langle z_x, \cdot \rangle$. Thus, simply defining $S: X_1 \to X_2: x \mapsto z_x$ suffices after simple checks for linearity.

Consider

$$||h|| = \sup_{x,y \neq 0} \frac{|h(x,y)|}{||x|| ||y||} = \sup_{x,y \neq 0} \frac{|\langle Sx,y \rangle|}{||x|| ||y||} \ge \sup_{x \neq 0} \frac{|\langle Sx,Sx \rangle|}{||x|| ||Sx||} = \sup_{x \neq 0} \frac{||Sx||}{||x||} = ||S||.$$

On the other hand,

$$||h|| = \sup_{x,y \neq 0} \frac{|\langle Sx, y \rangle|}{||x|| ||y||} \le \sup_{x,y \neq 0} \frac{||Sx|| ||y||}{||x|| ||y||} = ||S||,$$

where the inequality is due to Cauchy-Schwarz. Thus ||h|| = ||S|| as required.

3.3 Tietze-Urysohn and Hahn-Banach

Lemma 3.2 (Urysohn's Lemma). For $A, B \subseteq X$ closed with $A \cap B = \emptyset$, then there exists a continuous function such that $h \mid_A = 1$ and $h \mid_B = 0$.

Proof. Consider

$$h(x) := \frac{\operatorname{dist}(x,B)}{\operatorname{dist}(x,A) + \operatorname{dist}(x,B)}.$$

Theorem 4 (Tietze-Urysohn). If $f: A \to \mathbb{R}$ is a continuous function where A is a closed set in a metric space X, then there exists a continuous function $\tilde{f}: X \to \mathbb{R}$ such that $\tilde{f} \mid_A = f$ and $\|\tilde{f}\| = \|f\|$.

Proof. We may assume ||f|| = 1 and $0 \le f \le 1$ by scaling the function.

Define $f_0 = f$ and $f_{n+1} = f_n - g_n \mid_A$ where g_n is defined using Urysohn's Lemma such that

$$g_n(x) = \begin{cases} 0, & x \in f_n^{-1}([0, \frac{1}{3}(\frac{2}{3})^n]); \\ \frac{1}{3}\left(\frac{2}{3}\right)^n, & x \in f_n^{-1}([(\frac{2}{3})^n, (\frac{2}{3})^{n+1}]). \end{cases}$$

In some sense, what we are doing taking g_{n+1} to approximate the errors of $f_n - g_n \mid A$.

By construction, we see that $0 \le f_n \le (\frac{2}{3})^n$, and $\sum_{i=0}^n g_i = f - f_{n+1}$, defining $\tilde{f} = \sum_i g_i$ (which exists as $0 \le g_n \le \frac{1}{3}(\frac{2}{3})^n$, implying $\sum^n g_i$ is Cauchy, hence convergent by the completeness of C(A)), we have

$$\sum_{i=0}^{n} g_i \mid_C -f = -f_{n+1} \to 0,$$

and so $\tilde{f}|_{C} = f$ as required.

Definition 3.9. A functional $p: X \to \mathbb{R}$ is called sublinear if

- $p(x+y) \le p(x) + p(y)$;
- for all $\alpha \geq 0$, $p(\alpha x) = \alpha p(x)$.

Theorem 5 (Hahn-Banach). Let X be a normed space, Z a proper subspace of X, $p: X \to \mathbb{R}$ a sublinear functional and $f: Z \to \mathbb{R}$ such that $f(x) \leq p(x)$ for all $x \in Z$. Then, there exists some linear functional $\tilde{f}: X \to \mathbb{R}$ such that

$$\tilde{f}|_{z} = f$$
 and $\tilde{f}(x) \le p(x)$

for all $x \in X$.

Proof. Let us first consider the special case of extending f by 1-dimension. Let $v \in X \setminus Z$ and $W := \operatorname{span}(Z, v)$. Define

$$\tilde{f}: W \to \mathbb{R}: z + \lambda v \mapsto f(z) + \lambda \alpha$$

for some $\alpha \in \mathbb{R}$. It suffices to show that

$$\tilde{f}(z + \lambda v) \le p(z + \lambda v).$$

In particular, if $\lambda > 0$, then $\alpha \le p\left(\frac{1}{\lambda}z + v\right) - \tilde{f}\left(\frac{1}{\lambda}z\right)$, and if $\lambda < 0$, then $\alpha \ge -p\left(\frac{1}{-\lambda}z - v\right) + \tilde{f}\left(\frac{1}{-\lambda}z\right)$. Combining the two, we have for all $\lambda > 0$,

$$-p\left(\frac{1}{\lambda}z-v\right)+\tilde{f}\left(\frac{1}{\lambda}z\right)\leq\alpha\leq p\left(\frac{1}{\lambda}z+v\right)-\tilde{f}\left(\frac{1}{\lambda}z\right),$$

and by rescaling, the condition becomes

$$-p\left(z-v\right)+\tilde{f}\left(z\right)\leq\alpha\leq p\left(z+v\right)-\tilde{f}\left(z\right).$$

This holds if and only if

$$-p(z_1-v)+\tilde{f}(z_1)\leq p(z_2+v)+\tilde{f}(z_2)$$

for all $z_1, z_2 \in \mathbb{Z}$. Indeed, this holds as,

$$\tilde{f}(z_1) + \tilde{f}(z_2) = \tilde{f}(z_1 + z_2) \leq p(z_1 + z_2) = p((z_1 - v) + (z_2 + v)) \leq p(z_1 - v) + p(z_2 + v).$$

With this 1-dimensional extension in mind, the result follows by Zorn's lemma. In particular, given two extensions of f, $(M_1,g_1),(M_2,g_2)$ where $Z\subseteq M_1,Z\subseteq M_2$ and $g_1\mid_{Z}=g_2\mid_{Z}=f$, we define the partial order \prec such that $(M_1,g_1)\prec (M_2,g_2)$ if and only if $M_1\subseteq M_2$ and $g_2\mid_{M_1}=g_1$. Then, for any chain of extensions $(M_\gamma,g_\gamma)_{\gamma\in T}$, define $M=\bigcup_{\gamma\in T}M_\gamma$ and

$$G:M\to \mathbb{R}: x\mapsto g_\gamma(x) \text{ if } x\in M_\gamma.$$

It is clear that G is continuous and for all (M_{γ}, g_{γ}) , we have $(M_{\gamma}, g_{\gamma}) \prec (M, G)$. Hence, every chain of extensions has an upper bounds, and thus, by Zorn's lemma, there is an maximal extension (M, G). Finally, it suffices to show that M = X which is clear since if otherwise, we may extend G with an additional dimension, contradicting the maximality of (M, G).

3.4 Application of Hahn-Banach

In this section we will demonstrate some applications of the Hahn-Banach theorem.

Corollary 3.1 (Existence of tangent functional). Let X be a normed space and let $x \in X$, then there exists some $l \in X^*$ such that ||l|| = 1 and l(x) = ||x||.

Proof. Apply Hahn-Banach to $f: \mathbb{R} \cdot x \to \mathbb{R} : \lambda \mapsto \lambda \|x\|$.

Corollary 3.2. Let X be a normed space, for all $x \in X$,

$$\|x\| = \sup\{|l(x)| \mid l \in X^*, \|l\| = 1\}.$$

Proof. For all ||l|| = 1, we have $|l(x)| \le ||l|||x|| = ||x||$. Now, by the previous corollary, ||x|| is achieved by some $l \in X^*$, ||l|| = 1 and so, $||x|| = \sup\{|l(x)| \mid l \in X^*, ||l|| = 1\}$ as required. \square

Theorem 6 (Banach Limit Theorem). There exists $L \in (\ell_{\infty})^*$ such that

- ||L|| = 1;
- if $x \in c \subseteq \ell_{\infty}$, then $L(x) = \lim_{n \to \infty} x_n$;
- if $x \in \ell_{\infty}$ and $x_i \geq 0$ for all i, then $L(x) \geq 0$;
- if $x \in \ell_{\infty}$ and $x'_n := x_{n+1}$, then L(x) = L(x').

Theorem 7 (Müntz-Szäsz). Suppose $0 < \lambda_1 < \lambda_2 < \cdots$, and let X be the closure of the set of linear combinations of t^{λ_j} in $\mathcal{C}[0,1]$. Then

- if $\sum_{j} \frac{1}{\lambda_j} = \infty$, then $X = \mathcal{C}[0, 1]$;
- if $\sum_j \frac{1}{\lambda_k} < \infty$, then for $\lambda \notin \{\lambda_j\}_{j \in \mathbb{N}}, t^{\lambda} \notin X$, and so $X \subsetneq \mathcal{C}[0,1]$.

Proposition 3.10. Let Y be a closed proper subspace of a normed space X. Then, there exists some $f \in X^*$ such that ||f|| = 1 and f(y) = 0 for all $y \in Y$.

Proof. Let $x \in X \setminus Y$. If $X = \operatorname{span}(\{x\} \cup Y)$, then the map $\lambda x + y \mapsto \lambda$ suffices. On the other hand, defining $l : \lambda x + y \mapsto \lambda$, with Hahn-Banach, there exists some $f \in X^*$ such that $f|_{Y} = l = 0$ and ||f|| = ||l|| = 1.

Proposition 3.11. If X^* is separable, then so is X.

Proof. Let $S^* := \{ \phi \in X^* \mid \|\phi\| = 1 \}$. Then, as a subset of a separable space is separable, S^* is separable by some $\{ \phi_n \} \subseteq S^*$. By definition, for each n, we may define x_n such that $\|x_n\| = 1$ and $\phi_n(x_n) > 1/2$. Now, let

$$\mathcal{D} := \overline{\operatorname{span}\{x_n \mid n \in \mathbb{N}\}}.$$

By definition, it is clear that \mathcal{D} is dense by considering the density of \mathbb{Q} in \mathbb{R} and thus, it suffices to show $\mathcal{D} = X$.

Suppose $\mathcal{D} \neq X$, then by the previous proposition, there exists a linear functional $\phi \in S^*$ such that $\phi(y) = 0$ for all $y \in \mathcal{D}$. Now, as $\{\phi_n\}$ is dense in S^* , there exists n such that $\|\phi - \phi_n\| < 1/2$. Hence,

$$\begin{split} |\phi(x_n)| &\geq |\phi_n(x_n)| - |\phi_n(x_n) - \phi(x_n)| > 1/2 - |(\phi_n - \phi)(x_n)| \\ &\geq 1/2 - \|\phi - \phi_n\| \|x_n\| > 1/2 - 1/2 = 0. \end{split}$$

But $x_n \in \mathcal{D}$ implying $\phi(x_n) = 0$, contradiction!

3.4.1 Stieltjes Integral

Stieltjes integral is a method of defining integration similar to that of the Riemann integral (one may construct a similar version to the Lebesgue integral as well). In particular, given some function ω , we replace the individual segments $x_{i+1} - x_i$ with $|\omega(x_{i+1}) - \omega(x_i)|$.

Definition 3.10 (Total Variation of Functions). The total variation of a function ω on the interval [a, b] is

$$V(\omega) := \sup_{p \in \mathcal{P}} \sum_{i=1}^{|p|-1} |\omega(x_{i+1}) - \omega(x_i)|,$$

where \mathcal{P} is the set of all partitions on [a, b].

In the case that the total variation is finite, we may define the lower Stieltjes sum of the function f to be

$$s_{\omega}(p) := \sum_{i=1}^{|p|-1} f(\underline{x_i})(\omega(x_{i+1}) - \omega(x_i)),$$

and the upper sum to be

$$S_{\omega}(p) := \sum_{i=1}^{|p|-1} f(\overline{x_i})(\omega(x_{i+1}) - \omega(x_i)),$$

where p is a partition, $f(\underline{x_i}) = \min_{x \in [x_i, x_{i+1}]} f(x)$ and $f(\overline{x_i}) = \max_{x \in [x_i, x_{i+1}]} f(x)$. We observe that $|s_{\omega}|, |S_{\omega}| \leq \|f\|_{\infty} V(\overline{\omega})$.

If $\inf S_{\omega} = \sup s_{\omega}$ as the size of the segments of the partition tends to zero, then we define the Stieltjes integral of f with respect to $d\omega$ to be

$$\int_a^b f \mathrm{d}\omega := \inf S_\omega.$$

In the case that ω is differentiable then we see $\int f d\omega = \int f \omega' dx$.

Proposition 3.12. Let $l \in \mathcal{C}([a,b])^*$ can be represented as

$$l(f)=l_{\omega}(f):=\int f\mathrm{d}\omega,$$

for some ω with finite total variation and $||l_{\omega}|| = V(\omega)$.

Proof. By the Hahn-Banach theorem, as $\mathcal{C}([a,b]) \subseteq \mathcal{B}([a,b])$, there exists some $\tilde{l} \in \mathcal{B}([a,b])^*$ such that $\|l\| = \|\tilde{l}\|$ and $\tilde{l}|_{\mathcal{C}(a,b)} = l$. Define $\omega(t) := \tilde{l}(\chi_{[a,t]})$ where χ is the indicator function, we see that ω has bounded variation as

$$\begin{split} V(\omega) &= \sum |\omega(x_{i+1} - x_i)| = \sum |\tilde{l}(\chi_{[a,t]}(x_{i+1}) - \chi_{[a,t]}(x_i))| \\ &= \sum s_i(\tilde{l}(\chi_{[a,t]}(x_{i+1}) - \chi_{[a,t]}(x_i)) = \tilde{l} \sum s_i(\chi_{[a,t]}(x_{i+1}) - \chi_{[a,t]}(x_i) \\ &\leq \|\tilde{l}\| \left\| \sum s_i(\chi_{[a,t]}(x_{i+1}) - \chi_{[a,t]}(x_i) \right\| = \|\tilde{l}\| \left\| \sum s_i\chi_{[x_i,x_{i+1}]}(x) \right\| \end{split}$$

where $s_i = \mathrm{sign}(\tilde{l}(\chi_{[a,t]}(x_{i+1}) - \chi_{[a,t]}(x_i)).$ Then, for all $f \in \mathcal{C}([a,b])$ and a partition p, define

$$g_n = \sum f(x_i) (\chi_{[a,t]}(x_{i+1}) - \chi_{[a,t]}(x_i)).$$

In particular, we note that $\|g_n - f\|_{\infty} \to 0$ as $n \to \infty$ and thus,

$$l(f) = \tilde{l}(f) \leftarrow \tilde{l}(g_n) = \sum f(x_i)(\chi_{[a,t]}(x_{i+1}) - \chi_{[a,t]}(x_i)) = \int_a^b f \mathrm{d}\omega.$$

4 Uniform Boundedness Principle

In this section we will prove the uniform boundedness principle, also known as the Banach-Steinhaus theorem. To achieve this we will first prove the Baire's category theorem. We will also provide some application of this principle.

4.1 Baire's Category Theorem

Definition 4.1 (Baire's Category). Let (X, ρ) be a metric space. Then a subspace $M \subseteq X$ is said to be

- nowhere dense if $(\overline{M})^{\circ} = \emptyset$;
- of the 1st category (or meager) if there exists a sequence of nowhere dense set $(M_n)_{n\in\mathbb{N}}$ such that $M=\bigcup_{n\in\mathbb{N}}M_n$;
- of the 2nd category (or nonmeager) if it is not of the first category.

An example of a meager set is $\mathbb{Q} \subseteq \mathbb{R}$. Indeed, as \mathbb{Q} is countable, it is a countable union of singletons, each of which are nowhere dense.

Theorem 8 (Baire's Category Theorem). If a metric space $X \neq \emptyset$ is complete, then it is of the 2nd category. Thus, if $X \neq \emptyset$ and

$$X = \bigcup_{k=1}^{\infty} A_k,$$

for some sequence of sets, then at least one A_k is not nowhere dense, i.e. contains a non-empty open subset.

Proof. Suppose otherwise, i.e. $X = \bigcup A_n$ where A_n is nowhere dense for all $n \in \mathbb{N}$. By definition $\overline{A_n}$ does not contain a non-empty open set and so, $\overline{A_n} \neq X$ (as X contains itself which is a non-empty open set) and $\overline{A_n}^c \neq \emptyset$ is open.

Let $p_1\in\overline{A_1}^c$ and let $\epsilon_1\in(0,1/2)$ such that $B_{\epsilon_1}(p_1)\subseteq\overline{A_1}^c$. Now, as A_2 is nowhere dense, $B_{\epsilon_1}(p_1)\nsubseteq A_2$ and so $\overline{A_2}^c\cap B_{\epsilon_1}(p_1)$ is a non-empty open set. Then, we may choose $p_2\in\overline{A_2}^c\cap B_{\epsilon_1}(p_1)$ and $\epsilon_2\in(0,1/4)$ such that $B_{\epsilon_2}(p_2)\subseteq\overline{A_2}^c\cap B_{\epsilon_1}(p_1)$. Repeating this process, we may find $p_{n+1}\in\overline{A_{n+1}}^c\cap B_{\epsilon_n}(p_n)$ and $\epsilon_{n+1}\in(0,1/2^{n+1})$ such that

$$B_{\epsilon_{n+1}}(p_{n+1}) \subseteq \overline{A_{n+1}}^c \cap B_{\epsilon_n}(p_n).$$

It is clear that $(p_n)_{n\in\mathbb{N}}$ is Cauchy as for all $n,m\geq N,$ $p_n,p_m\in B_{\epsilon_N}(p_N)\subseteq B_{1/2^N}(p_N)$ and thus,

$$d(p_n,p_m) \leq d(p_n,p_N) + d(p_N,p_m) < \frac{1}{2^N} + \frac{1}{2^N} = \frac{1}{2^{N-1}} \to 0$$

as $N \to \infty$. Hence, as X is complete, there exists some $p \in X$ such that $p_n \to p$ as $n \to \infty$. Now, by the triangle inequality, for all n,

$$d(x,x_n) \le d(x,x_{n+k}) + d(x_{n+k},x_n) < d(x,x_{n+k}) + \frac{1}{2^n},$$

and so, taking $k \to \infty$, $d(x, x_{n+k}) \to 0$ and so, $d(x, x_n) < 1/2^n$ implying $x \in B_{\epsilon_n}(p_n)$. But then, $x \in \bigcap B_{\epsilon_n}(p_n) \subseteq \bigcap \overline{A_n}^c$ implying $x \notin \bigcup A_n$, and hence, $\bigcup A_n \neq X$.

4.2 Banach-Steinhaus Theorem

Theorem 9 (Banach-Steinhaus). Let $(T_n)_{n\in\mathbb{N}}$ be a sequence of bounded linear operators from a Banach space X to a normed space Y such that for all $x\in X$, there exists $c_x\in(0,\infty)$ and

$$\sup_{n\in\mathbb{N}}\|T_nx\|\le c_x.$$

Then, there exists some $c \in (0, \infty)$ such that

$$\sup_{n\in\mathbb{N}}\|T_n\|\leq c.$$

Proof. For $k \in \mathbb{N}$, define

$$A_k := \{ x \in X \mid ||T_n x|| \le k, n \in \mathbb{N} \}.$$

It is easy to see that A_k is closed for each k. Indeed, if $x_n \in A_k$ such that $x_n \to x \in X$, then $\|T_n x\| \le k$ for all n by the continuity of the $\|T_n(\cdot)\|$. Furthermore, as $X = \bigcup A_k$ (as T_n is pointwise uniformly bounded), by the Baire's category theorem, there exists some $k_0 \in \mathbb{N}$, $x_0 \in X$, r > 0, such that

$$B_r(x_0) \subseteq A_{k_0}$$
.

Then, for all $x \in X \setminus \{0\}$, let $\gamma_x := r/(2\|x\|)$ and $z := x_0 + \gamma x$. It is clear that $z \in B_r(x_0)$ and so, for all $n \in \mathbb{N}$,

$$k_0 \geq \|T_n z\| = \|T_n(x_0 + \gamma x)\| \geq |\gamma\|T_n x\| - \|T_n x_0\|| \geq r \frac{\|T_n x\|}{\|x\|} - \|T_n x_0\|.$$

Hence, $\|T_nx\|/\|x\| \le (k_0 + \|T_nx_0\|)/r$, and since $\|T_nx_0\| \le \sup_n \|T_nx_0\| \le c_{x_0}$, we have the bound $\|T_nx\|/\|x\| \le (k_0 + c_{x_0})/r$. Thus, n and x are arbitrary, we have

$$\sup_{n\in\mathbb{N}}\|T_n\|\leq \frac{1}{r}(k_0+c_{x_0}).$$

Proposition 4.1. Let X be the space of polynomials equipped with the norm $||a_0 + a_1 t + \cdots + a_n t^n|| := \max_{i=0,\cdots,n} |a_i|$. Then X is not complete.

Proof. Define $T_n(p(t)):=\sum_{i=0}^n a_i$ where $p(t)=\sum_{i=0}^m a_i t^i$. Clearly, T_n is linear and for all $p(t)=\sum_{i=0}^m a_i t^i \in X$, $\|p\|=1$, $a_i \leq 1$ for all $i=1,\cdots,m$ implying $\|T_n(p)\|=|\sum^n a_i| \leq n+1$. Now, fixing $p(t)=\sum_{i=0}^m a_i t^i \in X$, we have $\|T_n p\| \leq \sum_{i=0}^m |a_i|$, and so, if X is complete, by the Banach-Steinhaus theorem, $\sup_n \|T_n\|$ is bounded. But for all n, we have

$$\|T_n(1+x+\cdots+x^n)\|=\sum_{i=0}^n 1=n+1,$$

where $\|1+x+\cdots+x^n\|=1$, we have $\|T_n\|\geq n+1$. Thus, $\sup_n\|T_n\|\geq \sup_n(n+1)=\infty$ implying $\sup_n\|T_n\|$ is not bounded and hence, X is not complete.

The Banach-Steinhaus theorem also allows us to show the existence of a continuous function which has Fourier series divergent at a point.

Let $u \in \mathcal{C}([0,2\pi],\mathbb{R})$, and recall that it has Fourier coefficients defined by

$$a_m := \frac{1}{\pi} \int_0^{2\pi} u(t) \cos(mt) \mathrm{d}t; \ b_m := \frac{1}{\pi} \int_0^{2\pi} u(t) \sin(mt) \mathrm{d}t,$$

and its Fourier series is defined by

$$\mathcal{F}_u := \sum_{m \in \mathbb{N}} (a_m \cos(mt) + b_m \sin(mt)).$$

Let $X := \mathcal{C}([0, 2\pi], \mathbb{R})$ and define the sequence of linear operator T_n on X such that, for all $x \in X$,

$$T_n x := \frac{1}{2} a_0 + \sum_{m=1}^n a_m = \frac{1}{\pi} \int_0^{2\pi} x(t) \left(\frac{1}{2} + \sum_{m=1}^n \cos(mt) \right) \mathrm{d}t.$$

That is $T_n x$ is the Fourier series at t = 0 resumed only up to the *n*-th term. We will find some $x \in X$ such that $||T_n x||$ is not uniformly bounded, and so, the Fourier series of x diverges. Noting that

$$\begin{split} 2\sin\left(\frac{1}{2}t\right)\sum_{m=1}^{n}\cos(mt) &= \sum_{m=1}^{n}\left(\sin\left(\left(m+\frac{1}{2}\right)t\right) - \sin\left(\left(m-\frac{1}{2}\right)t\right)\right) \\ &= \sin\left(\left(n+\frac{1}{2}\right)t\right) - \sin\left(\frac{1}{2}\right), \end{split}$$

as the second sum is telescoping, we have

$$1 + 2\sum_{m=1}^{n} \cos(mt) = \frac{\sin((n + \frac{1}{2})t)}{\sin(\frac{1}{2}t)} =: q_n(t).$$

Thus,

$$T_n x = \frac{1}{2\pi} \int_0^{2\pi} x(t) q_n(t) \mathrm{d}t.$$

With this representation in mind, we see that

$$\|T_n x\| \leq \frac{1}{2\pi} \|x\| \int_0^{2\pi} |q_n(t)| \mathrm{d}t,$$

and so, $||T_n|| \leq \frac{1}{2\pi} \int_0^{2\pi} |q_n(t)| \mathrm{d}t$. On the other hand, write $y(t) := \mathrm{sign}(q_n(t))$ so that |q(t)| = |y(t)q(t)|. While y is not continuous, it can be approximated by continuous functions of norm 1 in the sense that for all $\epsilon > 0$, there exists a continuous function x of norm 1 such that

$$\epsilon > \frac{1}{2\pi} \left| \int_0^{2\pi} (x(t) - y(t)) q_n(t) \mathrm{d}t \right| = \left| T_n x - \frac{1}{2\pi} \int_0^{2\pi} \left| q_n(t) \right| \right|.$$

Thus, as $\int_0^{2\pi} |q_n(t)| dt \to \infty$ as $n \to \infty$, there must be some $x \in X$ such that $||T_n x||$ is not uniformly bounded as otherwise, this would contradict Banach-Steinhaus.

Let us now turn our focus back to ℓ_p spaces.

Proposition 4.2. Let $p,q\in(1,\infty)$ such that 1/p+1/q=1 and suppose $(a_n)_{n\in\mathbb{N}}$ is a sequence of complex numbers such that $|\sum a_nx_n|<\infty$ for all $(x_n)\in\ell_p$. Then $(a_n)\in\ell_q$.

Proof. WLOG. let us assume (a_n) does not have any 0 terms. Let $f_n(x) := \sum_{i=0}^n a_i x_i$. It is not difficult to see that (f_n) are bounded linear and is pairwise uniformly bounded. Now, by Hölder, we have

$$|f_n(x)| \leq \left(\sum_{i=1}^n |a_i|^q\right)^{1/q} \|x\| p,$$

and so, $||f_n|| \leq \left(\sum_{i=1}^n |a_i|^q\right)^{1/q}$. On the other hand, this bound is achieved by taking

$$x_i := \begin{cases} \frac{\overline{a_k}|a_i|^{q-2}}{(\sum_j^n|a_j|^q)^{1-q/q}}, \ k=1,\cdots,n, \\ 0, \ \text{otherwise}. \end{cases}$$

So, $\left(\sum_{i=1}^{n}|a_{i}|^{q}\right)^{1/q}=\|f_{n}\|$ and by Banach-Steinhaus,

$$\|a\|_q = \left(\sum_{i=1}^\infty |a_i|^q\right)^{1/q} = \sup_n \|f_n\| < \infty.$$

4.3 Open Mapping Theorem

Definition 4.2. Let X, Y be metric spaces, then the function $T: D(T) \subseteq X \to Y$ is an open mapping if for all $U \subseteq D(T)$ open, T(U) is open in Y.

Theorem 10 (The Open Mapping Theorem). A bounded linear operator $T: X \to Y$ between Banach spaces X, Y is an open mapping if it is surjective.

Proof. Let $B_r^X(x)$, $B_r^Y(y)$ denote open balls of radius r in X and Y respectively and B_r^X , B_r^Y denote open balls centred at the origin with radius r.

Since T is linear, it suffices to show that $T(B_1^X)$ contains an open ball containing 0 in Y. Indeed, for all open $A \subseteq D(T)$, if $y \in T(A)$, by definition, there exists some $x \in A$ such that T(x) = y. Now, as A is open, there exists some $B_r^X(x) \subseteq A$, and so $B_1^X = \frac{1}{r}(B_r^X(x) - x) \subseteq \frac{1}{r}(A - x)$. Then, by assumption, there exists some $\epsilon > 0$ such that

$$B_{\epsilon}^Y \subseteq T(B_1^X) \subseteq T\left(\frac{1}{r}(A-x)\right) = \frac{1}{r}(T(A)-T(x)) = \frac{1}{r}(T(A)-y).$$

Thus, $rB_{\epsilon}^Y + y \subseteq T(A)$. Now, since $y \in rB_{\epsilon}^Y + y \subseteq T(A)$ we have found an open ball containing y which is contained in T(A). Hence, T(A) is open and T is an open mapping.

We will first show $T(B_{1/2}^X(0))$ contains an open ball B^* not necessary centred at the origin. Consider

$$Y = T(X) = T\left(\bigcup_{k=1}^{\infty} kB_{1/2}(0)\right) = \bigcup_{k=1}^{\infty} kT(B_{1/2}(0)) = \bigcup_{k=1}^{\infty} \overline{kT(B_{1/2}(0))}.$$

By the Baire category theorem, at least on of the $\overline{kT(B_{1/2}(0))}$ must contain an open ball, and thus, by rescaling, we obtain an open ball $B^* = B_{\epsilon}(y_0) \subseteq \overline{T(B_{1/2}(0))}$.

Now, as $y_0 \in B_{\epsilon}(y_0) \subseteq \overline{T(B_{1/2}(0))}$ and, for all $y \in B_{\epsilon}(0) = B_{\epsilon}(y_0) - y_0$, we have $y + y_0 \in B_{\epsilon}(y_0) \subseteq \overline{T(B_{1/2}(0))}$, taking sequences $(u_n), (v_n) \subseteq T(B_{1/2}(0))$ such that $u_n \to y + y_0$ and $v_n \to y_0$, there exists some $(w_n), (z_n) \subseteq B_{1/2}(0)$ such that $Tw_n = u_n \to y + y_0, Tz_n = v_n \to y_0$. Then, by sequential continuity

$$T(w_n-z_n)=Tw_n-Tz_n=u_n-v_n\to y,$$

and $w_n - z_n \in B_1(0)$ as $\|w_n - z_n\| \le \|w_n\| + \|z_n\| < 1/2 + 1/2 = 1$. Hence, $y \in \overline{T(B_1(0))}$ and thus, $B_{\epsilon}(0) \subseteq \overline{T(B_1(0))}$.

Finally, we will show that $B_{\epsilon/2}(0) \subseteq T(B_1(0))$. By linearity, we have

$$V_n := B_{\epsilon/2^n}(0) \subseteq 2^{-n} \overline{T(B_1(0))} = \overline{T(B_{1/2^n}(0))} =: \overline{T(B_n)}.$$

Let $y \in B_{\epsilon/2} = V_1$, then $y \in \overline{T(B_1)}$ and thus, there exists some $x_1 \in B_1$ such that $\|y - Tx_1\| < \epsilon/4$. This means that $y - Tx_1 \in V_2 \subseteq \overline{T(B_2)}$ and there exists some $x_2 \in B_2$, $\|y - Tx_1 - Tx_2\| < \epsilon/8$. Repeating this process, we find a sequence (x_n) such that $x_n \in B_n$ and

$$\left\| y - \sum_{k=1}^{n} Tx_k \right\| < \frac{\epsilon}{2^{n+1}}.$$

Considering for n > m,

$$\left\| \sum_{k=1}^n Tx_k - \sum_{k=1}^m Tx_k \right\| = \left\| \sum_{k=m+1}^n Tx_k \right\| \leq \sum_{k=m+1}^n \|Tx_k\| \leq \sum_{k=m+1}^\infty \|Tx_k\| < \sum_{k=m+1}^\infty \frac{1}{2^k} \to 0,$$

as $m \to \infty$, we have $S_n := \sum_{k=1}^n Tx_k$ is Cauchy, and thus converges to some $s \in Y$. As $\|y - S_n\| < \epsilon/2^{n+1}$, $\|y - s\| \le \|y - S_n\| + \|S_n - s\| \to 0$ as $n \to \infty$, $\|y - s\| = 0$ and thus, y = s.

Now, $\sum_{k=1}^n x_k$ converges to some $x \in X$ as it is absolutely convergent since $x_n \in B_n$ implying $\|x_n\| < 1/2^n$ and so $\sum \|x_n\| < \sum 1/2^n = 1 < \infty$. Thus, by sequential continuity, we have $T(\sum_{k=1}^n x_k) \to Tx$ as $n \to \infty$ and so, Tx = y. Finally, $x \in B_1(0)$ since addition is continuous, and so

$$\|x\| = \lim_{n \to \infty} \left\| \sum_{k=1}^n x_n \right\| \le \lim_{n \to \infty} \sum_{k=1}^n \|x_n\| < \lim_{n \to \infty} \sum_{k=1}^n \frac{1}{2^k} = 1,$$

implying $x \in B_1(0)$ and thus, as y = Tx, $y \in T(B_1(0))$.

With the open mapping theorem, we see that a bijective bounded linear operator is automatically a homeomorphism and T^{-1} is bounded.

Theorem 11 (Bounded Inverse Theorem). Let X, Y be Banach spaces and suppose $T : X \to Y$ is a bijective, bounded linear operator. Then, so is $T^{-1} : Y \to X$.

Proof. The inverse of a bijective linear operator is linear and so it suffices to show boundedness. However, this follows, as boundedness is equivalent to continuous which follows by the open mapping theorem. \Box

4.4 Closed Graph Theorem

Definition 4.3 (Closed Linear Operator). Let X, Y be normed spaces and $T : D(T) \subseteq X \to Y$ be a linear operator. The graph of T is defined to be the set

$$\mathcal{G}(T) := \{ (x, Tx) \in X \times Y \mid x \in D(T) \}.$$

T is said to be a closed linear operator if its graph is closed in the normed space equipped with the norm $\|(x,y)\| = \|x\|_X + \|y\|_Y$.

Proposition 4.3. Let X,Y be normed spaces and $T:D(T)\subseteq X\to Y$ be a linear operator. Then T is a closed linear operator if and only if for all $(x_n)\subseteq D(T),\,x_n\to x$ and $Tx_n\to y$, we have $x\in D(T)$ and Tx=y.

Proof. Suppose $(x_n, Tx_n) \in \mathcal{G}(T)$ such that $(x_n, Tx_n) \to (x, y) \in X \times Y$. Then

$$0 \leftarrow \|(x_n, Tx_n) - (x, y)\| = \|(x_n - x, Tx_n - y)\| = \|x_n - x\|_X + \|Tx_n - y\|_Y,$$

and so, $x_n \to x$ and $Tx_n \to y$ and thus, Tx = y implying $(x, y) \in \mathcal{G}(T)$ and $\mathcal{G}(T)$ is closed.

Conversely, if $\mathcal{G}(T)$ is closed, then for all $x_n \to x$, $Tx_n \to y$, (x,y) is a limit point of $\mathcal{G}(T)$. Thus,, as $\mathcal{G}(T)$ is closed, $(x,y) \in \mathcal{G}(T)$ and so, y = Tx.

Corollary 4.1. Let X, Y be normed spaces and $T : D(T) \subseteq X \to Y$ be a continuous linear operator. Then T is a closed linear operator if D(T) is closed.

Proof. Suppose $x_n \to x \in X$ and $Tx_n \to y$. As D(T) is closed, $x \in D(T)$, and by sequential continuity, Tx = y.

Theorem 12 (Closed Graph Theorem). Let X, Y be Banach spaces and $T : D(T) \subseteq X \to Y$ be a closed linear operator. Then if D(T) is closed in X, then T is bounded.

Proof. We first observe that $X \times Y$ is complete. Indeed, if $((x_n, y_n))_{n \in \mathbb{N}}$ is Cauchy, then so are $(x_n), (y_n)$. Thus, as both X, Y are Banach, there exists some $x \in X, y \in Y, x_n \to x, y_n \to y$ and so,

$$\|(x_n, y_n) - (x, y)\| = \|x_n - x\| + \|y_n - y\| \to 0.$$

Furthermore, since $\mathcal{G}(T)$ and D(T) are by assumption closed, they are also complete as they are closed subspaces of a Banach space.

Now, define

$$P:\mathcal{G}(T)\to D(T):(x,Tx)\to x.$$

It is clear that P is linear and is bounded since for all $(x, Tx) \in \mathcal{G}(T)$, $\|(x, Tx)\| = 1$, we have $1 = \|(x, Tx)\| = \|x\| + \|Tx\| \ge \|x\| = \|P(x, Tx)\|$. Furthermore, P is bijective with the inverse $P^{-1}(x) = (x, Tx)$ which is also a bounded linear operator (as the inverse of a bounded linear operator is bounded). But, this implies

$$||Tx|| \le ||x|| + ||Tx|| = ||(x, Tx)|| = ||P^{-1}(x)|| \le ||P^{-1}|| ||x||,$$

proving T is bounded.

5 Spectral Theory

In this section we will introduce some tools applicable for the study of PDEs.

5.1 Weak Convergence

Definition 5.1 (Weak Convergence). A sequence (x_n) in a normed space X is said to be weakly convergent if there exists some $x \in X$ such that for all $f \in X^*$,

$$\lim_{n \to \infty} f(x_n) \to f(x).$$

In this case, we say (x_n) converges weakly to x and denote it by $x_n \rightharpoonup x$. In contrast to this, if (x_n) converges in the norm sense, then we say (x_n) converges strongly.

Proposition 5.1. Let (x_n) be a sequence in a normed space X which converges weakly, then

- it has a unique weak limit;
- every subsequence of (x_n) converges to the same limit;
- $\{\|x_n\|, n \in \mathbb{N}\}$ is bounded.

Proof. If $x_n \to x$ and $x_n \to y$, then by definition, for all $f \in X^*$, $f(x) \leftarrow f(x_n) \to f(y)$ and so, as limits are unique in the underlying field, f(x) = f(y) and so f(x - y) = 0. If $x \neq y$ then we may define a non-zero linear functional from the span of x - y which may be extended to the whole space by Hahn-Banach. Thus, x - y = 0 and so x = y.

A subsequence of $f(x_n)$ converges to f(x) for all $f \in X^*$ through usual convergence and so the claim is as required.

Since $f(x_n) \to f(x)$ for all $f \in X^*$, $|f(x_n)|$ is bounded by some c_f . Define $g_n \in (X^*)^*$: $f \mapsto f(x_n)$, we have $\sup_{n \in \mathbb{N}} \|g_n(f)\| \le c_f$, and so by Banach-Steinhaus, there exists some c such that $\sup_{n \in \mathbb{N}} \|g_n\| \le c$. Now, since $g_n = \phi(x_n)$ where $\phi : X \to (X^*)^*$ is the canonical isometry, we have $\|g_n\| = \|\phi(x_n)\| = \|x_n\|$. Thus, $\|x_n\|$ is bounded by c.

Proposition 5.2. Let (x_n) be a sequence in the normed space X and $x_n \to x$, then $x_n \rightharpoonup x$.

Proof. Clear by sequential continuity.

Weak convergence is a infinite dimensional construct as in the finite dimensional case, weak convergence and convergence in norms is equivalent.

Proposition 5.3. Let (x_n) be a sequence in the finite dimensional normed space X such that $x_n \rightharpoonup x$. Then $x_n \to x$.

Proof. Let $\{e_i\}_{i=1}^n$ be a basis of X. Recall that every linear map is continuous in a finite dimensional normed space and so, the linear map defined by $f_i(e_j) = \delta_{ij}$ is in X^* . Thus, if we write $x_n = \sum_i \lambda_i^n e_i$, $x = \sum_i \lambda_i^n e_i$, we have

$$\lambda_i^n = f_i(x_n) \to f_i(x) = \lambda_i.$$

Thus,

$$\|x_n-x\| = \left\|\sum_{i=1}^n (\lambda_i^n-\lambda_i)e_i\right\| \leq \sum_i |\lambda_i^n-\lambda_i|\|e_i\| \to 0.$$

As one would hope, these two notions are not equivalent in the infinite dimensional case. Consider the sequence e_i in ℓ_2 where $e_i = (\delta_{ij})_{j=1}^{\infty}$. By recalling that there is a canonical isomorphism between $(\ell_p)^*$ and ℓ_q for all 1/p+1/q=1, we have $(\ell_2)^*\cong \ell_2$. Thus, for all $f\in (\ell_2)^*$, $f(e_i)=\sum_j f_j e_i=f_i\to 0$ as $i\to\infty$. Thus, $e_i\rightharpoonup 0$. On the other hand, e_i does not converge to 0 since $\|e_i-0\|=\|e_i\|=\sqrt{2}$ for all i.

While weak convergence seems uncontrollable, we have a good understanding of it behaviour in some classical spaces and in Hilbert spaces. The next two proposition illustrates this.

Proposition 5.4. Let (x_n) be a sequence in $X=c_0$ or ℓ_p for $p\in(1,\infty)$. Then, $x_n\rightharpoonup x$ if and only if (x_n) is bounded and converges to x pointwise, i.e. $x_n(j)\to x(j)$ for all $j\in\mathbb{N}$.

Proof of the ℓ_p case. The forward direction is obvious so let us consider the converse. Suppose $(x_n) \in \ell_p$ is bounded by M (so that $\|x_n - x\|_p \le \|x_n\|_p + \|x\|_p \le 2M$) and converges point-wise to x. Then, for all $f \in (\ell_p)^* \cong \ell_q$, $\epsilon > 0$, choose $N \in \mathbb{N}$ such that

$$\left(\sum_{j=N+1}^{\infty}|f_j|^q\right)^{1/q}<\frac{\epsilon}{2M}.$$

Then, for sufficiently large n, we have

$$\left|\sum_{j=1}^N (x_n(j)-x(j))f_j\right|<\frac{\epsilon}{2}.$$

Thus,

$$\begin{split} |f(x_n)-f(x)| &= \left|\sum_{j=1}^{\infty} (x_n(j)-x(j))f_j\right| \leq \left|\sum_{j\leq N} (x_n(j)-x(j))f_j\right| + \left|\sum_{j>N} (x_n(j)-x(j))f_j\right| \\ &< \frac{\epsilon}{2} + \left(\sum_{j>N} (x_n(j)-x(j))^p\right)^{1/p} \left(\sum_{j>N} |f_j|^q\right)^{1/q} < \frac{\epsilon}{2} + 2M\frac{\epsilon}{2M} = \epsilon \end{split}$$

implying $x_n \rightharpoonup x$ as required.

Proposition 5.5. Let (x_n) be a sequence in a Hilbert space \mathcal{H} such that $x_n \to x$ and $||x_n|| \to ||x||$, then $x_n \to x$ in \mathcal{H} .

Proof. Consider $\|x_n-x\|^2=\|x_n\|^2+\|x\|^2-\langle x_n,x\rangle-\langle x,x_n\rangle$. Defining $f_x(y):=\langle y,x\rangle$, we have $f_x\in\mathcal{H}^*$ and so, $\langle x_n,x\rangle=f_x(x_n)\to f_x(x)=\langle x,x\rangle=\|x\|^2$. On the other hand, $\langle x,x_n\rangle=\overline{f_x(x_n)}\to\overline{\|x\|^2}=\|x\|^2$. Thus,

$$\|x_n - x\|^2 = \|x_n\|^2 + \|x\|^2 - \langle x_n, x \rangle - \langle x, x_n \rangle \to 2\|x\|^2 - 2\|x\|^2 = 0.$$

Definition 5.2 (Weak Topology). Let X be a Banach space. The weak topology on X is the topology with the base with elements of the form

$$U_{\epsilon_i}^{f_i}(x) := \{ y \in X \mid |f_i(y) - f_i(x)| < \epsilon_i \}$$

for some $\epsilon_1, \dots, \epsilon_n > 0$ and $f_1, \dots, f_n \in X^*$.

In other words, the weak topology on X is the coarsest topology on which every linear functional in X^* remains continuous.

As one might expect, a sequence converge in the weak topology if and only if it converges weakly.

Proposition 5.6. A convex set $C \subseteq X$ is strongly closed (i.e. closed with respect to the topology induced by the Norm) if and only if it is weakly closed (i.e. closed with respect to the weak topology).

Definition 5.3 (Weak* Topology). Let X be a Banach space. The weak* topology is a topology on X* with the base with elements of the form

$$U_{\epsilon_i}^{x_i} := \{g \in X^* \mid |g(x_i) - f(x_i)| < \epsilon_i\}$$

for some $\epsilon_1, \dots, \epsilon_n > 0, x_1, \dots, x_n \in X$.

One may show that the weak* topology is Hausdorff as pairs of distinct functionals can be separated by elements of X. Also, a sequence of linear functionals which converge in the weak* topology is necessary bounded by the Banach-Steinhaus theorem.

The weak topology is in general not metrizable. On the other hand, one may show that if X is separable, the the unit ball in X^* endowed with the topology induced from the weak* topology is metrizable.

Lastly, we recall that the unit ball is never compact in a infinite dimensional normed space, the following theorem demonstrate that the weak* topology allows us to recover some sense of compactness in normed spaces.

Theorem 13 (Banach-Alaoglu). The unit ball of a dual space is compact in the weak* topology.

5.2 Compact Sets in Functional Spaces

Definition 5.4 (ϵ -cover). An ϵ -cover of a metric space for some $\epsilon > 0$ is a cover of the space consisting of open sets with diameter at most ϵ . A metric space is totally bounded if it admits a finite ϵ -cover for every $\epsilon > 0$.

Lemma 5.1. Let X be a metric space, such that for every $\epsilon > 0$, there exists some $\delta > 0$ and a metric space W, a continuous map $\Phi : X \to W$ with $\Phi(X)$ is totally bounded such that for all $x, y \in X$, $d(\Phi(x), \Phi(y)) < \delta$ implies $d(x, y) < \epsilon$. Then X is totally bounded.

Proof. Follows immediately by pulling back the δ -covers of $\Phi(X)$ along Φ .

Proposition 5.7. A metric space is compact if and only if it is complete and totally bounded.

Proof. Exercise. \Box

Proposition 5.8. The subset $\mathcal{G} \subseteq \ell_p$ where $1 \leq p < \infty$ is totally bounded if and only if it is point-wise bounded and for every $\epsilon > 0$ there exists some n such that for all $x \in \mathcal{G}$,

$$\sum_{j>n} |x_j|^p < \epsilon^p.$$

Proof. Suppose \mathcal{G} is totally bounded. Then, it is point-wise bounded since totally boundedness implies boundedness which in turn implies point-wise boundedness. On the other hand, for all $\epsilon > 0$, there exists a finite $\epsilon/2$ -cover $(B_{\epsilon/2}(x^i))_{i=1}^n$ of \mathcal{G} . Then, for all $(y_n^i) \in B_{\epsilon/2}(x^i)$, by definition

$$\frac{\epsilon}{2} > \|(y_n^i) - x^i\|_p = \left(\sum_{n=1}^{\infty} |y_n^i - x_n^i|^p\right)^{1/p}.$$

Then, taking $N_i \in \mathbb{N}$ such that $\sum_{n>N_i} |x_n^i|^p < \frac{\epsilon^p}{2^p}$, we can define $\tilde{x}^i, \tilde{y}^i \in \ell_p$,

$$\tilde{x}_n^i := \begin{cases} 0, & n \leq N_i, \\ x_n^i, & n > N_i. \end{cases} \quad \tilde{y}_n^i := \begin{cases} 0, & n \leq N_i, \\ y_n^i, & n > N_i. \end{cases}$$

So, by Hölder's inequality,

$$\begin{split} \left(\sum_{n>N_i} |y_n^i|^p\right)^{1/p} &= \|\tilde{y}^i\|_p \leq \|\tilde{y}^i - x^i\|_p + \|\tilde{x}^i\| < \left(\sum_{n>N_i} |y_n^i - x_n^i|^p\right)^{1/p} + \left(\sum_{n>N_i} |x_n^i|^p\right)^{1/p} \\ &< \left(\sum_{n=1}^\infty |y_n^i - x_n^i|^p\right)^{1/p} + \frac{\epsilon}{2} < \epsilon. \end{split}$$

Thus, $\sum_{n>N_i} |y_n^i|^p < \epsilon^p$ and hence, taking $N := \max_i N_i$ suffices.

Conversely, for all $\epsilon > 0$, let $n \in \mathbb{N}$ such that for all $x \in \mathcal{G}$, $\sum_{j>n} |x_j|^p < (\epsilon/4)^p$. Define

$$\Phi:\mathcal{G}\to\mathbb{R}^n:x\mapsto (x_1,\cdots,x_n).$$

As \mathcal{G} is point-wise bounded, $\Phi(\mathcal{G})$ is totally bounded. Furthermore, if $x, y \in \mathcal{G}$ such that

$$\|\Phi(x)-\Phi(y)\|_p=\left(\sum_{i=1}^n|x_i-y_i|^p\right)^{1/p}<\frac{\epsilon}{2},$$

then

$$\|x-y\|_p \leq \|\Phi(x)-\Phi(y)\|_p + \left(\sum_{i>n} |x_i-y_i|^p\right)^{1/p} < \frac{\epsilon}{2} + \frac{\epsilon}{2} = \epsilon$$

where the first inequality is due to a similar construction as the forward direction along with Hölder's inequality. Hence, by lemma 5.1, \mathcal{G} is totally bounded.

Proposition 5.9. Let \mathcal{H} be a separable Hilbert space and suppose $D \subseteq \mathcal{H}$ is bounded and for some orthonormal basis $\{e_n\}_{n\in\mathbb{N}}$ of \mathcal{H} , we have, for all $\epsilon>0$, there exists some $N\in\mathbb{N}$ such that for all $f\in D$,

$$\sum_{n \ge N} |\langle f, e_n \rangle|^2 < \epsilon^2.$$

Then D is precompact (i.e. \overline{D} is compact) in \mathcal{H} .

Proof. See official notes for full proof.

Outline: given a sequence in D, it suffices to show it has a convergent subsequence in \mathcal{H} . This follows by projecting the sequence on to $\{e_1, \cdots, e_n\}$ for appropriatly choosing n. Then, with Heine-Borel, we obtain a convergent subsequence in the projection. Pulling back, we obtain a convergent subsequence in \mathcal{H} .

We recall the Arzela-Ascoli theorem in a more general context.

Theorem 14 (Arzela-Ascoli). Let Ω be a compact topological space. Then a subset $\mathcal{F} \subseteq \mathcal{C}(\Omega)$ is totally bounded in the supremum norm if and only if for all $f \in \mathcal{F}$, f is bounded, and \mathcal{F} is equicontinuous (i.e. for all $x \in \Omega$, $\epsilon > 0$, there exists a open neighbourhood V of x such that, for all $y \in V$, $|f(x) - f(y)| < \epsilon$ for all $f \in \mathcal{F}$).

Proof. Similar to the \mathbb{R}^n case.

NB: In many context totally boundedness is replaced by uniform boundedness.

Theorem 15 (Kolmogorov-Riesz). A subset \mathcal{F} of $L_p(\mathbb{R}^2)$ where $1 \leq p < \infty$ is totally bounded if and only if

- \mathcal{F} is bounded;
- for all $\epsilon > 0$, there exists some R > 0 such that for all $f \in \mathcal{F}$,

$$\int_{|x|>R} |f(x)|^p \lambda(\mathrm{d}x) < \epsilon^p;$$

• for all $\epsilon > 0$, there exists some $\rho > 0$ such that for all $f \in \mathcal{F}, y \in \mathbb{R}^n, ||y|| < \rho$,

$$\int_{\mathbb{P}^n} |f(x+y) - f(x)|^p \lambda(\mathrm{d} x) < \epsilon^p.$$

5.3 Compact Operators

Definition 5.5. Let X, Y be normed spaces. An operator $T: X \to Y$ is a compact operator if for all $B \subseteq X$ bounded, $\overline{T(B)}$ is compact.

Proposition 5.10. Let X, Y be normed spaces and $T: X \to Y$ be an operator. Then T is compact if and only if for all bounded sequence (x_n) of X, (Tx_n) has a convergent subsequence.

Proof. Follows by considering the criterion for relatively compactness in metric spaces. In particular, given a subset B of a metric space, \overline{B} is compact if and only if all sequences in B contain a subsequence which converges in \overline{B} . Indeed, if (x_n) is a sequence in \overline{B} , then we may construct a sequence $(y_n) \subseteq B$ such that $d(x_n, y_n) < 1/n$. Then, if $(y_{n_i}) \subseteq (y_n)$ such that $y_{n_i} \to y \in \overline{B}$,

$$d(x_{n_i},y) \leq d(x_{n_i},y_{n_i}) + d(y_{n_i},y) < \frac{1}{n_i} + d(y_{n_i},y) \to 0$$

as $i \to \infty$. Thus, \overline{B} is compact.

Proposition 5.11. Let X, Y be normed spaces. Then the set of compact operators from X to Y form an linear space.

Proof. Exercise. \Box

Proposition 5.12. A linear operator $T: X \to Y$ where X, Y are normed spaces is compact if T is bounded and $\dim T(X) < \infty$ (such operators are known as finite rank operators). Thus, if X is finite-dimensional, every bounded linear operator is compact.

Proof. Recall that for finite dimensional spaces, closed and bounded implies compactness. Thus, for all bounded B, as T(B) is bounded, $\overline{T(B)}$ is closed and bounded and hence, T is compact.

Proposition 5.13. Let (T_n) be a sequence of compact linear operators from a normed space X to a Banach space Y. Then if $T_n \to T$ with respect to the operator norm, T is also compact.

Proof. Let (x_n) be a bounded sequence in X by some $c \in \mathbb{R}^+$. By assumption, as T_1 is compact, there exists a subsequence $(x_n^{(1)})$ of (x_n) such that $T_1x_n^{(1)}$ converges. Then, as T_2 is compact, there is a subsequence $(x_n^{(2)})$ of $(x_n^{(1)})$ such that $(T_2x_n^{(2)})$ converges as well. Repeating this process, we can find $(x_n^{(k)})$ a subsequence of $(x_n^{(l)})$ for all $l \leq k$ such that $T_ix_n^{(k)}$ converges for $i=1,2,\cdots,k$. Now, defining $y_n:=x_n^n$, I claim (y_n) is a subsequence of (x_n) such that T_iy_n converges for all $i\in\mathbb{N}$. Indeed, for all $i\in\mathbb{N}$, once $n\geq i$, the remaining sequence of (y_n) is contained $(x_n^{(i)})$. Thus, T_iy_n is eventually contained in $T_ix_n^{(i)}$ which converges.

Now, as $T_n \to T$, for all $\epsilon > 0$, there exists N such that for all $n \ge N$, $\|T_n - T\| < \epsilon/(3c)$. On the other hand, as $(T_N y_n)$ is convergent, it is Cauchy, and so, there exists sufficiently large M, such that $\|T_N y_i - T_N y_j\| < \epsilon/3$ for all $i, j \ge M$. Hence, for all $i, j \ge M$,

$$\|Ty_i-Ty_j\|\leq \|Ty_i-T_Ny_i\|+\|T_Ny_i-T_Ny_j\|+\|T_Ny_j-Ty_j\|<\epsilon.$$

Therefore (Ty_n) is Cauchy and so, T is compact.

Theorem 16. Let X, Y be normed spaces and suppose $T: X \to Y$ is a compact operator. Then, if $(x_n) \subseteq X$ is a sequence which converges weakly to $x \in X$, Tx_n converges strongly to Tx.

Proof. We see that $Tx_n \rightharpoonup Tx$ since for all $g \in Y^*$, $g \circ T$ is a linear functional of X^* , and so, $g(Tx_n) \to g(Tx)$ implying $Tx_n \rightharpoonup Tx$. Suppose Tx_n does not converge to Tx strongly, then, there exists some $\epsilon > 0$ and a subsequence (x_{n_i}) of (x_n) such that for all i, $\|Tx_{n_i} - Tx\| \ge \epsilon$. Now, since (x_{n_i}) is bounded, and T is compact, there exists a subsequence $(x_{n_{i_j}})$ of (x_{n_i}) such that $Tx_{n_{i_j}} \to y$, for some $y \in Y$ and so, $Tx_{n_{i_j}} \rightharpoonup y$. But $Tx_{n_{i_j}} \rightharpoonup Tx$, so by the uniqueness of the weak limit, y = Tx. But, this contradicts $\|Tx_{n_{i_j}} - Tx\| \ge \epsilon$ for all j. Thus, $Tx_n \to Tx$ strongly.

Corollary 5.1. If T is a compact operator on X and (x_n) is a sequence of X which converges weakly to 0. Then Tx_n converges strongly to 0.

Proposition 5.14. Let X, Y be Banach spaces and let $T: X \to Y$ be a bounded linear operator. Then T is compact if and only if $T^*: Y \to X$ is compact.

Proposition 5.15. Let \mathcal{H} be a separable Hilbert space. Then every compact operator T on \mathcal{H} is a strong limit of operators of finite rank.

Proof. Let (e_i) be an orthonormal basis of \mathcal{H} and let us define

$$\lambda_n:=\sup_{f\perp\{e_j|j=1,\cdots n\},\|f\|=1}\|Tf\|.$$

It is clear that (λ_n) is bounded and decreasing, and so, it converges to some $\lambda \geq 0$. By definition, there exists a sequence (f_n) , $f_n \perp \{e_j \mid j=1,\cdots n\}$ and $\|f_n\|=1$ such that $\|Tf_n\| \geq \lambda/2$ for all n. Then, as $f_n \rightharpoonup 0$ since T is compact, we have $Tf_n \rightharpoonup 0$ and thus, $\lambda = 0$.

Thus, defining

$$T^{(n)} := \sum_{j=1}^n \langle e_j, \cdot \rangle T(e_j),$$

we have $\lambda_n = \|T - T^{(n)}\|$ and so, $\|T - T^{(n)}\| \to 0$ as $n \to \infty$ where $T^{(n)}$ are finite rank opertors.

Theorem 17 (Fredholm Alternative). If A is a compact operator on a Hilbert space, then either $A\Psi = \Psi$ has a solution of id -A is invertible.

Proposition 5.16. Let $D \subseteq \mathbb{C}$ be open and connected. Let $\Psi: D \to \mathcal{L}(\mathcal{H})$ be an operator valued function such that $\Psi(z)$ is compact for any $z \in D$. Then, either id $-\Psi(z)$ is not invertible for any $z \in D$ or id $-\Psi(z)$ is invertible for all $z \in D \setminus S$ where S is any set with no limit points in D.

5.3.1 Dirichlet Problem

Definition 5.6 (Dirichlet Problem). u is called a solution of the Dirichlet problem in an open domain if $u \in \mathcal{C}^2(D) \cap \mathcal{C}(\overline{D})$ and

$$\begin{cases} (\Delta u) \mid_{x} = 0, & x \in D, \\ u(x) = f(x), & x \in \partial D, \end{cases}$$

where Δ is the Laplacian operator and f is some (say smooth) function.

Define the space

 $\tilde{\mathcal{C}}_0^1(\overline{D}) := \{ \text{continuously differentiable function on } \overline{D} \text{ vanishing on } \partial D \},$

and equip it with the inner product

$$\langle u,v\rangle := \int_D \nabla u \nabla v \mathrm{d}x = \int_D \sum_k (\partial_{x_k} u)(\partial_{x_k} v) \mathrm{d}x.$$

Suppose that $u \in \mathcal{C}^2(\overline{D})$ is a solution to the Dirichlet problem (DP) where $f \in C^0(\overline{D})$, then by Stokes' theorem,

$$\langle u,v\rangle = \int_D \nabla u \nabla v \mathrm{d}x = \int_{\partial D} v \Delta u \mathrm{d}x = \int_{\partial D} v f \mathrm{d}x,$$

for all $v \in \tilde{\mathcal{C}}_0^1(\overline{D})$. Thus, the above is a necessary condition of u being a solution of DP. With this, we define the weak solution.

Definition 5.7. Let $u \in H_0^1(D)$ (where $H_0^1(D)$ is the completion of $\tilde{\mathcal{C}}_0^1(\overline{D})$). We say u is a weak solution of DP if

$$\langle u, v \rangle = \int v f \mathrm{d}x$$

for all $v \in H_0^1(D)$.

Given the above formulation, we see that the map $v\mapsto \int vf\mathrm{d}x$ is a linear functional from $H^1_0(D)$ and thus, by the Riesz representation theorem, there exists a unique $u\in H^1_0(D)$ such that $\langle u,v\rangle=\int vf\mathrm{d}x$ for all $v\in H^1_0(D)$. This demonstrates the existence of the weak solution in $H^1_0(D)$ and provides a good candidate for the solution of DP.

5.4 Spectrum of Operators

Definition 5.8 (Resolvent). Let X be a complex normed space and let $T:D(T)\subseteq X\to X$ be a bounded operator. Then, for all $\lambda\in\mathbb{C}$, denote $T_\lambda:=T-\lambda\cdot\mathrm{id}_X$. If T_λ has a inverse then we denote $R_\lambda(T):=T_\lambda^{-1}$ and we call it the resolvent of T.

We see straight a way the existence of a resolvent for some value λ implies λ is not an eigenvalue of the operator.

Definition 5.9 (Regular Value). $\lambda \in \mathbb{C}$ is a regular value of the operator T if the λ -resolvent of T exists and is bounded and it is defined on a dense subspace of X.

Definition 5.10 (Resolvent Set and Spectrum). Given a bounded operator $T:D(T)\subseteq X\to X$, the T-resolvent set is

$$\rho(T) := \{ \lambda \in \mathbb{C} \mid \lambda \text{ is a regular value} \}.$$

The complement of the resolvent set

$$\sigma(T) := \mathbb{C} \setminus \rho(T)$$

is called the spectrum of T.

By observing the definition of the regular value, the spectrum can be decomposed into the following three categories.

Definition 5.11.

- The discrete spectrum is the set $\sigma_p(T)$ containing $\lambda \in \mathbb{C}$ for which $R_{\lambda}(T)$ does not exist. We call $\lambda \in \sigma_p(T)$ the eigenvalues of T.
- The continuous spectrum is the set $\sigma_c(T)$ containing $\lambda \in \mathbb{C}$ for which $R_{\lambda}(T)$ exists and is defined on a dense subset of X but is not bounded.
- The residual spectrum is the set $\sigma_r(T)$ containing $\lambda \in \mathbb{C}$ for which $R_{\lambda}(T)$ exists but is not defined on a dense subset of X.

Proposition 5.17. $\rho(T)$ is open and as a result $\sigma(T)$ is closed.

Proof. Let $\lambda \in \rho(T)$ and suppose $|\lambda_0 - \lambda| < ||R_{\lambda_0}(T)||^{-1}$. Then, we see

$$T - \lambda \cdot \operatorname{id}_X = (T - \lambda_0 \cdot \operatorname{id}_X)(\operatorname{id}_X + (\lambda_0 - \lambda)R_{\lambda_0}(T)),$$

and since,

$$(\operatorname{id}_X + (\lambda_0 - \lambda) R_{\lambda_0}(T))^{-1} = \sum_{n=0}^{\infty} (\lambda - \lambda_0)^n R_{\lambda_0}^n(T)$$

where the right hand side is convergent in operator norm. Thus,

$$(T-\lambda\cdot\mathrm{id}_X)^{-1}=(\mathrm{id}_X+(\lambda_0-\lambda)R_{\lambda_0}(T))^{-1}R_{\lambda_0}(T)=\sum_{n=0}^\infty(\lambda-\lambda_0)^nR_{\lambda_0}^{n+1}(T)$$

implying $\lambda \in \rho(T)$ as required.

We recall that in the finite dimensional case over \mathbb{C} , as \mathbb{C} is algebraically closed, the characteristic polynomial always has a root and thus, every operator has at least 1 eigenvalue. The similar is true for Hilbert spaces.

Lemma 5.2 (Neumann Series). If A is a bounded linear operator such that ||A|| < 1 and id -A is invertible, then

$$(\mathrm{id} - A)^{-1} = \sum_{k=0}^{\infty} A^k.$$

Proof. Exercise. \Box

Corollary 5.2. $R_{\lambda}(T) = \sum_{k=0}^{\infty} \lambda^{-k-1} T^k$.

Lemma 5.3. The resolvent $R_{\lambda}(T)$ is continuous and analytic with respect to λ .

Proof. Given $\lambda, \mu \in \mathbb{C}$, as an exercise, one may show $R_{\lambda}(T) - R_{\mu}(T) = (\lambda - \mu)R_{\lambda}(T)R_{\mu}(T)$. Then

$$\|R_{\lambda}(T)-R_{\mu}(T)\|=|\lambda-\mu|\|R_{\lambda}(T)\|\|R_{\mu}(T)\|\rightarrow 0$$

as $\lambda \to \mu$ and so $R_{\lambda}(T)$ is continuous with respect to λ provided we can find a bound of $\|R_{\lambda}(T)\|$ for λ in a neighbourhood of μ . By looking at the previous proof, we see that for $|\lambda - \mu|$ sufficiently small,

$$(T-\lambda\cdot\mathrm{id})^{-1}=\sum_{n=0}^\infty (\lambda-\mu)^n R_\mu^{n+1}(T)$$

and so $||R_{\lambda}(T)|| \to ||R_{\mu}(T)||$ as $\lambda \to \mu$.

 $R_{\lambda}(T)$ is analytic since it is holomorphic with respect to λ by the same argument through dividing both sides with $\lambda - \mu$.

Theorem 18. The spectrum of a bounded operator in a Hilbert space is non-empty.

Proof. Suppose A is a bounded operator in the Hilbert space \mathcal{H} . Then $R_{\lambda}(A)$ is an analytic and so, the so is the function

$$f: \mathbb{C} \to \mathbb{C}: \lambda \mapsto \langle y, R_{\lambda}(A)x \rangle,$$

analytic on $\rho(A)$ for all $x, y \in \mathcal{H}$. Furthermore, by the Neumann series representation of the resolvent, we see that $\lim_{\lambda \to \infty} f(\lambda) = 0$. Then, if $\sigma(A) = \emptyset$, we have $\rho(A) = \mathbb{C}$ and hence, we have found a bounded analytic function f on \mathbb{C} and thus, by Liouville's theorem, f = 0. But as x, y was arbitrary, this implies $R_{\lambda}(A) = 0$, contraction! Hence $\sigma(A)$ is non-empty. \square

Proposition 5.18. The eigenvectors corresponding to distinct eigenvalues of an operator are linearly independent.

Proof. Suppose $\{u_i\}$ are the eigenvectors of the operator T corresponding the distinct eigenvalues $\{\lambda_i\}$, i.e. $Tu_i = \lambda_i u_i$ for all i. Then, if $\{u_1, \cdots, u_n\}$ is linearly independent and $\{u_1, \cdots, u_{n+1}\}$ is linearly dependent, there exists β_i , $\beta_{n+1} \neq 0$ such that,

$$0 = \sum_{i=1}^{n+1} \beta_i u_i = \beta_{i+1} u_{n+1} + \sum_{i=1}^n \beta_i u_i.$$

Thus, $u_{n+1} = -\frac{1}{\beta_{n+1}} \sum_{i=1}^{n} \beta_i u_i$ and hence,

$$\left(-\frac{\lambda_{n+1}}{\beta_{n+1}}\sum_{i=1}^n\beta_iu_i\right)=\lambda_{n+1}u_{n+1}=Tu_{n+1}=T\left(-\frac{1}{\beta_{n+1}}\sum\beta_iu_i\right)=-\frac{1}{\beta_{n+1}}\sum\beta_i\lambda_iu_i.$$

So,

$$\sum_{i=1}^n \frac{\beta_i}{\beta_{n+1}} (\lambda_i - \lambda_{n+1}) u_i = 0.$$

But as $\{u_i\}$ is linearly independent this implies $\lambda_i - \lambda_{n+1} = 0$ contradicting $\lambda_i \neq \lambda_{n+1}$. \square

Proposition 5.19. Let T be a self-adjoint operator in a Hilbert space. Then, the eigenvectors of T corresponding to distinct eigenvalues are orthogonal.

Proof. Let u_i, u_j be eigenvectors of T with eigenvalues $\lambda_i \neq \lambda_j$. Then,

$$\lambda_i \langle u_i, u_j \rangle = \langle \lambda_i u_i, u_j \rangle = \langle Tu_i, u_j \rangle = \langle u_i, Tu_j \rangle = \langle u_i, \lambda_j u_j \rangle = \overline{\lambda_j} \langle u_i, u_j \rangle.$$

Hence, as the eigenvalues of a self-adjoint operator is real (by considering $\lambda\langle u,u\rangle$), $\lambda_i=\overline{\lambda_j}$ implies $\lambda_i=\lambda_j$ which contradicts $\lambda_i\neq\lambda_j$, we have $\langle u_i,u_j\rangle=0$.

5.4.1 Compact Operators

Theorem 19 (Riesz-Schauder). Let X be a normed space and let $T: X \to X$ be a compact operator. Then

- $\sigma(T)$ is countable;
- 0 can be the only limit point of $\sigma(T)$;
- the eigenvalues of T have finite multiplicity, i.e. the eigenspaces are finite dimensional.

Proof. We will first prove that any nonzero element cannot be a limit point of $\sigma(T)$.

Suppose otherwise such that there exists a sequence $\{\lambda_n\}$ of distinct eigenvalues such that $|\lambda_i| > \epsilon > 0$ for some ϵ and let $\{u_i\}$ be their corresponding eigenvectors. Then, denote $M_n := \mathrm{span}\{u_1, \cdots, u_n\}$. It is clear that M_n is closed as it is finite dimensional, and thus, by Riesz' lemma, for all n, there exists a $y_n \in M_n$ such that, $\|y_n\| = 1$ and $\|y_n - x\| \ge 1/2$ for all $x \in M_{n-1}$.

It suffices to show that $||Ty_n - Ty_m|| \ge \epsilon/2 > 0$ for all n, m since then, (Ty_n) does not have a convergent subsequence, contradicting the compactness of T. Indeed, for n > m,

$$Ty_n - Ty_m = \lambda_n y_n - (\lambda_n \mathrm{id}_X - T) y_n - Ty_m =: \lambda_n y_n - \tilde{x}$$

where we define $\tilde{x}:=(\lambda_n\mathrm{id}_X-T)y_n+Ty_m$. Since $m\leq n-1$, we have $y_m\in M_m\subseteq M_{n-1}$ and so, $Ty_m\in M_{n-1}$. By considering $(T-\lambda_n\mathrm{id}_X)M_n\subseteq M_{n-1}$, we have

$$(\lambda_n \mathrm{id}_X - T) y_n = - (T - \lambda_n \mathrm{id}_X) y_n \in M_{n-1}.$$

Hence, $\tilde{x} \in M_{n-1}$ and $\|Ty_n - Ty_m\| = \|\lambda_n y_n - \tilde{x}\| = |\lambda_n| \|y_n - \tilde{x}/\lambda_n\| \ge |\lambda_n|/2 \ge \epsilon/2$ as required.

With this, $\sigma(T)$ is countable follows by considering the union

$$\sigma(T) = \bigcup_{n \in \mathbb{N}} S_n := \bigcup_{n \in \mathbb{N}} \left\{ \lambda \mid \lambda \in \sigma(T), |\lambda| > \frac{1}{n} \right\}.$$

Since the limit point of $\sigma(T)$ can only by 0, and the set of eigenvalues are bounded (as compact operators are bounded), S_n is finite for each n, and so, the union of S_n is countable and hence, so is $\sigma(T)$.

Finally, we will show that the eigenspaces are finite dimensional. Let B be the closed unit ball in the λ -eigenspace E_λ . Then, if (x_n) is a sequence of E_λ , as T is compact, (x_n) has a subsequence (x_{n_k}) such that (Tx_{n_k}) converges. But $Tx_{n_k} = \lambda x_{n_k}$ and so, x_{n_k} converges to some $x \in B$ and hence B is compact in E_λ . Thus, by recalling that the closed unit ball is compact if and only if the space is finite dimensional, E_λ is finite dimensional. \Box

5.4.2 Hilbert-Schmidt Operator

Definition 5.12 (Hilbert-Schmidt Operator). Given a Hilbert space \mathcal{H} , $T:\mathcal{H}\to\mathcal{H}$ a linear operator and $\{e_j\}$ an orthonormal basis of \mathcal{H} , we define Hilbert-Schmidt norm $\|\cdot\|_{HS}$ such that

$$\|T\|_{HS} := \left(\sum_j \|Te_j\|^2\right)^{1/2}.$$

T is said to be a Hilbert-Schmidt operator if $||T||_{HS} < \infty$.

We note that the definition of the Hilbert-Schmidt operator depends on a choice of basis. This is not ideal though we are able to show the definition is in fact independent of this choice.

Proposition 5.20. The Hibert-Schmidt norm is independent of the choice of the basis and $||T||_{HS} = ||T^*||_{HS}$.

Proof. Suppose $\{e_i\}, \{f_i\}$ are two orthonormal basis of \mathcal{H} , then, for all linear operator T,

$$\sum_{i} \|Tf_i\|^2 = \sum_{i} \sum_{j} |\langle Tf_i, e_j \rangle|^2 = \sum_{j} \sum_{i} |\langle f_i, T^*e_j \rangle|^2 = \sum_{j} \|T^*e_j\|^2$$

where the first equality is due to Parseval's identity. Hence, replacing f_i with e_j shows $\|T\|_{HS} = \|T^*\|_{HS}$ and rewriting using this provides the first result.

Definition 5.13 (Trace). Given an operator T on a Hilbert space \mathcal{H} , we define its trace by

$$\mathrm{tr}(T) := \sum_i \langle e_i, Te_i \rangle$$

where $\{e_i\}$ is an orthonormal basis of \mathcal{H} whwhenever the right hand side converges.

Similar to before, we will show that this definition

Proposition 5.21. The trace of an operator is independent of the choice of basis and $||T||_{HS}^2 = \operatorname{tr}(T^*T)$.

Proof. The second statement is obvious while the first is not. To see this one will need to consider the polar decomposition. We will omit the proof here. \Box

As with other conditions, we would like to consider the space of all Hilbert-Schmidt operators and if we can equip it with an interesting structure. Let \mathcal{J}_2 denote the set of all Hilbert-Schmidt operators.

Proposition 5.22. \mathcal{J}_2 form a linear space with an inner product

$$\langle A, B \rangle_{HS} := \operatorname{tr}(A^*B).$$

Proposition 5.23. $||T|| \le ||T||_{HS}$.

Proof. By Parseval's identity, for all $x \in \mathcal{H}$ we have

$$\|Tx\|^2 = \sum_j |\langle Tx, e_j \rangle|^2 = \sum_j |\langle x, T^*e_j \rangle|^2 \leq \sum_j \|x\|^2 \|T^*e_j\|^2 = \|x\|^2 \|T^*\|_{HS}^2 = \|x\|^2 \|T\|_{HS}^2,$$

whee the inequality is due to Cauchy-Schwarz.

Proposition 5.24. $(\mathcal{J}_2, \langle \cdot, \cdot \rangle)$ form a Hilbert space.

Proposition 5.25. If $a_{ij} = \langle e_i, Te_j \rangle$, then $||T||_{HS}^2 = \sum_{ij} |a_{ij}|^2$.

Theorem 20. Hilbert-Schmidt operators are compact.

Proof. Let T be a Hilbert-Schmidt operator and for each $n \in \mathbb{N}$, define

$$T_n: x \mapsto \sum_{i,j=1}^n \langle e_i, Te_j \rangle \langle e_j, x \rangle e_i.$$

Then, each T_n has finite dimensional range and thus is compact. Now, by considering

$$\begin{split} \|T_n - T\|_{HS}^2 &= \sum_k \left\| \sum_{i,j=1}^n \langle e_i, Te_j \rangle \langle e_j, e_k \rangle e_i - Te_k \right\|^2 \\ &= \sum_k \left\| \sum_{i=1}^n \langle e_i, Te_k \rangle e_i - Te_k \right\|^2 \\ &= \sum_k \left\| \sum_{i=1}^n \langle e_i, Te_k \rangle e_i - \sum_i \langle e_i, Te_k \rangle e_i \right\|^2 \\ &= \sum_k \left\| \sum_{i>n} \langle e_i, Te_k \rangle e_i \right\|^2 = \sum_{i>n} \|Te_i\|^2 \end{split}$$

which tends to 0 as $n \to \infty$ as $\sum_i \|Te_i\|^2 < \infty$. Thus, as the space of compact operators form a closed normed space, $T \in \mathcal{J}_2$ is also compact.

Definition 5.14 (Hilbert-Schmidt Integral Operator). The Hilbert-Schmidt integral operator $T: H \to H$ where $H := L^2(\mathbb{R}^d)$ is the linear operator

$$Tf: x \mapsto \int_{\mathbb{R}^d} K(x, y) f(y) d\lambda(y),$$

for some kernel map $K \in L^2(\mathbb{R}^d \times \mathbb{R}^d)$.

The map $y \mapsto K(x,y)f(y)$ is integrable for all x since by Fubini, the map $y \mapsto K(x,y)$ is square integrable for all x and thus,

$$||K(x,\cdot)f(\cdot)||_1 = \langle K(x,\cdot), f \rangle^2 \le ||K(x,\cdot)||_2 ||f||_2.$$

We note that this also implies the operator is bounded with the bound $|T| \leq |K|_2$.

6 Weak Derivative

In light of the tools we have developed, we will now revisit the weak derivative. Recall that, motivated by the integration by parts formula, we have the following definition.

Definition 6.1 (Weak Derivative). A function $f \in L^1_{loc}(\mathbb{R}^n)$ (integrable on compact subsets of \mathbb{R}^n) is weakly differentiable if for all $\phi \in \mathcal{D}(\mathbb{R}^n) := \mathcal{C}^\infty_c(\mathbb{R}^n)$ (smooth functions on \mathbb{R}^n with compact support), there exists some $g \in L^1_{loc}(\mathbb{R}^n)$ such that

$$\int f \partial_i^{\alpha} \phi d\lambda = (-1)^{\alpha} \int g \phi d\lambda$$

where ∂_i denotes the partial derivative in the direction of x_i .

In this case, we call g the weak derivative of f in the direction x_i and we denote it by $\partial_i f$.

Denoting $\partial^{\alpha} = \prod_{i=1}^{n} \partial_{i}^{\alpha_{i}}$ where α is an *n*-tuple with the convention $\partial_{i}^{0} = \mathrm{id}$, we define the following analogous definition.

Definition 6.2. A function $f \in L^1_{loc}(\mathbb{R}^n)$ is α -weakly differentiable if for all $\phi \in \mathcal{D}(\mathbb{R}^n)$ there exists some $g \in L^1_{loc}(\mathbb{R}^n)$ such that

$$\int f \partial^{\alpha} \phi d\lambda = (-1)^{|\alpha|} \int g_{\alpha} \phi d\lambda$$

where g_{α} is called the weak derivative of order $|\alpha|$ of f and is denoted by $\partial^{\alpha} f$.

Lemma 6.1. Let $(f_n) \subseteq L^1_{loc}(\mathbb{R}^n)$ be a sequence of α -weakly differentiable functions and $f_n \to f$ and $\partial^{\alpha} f_n \to g$ in L^1 . Then, f is α -weakly differentiable and $g = \partial^{\alpha} f$.

Proof. By definition, for all $\phi \in \mathcal{D}(\mathbb{R}^n)$,

$$\int f_n \partial^\alpha \phi \mathrm{d}\lambda = (-1)^{|\alpha|} \int (\partial^\alpha f_n) \phi \mathrm{d}\lambda.$$

Then, as $f_n \to f$ in L^1 ,

$$\left| \int (f_n - f) \partial^\alpha \phi \mathrm{d} \lambda \right| \leq \| \partial^\alpha \phi \|_\infty \int |f_n - f| \mathrm{d} \lambda \to 0.$$

On the other hand as $\partial^{\alpha} f_n \to g$ in L^1 ,

$$\left| \int (\partial^\alpha f_n - g) \phi \mathrm{d} \lambda \right| \leq \|\phi\|_\infty \, \int |\partial^\alpha f_n - g| \mathrm{d} \lambda \to 0.$$

Thus, we obtain

$$\begin{split} \left| \int f \partial^{\alpha} \phi - (-1)^{|\alpha|} g \phi \mathrm{d}\lambda \right| &\leq \left| \int (f - f_n) \partial^{\alpha} \phi \mathrm{d}\lambda \right| + \left| \int f_n \partial^{\alpha} \phi - (-1)^{|\alpha|} g \phi \mathrm{d}\lambda \right| \\ &= \left| \int (f - f_n) \partial^{\alpha} \phi \mathrm{d}\lambda \right| + \left| \int (\partial^{\alpha} f_n - g) \phi \mathrm{d}\lambda \right| \to 0. \end{split}$$

Hence $\int f \partial^{\alpha} \phi d\lambda = (-1)^{|\alpha|} \int g \phi d\lambda$ implying $g = \partial^{\alpha} f$ as required.