# CS174A – Introduction to Computer Graphics MIDTERM STUDY GUIDE

#### General Instructions

- 1. Only students registered in the course may take this exam
- 2. Exam is closed book, closed notes, closed electronics including calculators
- 3. Unless explicitly specified, you don't have to multiply matrices
- 4. No points are deducted for wrong answers
- 5. I will NOT ask anything that I've not covered in class
- 6. Midterm carries 100 points

### Chapter 1: Graphics Systems and Models

- What are the 4 elements of computer graphics?
- Examples of procedural animation: physics-based, behavioral
- Difference between random scan (calligraphic) and raster output devices
- Difference between interlaced and non-interlaced devices
- Difference between single and double buffering
- Memory space needed by a frame buffer
- Max time to read pixel from memory at a certain refresh rate
- 1.8 1.11

#### Points and Vectors

- Vector operations, properties, inverse, etc.
- Find new point based on initial point and direction of vectors
- Dot products, special cases
- Cross products
- Parametric equations of line and triangle
- What is the diff between affine combinations and convex combination of points?
- Find point on an edge based on different values of  $\alpha_1$  and  $\alpha_2$ ; which is affine, which is convex?

## Chapter 2.4.1: Polygons

- What is tessellation and triangulation? Difference between them
- Provide the full index structure of a simple polyhedron
- Two problems with concave polygons: finding outward normals and determining if a point is inside or outside a polygon
- Give 3 reasons why triangles are preferred polys in graphics hardware
- 2.11-2.14, 2.18-2.19

## Chapter 4: Transformations

- Properties of affine combinations
- Properties of rigid body transformations
- Translation, scaling, rotation, shear matrices
- Prove using 2D HMs that scale followed by translation is not the same as translation followed by scaling; in what particular situation will they be same
- Prove using HMs that 2 consecutive transformations are commutative or associative
- How to rotate a point about a random point?
- How to rotate about a random vector, using sequence of rotations or changes of basis/frames?

#### Geometric Calculations

- Point in polygon test for convex/concave polys: semi-infinite ray, angle summation
- Normal vector calculations: 3 consecutive CCW vertices, summation method
- Plane equations: 3 points in a plane, surface normal + distance from origin
- On-line test
- Edge-edge intersections
- Collinearity test

## Chapter 5: Viewing & HSR

- What params are needed to form eye/camera matrix?
- What params are needed to form orth or pers proj matrix?
- Transformations from projection matrices to normalized forms
- Aspect ratio
- Normalized window to viewport mapping
- What is back face culling? How do you do this in world space, in eye space and in normalized projection space?