

# CS174A Lecture 13

# Announcements & Reminders

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- *Projects due: Dec 1*
- *Project presentations: Dec 3 and 5, in class*
- *Final exam: Dec 12, 11:30 AM – 2:30 PM, Place TBD*

# TA Session This Friday

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- *Return Midterms*
- *Project #4*
- *Collision Detection*

# Last Lecture Recap

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- *Barycentric Coordinates, Trilinear Interpolations*
- *Flat and Smooth Shading*

# Next Up

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- *Non-Photorealistic Rendering*
- *Global Illumination*
- *Mappings: Texture, Bump, Displacement, Environment*
- *Shadows*
  - 2-pass z-buffer algorithm
  - Shadow volumes
- *Hidden Surface Removal*
  - Ray casting

# Shading Recap

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- ***Flat Shading***
  - Illuminate a poly only once
  - No interpolation
- ***Gouraud Shading***
  - Illuminate vertices of poly
  - Interpolate colors at vertices
- ***Phong Shading***
  - Illuminate each point inside poly
  - Interpolate normals at vertices

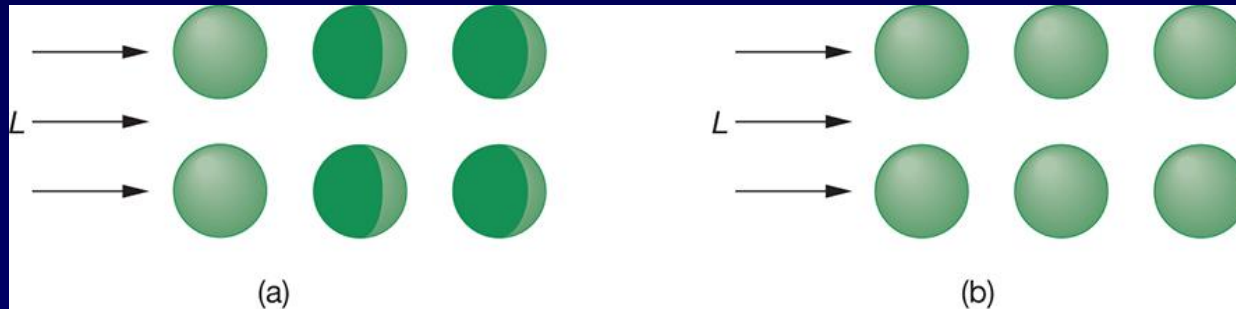
# Non-Photorealistic Shading

- *Cartoon like effects*
- *$\text{Color} = (L \cdot N > 0.5) ? \text{Color1} : \text{Color2}$*
- *Color changes with object's shape and light's position*
- *Silhouette:  $(V \cdot N < 0.01) ? \text{Black} : \text{Color}$*



# Global Illumination

- *Ray Tracing: shadows, reflections, refractions*
- *Radiosity*
  - Based upon light energy conservation
  - Requires solution of a large set of equations involving all surfaces





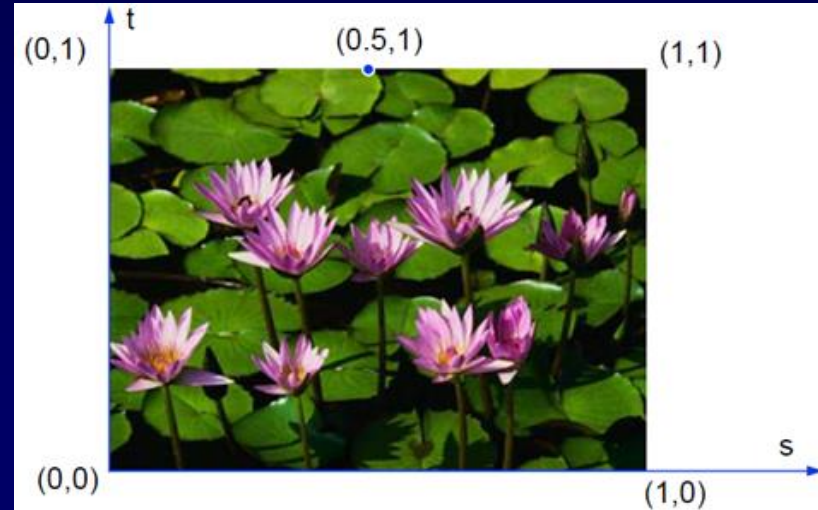
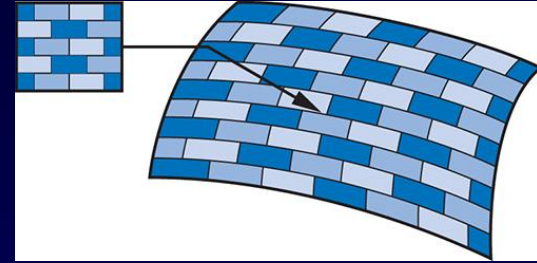
# Mappings

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- *Texture Mapping*
- *Bump Mapping*
- *Displacement Mapping*
- *Environment Mapping*
- *Procedural Mapping*

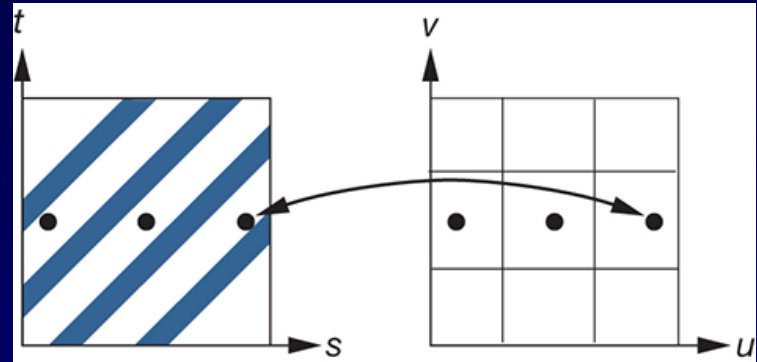
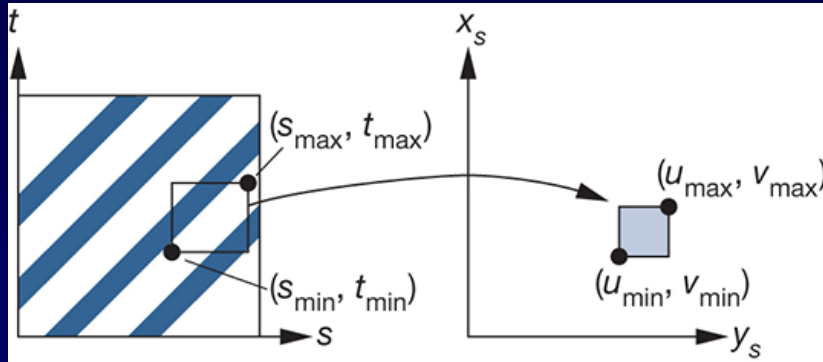
# Texture Mapping

- *AKA Pattern mapping*
- *Map a digitized image onto a poly face*
- *Individual elements are called Texels*
- *$u,v$  and  $s,t$  coordinates*
- *Use texel color as diffuse color*



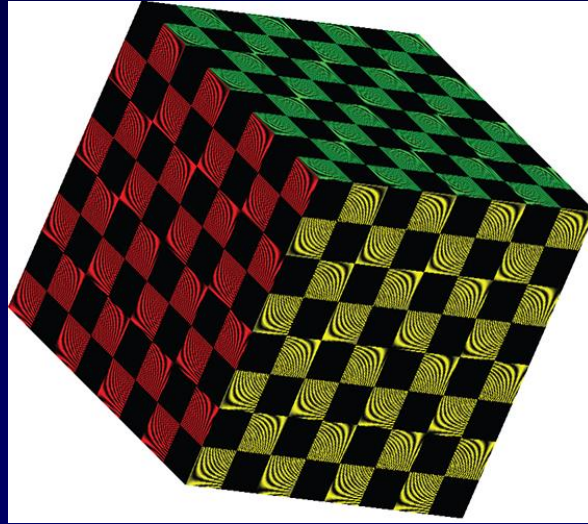
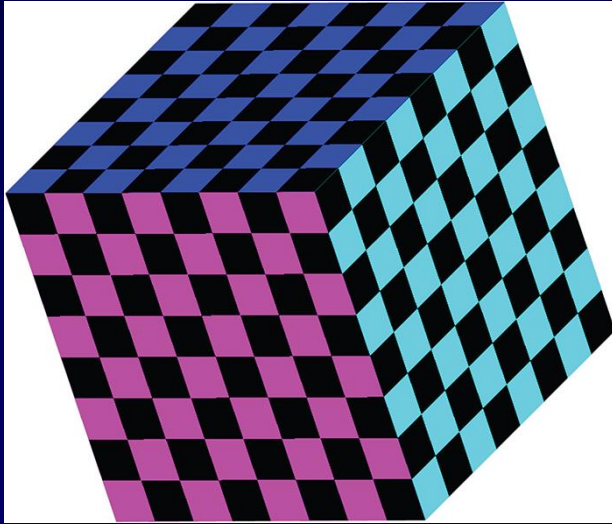
# Texture Mapping - Aliasing

- *Due to high-frequency patterns*



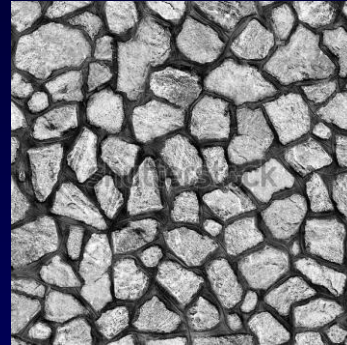
# Multi-Texturing

- *Apply multiple textures on the same object – blend*



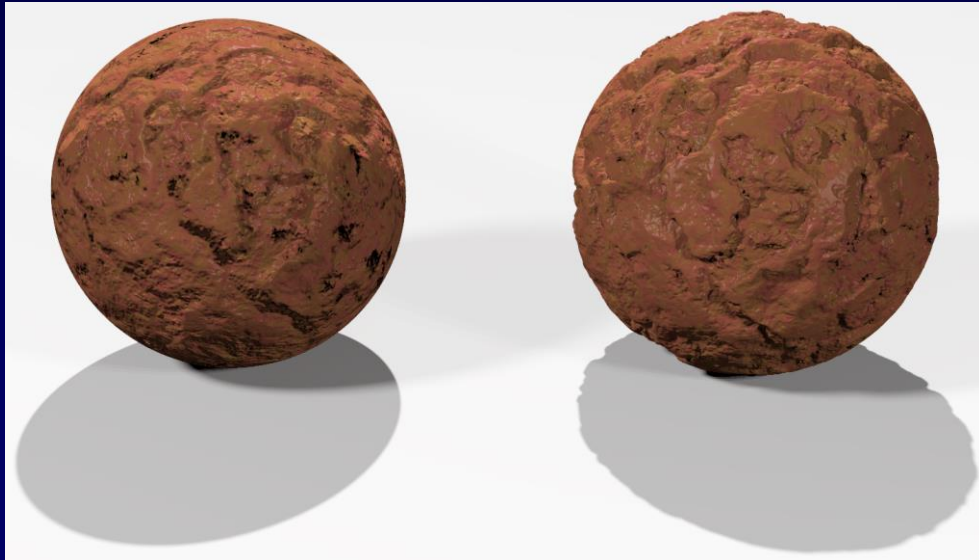
# Bump Mapping

- *Displace point on surface of object*
- $P' = P + B * N$
- $N' = \frac{B_u(N \times P_t) - B_v(N \times P_s)}{|N|}$
- $B_u, B_v = \text{partial derivatives of } B \text{ wrt } u, v$
- $P_s, P_t = \text{partial derivatives of } P \text{ wrt } s, t$



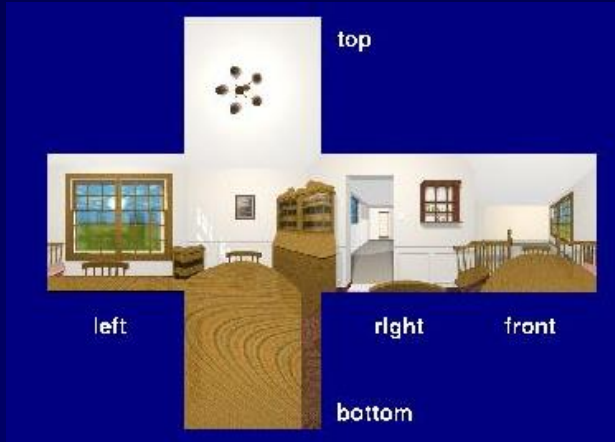
# Displacement Mapping

- *Points actually move*
- *Requires hidden surface removal*



# Environmental Mapping

- *AKA Reflection Mapping*
- *Use polar (or spherical) coordinates of reflected ray to map*
- *Map defined usually on 6 faces of a box (cube map) or a sphere*





# Shadow Algorithms

- **Types**

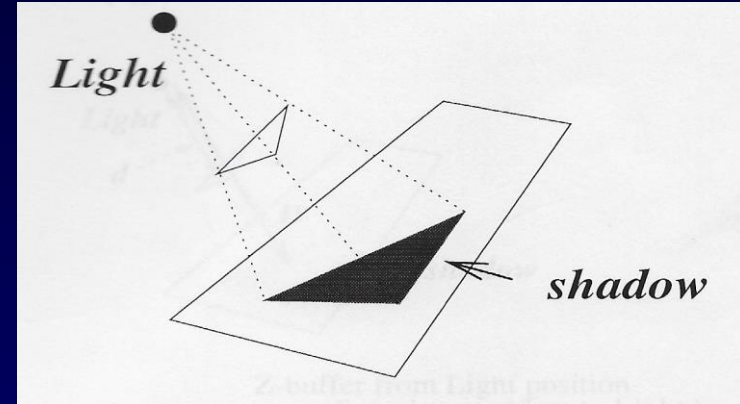
- Image precision: 2-pass z-buffer method
- Object precision: shadow volume method

- **Main Idea**

- P is not visible from light source  $\Leftrightarrow$  P is in shadow

- **Strategy**

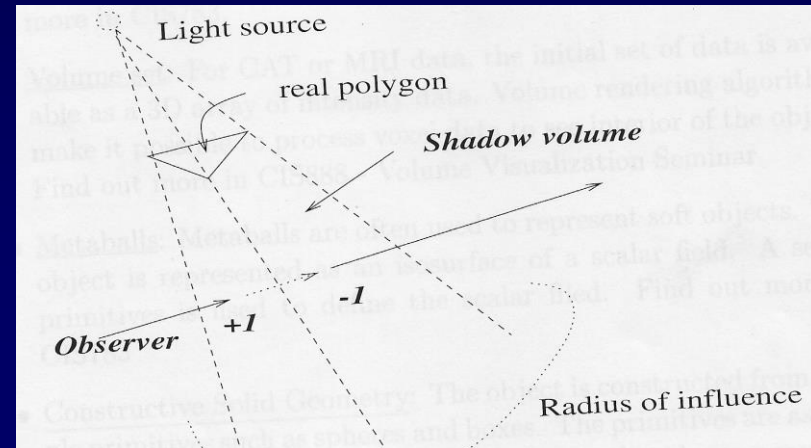
- Identify areas on polys which are not directly visible from light source
- Mark these areas
- Do HSR from eye position
- Areas marked for shadow are rendered only with ambient light



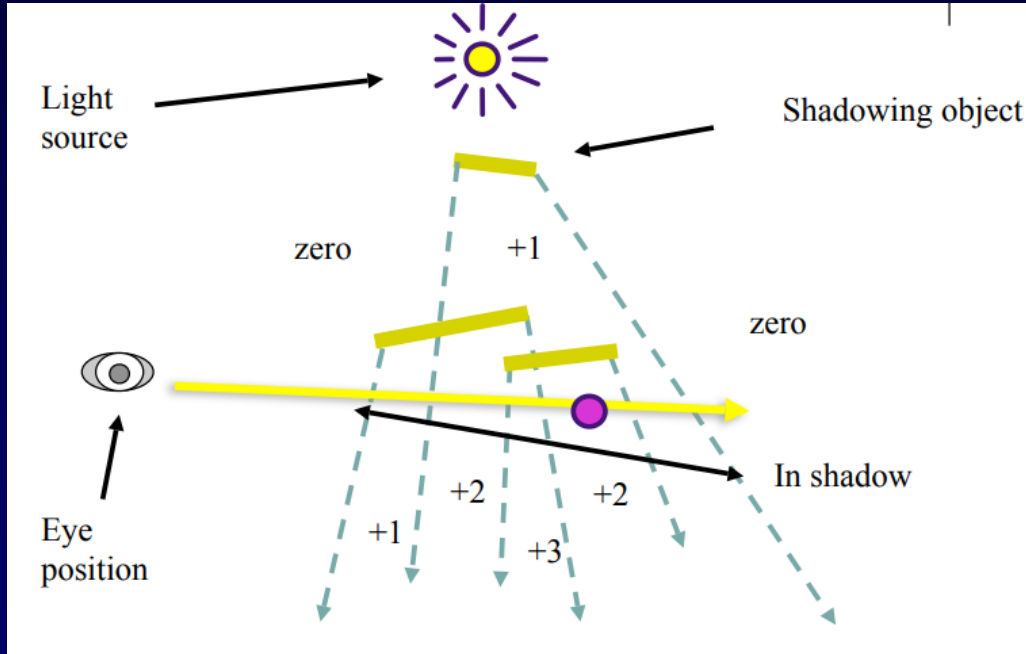


# Shadow Volume Method

1. **Create a shadow volume for each front facing poly**
2. **Put shadow volume in poly database**
3. **Do parity test to determine if a visible point is in shadow**
  - a. Initial value = # of shadow volumes containing eye position
  - b. Increment for front-facing shadow poly
  - c. Decrement for back-facing shadow poly
  - d. If parity  $> 0 \Rightarrow$  point is in shadow



# Shadow Volume Method



# 2-Pass Z-Buffer Method

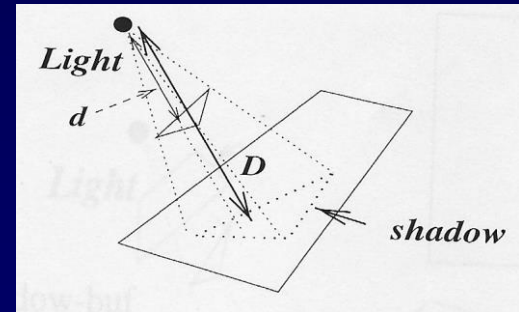
## *Aka Shadow Map method*

### **1. Do z-buffer (full) from light position**

- a. store results in shadow buffer

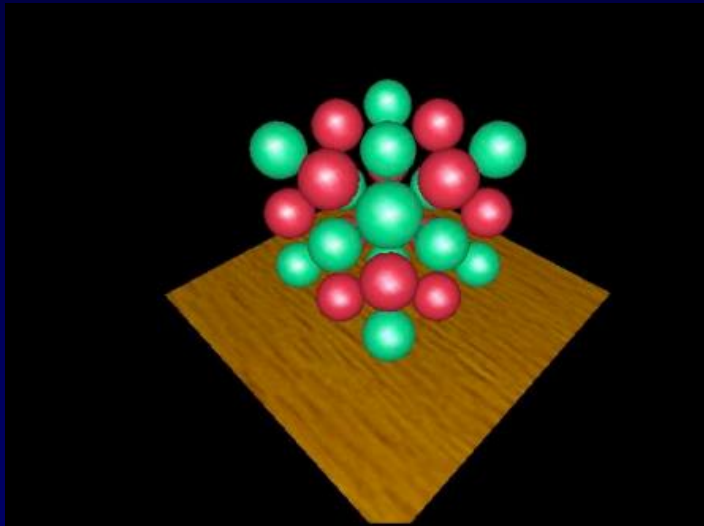
### **2. Do z-buffer (scanline or full) from eye position**

- a. For each (visible) pixel in scanline
  - i. Do inverse map point to WS
  - ii. Map to SS of shadow buffer
  - iii. Compare  $z$  with that of shadow buffer at  $x,y$
  - iv. If  $\text{shadow\_buf}[x][y] < z$ , then point is in shadow

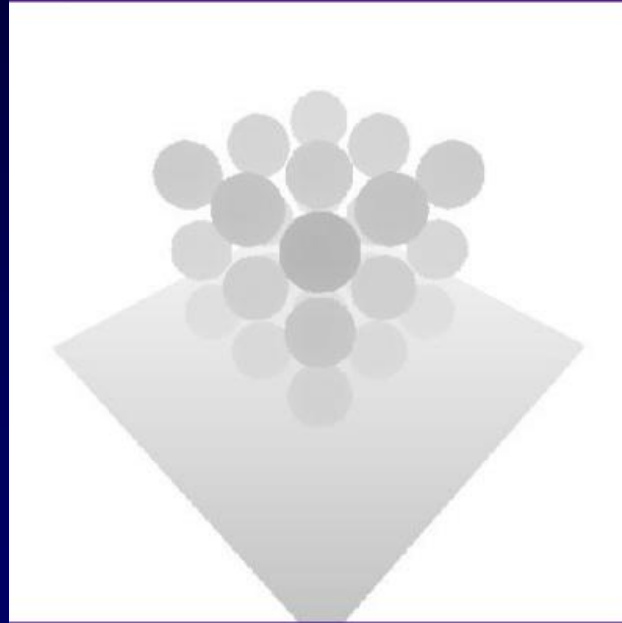


# 2-Pass Z-Buffer Method

*First Pass: from light's position*



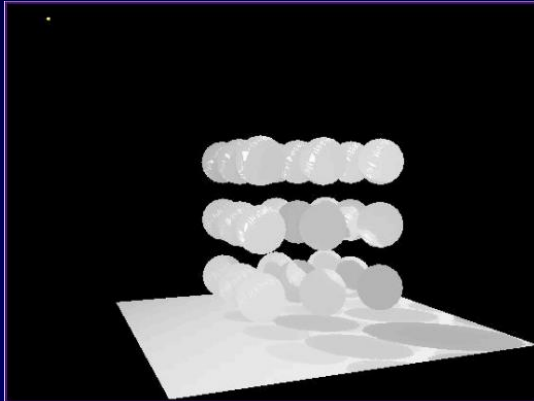
*View from light*



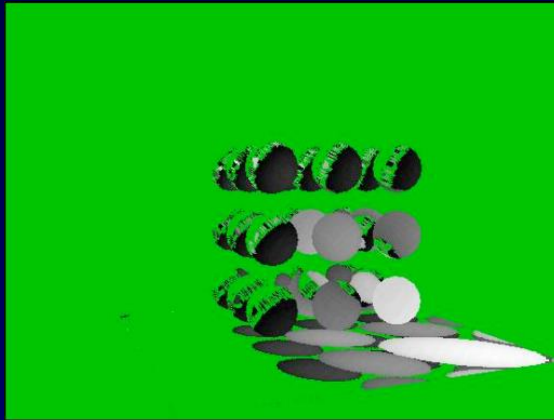
*Depth Buffer (shadow map)*

# 2-Pass Z-Buffer Method

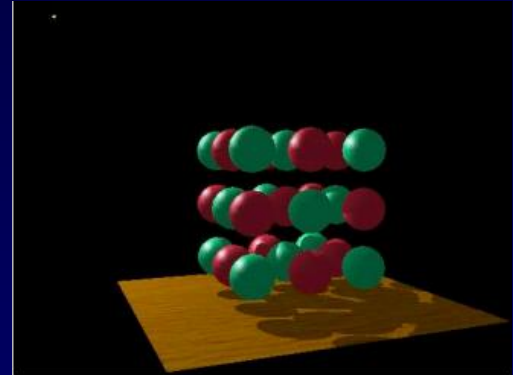
*Second Pass: from eye's position*



*Visible surface depth*



*Non-green in shadow*



*Final Image*

# 2-Pass Z-Buffer Method (Contd.)

- **Advantages**

- Simple to implement

- **Disadvantages**

- Shadow distant from light source may appear blocky
- A large size of shadow-buffer is required
- Depth buffer bit resolution – usually 8-bit
- Umbra vs. penumbra
- Light source in the view volume is problematic

