

# CV\_siamese\_v5

July 7, 2023

## 1 run load\_data.ipynb BEFORE running this!

```
[11]: import numpy as np
import torch
device = torch.device("cuda" if torch.cuda.is_available() else "cpu")
s = {
    'problem'          : "regression",
    'approach'         : "few-shot learning",
    'method'           : "non-parametric",
    'algorithm'        : "siamese network",
    'goal'             : "learn a distribution using few samples from it",
    'input'            : "samples from a distribution",
    'input type'       : "vectors",
    'input meaning'    : "spectrum",
    'output'           : "samples from a distribution",
    'output type'      : "one number",
    'output meaning'   : "temperature or pressure, depending on distribution",
    'number of ways'   : 2,
    'number of shots'  : 1,
    'number of folds'  : 8,
    'support-query ratio': 0.8,
    'task size'        : 5,
    'learning rate'    : 5e-5,
    'input dimension'  : 10000,
    'output dimension' : 1,
    'feature dimension' : 300,
    'epoch'            : 1000,
    'epoch development' : 36,
    'data'             : 'temperature_230509_discrete',
    'cross validation round': 16,
    'cross validation round-development' : 3,
    'best model folder' : 'siamese_best_model/'
}
```

```
[12]: import data_accessor as acc
data_names_list = [
    'temperature_230509_discrete',
```

```

        'pressure_230516_discrete'
    ]
    data_dictionary = acc.setup(data_names_list)

```

```

loading temperature_230509_discrete-----
    input shape (number, dimension): (6000, 10000)
    label shape (number, dimension): (6000, 1)
    there are 16 folds
    4200 for training, 600 for validating, 1200 for testing
loading pressure_230516_discrete-----
    input shape (number, dimension): (5000, 10000)
    label shape (number, dimension): (5000, 1)
    there are 16 folds
    3500 for training, 500 for validating, 1000 for testing

```

```

[13]: # task layout July 5, 2023

# siamese network extract feature space difference
# auxiliary network convert that difference into label difference

# Bing's feedback July 7th 2023
# need to fix:
# 1 convergence graph good for some CV round, bad for others
# 2 wrong use of cross-validation
# 3 try bigger dim, to fix 1
# 4 test on pressure data
# 5 try different architecture
# if layer k has dimension d_k, d_{k+1} should be > d_k / 10

```

```

[14]: import torch.nn as nn
class SiameseNetwork(torch.nn.Module):
    def __init__(self, device, input_dimension, feature_dimension,
        ↪output_dimension):
        """ Input: input, anchor, anchor label
        Output: prediction for input"""
        super().__init__()
        self.input_dimension = input_dimension
        self.hidden_dimension = 32
        self.feature_dimension = feature_dimension
        self.output_dimension = output_dimension
        self.device = device
        self.feature_sequential = torch.nn.Sequential(
            torch.nn.Linear(self.input_dimension, self.hidden_dimension),
            nn.ReLU(),
            torch.nn.Linear(self.hidden_dimension, self.hidden_dimension),
            nn.ReLU(),
            torch.nn.Linear(self.hidden_dimension, self.feature_dimension)

```

```

    )
    self.auxiliary_sequential = torch.nn.Sequential(
        torch.nn.Linear(self.feature_dimension, self.feature_dimension),
        nn.ReLU(),
        torch.nn.Linear(self.feature_dimension, self.feature_dimension),
        nn.ReLU(),
        torch.nn.Linear(self.feature_dimension, self.output_dimension)
    )
    self.to(device)
    self.float()
    def forward(self, input, anchor, anchor_label):
        feature_input = self.feature_sequential(input)
        feature_anchor = self.feature_sequential(anchor)
        feature_space_difference_input_from_anchor = feature_input -
↪ feature_anchor
        label_difference_input_from_anchor = self.
↪ auxiliary_sequential(feature_space_difference_input_from_anchor)
        prediction = anchor_label + label_difference_input_from_anchor
    return prediction

```

```

[15]: import matplotlib.pyplot as plt
def plot_loss(train_loss, valid_loss):
    plt.subplot()
    plt.plot(train_loss)
    plt.plot(valid_loss)
    plt.legend(["train loss", "valid loss"], loc="upper right")
    plt.show()

```

```

[16]: from tools import SaveBestModel, PatienceEarlyStopping, Scheduler
class Manager:
    """ DOES: train & evaluate a Siamese network
        """
    def __init__(self, epoch, cross_validation_round):
        self._network = SiameseNetwork(device, s['input dimension'], s['feature_
↪ dimension'], s['output dimension'])
        # self._network = SiameseNetwork(device, 10000, 16, 1)
        self._network.apply(self.initializer)
        self._learning_rate = 1e-4
        self._optimizer = torch.optim.Adam(
            params=self._network.parameters(), lr=self._learning_rate,
            weight_decay=3e-3)
        self._energy = nn.MSELoss()
        self._train_loss = []
        self._valid_loss = []
        self._test_loss = []
        self._epoch = epoch
        self._stopper = PatienceEarlyStopping(patience=10, min_delta=1e-7)

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self._cross_validation_round = cross_validation_round
self._saver = SaveBestModel(s['best model folder'])
self._scheduler = Scheduler(optimizer=self._optimizer,
                             minimum_learning_rate=1e-6,
                             patience=5,
                             factor=0.5)
def initializer(self, layer):
    if type(layer) == nn.Linear:
        nn.init.kaiming_normal_(layer.weight) # normal version
def _step(self, job):
    input, input_label, anchor, anchor_label = job
    # print(f"input dtype is {input_1.dtype}")
    prediction = self._network(input, anchor, anchor_label)
    loss = self._energy(input_label, prediction)
    return loss
def train(self, train_dataloader, valid_dataloader):
    """ DOES: calculate loss from tasks
        NOTE: we have a BATCH of tasks here """
    for e in range(self._epoch):
        # print(f"train() epoch {e}")
        batch_train_loss = []
        for _, batch in enumerate(train_dataloader):
            loss = self._step(batch)
            loss.backward()
            self._optimizer.step()
            batch_train_loss.append(loss.item())
        self._train_loss.append(np.mean(batch_train_loss))
        batch_valid_loss = []
        with torch.no_grad():
            for _, batch in enumerate(valid_dataloader):
                loss = self._step(batch)
                batch_valid_loss.append(loss.item())
            self._valid_loss.append(np.mean(batch_valid_loss))
        # saving, early stopping, scheduler for EACH epoch!
        self._saver(current_loss=np.mean(batch_valid_loss),
                    model=self._network,
                    round=self._cross_validation_round
                    )
        self._scheduler(np.mean(batch_valid_loss))
        self._stopper(np.mean(batch_valid_loss))
        if self._stopper.early_stop == True:
            print(f"EARLY STOPPING @ epoch {e}")
            break
    # summary printout, after we're done with epochs
    print(f"min train loss: {np.min(self._train_loss)}")
    print(f"min valid loss: {np.min(self._valid_loss)}")
    plot_loss(self._train_loss, self._valid_loss)

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        return np.min(self._valid_loss)
    def test(self, test_dataloader):
        with torch.no_grad():
            batch_test_loss = []
            with torch.no_grad():
                for _, batch in enumerate(test_dataloader):
                    loss = self._step(batch)
                    batch_test_loss.append(loss.item())
            self._test_loss.append(np.mean(batch_test_loss))
        return np.min(self._test_loss)

```

```

[17]: from torch.utils.data import DataLoader
      from tools import SiameseDataset, SaveBestCrossValidationModel

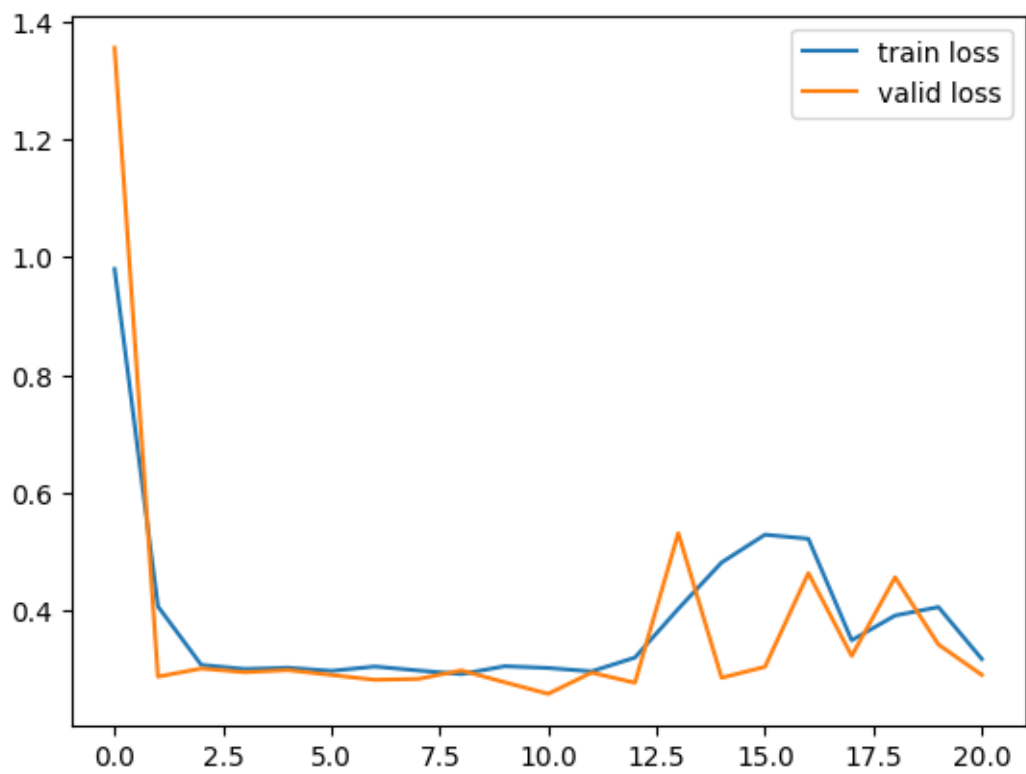
      CV_saver = SaveBestCrossValidationModel(s['best model folder'])
      test_indices = data_dictionary[s['data']]['test indices']
      epoch = s['epoch']
      print(f"data: {s['data']}")
      for cross_validation_round, (train, valid) in enumerate(zip(
          data_dictionary[s['data']]['train indices'],
          data_dictionary[s['data']]['valid indices'])):
          if cross_validation_round < s['cross validation round']:
              print(f"CV round {cross_validation_round}")
              network_object = Manager(epoch, cross_validation_round)
              valid_loss = network_object.train(
                  DataLoader(SiameseDataset(
                      data_dictionary[s['data']]['data'],
                      data_dictionary[s['data']]['label'],
                      data_dictionary[s['data']]['train indices'][cross_validation_round],
                      device=device,), shuffle=False, batch_size=32),
                  DataLoader(SiameseDataset(
                      data_dictionary[s['data']]['data'],
                      data_dictionary[s['data']]['label'],
                      data_dictionary[s['data']]['valid indices'][cross_validation_round],
                      device=device,), shuffle=False, batch_size=32))
              CV_saver(current_loss=valid_loss, round=cross_validation_round)
      print(f"\nbest model is: {CV_saver.best_model_name} with {CV_saver.
          ↪current_best_loss}")

```

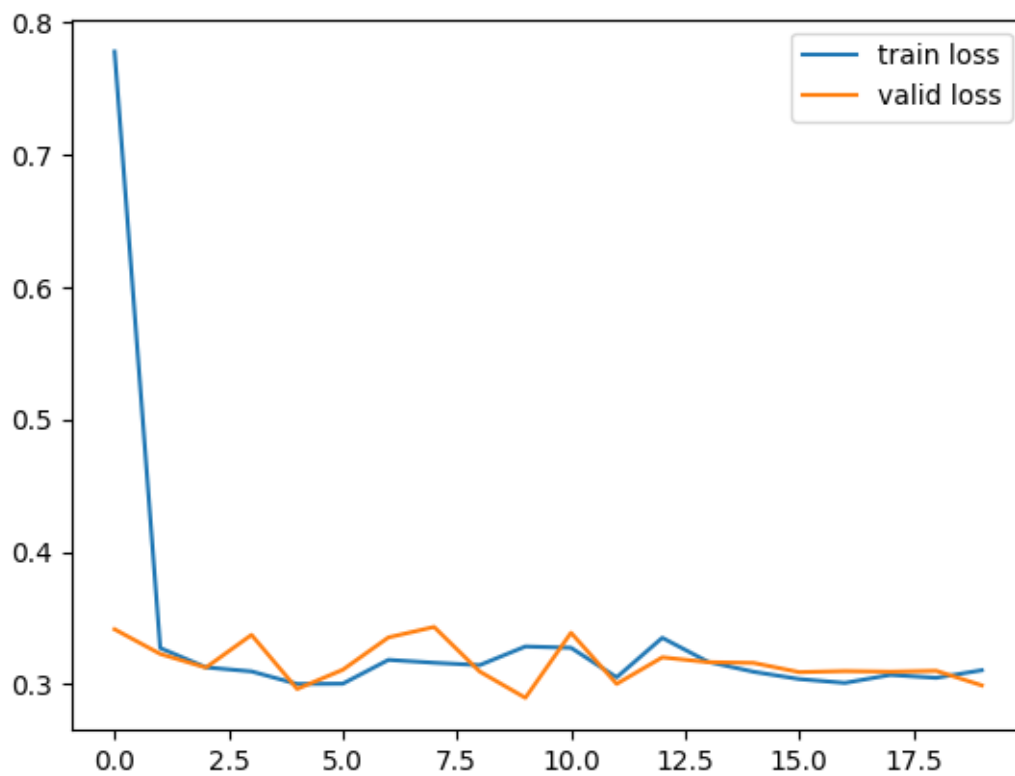
```

data: temperature_230509_discrete
CV round 0
EARLY STOPPING @ epoch 20
min train loss: 0.2921668171431079
min valid loss: 0.2586006294739874

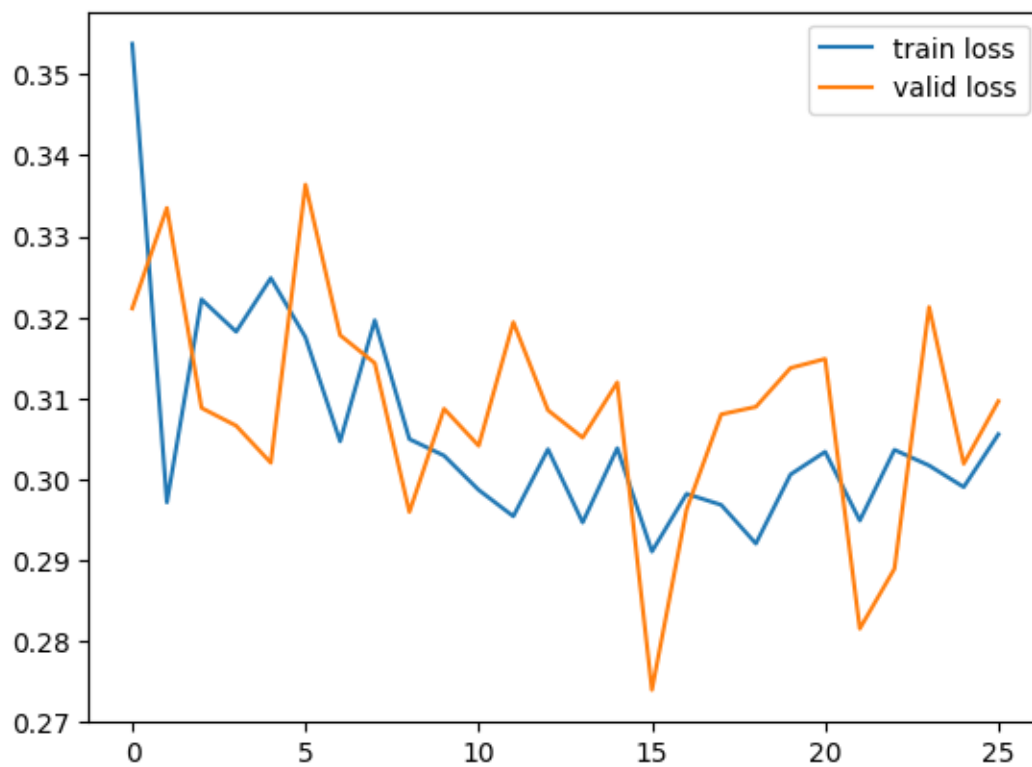
```



CV round 1  
EARLY STOPPING @ epoch 19  
min train loss: 0.30011898617852817  
min valid loss: 0.2896560665808226

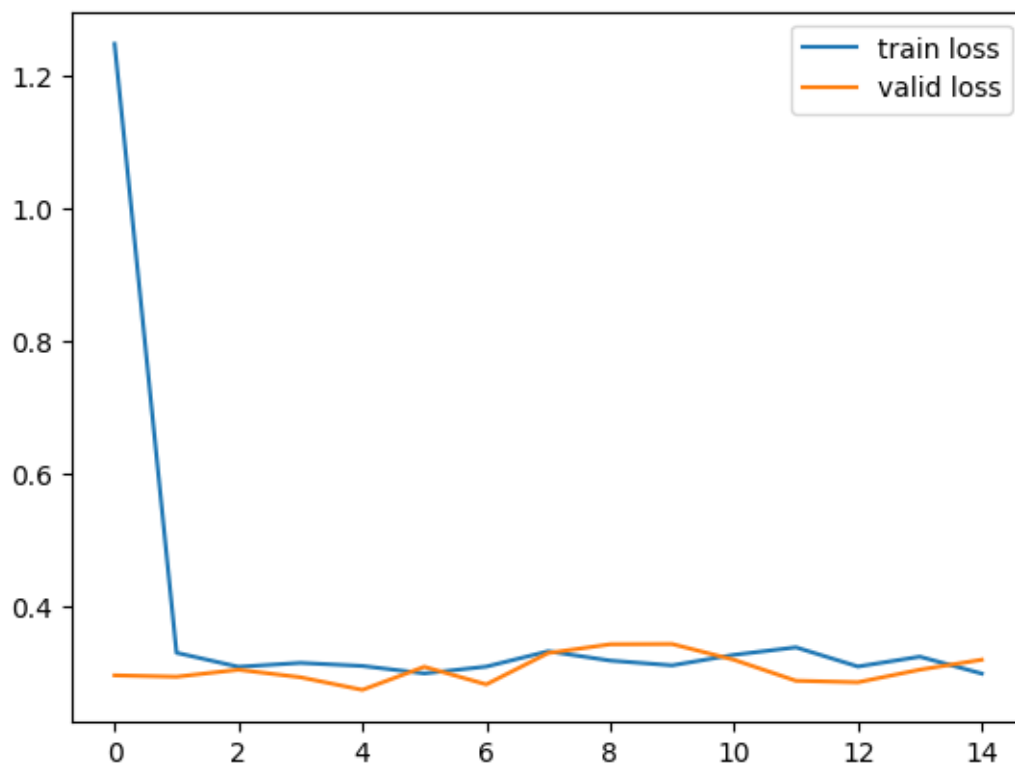


CV round 2  
EARLY STOPPING @ epoch 25  
min train loss: 0.29107263447208837  
min valid loss: 0.2739839632260172

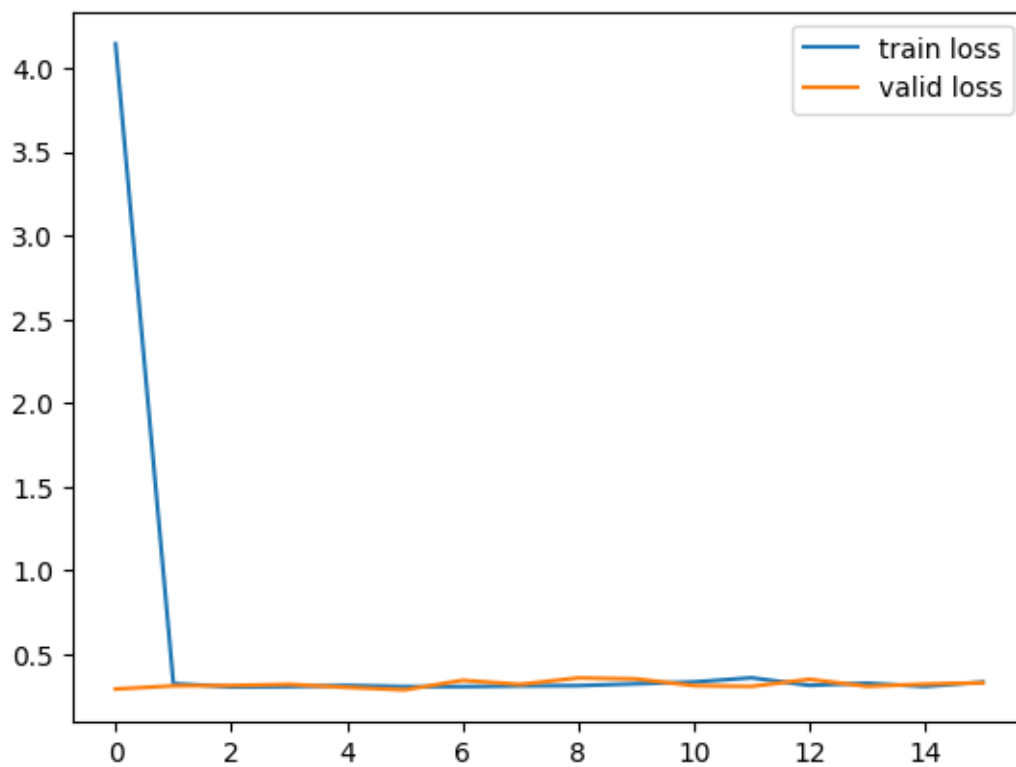


CV round 3  
EARLY STOPPING @ epoch 14  
min train loss: 0.29763769911545696  
min valid loss: 0.2730579838940972

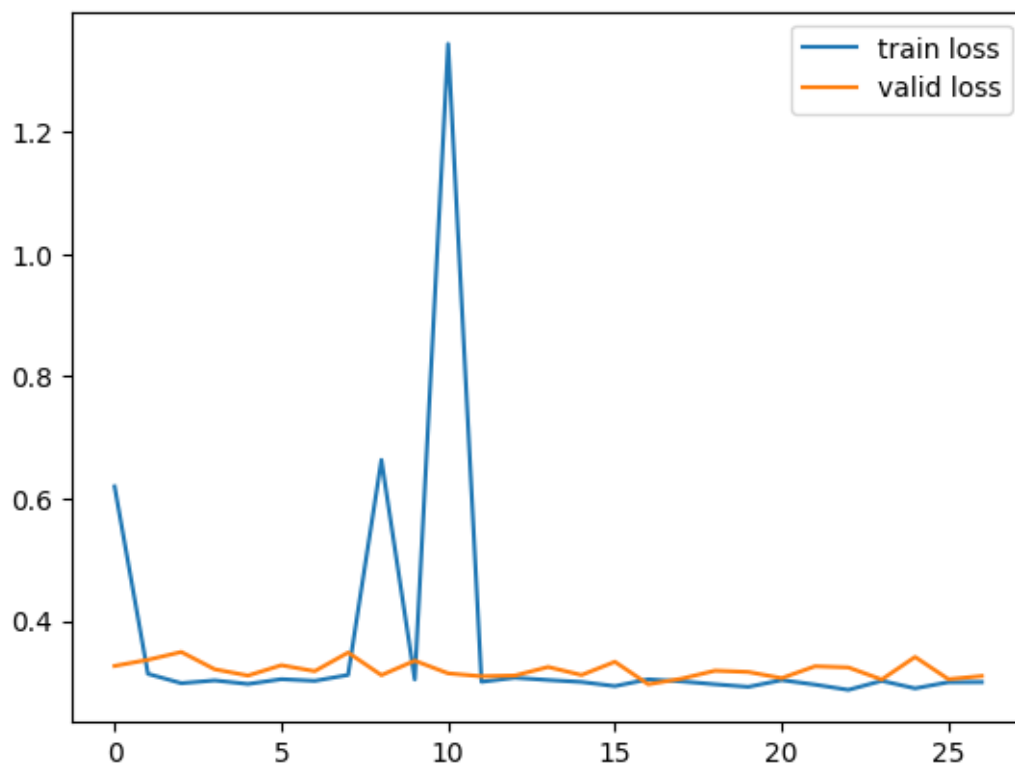




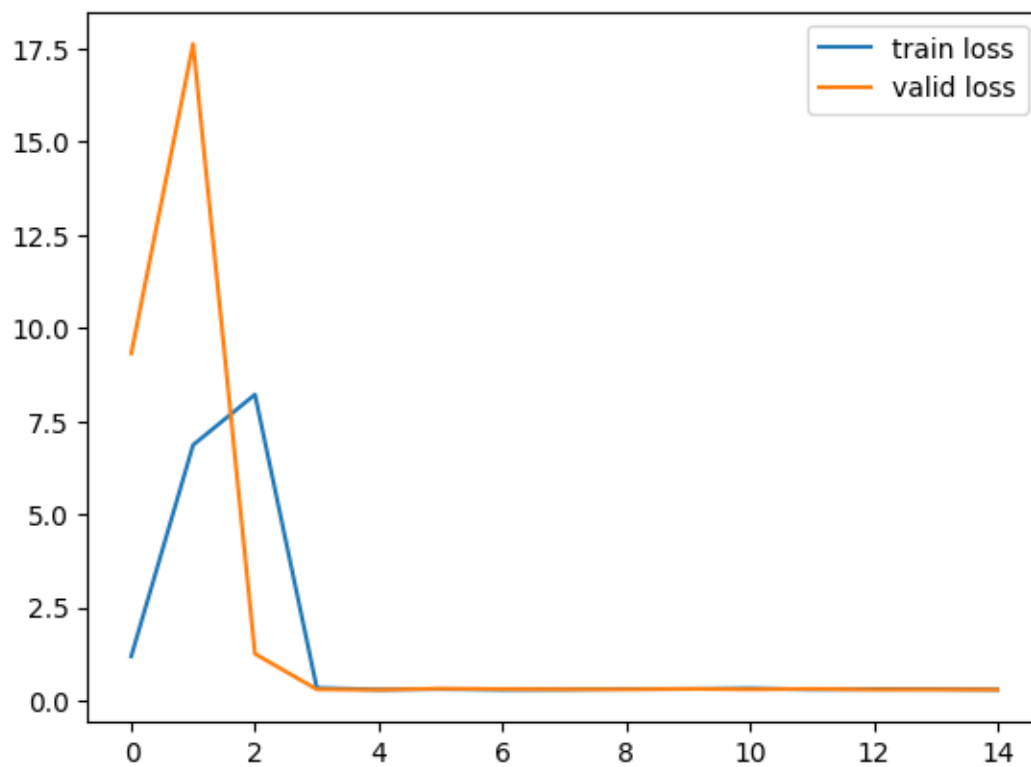
CV round 4  
EARLY STOPPING @ epoch 15  
min train loss: 0.305350693902283  
min valid loss: 0.28792562139661687



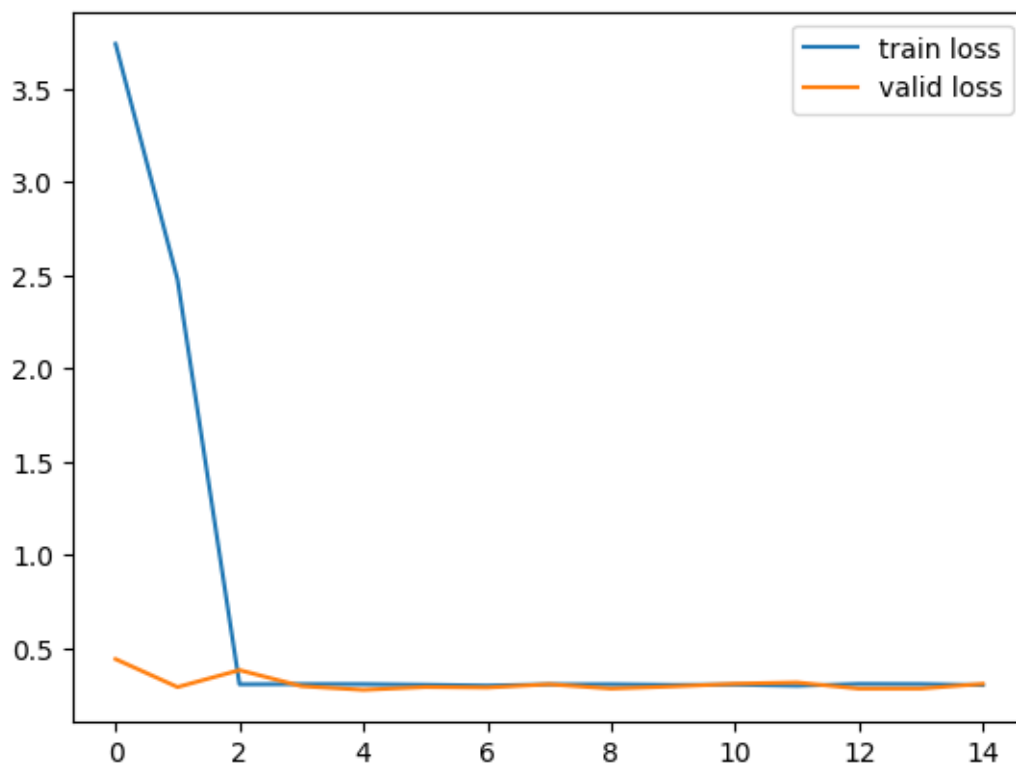
CV round 5  
EARLY STOPPING @ epoch 26  
min train loss: 0.28732144076264265  
min valid loss: 0.2964565314744648



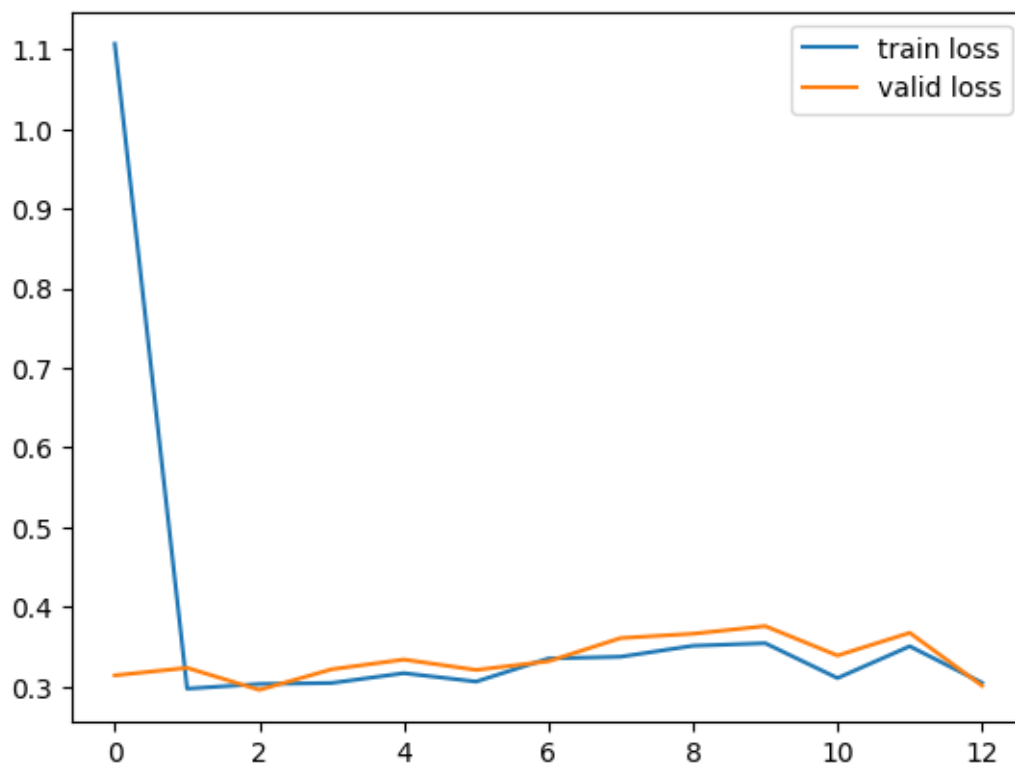
CV round 6  
EARLY STOPPING @ epoch 14  
min train loss: 0.28683323142203415  
min valid loss: 0.2821706564802873



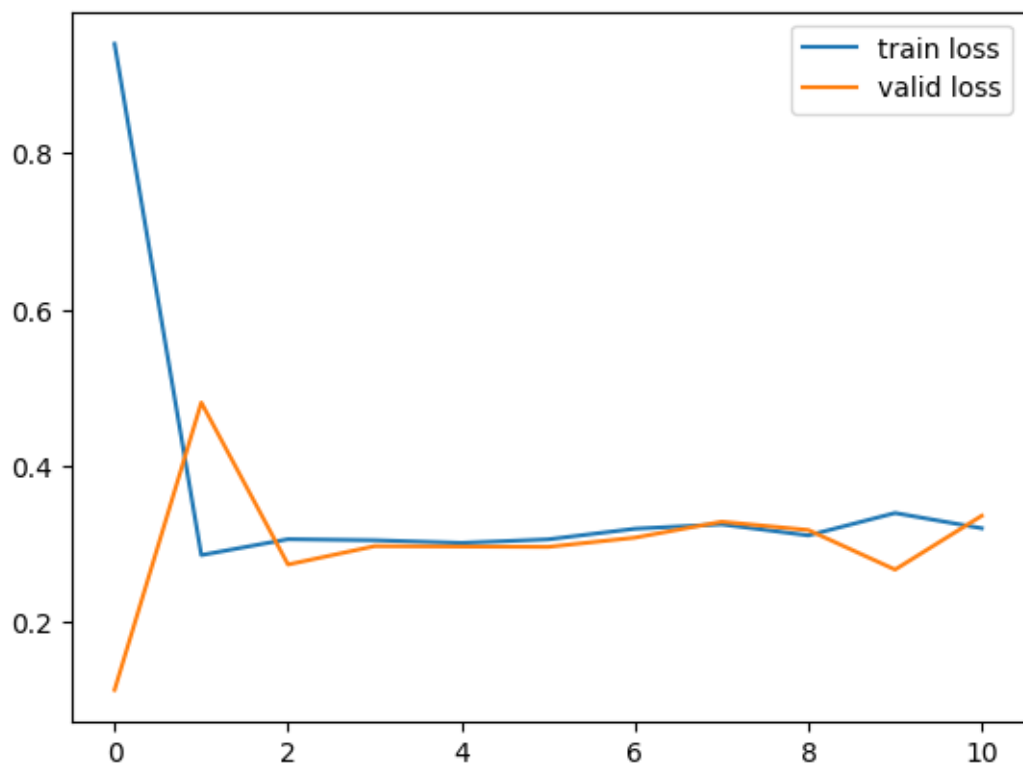
CV round 7  
EARLY STOPPING @ epoch 14  
min train loss: 0.29972398777802783  
min valid loss: 0.2774925357417056



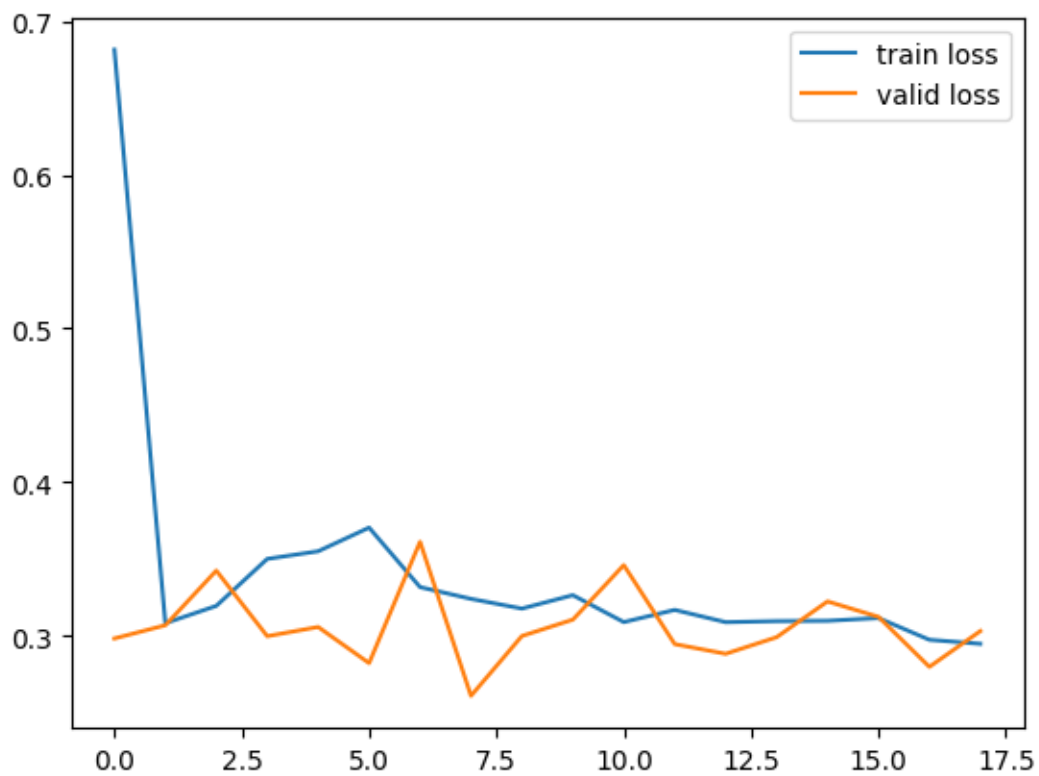
CV round 8  
EARLY STOPPING @ epoch 12  
min train loss: 0.2971803545951843  
min valid loss: 0.2956592746471104



CV round 9  
EARLY STOPPING @ epoch 10  
min train loss: 0.28574483799324796  
min valid loss: 0.11320586855474271

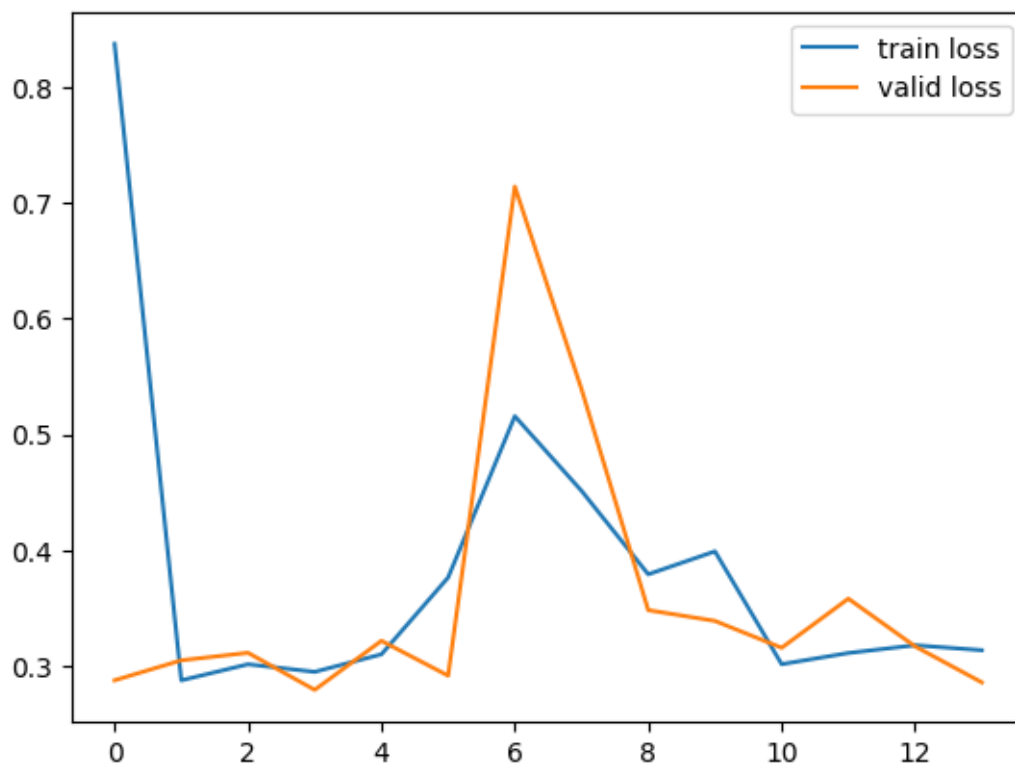


CV round 10  
EARLY STOPPING @ epoch 17  
min train loss: 0.2947077210428137  
min valid loss: 0.2608380090249212

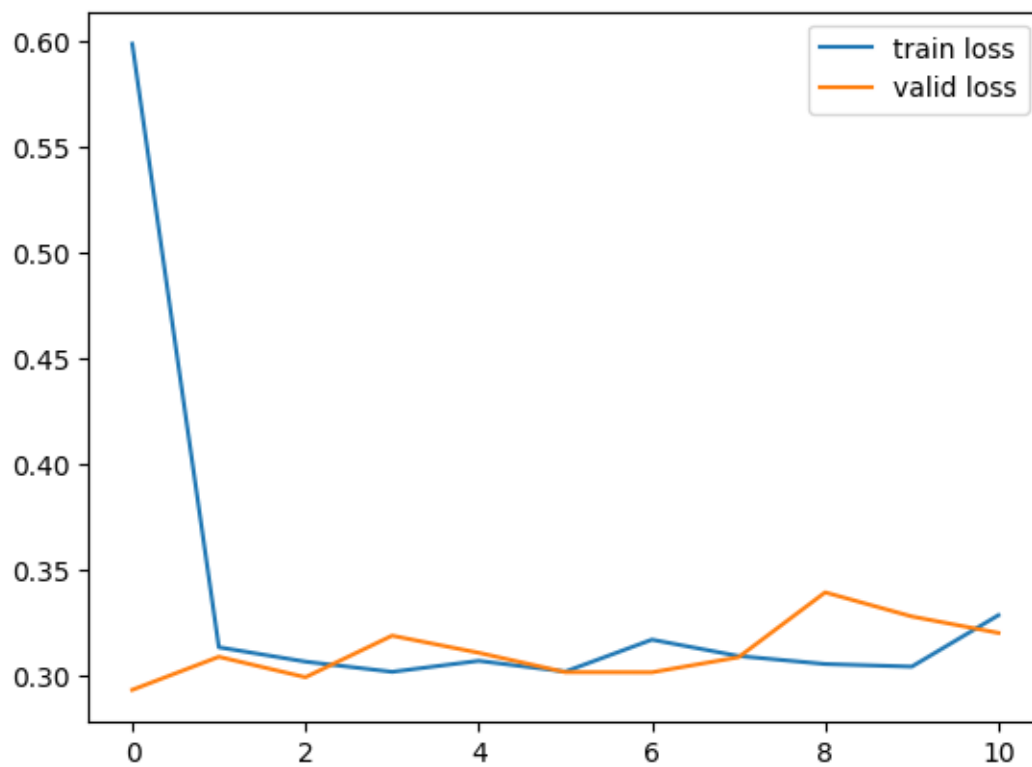


CV round 11  
EARLY STOPPING @ epoch 13  
min train loss: 0.2877337613679243  
min valid loss: 0.27950759467325714

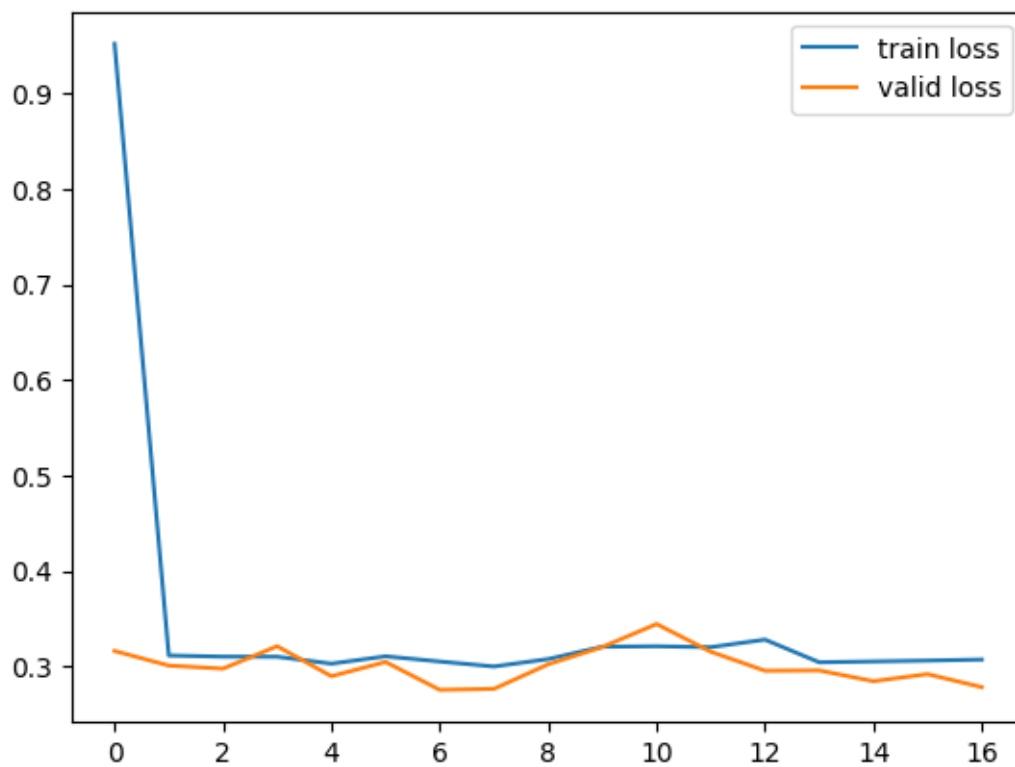




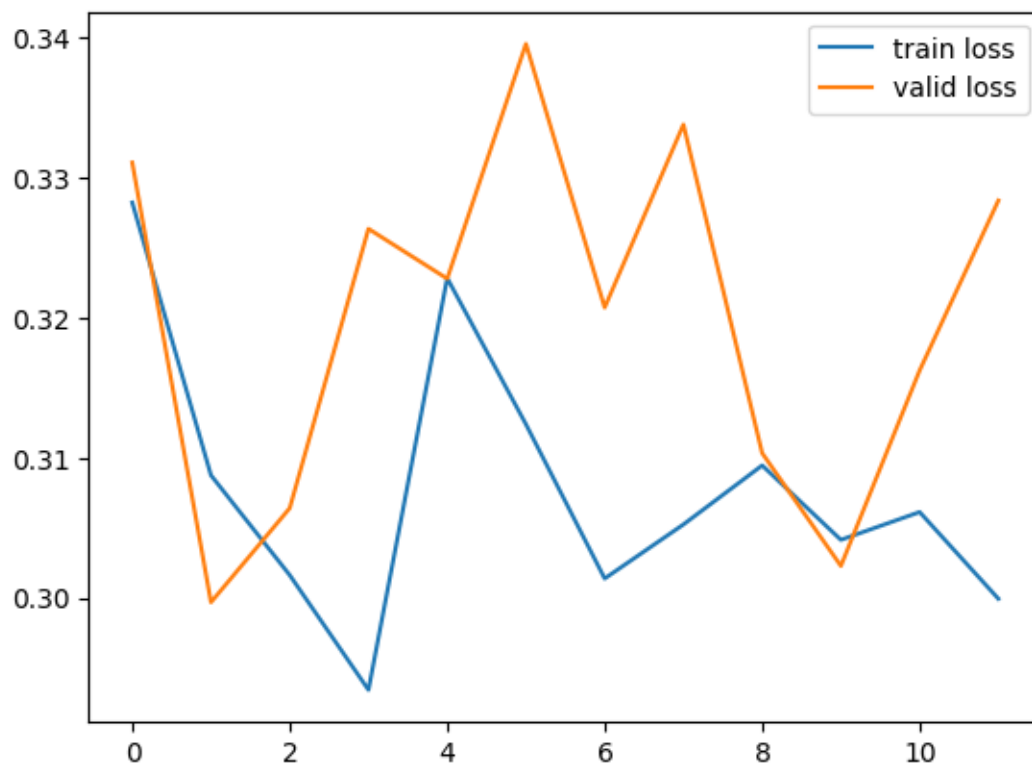
CV round 12  
EARLY STOPPING @ epoch 10  
min train loss: 0.30183328326904413  
min valid loss: 0.29331014501421077



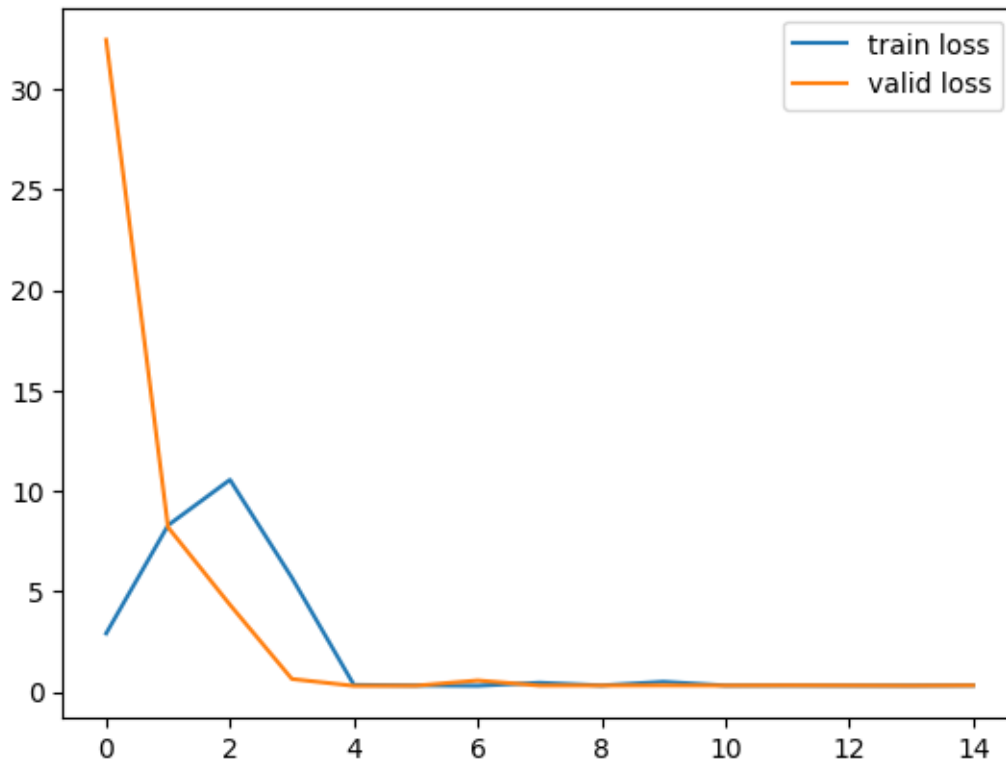
CV round 13  
EARLY STOPPING @ epoch 16  
min train loss: 0.29976136293826683  
min valid loss: 0.2752775973395297



CV round 14  
EARLY STOPPING @ epoch 11  
min train loss: 0.2934210763849092  
min valid loss: 0.29968001811127915



CV round 15  
EARLY STOPPING @ epoch 14  
min train loss: 0.2943132966192383  
min valid loss: 0.2893774815295872



best model is: CV=9.pth with 0.11320586855474271

```
[18]: network_object._network.load_state_dict(torch.load(s['best model folder'] +
    ↪ CV_saver.best_model_name))
test_loss = network_object.test(
    DataLoader(SiameseDataset(
        data_dictionary[s['data']]['data'],
        data_dictionary[s['data']]['label'],
        data_dictionary[s['data']]['test indices'],
        device=device,), shuffle=False, batch_size=32))
print(f"testing loss: {test_loss}")
```

testing loss: 0.35837633398018387