Analysis of Algorithms CSC 402

2022-23



Subject Incharge

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BRANCH AND BOUND

The Method

- Branch-and-Bound (BnB) algorithms are based on searches of an associated state space tree for goal states.
- In BnB algorithms, all the children of the E-node (the node currently being expanded) are generated before the next E-node is chosen. (unlike Backtracking where the tree is generated depth wise).
- The traversal is in BFS manner.

The Method

- When the children are generated, they become live nodes and are stored in a suitable data structure, say LiveNodes.
- Various versions of BnB (Branch and Bound) exist, each differing only in the manner the next E-Node amongst LiveNodes is selected
 - FIFO BnB □ LiveNode implemented as queue
 - □ LIFO BnB □ LiveNode implemented as stack
 - LC (Least Cost) BnB ☐ LiveNode implemented as priority queue i.e. the node with the best cost is expanded all others are discarded
 - We will be discussing LC BnB only

15 puzzle problem

- I5 numbered tiles on a single square frame of I6 tiles.
- Transform the initial arrangement of tiles into goal arrangement from a series of legal moves.

I	3	4	15	I	2	3	4
2		5	12	5	6	7	8
7	6	11	14	9	10	11	12
8	9	10	13	13	14	15	

Initial Position

Goal Position

15 puzzle problem... contd

I	2	3	4	I	2	3	4
5	6		8	5	6	7	8
9	10	7	11	9	10	11	12
13	14	15	12	13	14	15	

Initial Position

Goal Position

- Cost function $C^{\wedge}(x) = f(x) + g^{\wedge}(x)$
 - $C^{(x)}$ = estimated cost to reach goal node
 - f(x) = number of moves from initial state
 - g[^](x) = estimate of cost of reaching from current state to answer state (number of non blank tiles not in their goal position)



