

Analysis of Algorithms

CSC 402

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Dynamic Programming



Dynamic Programming

- An algorithm design method that can be used when the solution to a problem can be viewed as a sequence of decisions.
- “***Programming***” refers to *planning*.
- Final solution by combining the solution to sequence of subproblems.

Elements of Dynamic Programming (Steps)

- Characterize the structure of an optimal solution.
- Recursively define the value of an optimal solution.
- Compute the value of an optimal solution, typically in a bottom-up fashion.
- Construct an optimal solution from computed information.

Greedy Vs. Dynamic Programming

Greedy algorithm

- The best choice is made at each step and after that the subproblem is solved.
- The choice made by a greedy algorithm may depend on choices so far, but it cannot depend on any future choices or on the solutions to subproblems.
- A greedy strategy usually progresses in a top-down fashion, making one greedy choice after another, reducing each given problem instance to a smaller one

Dynamic programming

- A choice is made at each step.
- The choice made at each step usually depends on the solutions to subproblems.
- Dynamic-programming problems are often solved in a bottom-up manner.

Problems to be considered

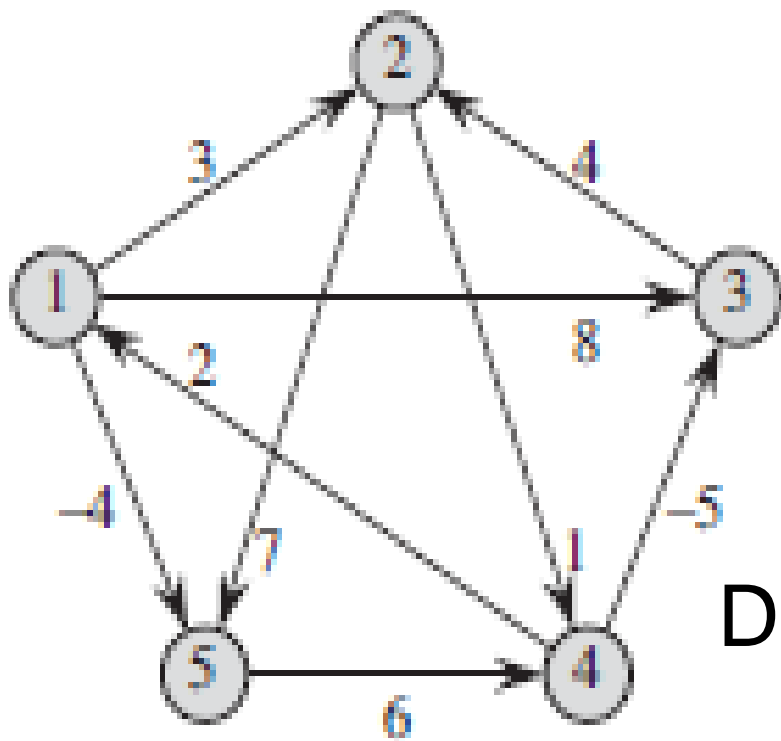
- All pairs shortest path
- Longest Common Subsequence
- Multistage Graphs
- Single source shortest path
- 0/1 knapsack problem
- TSP
- Assembly Line Scheduling

All pairs shortest paths

- Given a graph $G = (V, E)$, find the shortest path between every pair of vertices in the given graph.
- Dynamic Program Technique: Floyd-Warshall's Algorithm
 - Graph may contain negative edges but no negative weight cycles
 - A weight matrix W where
 - $W(i, j) = 0$ if $i = j$.
 - $W(i, j) = \text{INFINITY}$ if there is no edge between i and j .
 - $W(i, j) = \text{"weight of edge"}$

Floyd-Warshall's Algorithm

- Floyd-Warshall (W)
 - $n \leftarrow \text{rows}(W)$
 - $D^{(0)} \leftarrow W$
 - for $k \leftarrow 1$ to n
 - do for $i \leftarrow 1$ to n
 - do for $j \leftarrow 1$ to n
 - » do $D_{(i,j)}^k \leftarrow \min (D_{(i,j)}^{(k-1)}, (D_{(i,k)}^{(k-1)} + D_{(k,j)}^{(k-1)})$
 - Return $D^{(n)}$
- Complexity $O(V^3)$.



$D^{(0)} =$

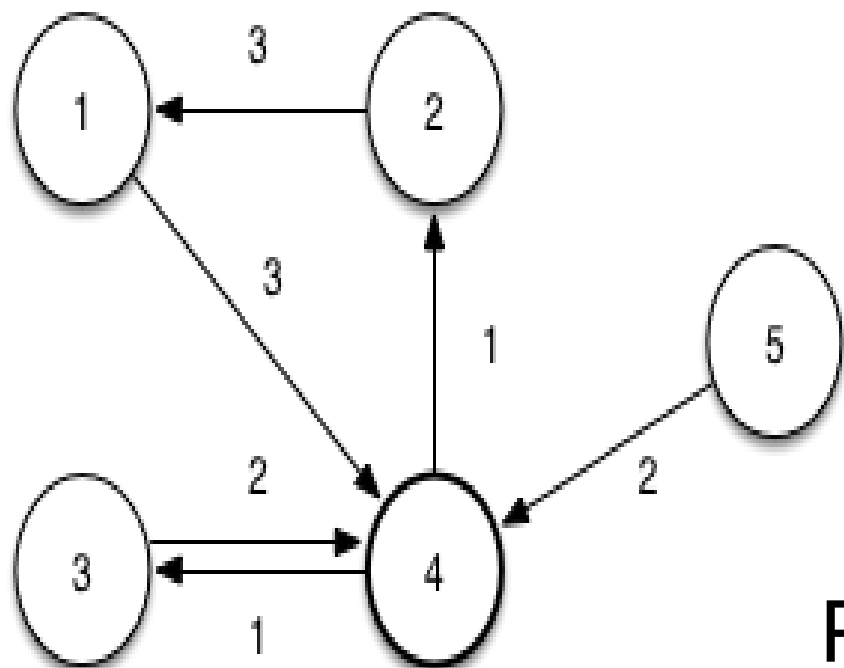
| | | | | |
|----------|----------|----------|----------|----------|
| 0 | 3 | 8 | ∞ | -4 |
| ∞ | 0 | ∞ | 1 | 7 |
| ∞ | 4 | 0 | ∞ | ∞ |
| 2 | ∞ | -5 | 0 | ∞ |
| ∞ | ∞ | ∞ | 6 | 0 |

Floyd-Warshall's Algorithm

- Path can be traced by simultaneously tracing a path matrix.
- Path matrix is constructed as follows:
 - If $i=j$ || $W[i][j]=\infty$
 - $P[i][j]=0$
 - If $i \neq j$ && $W[i][j] \neq \infty$
 - $P[i][j] = i$

Floyd-Warshall's Algorithm

- Code modified to trace path
- Floyd-Warshall (W)
 - $n \leftarrow \text{rows}(W)$
 - $D^{(0)} \leftarrow W$
 - for $k \leftarrow 1$ to n
 - do for $i \leftarrow 1$ to n
 - do for $j \leftarrow 1$ to n
 - » If $(D_{(i,j)}^{(k-1)} > (D_{(i,k)}^{(k-1)} + D_{(k,j)}^{(k-1)})$
 - » do $D_{(i,j)}^k \leftarrow \min (D_{(i,j)}^{(k-1)}, (D_{(i,k)}^{(k-1)} + D_{(k,j)}^{(k-1)})$
 - » $P[i][j]=k$
 - Return $D^{(n)}$



$$D^{(0)} =$$

| | | | | |
|----------|----------|----------|----------|----------|
| 0 | ∞ | ∞ | 3 | ∞ |
| 3 | 0 | ∞ | ∞ | ∞ |
| ∞ | ∞ | 0 | 2 | ∞ |
| ∞ | 1 | 1 | 0 | ∞ |
| ∞ | ∞ | ∞ | 2 | 0 |

$$P^{(0)} =$$

| | | | | |
|----------|----------|----------|----------|----------|
| 0 | 0 | 0 | 1 | 0 |
| 2 | 0 | 0 | 0 | 0 |
| 0 | 0 | 0 | 3 | 0 |
| 0 | 4 | 4 | 0 | 0 |
| 0 | 0 | 0 | 5 | 0 |

Longest Common Subsequence

- Substring and Subsequence
- A **substring** of a string S is another string S' that occurs in S and all the letters are **contiguous** in S
- E.g. HelloWorld
- substring1 : Hello substring2 : World
- A **subsequence** of a string S is another string S' that occurs in S and all the letters **need not to be contiguous** in S
- E.g. HelloWorld
- subsequence1 : Herd subsequence2 : eow

Longest Common Subsequence

- The Longest Common Subsequence (LCS) problem is as follows:
- We are given two strings: **string A** of length **x** and **string B** of length **y**.

We have to find the longest common subsequence :

The longest sequence of characters that appear left-to-right in both strings.

Example, A= KASHMIR

B= CHANDIGARH

LCS has 3 length and string is **HIR**

Longest Common Subsequence

- Brute Force Method
 - Given two strings X of length m and Y of length n, find a longest subsequence common to both X and Y
 - STEP1 : Find all subsequences of 'X'. 2^m
 - STEP2: For each subsequence, find whether it is a subsequence of 'Y'. $n * 2^m$
 - STEP3: Find the longest common subsequence from available subsequences. $T.C = O(n2^m)$
- To improve time complexity, we use dynamic programming

Longest Common Subsequence

- **Optimal substructure**

We have two strings

$$X = \{x_1, x_2, x_3, \dots, x_m\}$$

$$Y = \{y_1, y_2, y_3, \dots, y_n\}$$

First compare x_m and y_n . If they matched, find the subsequence in the remaining string and then append the x_m with it.

If $x_m \neq y_n$,

- Remove x_m from X and find LCS from x_1 to x_{m-1} and y_1 to y_n
- Remove y_n from Y and find LCS from x_1 to x_m and y_1 to y_{n-1}

In each step, we reduce the size of the problem into the subproblems. It is **optimal substructure**.

Longest Common Subsequence

Recursive Equation

$$X = \{x_1, x_2, x_3, \dots, x_m\}$$

$$Y = \{y_1, y_2, y_3, \dots, y_n\}$$

- Let $c[i, j]$ be the length of an LCS of X_i & Y_j

$$c[i, j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0 \\ c[i-1, j-1] + 1 & \text{if } i, j > 0 \text{ and } x_i = y_j \\ \max(c[i, j-1], c[i-1, j]) & \text{if } i, j > 0 \text{ and } x_i \neq y_j \end{cases}$$

Longest Common Subsequence

LCS-LENGTH(X, Y)

```
1   $m \leftarrow \text{length}[X]$ 
2   $n \leftarrow \text{length}[Y]$ 
3  for  $i \leftarrow 1$  to  $m$ 
4      do  $c[i, 0] \leftarrow 0$ 
5  for  $j \leftarrow 0$  to  $n$ 
6      do  $c[0, j] \leftarrow 0$ 
7  for  $i \leftarrow 1$  to  $m$ 
8      do for  $j \leftarrow 1$  to  $n$ 
9          do if  $x_i = y_j$ 
10             then  $c[i, j] \leftarrow c[i - 1, j - 1] + 1$ 
11                   $b[i, j] \leftarrow \nwarrow$ 
12             else if  $c[i - 1, j] \geq c[i, j - 1]$ 
13                 then  $c[i, j] \leftarrow c[i - 1, j]$ 
14                       $b[i, j] \leftarrow \uparrow$ 
15                 else  $c[i, j] \leftarrow c[i, j - 1]$ 
16                       $b[i, j] \leftarrow \leftarrow$ 
17  return  $c$  and  $b$ 
```

Input: Two sequences :

$X = \{x_1, x_2, x_3, \dots, x_m\}$

$Y = \{y_1, y_2, y_3, \dots, y_n\}$

For $i=0..m$ and $j=0..n$
C[i,j] holds the LCS of
sequences X_i and Y_j

For $i=1..m$ and $j=1..n$
B[i,j] points to table
entries corresponding to
optimal sub-problem.

Printing the Solution

PRINT-LCS(b, X, i, j)

```
1  if  $i == 0$  or  $j == 0$ 
2      return
3  if  $b[i, j] == "\backslash"$ 
4      PRINT-LCS( $b, X, i - 1, j - 1$ )
5      print  $x_i$ 
6  elseif  $b[i, j] == "\uparrow"$ 
7      PRINT-LCS( $b, X, i - 1, j$ )
8  else PRINT-LCS( $b, X, i, j - 1$ )
```

Initial call:

Print_LCS($b, X, X.length, Y.length$)

Analysis

- We have two nested loops
 - The outer one iterates m times
 - The inner one iterates n times
 - A constant amount of work is done inside each iteration of the inner loop
 - Thus, the total running time is $O(mn)$

Application

- Bioinformatics
 - DNA Matching of different organisms

DNA comprises of {A,C,G,T}.

DNA1= AGCCTCAGT

DNA2=ATCCT

DNA3=AGTAGC

DNA 1 and DNA 3 are more similar.
- File Comparison
- Revision Control Systems (Git)
- Screen Redisplay

Single source Shortest Path

- Given a graph $G = (V, E)$, to find the shortest path from a given **source** vertex $s \in V$ to every other vertex $v \in V$.
- Algorithms to be considered in dynamic programming
 - Bellman-Ford Algorithm.

Bellman-Ford Algorithm

- Provides general solution to the SSSP problem.
 - i.e. edge weights may be negative.
- Given a weighted, directed graph $G = (V, E)$ with source s , the Bellman-Ford Algorithm returns a boolean value indicating whether or not there is a negative weight cycle that is reachable from the source.

Bellman-Ford Algorithm

- Bellman-Ford (G, w, s)
 - INITIALIZE-SINGLE-SOURCE(G, s)
 - for $i \leftarrow 1$ to $|V[G]| - 1$
 - do for each edge $(u, v) \in E[G]$
 - do RELAX(u, v, w)
 - for each edge $(u, v) \in E[G]$
 - do if $d[v] > d[u] + w(u, v)$
 - then return FALSE
 - return TRUE

INITIALIZE-SINGLE-SOURCE(G, s)

```
1  for each vertex  $v \in V[G]$ 
2      do  $d[v] \leftarrow \infty$ 
3       $\pi[v] \leftarrow \text{NIL}$ 
4   $d[s] \leftarrow 0$ 
```

RELAX(u, v, w)

```
1  if  $d[v] > d[u] + w(u, v)$ 
2      then  $d[v] \leftarrow d[u] + w(u, v)$ 
3       $\pi[v] \leftarrow u$ 
```

Bellman-Ford Algorithm

- Analysis
 - The for loop executes $O(V)$ times and each time checks for $|E|$ edges, i.e. $O(VE)$
- Applications
 - Variants of Bellman-Ford Algorithm used in routing protocols like Routing Information Protocol (RIP).

Multistage Graphs

- A multistage graph $G = (V, E)$ is a directed graph in which vertices are partitioned into $k \geq 2$ disjoint sets V_i , $1 \leq i \leq k$.
- In addition if (u, v) is an edge in E , then $u \in V_i$ and $v \in V_{i+1}$.
- Sets V_1 and V_k are such that $|V_1| = |V_k| = 1$.

Multistage Graphs

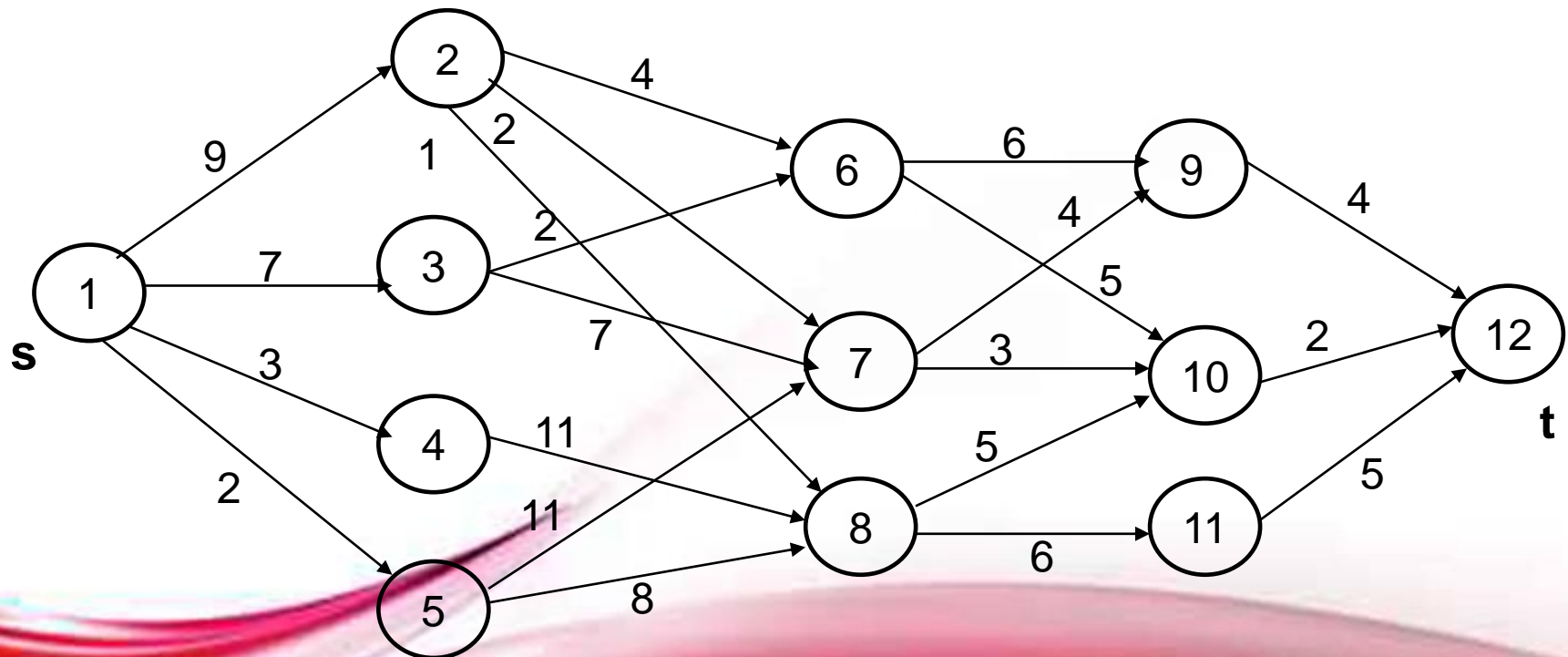
I Stage

II Stage

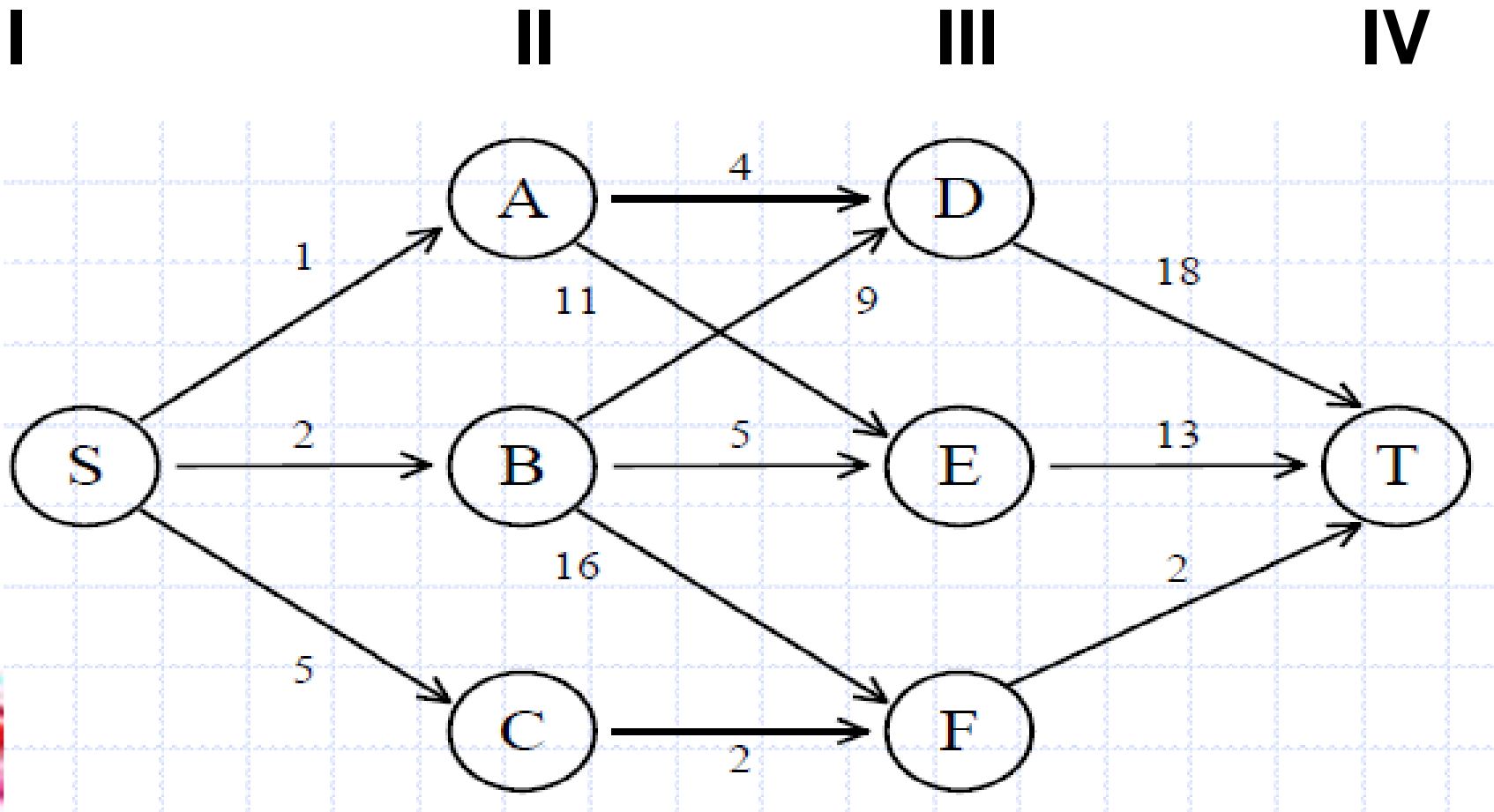
III Stage

IV Stage

V Stage



Multistage Graphs



Multistage Graphs

- Problem: to find the shortest path between source and sink
- Can be solved using
 - Forward Approach
 - Backward Approach
- For algorithm for both the approaches refer... Fundamentals of Algorithms, Hurowitz, Rajasekaran, Sahani.

Forward Approach

- Solve backwards and trace the path forwards
 - $c(i,j)$ = cost/weight/distance of edge (i,j)
 - $\text{cost}(k,j)$ = cost of shortest path for node j in stage k to sink node t
 - E.g. $\text{cost}(\text{III},6)$ = cost of shortest path for node 6 in stage III to sink t
- Recursive formula:
 - $\text{cost}(i,j) = \min \{c(j,l) + \text{cost}(i+1,l)\}$
 - $(j,l) \in E$
 - $l \in V_{i+1}$

Forward Approach

- Initial condition
 - $\text{cost}(k, t) = 0$
 - i.e. cost of shortest path from sink node t in last stage to itself is 0

Backward Approach

- $\text{bcost}(l,j)$ = backward cost of node j in stage l to initial source node.
 - $\text{bcost}(i,j) = \min \{ \text{bcost}(i-1,l) + c(l,j) \}$
 $(l,j) \in E$
 $l \in V_{i-1}$
- Initial Condition
 - $\text{bcost}(l,s) = 0$
 - Cost of shortest path from node s to source node in stage l is 0

Applications

- Project Scheduling

0/1 Knapsack Problem

- A thief robbing a store finds n items; the j^{th} item is worth c_j cost units and weighs w_j weight units. The thief wants to take as valuable load as possible, but he can carry at most W weight units in his knapsack.
- **Which items should he take ???** is the 0-1 knapsack problem (each item can be taken or left)

0/1 Knapsack Problem

- Select objects out of n objects such that $\sum_{1 \leq i \leq n} v_i x_i$ is maximum subject to $\sum_{1 \leq i \leq n} w_i x_i \leq m$ where $[p_1, p_2, p_3, \dots p_n]$ is the profit vector, x_i is either 0 or 1, $1 \leq i \leq n$ and m is the capacity of knapsack.
- The principal of optimality holds if
 - $V[i,j] = \max \{V[i-1,j], p_i + V[i-1,j-w_i]\}$
 - V is the array of solution of subproblems of size j with i items.

0/1 Knapsack Problem

- Inputs:
 - Set of n items, with weights w_i and profits p_i
 - Knapsack capacity M
- Output: Array V which holds the solution
- Conditions
 - $V[i,j] = 0$ if $i=0$ or $j=0$
 - $V[i,j] = V[i-1,j]$ if $j < w_i$
 - $\text{Max} \{V[i-1,j], p_i + V[i-1,j-w_i]\}$ if $j \geq W$

DP_Knapsack(V,p,w,M,n)

- for $i \leftarrow 1$ to n do
 - $V[i,0] \leftarrow 0$
- for $j \leftarrow 1$ to M do
 - $V[0,j] \leftarrow 0$
- for $i \leftarrow 1$ to n do
 - for $j \leftarrow 0$ to M do
 - If $w[i] \leq j$
 - $V[i,j] \leftarrow \max \{V[i-1,j], p[i]+V[i-1, j-w[i]]\}$
 - Else
 - $V[i,j] \leftarrow V[i-1,j]$

Complexity:
 $O(n \cdot M)$

Trace_Knapsack(w,p,V,M)

- $SW \leftarrow \phi$ //set of weights and profits
- $SP \leftarrow \phi$ // to be added to knapsack
- $i \leftarrow n, j \leftarrow M$
- while ($j > 0$) do
 - if ($V[i,j] == V[i-1,j]$) then
 - $i \leftarrow i-1$
 - else
 - $SW \leftarrow SW + w[i]$
 - $SP \leftarrow SP + p[i]$
 - $j \leftarrow j - w[i]$
 - $i \leftarrow i-1$

Additional Problems

- Some problems
 - $n=4$, $(w_1, w_2, w_3, w_4) = (1, 5, 3, 4)$, $(p_1, p_2, p_3, p_4) = (15, 10, 9, 5)$ and $m=8$
 - $n=3$, $(w_1, w_2, w_3) = (2, 3, 3)$, $(p_1, p_2, p_3) = (1, 2, 4)$ and $m=6$
 - $n=3$, $(w_1, w_2, w_3) = (2, 3, 4)$, $(p_1, p_2, p_3) = (1, 2, 5)$ and $m=6$.

0/1 Knapsack Problem

- Consider the following case

| Weight & Cost | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 |
|---------------|---|---|---|---|---|----|----|----|----|----|----|----|
| | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| w1=1,p1=1 | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| w2=2,p2=6 | 0 | 1 | 6 | 7 | 7 | 7 | 7 | 7 | 7 | 7 | 7 | 7 |
| w3=5,p3=18 | 0 | 1 | 6 | 7 | 7 | 18 | 19 | 24 | 25 | 25 | 25 | 25 |
| w4=6,p4=22 | 0 | 1 | 6 | 7 | 7 | 18 | 22 | 24 | 28 | 29 | 29 | 40 |
| w5=7,p5=28 | 0 | 1 | 6 | 7 | 7 | 18 | 22 | 28 | 29 | 34 | 35 | 40 |

0/1 Knapsack Problem

- Applications
 - Data Compression
 - Internet Download Managers
 - Resource Allocation

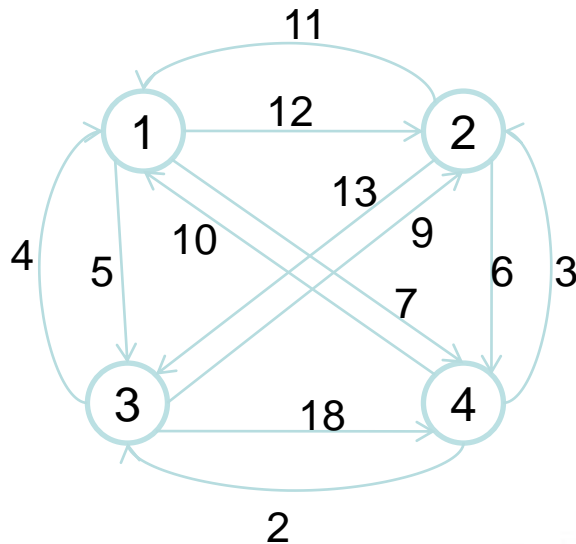
Travelling Salesman Problem

- Let $G=(V, E)$ be a directed graph with n vertices and $w(u, v)$ be the length/weight of edge (u, v) .
- A path starting at a given vertex v_1 , going thru every vertex exactly once, and finally returning to v_1 is called a tour
- Length of a tour is the sum of the lengths of the edges in the path defining the tour

Travelling Salesman Problem



Travelling Salesman Problem... contd



| | 1 | 2 | 3 | 4 |
|---|----|----|----|----|
| 1 | 0 | 12 | 5 | 7 |
| 2 | 11 | 0 | 13 | 6 |
| 3 | 4 | 9 | 0 | 18 |
| 4 | 10 | 3 | 2 | 0 |

Travelling Salesman Problem ... contd

- TSP: Finding the tour of minimum length.
- Greedy method fails to find the optimum solution
 - Therefore dynamic programming for optimal solution is used.
- Logic: Every tour consists of an edge $(1, k)$ for some $k \in V - \{1, k\}$ and finally a return path from k to 1 .
 - The path from k to 1 goes thru each vertex $V - \{1, k\}$ exactly once.

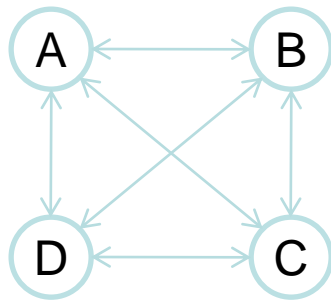
Travelling Salesman Problem... contd

- We calculate shortest path $sp(i, S) \rightarrow$ length of shortest path starting at vertex i and going thru all vertices in set S and terminating at 1.
- $sp(1, V - \{1\}) = \min_{2 \leq k \leq n} \{w_{1k} + sp(k, V - \{1, k\})\}$
- In general for i not belonging to S
 - $sp(i, S) = \min_{j \in S} \{w_{ij} + sp(j, S - \{j\})\}$
- Initial condition (initially $S = \Phi$)
 - $sp(i, \Phi) = w_{i1}$

Travelling Salesman Problem... contd

- Time complexity
 - Let N be the number of $sp(i, S)$ that have to be computed before general equation can be used to compute $sp(1, V - \{1\})$
 - $N = \sum_{k=0}^{n-2} (n-1) \binom{n-2}{k} = (n-1)2^{n-2}$
 - Total time = $O(n^2 2^n)$
 - This is better than enumerating all $n!$ different tours

Travelling Salesman Problem... contd



| | A | B | C | D |
|---|---|----|----|----|
| A | 0 | 10 | 15 | 20 |
| B | 5 | 0 | 9 | 10 |
| C | 5 | 13 | 0 | 12 |
| D | 8 | 8 | 9 | 0 |

Applications of TSP

- Route a **postal van** to pick up mail from mail boxes located at n different sites
- In the manufacture of a **circuit board**, it is important to determine the best order in which a laser will drill thousands of holes.

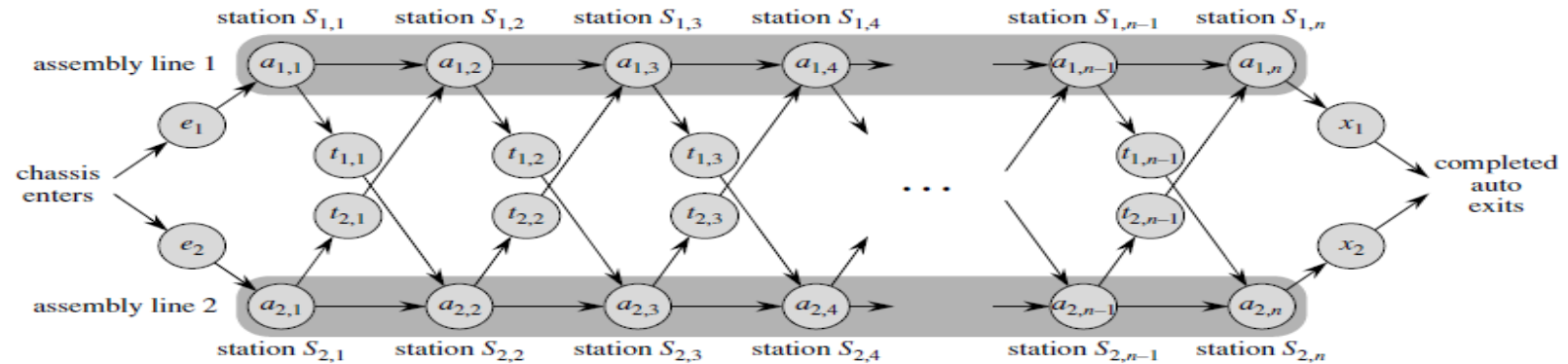


Applications of TSP



- Using a **robot arm** to tighten the nuts on some piece of machinery on an assembly line.
 - The arm will start from its initial position, successively move to each of the remaining nuts and return to the initial position.
 - The path of the arm is a tour on a graph in which vertices represent the nuts.
 - A minimum cost tour will minimize the time needed for the arm to complete its task.

Assembly Line Scheduling



- There are two assembly lines, each with n stations; the j^{th} station on line i is denoted $S_{i,j}$ and the assembly time at that station is $a_{i,j}$.
- An automobile chassis enters the factory, and goes onto line i (where $i = 1$ or 2), taking e_i time. After going through the j^{th} station on a line, the chassis goes on to the $(j+1)^{\text{st}}$ station on either line. There is no transfer cost if it stays on the same line, but it takes time $t_{i,j}$ to transfer to the other line after station $S_{i,j}$.
- After exiting the n^{th} station on a line, it takes x_i time for the completed auto to exit the factory.
- The problem is to determine which stations to choose from line 1 and which to choose from line 2 in order to minimize the total time through the factory for one auto.

Other Problems

- Chain Matrix Multiplication
- Flowshop Scheduling