Probability distributions for number of points in ambient pointcloud after filtering Normal distribution: location = 856.79933414, scale = 76.0530789035 $Log Normal \ distribution: location = -394.937051135, \ scale = 1249.42211965, \ shape = 0.0605688775744$ Generalized Extreme Value distribution: location = 824.925360762, scale = 73.8096956393, shape = 0.1410621083250.05 | 0.01 

908.5

Pointcloud size

959.0

1009.5

1060.0

1110.5

1161.0

0.00 | 0.0

706.5

757.0

807.5

858.0