

# 3d Rotation with Quaternions

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# Why Calculating Rotation in 3d is Valuable:

- Physics Simulations.
- 3d Animation.
- Navigation.
- And MUCH MORE!

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- Physics Simulations.
- 3d Animation.
- Navigation.
- And MUCH MORE!
- Rotation Around Axis.
- Gimbals.

# Why They Fail: Rotation Around Axis

Left rotation

# Why They Fail: Rotation Around Axis

Left rotation

Right rotation

# Why They Fail: Gimbals

Normal Gimbal

# Why They Fail: Gimbals

Normal Gimbal

Gimbal Lock

# What we would like

Stick in ball



# Complex Numbers

Graph overview, unit multiplication.

# Complex Number Angles

Show briefly the angle formula for complex numbers

# Introduce Quaternions

Complex Numbers

Quaternions

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Complex Numbers

$$c_0(\textcolor{yellow}{1}) + c_1\textcolor{red}{i}$$

Quaternions

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Quaternions

$$c_0(\textcolor{yellow}{1}) + c_1\textcolor{red}{i} + c_2\textcolor{green}{j} + c_3\textcolor{blue}{k}$$

# Introduce Quaternions

## Complex Numbers

$$c_0(\textcolor{yellow}{1}) + c_1\textcolor{red}{i}$$

$$\textcolor{red}{i}^2 = -\textcolor{yellow}{1}$$

## Quaternions

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The product of any 2 different complex parts gives the third and they **anti-commute**



# Introduce Quaternions

## Complex Numbers

$$c_0(1) + c_1 i$$

$$i^2 = -1$$

## Quaternions

$$c_0(1) + c_1 i + c_2 j + c_3 k$$

$$i^2 = j^2 = k^2 = -1$$

The product of any 2 different complex parts gives the third and they **anti-commute**

$$i * j = -j * i = k$$

# Times Tables

*	1	$i$	$j$	$k$
1	1	$i$	$j$	$k$
$i$	$i$	-1	$k$	$-j$
$j$	$j$	$-k$	-1	$i$
$k$	$k$	$j$	$-i$	-1

# But What About Rotation

$$i * \mathbb{H}$$

1 i graph

j k graph

# But What About Rotation

$$\mathbb{H} * i$$

1 i graph

j k graph

# The Big Idea

$$i * \mathbb{H} * i$$

1 i graph

j k graph

# Rotation!

$$i * \mathbb{H} * i$$

1 i graph

j k graph