



暑期課程 基本影像處理 day6-I

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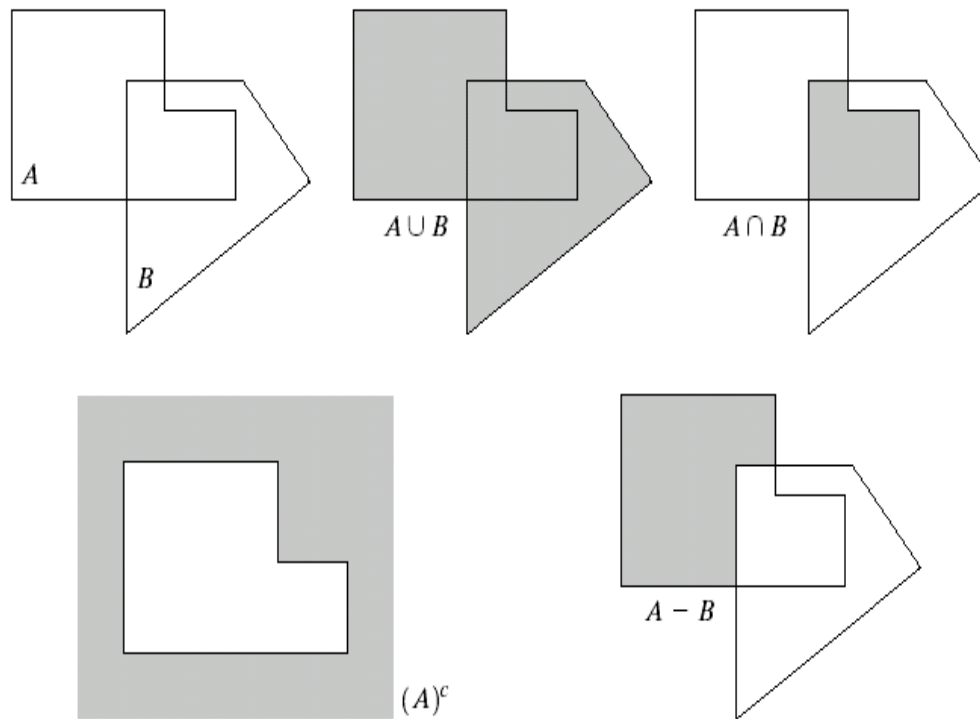
2015.07.08

Course Outline

- 型態影像學
 - Dilation (膨脹)
 - Erosion (侵蝕)
 - Opening and Closing
- Connected Component Labeling
 - (連通元件標記法)

Image Morphology

- 型態影像學，又稱型態學影像處理
 - 針對binary image中的像素執行集合運算 (set operation)



a	b	c
d	e	

FIGURE 9.1

(a) Two sets A and B . (b) The union of A and B . (c) The intersection of A and B . (d) The complement of A . (e) The difference between A and B .

Image Morphology

- 在離散空間(discrete space) Z^2 ，考慮一張二值化影像為一個具有兩個離散變數(x, y)的函數。我們定義影像中的物件A 為所有具有共同屬性↓性的像素的集合:

$I(x, y)$

- $A = \{ a \mid \text{property}(a) == \text{TRUE} \}$

TRUE = 1;
FALSE = 0;

- 至於A的背景則表示為 A^c (A的補集):
 - $A^c = \{ a \mid a \notin A \}$

a: a pixel point at (x, y) in image.

property(a): pixel value in *binary image* at point a

$$A = \{ a \mid \text{property}(a) == 1 \}$$

A^c

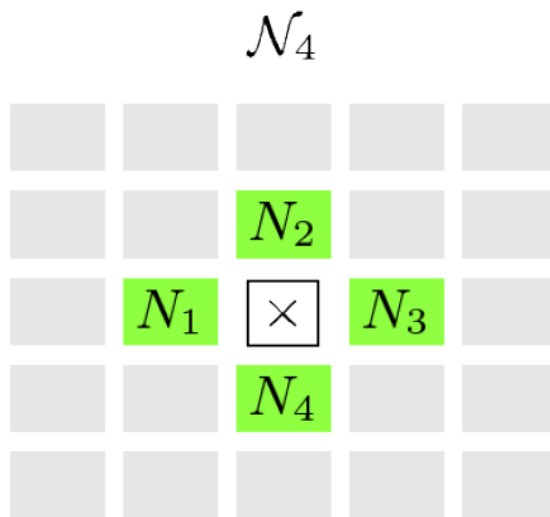
0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0
0	0	0	1	1	0	0	0	0
0	0	0	1	1	1	0	0	0
0	0	0	1	1	1	0	0	0
0	0	0	0	1	1	1	0	0
0	0	0	0	0	1	1	0	0
0	0	0	0	0	0	0	0	0

A

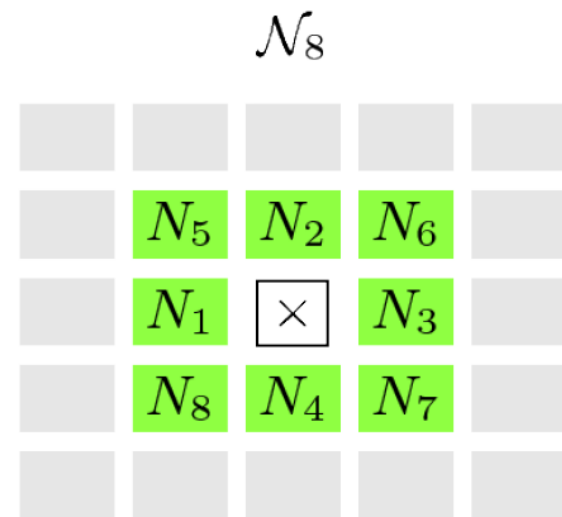
TRUE = 1; //foreground, object, target, etc.
FALSE = 0; //background

Pixel Neighborhoods

- the two definitions of “neighbors”



4 Neighborhood



8 Neighborhood

Dilation & Erosion

- 型態學影像處理常用的基本運算
 - 膨脹(dilation)和侵蝕(erosion)。
- 其運算的原理是將影像A與一個區域視窗(local window)一稱為結構元素B (structuring element) 的特定集合運算，其結果為一個新的濾波影像。

常見結構元素：

	1	
1	1	1
	1	

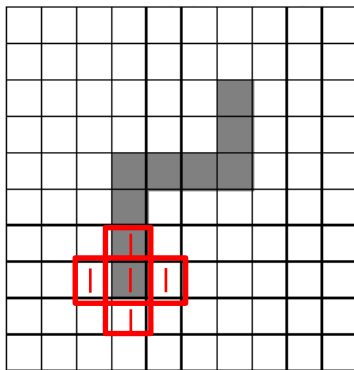
1	1	1
1	1	1
1	1	1

Dilation

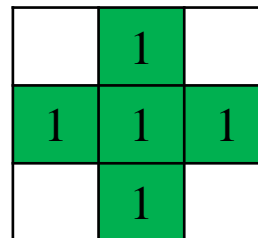
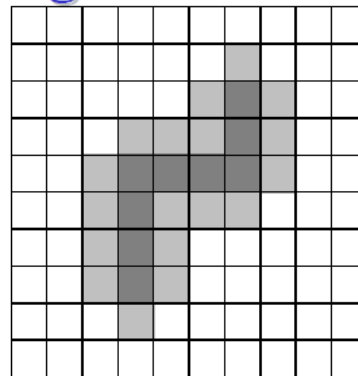
- 膨脹(dilation)

$$D(A, B) = A \oplus B = \bigcup_{b \in B} (A + b)$$

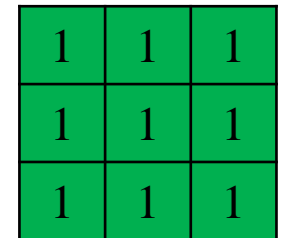
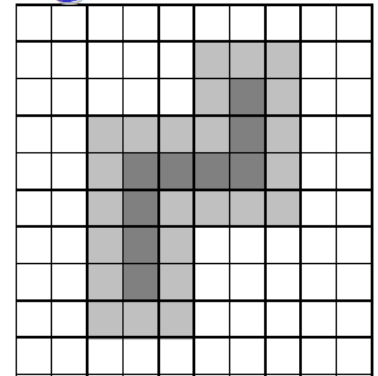
Original image



4-neighbor Dilation



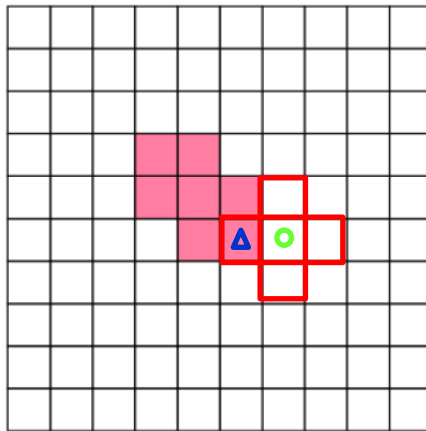
8-neighbor Dilation



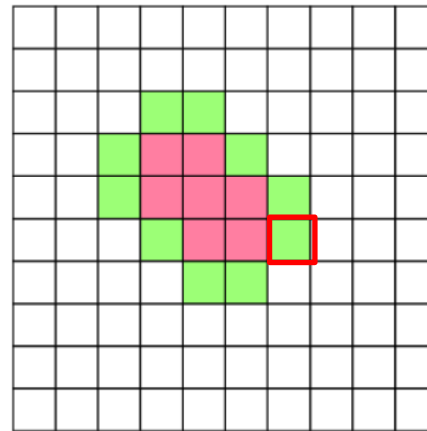
Dilation

- 方法：
 - 如果某個背景像素的4-neighbor或8-neighbor中有任何一個像素之素值為1，則將該像素之像素值以1取代，亦即將此像素加入至原始圖形內。
 - 也就是說，若中間元素為1(前景像素)則 4-neighbor或8-neighbor也會為1。

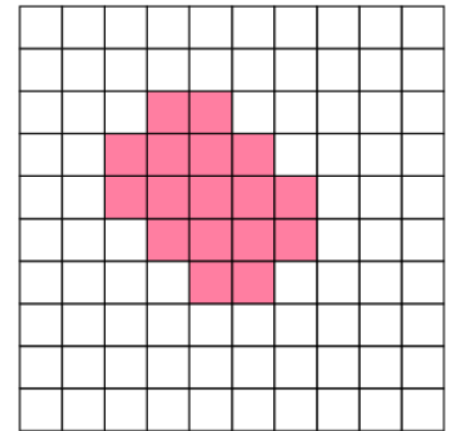
Dilation



(a)



(b)



(c)

Change a background pixel to foreground if it has a foreground pixel as a 4-neighbor.

Dilation

PS: 白色部分灰
階值為1



original



Iteration once



Iteration 3 times

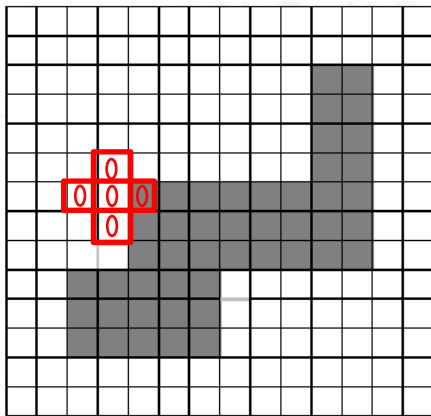


Erosion

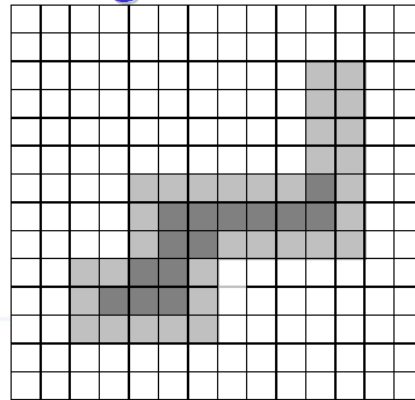
- 侵蝕(erosion)

$$E(A, B) = A \ominus (-B) = \bigcap_{b \in B} (A - b)$$

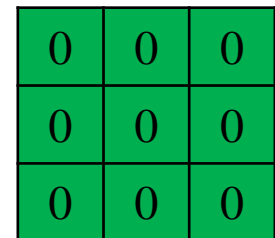
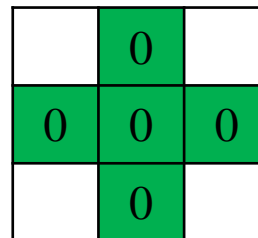
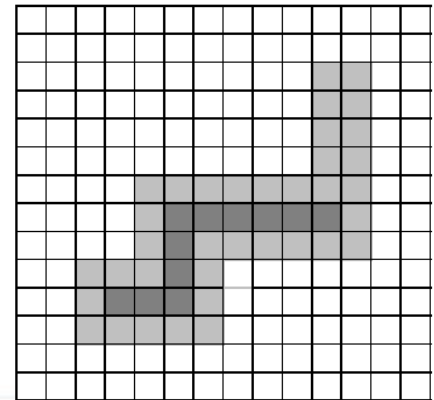
Original image



4-neighbor Erosion



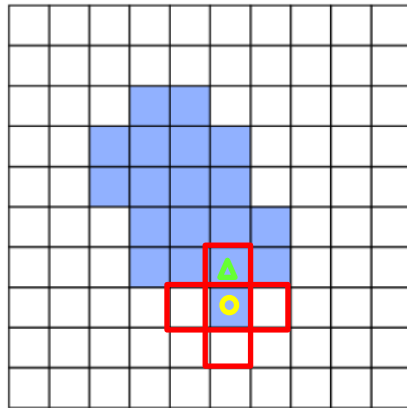
8-neighbor Erosion



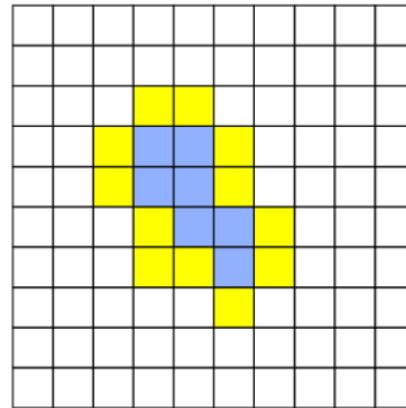
Erosion

- 方法：
 - 如果某個前景像素的4-neighbor或8-neighbor中有任何一個像素之素值為0，則將該像素之像素值以0取代，亦即將此像素從原始圖形內去掉。
 - 也就是說，若4-neighbor或8-neighbor有任一元素為0 (背景像素)，則中間元素為0。

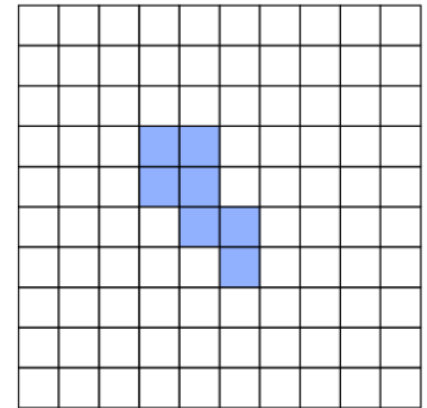
Erosion



(a)



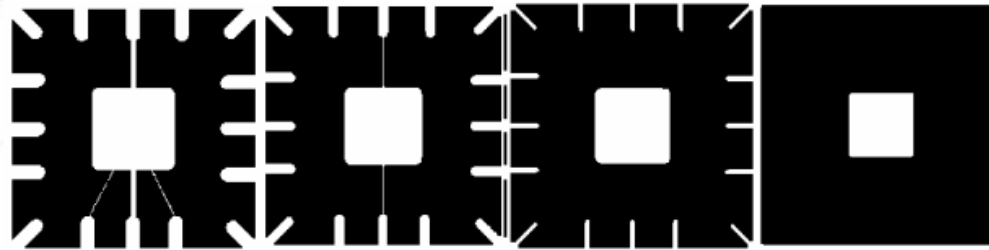
(b)



(c)

Change a foreground pixel to background if it has a background pixel as a 4-neighbor.

Erosion



Original

$R_B=5$

$R_B=10$

$R_B=20$



original

Iteration 2 times



Course Outline

- 型態影像學
 - Dilation (膨脹)
 - Erosion (侵蝕)
 - Opening and Closing
- A short introduction to Pattern Recognition
- Histogram of Oriented Gradients

Opening and Closing

- 建立在dilation和erosion運算的基礎上，
可以建構出更高階的型態學運算：

- 斷開(Opening)

$$I \circ H = (I \ominus H) \oplus H$$

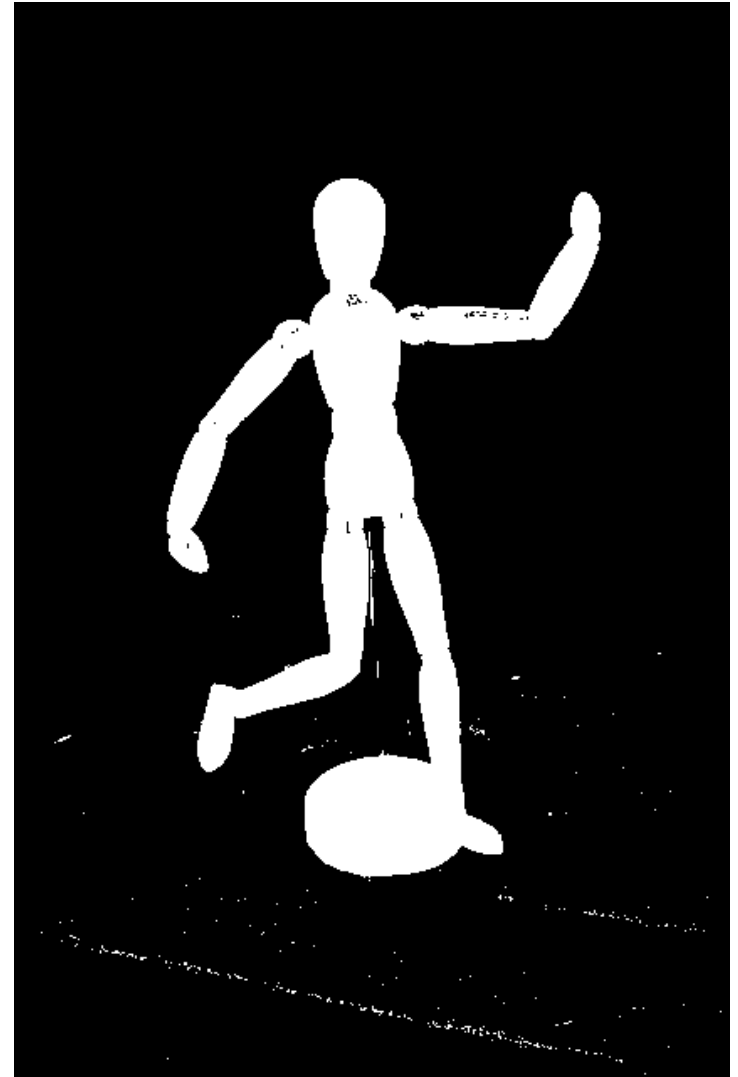
- 閉合(Closing)

$$I \bullet H = (I \oplus H) \ominus H$$

- I : image
- H : structure element



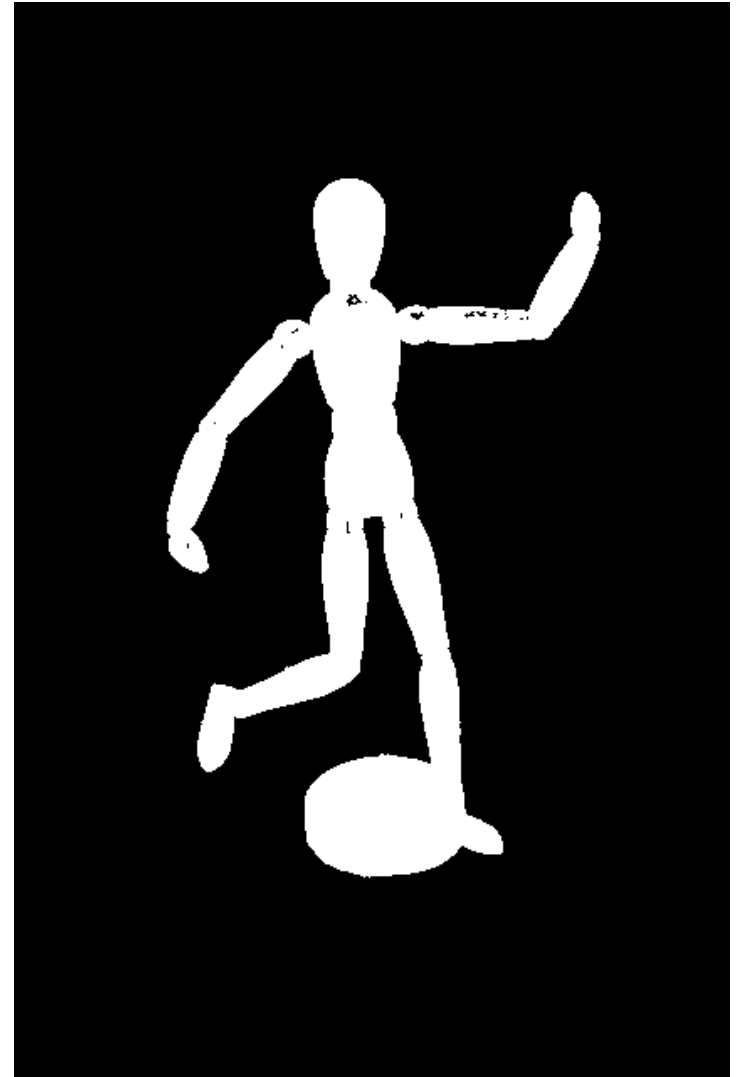
Original image



Initial threshold



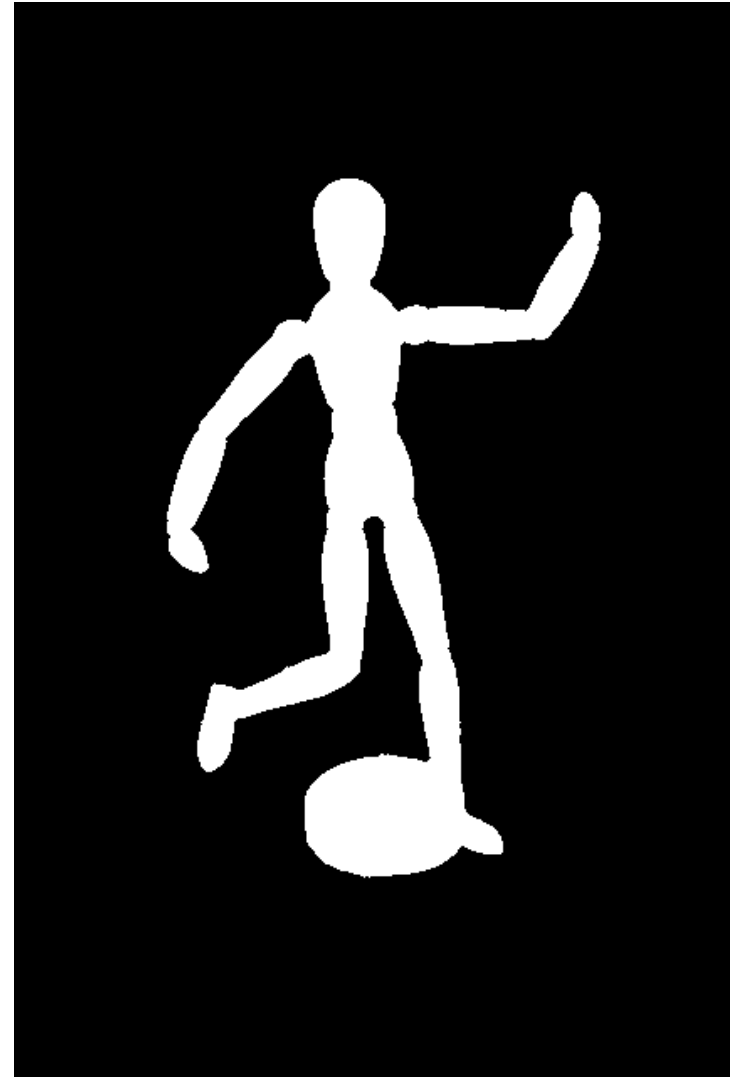
Original image



After opening



Original image

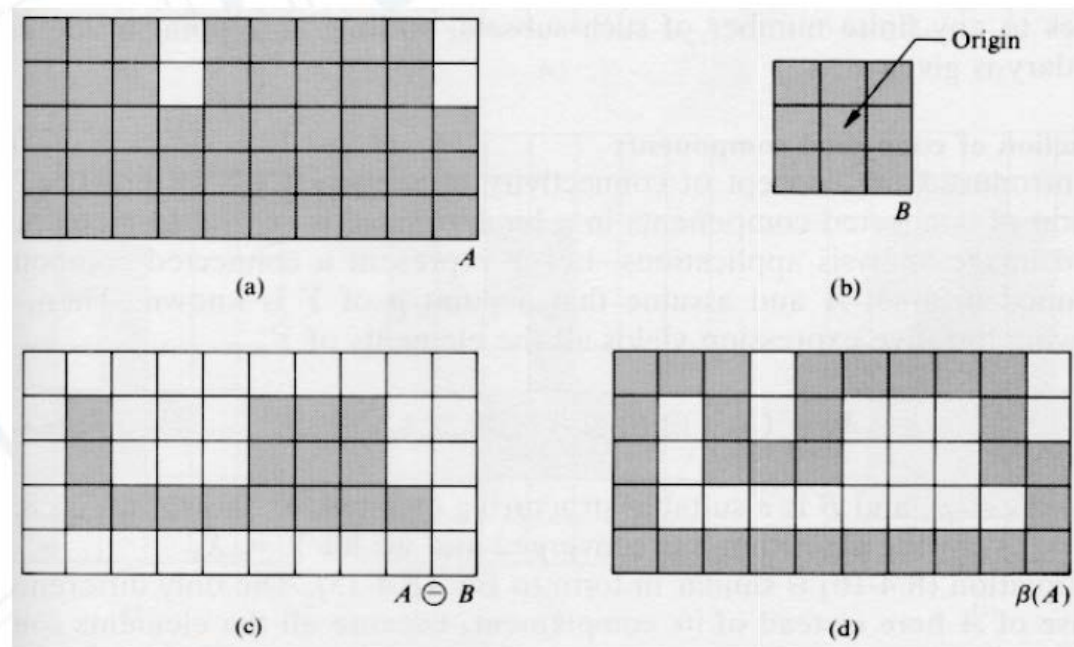


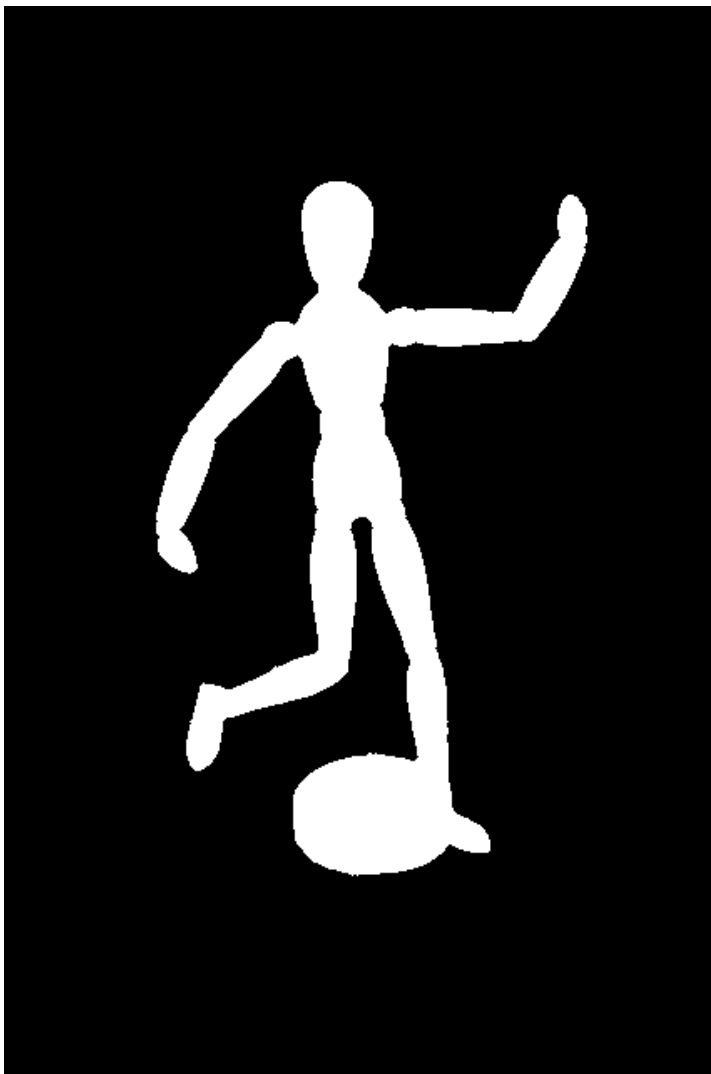
After closing

Applications

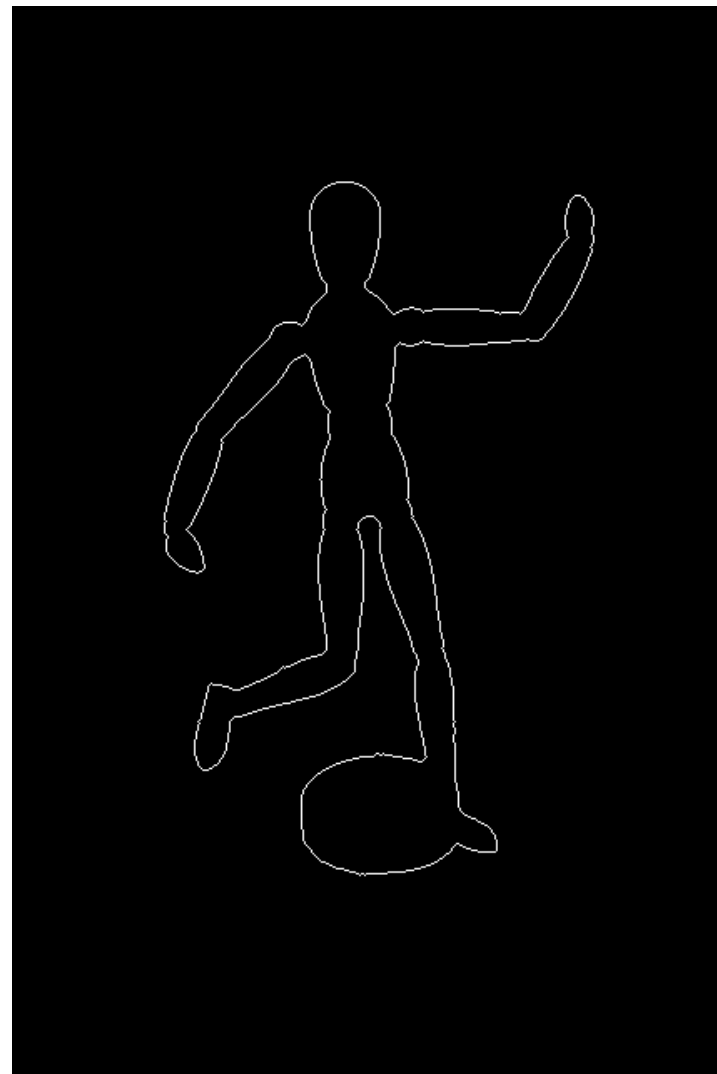
- **Boundary extraction** (邊界的萃取)

$$\beta(A) = A - (A \ominus B)$$

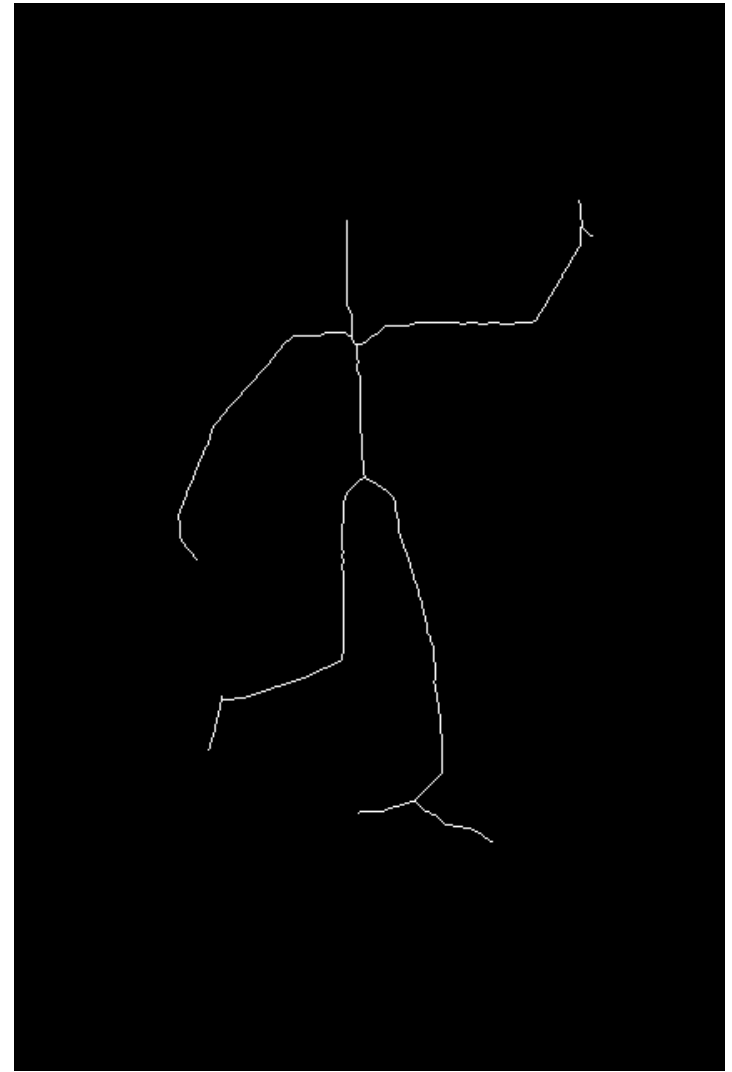
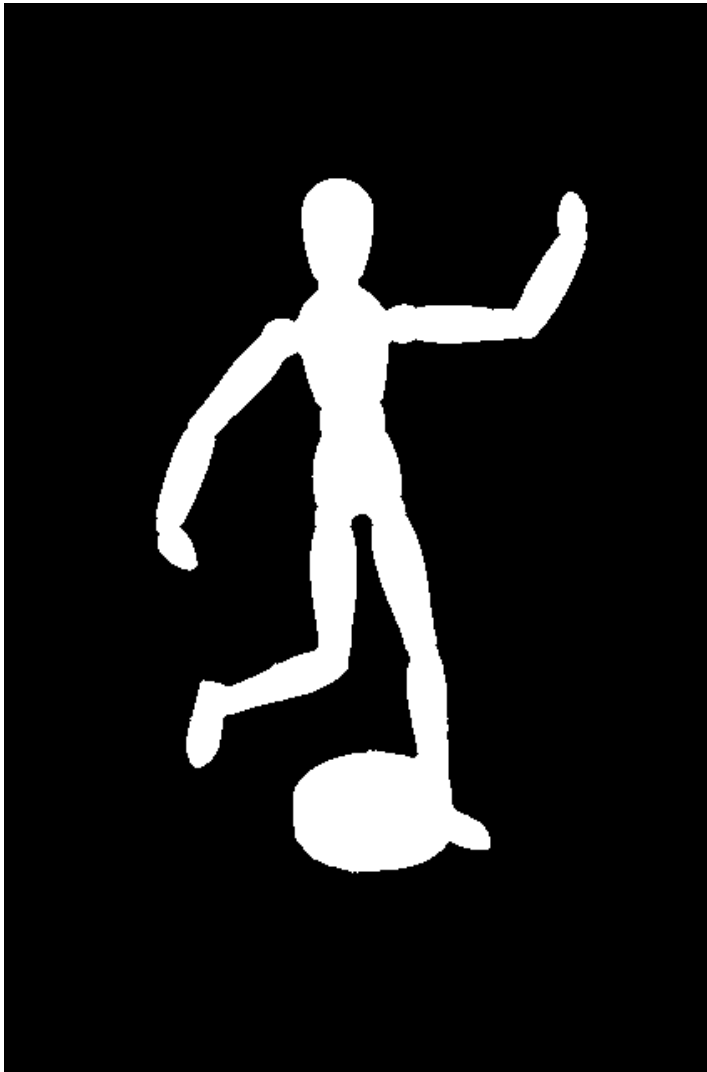




Binary segmentation



After boundary extraction

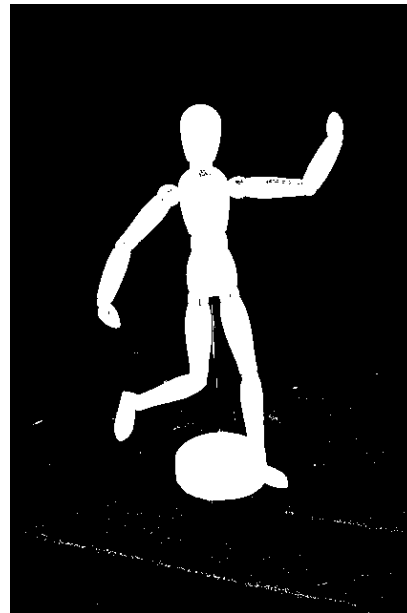


Repeatedly run erosion, stop when 1-pixel thick

Homework (plus)

- #6.1
 - 實做dilation
- #6.2
 - 實做erosion

MIAT




```

#include "array.h"

/*-----*/
//          Binary morphological image processing
//          MIAT Lab
//          CHEN Ching-Han , 2004.11.18
/*-----*/

#define OBJ 0    // object
#define BG 255  // background
#define NumPtSet 5 // number of elements in structuring element
//      +
//      + + + structuring element using N4
//      +

int seX[NumPtSet]={0,-1,0,1,0},seY[NumPtSet]={-1,0,0,0,1};

void clearImage(uc2D &ima)
{
    for(int i=0;i<nr;i++)for(int j=0;j<nc;j++)ima.m[i][j]=BG;
}

```

```
//-----//
//          Binary Mathematical Morphology
//
//-----//
void binaryDilation(uc2D &im1, uc2D &im2)
{
    for(int i=0;i<nr;i++)for(int j=0;j<nc;j++)im2.m[i][j]=im1.m[i][j];
    for(int i=1;i<nr-1;i++)for(int j=1;j<nc-1;j++)
    {
        if(im1.m[i][j]==BG)
            for(int k=0;k<NumPtSet;k++)if(im1.m[i+seY[k]][j+seX[k]]==OBJ)
            {
                im2.m[i][j]=OBJ;
                break;
            }
    }
}
```

```
void binaryErosion(uc2D &im1, uc2D &im2)
{
    for(int i=0;i<nr;i++) for(int j=0;j<nc;j++) im2.m[i][j]=im1.m[i][j];
    for(int i=1;i<nr-1;i++) for(int j=1;j<nc-1;j++)
    {
        if(im1.m[i][j]==OBJ)
            for(int k=0;k<NumPtSet;k++) if(im1.m[i+seY[k]][j+seX[k]]==BG)
            {
                im2.m[i][j]=BG;
                break;
            }
    }
}
```