## **CS 273 Laboratory 4: Selection**

This laboratory will give you experience with Java's if-statements (conditionals).

#### **Preliminaries**

- 1. Login to your machine and create a folder named lab4 on the cs273 area of your network drive.
- 2. Go to the course website on <a href="http://learning.up.edu">http://learning.up.edu</a>; download the lab4.zip file; and unzip it into the lab4 folder you just created. The project has already been built for you.
- 3. Open the project and run Lab4Main. It should display a primitive-looking drawing of a robot, with a set of labeled check-boxes above the robot.
- 4. Open the code editor for Lab4Area. This is the class that you will be changing. (Do not change Lab4Main!)
- 5. Examine the paint method. Notice the code fragment:

g.fillPolygon(body);

- 6. The pre-defined polygon named "body" is defined in Lab4BaseArea.java, for which you have not been given the source code. Lab4Area.java currently uses these pre-defined polygons to draw the robot:
  - body
  - leftEye
  - rightEye
  - smileMouth
  - leftEar
  - rightEar
  - leftArm
  - rightArm
  - leftLeg
  - rightLeg
- 7. There are a number of other "body parts" that are also defined in Lab4BaseApplet.class. You should use these body parts instead of creating your own. The following is the entire list that is available:
  - body the robot's body
  - arms:
    - o leftArm the robot's left arm, normal length, straight
    - o rightArm right arm, normal length, straight
    - o longLeftArm left arm, long, straight
    - o shortLeftArm left arm, very short
    - o longLeftArmBentUp left arm, long, bent up
    - o leftArmBentUp left arm, normal length, bent up
    - o longLeftArmBentDown left arm, long, bent down
    - o leftArmBentDown left arm, normal length, bent down
    - O longRightArm right arm, long, straight
    - o shortRightArm right arm, short
    - o longRightArmBentUp right arm, long, bent up
    - o rightArmBentUp right arm, normal length, bent up

- o longRightArmBentDown right arm, long, bent down
- o rightArmBentDown right arm, bent down
- legs
  - o leftLeg left leg, straight
  - o rightLeg right leg, straight
  - o rightLegBent right leg, bent
  - O leftLegBent left leg, bent
  - o rightLegBigFeet right leg, straight, with big feet
  - o leftLegBigFeet left leg, straight, with big feet
  - o rightLegBentBigFeet right leg, bent, with big feet
  - leftLegBentBigFeet left leg, bent with big feet
- ears
  - o rightEar right ear, normal size
  - o bigRightEar right ear, big
  - o leftEar left ear, normal size
  - o bigLeftEar left ear, big
- mouths
  - o smileMouth smiling mouth
  - o frownMouth frowning mouth
  - o whistleMouth whistling mouth
- eyes:
  - o leftEye left eye, looking straight
  - o leftEyeOut left eye, looking outward (i.e., left)
  - o leftEyeIn left eye looking inward (i.e., right)
  - o rightEye right eye, looking straight
  - o rightEyeOut right eye, looking outward (i.e., right)
  - o rightEyeIn right eye, looking inward (i.e., left)

Most of this laboratory will consist of modifying the paint method in Lab4Area so that it examines one or more check-boxes, and, uses that information to draw a robot that is customized according to color and body-part options. Every time a check-box is checked or unchecked, Lab4BaseArea repaints itself by calling your paint method. Your program can therefore continually keep the display of the robot consistent with the boxes that are checked.

## Laboratory

# Part 1: Allow the user to specify an alternate (green) color for the robot's body.

Modify the paint method so that if the "green body" box is checked, the robot's body is painted green. If the "green body" box is not checked, the robot's body should be silver.

The Lab4BaseArea class provides a method, isChecked(), that allows you to test whether a particular box is checked. For example, the following code can be used to check whether the "green body" box is checked:

```
if (isChecked("green body"))
{
```

```
(etc...)
```

<u>checkpoint 1 (10 points):</u> Have your lab instructor or assistant verify that your robot's body changes to green when appropriate.

#### Part 2: Allow the user to further customize the color of the robot's body.

Modify the paint method so that if <u>any</u> of the following boxes are checked, the robot's body is painted be the corresponding color:

- silver body
- green body
- pink body
- sky blue body

If none of the above boxes are checked, the body color should be silver. If more than one is checked, select the one nearest to the top of the above list (e.g., silver has priority over green). **Note:** Your CS203 Graphics Handout has a list of custom colors that may prove useful.

<u>checkpoint 2 (10 points):</u> Have your lab instructor or assistant verify that your robot's body changes color appropriately.

#### Part 3: Allow the user to customize the robots legs.

Modify the paint method so that if the bent legs box is checked then the robot's legs are drawn as bent rather than straight. Also, if big feet is checked, then the robot's feet are drawn "big" rather than normal size. If both of these boxes are checked, the robot should be drawn with big feet *and* with bent legs. The robot's legs should always be green.

<u>checkpoint 3 (10 points):</u> Have your lab instructor or assistant verify that your robot's legs change appropriately.

#### Part 4: Allow the user to customize the robot's ears.

Modify the paint method so that if the big ears box is checked, the robot is drawn with big ears. Also, if either of the following is checked, give the ears the corresponding color rather than pink:

- red ears
- blue ears

If both of the above boxes are checked, make the ears *purple*.

<u>checkpoint 4 (15 points):</u> Have your lab instructor or assistant verify that your robot's ears change appropriately.

#### Part 5: Allow the user to customize the robot's mouth

Modify the paint method so that if either of boxes

- frown
- whistle

is checked, the corresponding mouth-shape is drawn instead of a smile. If both boxes are checked, use the one that was checked the most recently. You can test whether the "whistle" box was checked more recently than the "frown" box using the whistleMoreRecent method, as in:

```
if (whistleMoreRecent())
{
    ...
}
```

The robot's mouth should always be red (for now).

<u>checkpoint 5 (10 points)</u>: Have your lab instructor or assistant verify that your robot's mouth changes appropriately.

#### Part 6: Allow the user to customize the robot's eyes

Modify the paint method so that if one of

- look left
- look right
- cross-eyed

is checked, the robot's eyes look the corresponding direction (i.e., left or right) rather than straight ahead. (Note: that this is the robot's left/right not your left/right.) If more than one of the above boxes is checked, then:

- if cross-eyed is checked, it takes precedence over the other two
- otherwise, if look left and look right are both checked, then they cancel each other out, and the robot looks straight ahead.

The robot's eyes should always be blue (for now).

<u>checkpoint 6 (15 points)</u>: Have your lab instructor or assistant verify that your robot's eyes change appropriately.

If you have *fully* completed all the above checkpoints, you now have a grade of C- (70) for this lab.

#### Part 7: Allow eyes to be green, changing body color if conflicting

If the green eyes box is checked, change the color of the eyes to green. <u>If this is done</u> and if the body color would also be green, then make the body color *light green* so that the eyes can still be seen against the background of the body.

<u>checkpoint 7 (10 points):</u> Have your lab instructor or assistant verify that your robot changes appropriately.

If you have *fully* completed all the above checkpoints, you now have a grade of B- (80) for this lab.

## Part 8: Customize the color of the robot's mouth based on the number of boxes checked

Use cascaded <u>if-else</u> statements so that the robot's mouth is colored as follows (listed in order from highest to lowest precedence):

- If the total number of boxes checked is greater than 10, the mouth-color should be black.
- Otherwise, if the number of boxes checked is even, the mouth-color should be white. (**Note:** 0 is a an even number.)
- Otherwise if the number of boxes checked is a prime number, the mouth-color should be <u>orange</u>. (**Note:** 1 is not a prime number)
- Otherwise, the mouth-color should be red.

The totalNumChecked() method returns an int to you that tells you how many boxes are checked.

<u>checkpoint 8 (10 points)</u>: Have your lab instructor or assistant verify that your robot's mouth changes color appropriately. Let him/her examine your code.

If you have *fully* completed all the above checkpoints, you now have a grade of A- (90) for this lab.

#### Part 9: Allow the user to customize the robot's arms

If any of the following boxes are checked, and draw the robot's arms as follows:

- short arms draw a short-armed robot. In this case, ignore any directives about bent arms or long arms.
- long arms draw a long-armed robot. In this case, any directives about bent arms should imply *long* bent arms.
- arms bent up the robot's arms should be bent up (unless short arms are specified).
- arms bent down the robot's arms should be bent down (unless short arms are specified).

If both long arms and short arms are checked, use *short arms*. If both directions of bending are checked (and short arms is not checked), bend the arms down.

<u>checkpoint 9 (10 points):</u> Have your lab instructor or assistant verify that your robot's arms change appropriately.

If you have *fully* completed all the above checkpoints, you now have a grade of A (100) for this lab

# Part 10: Allow the user to override all changes to the left side of the robot

If left normal is checked, have all body parts on the <u>left side</u> of the robot (arm, leg, ear, eye) be drawn according to their default appearance (including coloring). For example, the left ear would be small and pink, regardless of which other boxes might be checked. The right side should still have an appearance that is consistent with the check-boxes.

<u>checkpoint 10 (10 points):</u> Have your lab instructor or assistant verify that your robot changes appropriately.

### Part 11: finish up

Close all windows. Log off. You're done!.