

# Jason Zhao

(484) 756-9021 | jzhao1553@gmail.com | [LinkedIn](#) | [GitHub](#)

## EDUCATION

University of Maryland College Park | College Park, MD

May 2026

B.S. in Computer Science, Minors in Statistics / GPA: 3.7/4.0

- Courses: Operating Systems, Computer Vision, Advanced Data Structures, Actuarial Mathematics

## TECHNICAL SKILLS

Languages: Python, C++, C, Java

Tools and Frameworks: MuJoCo, Git, OpenCV, YAML JSON serialization, Docker

Skills: Trajectory Optimization, CAD, Soldering

Portfolio: <https://jasonzhao1553.github.io/Website/>

## RELEVANT EXPERIENCE

Embodied Robotics Researcher | Perception Robotics Group

Jun 2025 - Present

- Architected end-to-end throwing pipeline for **UR10**, achieving **1.5m** throw distance accuracy within **5 cm**
- Developed a Python-based system identification that calibrated the MuJoCo simulation to match real-world robot dynamics, **reducing the sim-to-real transfer gap** and accelerating development cycles
- Diagnosed joint-speed-limit constraints from sensor data using Python, then guided redesign of motion profiles, which eliminated overshoot errors and improved trajectory reliability

Software Development Intern | Runsafe Security

March 2024 - Feb 2025

- Delivered exploitability assessment tool that identifies syscalls reachable via ROP chains allowing sales teams to demonstrate measurable reduction in attack surface after hardening.
- Implemented multi-process search algorithm to detect high-risk gadget chains speeding up **search algorithm 10x**
- Re-architected Python prototype in C++, achieving **50x** speedup
- Shipped **Dockerized** customer beta enabling reproducible deployment

## PROJECTS

### Robotics Perception and Path Planning

- 2nd place (14 teams) in adversarial autonomous navigation competition
- Designed state estimator and end-effector controller for object pickup
- Implemented obstacle avoidance and hallway navigation
- Fused dead reckoning with computer vision for localization

### RC Car

- Designed CAD chassis integrating power and control electronics
- Implemented Arduino-based PWM motor control for differential steering
- Developed Bluetooth laptop interface for real-time operation

### LeetCode Clone

- Built a full-stack LeetCode-style coding platform that supports problem authoring, submissions, real-time code execution, and automated test case evaluation across multiple programming languages.
- Designed and implemented a secure **Docker-based sandboxing** system to run untrusted user code in isolated containers with strict CPU, memory, network, and time limits