

Batch Norm

```
CLASS torch.nn.BatchNorm2d(num_features, eps=1e-05, momentum=0.1, affine=True,  
track_running_stats=True, device=None, dtype=None) [SOURCE]
```

Applies Batch Normalization over a 4D input (a mini-batch of 2D inputs with additional channel dimension) as described in the paper [Batch Normalization: Accelerating Deep Network Training by Reducing Internal Covariate Shift](#).

$$y = \frac{x - \mathbb{E}[x]}{\sqrt{\text{Var}[x] + \epsilon}} * \gamma + \beta$$

The mean and standard-deviation are calculated per-dimension over the mini-batches and γ and β are learnable parameter vectors of size C (where C is the input size). By default, the elements of γ are set to 1 and the elements of β are set to 0. The standard-deviation is calculated via the biased estimator, equivalent to `torch.var(input, unbiased=False)`.

Also by default, during training this layer keeps running estimates of its computed mean and variance, which are then used for normalization during evaluation. The running estimates are kept with a default `momentum` of 0.1.

If `track_running_stats` is set to `False`, this layer then does not keep running estimates, and batch statistics are instead used during evaluation time as well.

• NOTE

This `momentum` argument is different from one used in optimizer classes and the conventional notion of momentum. Mathematically, the update rule for running statistics here is $\hat{x}_{\text{new}} = (1 - \text{momentum}) \times \hat{x} + \text{momentum} \times x_t$, where \hat{x} is the estimated statistic and x_t is the new observed value.

Because the Batch Normalization is done over the C dimension, computing statistics on (N, H, W) slices, it's common terminology to call this Spatial Batch Normalization.

SVD

Singular value decomposition

From Wikipedia, the free encyclopedia

In [linear algebra](#), the **singular value decomposition** (**SVD**) is a [factorization](#) of a [real](#) or [complex matrix](#). It generalizes the [eigendecomposition](#) of a square [normal matrix](#) with an orthonormal eigenbasis to any $m \times n$ matrix. It is related to the [polar decomposition](#).

Specifically, the singular value decomposition of an $m \times n$ complex matrix \mathbf{M} is a factorization of the form $\mathbf{M} = \mathbf{U}\mathbf{\Sigma}\mathbf{V}^*$, where \mathbf{U} is an $m \times m$ complex [unitary matrix](#), $\mathbf{\Sigma}$ is an $m \times n$ [rectangular diagonal matrix](#) with non-negative real numbers on the diagonal, and \mathbf{V} is an $n \times n$ complex unitary matrix. **If \mathbf{M} is real, \mathbf{U} and \mathbf{V} can also be guaranteed to be real orthogonal matrices.** In such contexts, the SVD is often denoted $\mathbf{U}\mathbf{\Sigma}\mathbf{V}^T$.

The diagonal entries $\sigma_i = \Sigma_{ii}$ of $\mathbf{\Sigma}$ are uniquely determined by \mathbf{M} and are known as the [singular values](#) of \mathbf{M} . The number of non-zero singular values is equal to the [rank](#) of \mathbf{M} . The columns of \mathbf{U} and the columns of \mathbf{V} are called left-singular vectors and right-singular vectors of \mathbf{M} , respectively. They form two sets of [orthonormal bases](#) $\mathbf{u}_1, \dots, \mathbf{u}_m$ and $\mathbf{v}_1, \dots, \mathbf{v}_n$, and the singular value decomposition can be written as

$$\mathbf{M} = \sum_{i=1}^r \sigma_i \mathbf{u}_i \mathbf{v}_i^*, \text{ where } r \leq \min\{m, n\} \text{ is the rank of } \mathbf{M}.$$

The SVD is not unique. It is always possible to choose the decomposition so that the singular values Σ_{ii} are in descending order. In this case, $\mathbf{\Sigma}$ (but not \mathbf{U} and \mathbf{V}) is uniquely determined by \mathbf{M} .

The term sometimes refers to the **compact SVD**, a similar decomposition $\mathbf{M} = \mathbf{U}\mathbf{\Sigma}\mathbf{V}^*$ in which $\mathbf{\Sigma}$ is square diagonal of size $r \times r$, where $r \leq \min\{m, n\}$ is the rank of \mathbf{M} , and has only the non-zero singular values. In this variant, \mathbf{U} is an $m \times r$ [semi-unitary matrix](#) and \mathbf{V} is an $n \times r$ [semi-unitary matrix](#), such that $\mathbf{U}^* \mathbf{U} = \mathbf{V}^* \mathbf{V} = \mathbf{I}_r$.

