# INVARIANT — ZeroDrift Validation Brief

Patent pending: U.S. Provisional 63/873,397

## Core Claims (measured)

- Machine-precision conservation: dH\_rel,max = 1.11e-16 (double precision limit).
- Baseline vs ZeroDrift: Baseline drift ~0.976 (loss), ZeroDrift drift = 0.000.
- Deterministic replay: psi-replay error = 0.0 (bit-exact reproducibility).
- Stability: largest Lyapunov lambda ~ -1.0e-6 (non-divergent).
- Live topology morphing: chain -> strong -> ring -> grid with exact conservation.
- Throughput ~513 samples/s; median step latency ~1.625 ms (classical hardware).

## Public Artifacts (open inline)

Paper (PDF)	/papers/Zero_Drift_Neural_Computation.pdf	
Canonical Proof (JSON)	/proof/canonical_run_proof.json (append ?v=1 if cached)	
Figures	/figures/energy_vs_step.png, /figures/topology_schedule.png,	/figures/psi_replay.png
Validation Hub	/validation/	

## Independent Verification Protocol (no engine code needed)

- Energy: Load canonical\_run\_proof.json; compute dH\_rel(t)=|H(t)-H0|/H0. Verify max(dH\_rel) <= 1.2e-16.</li>
- Baseline: Confirm baseline\_rnn\_drift ~ 0.911 (JSON) and ZeroDrift drift = 0.000.
- Determinism: Confirm psi\_replay\_error\_max == 0.0; reruns match bit-for-bit.
- Stability: Confirm lyapunov max <= 0.
- $\bullet$  Coherence (order parameter): r\_mean  $\sim$  0.962 (+5.4% order). This is mesoscopic coherence, not global entropy.
- Topology morphing: topology\_sequence = [chain,strong,ring,grid] with H0 constant at swap points.

## Optional JSON check (Python, 5 lines)

```
import json,urllib.request; d=json.load(urllib.request.urlopen('https://invariant.pr
o/proof/canonical_run_proof.json'))
m=d['metrics']; assert m['psi_replay_error_max']==0.0 and m['lyapunov_max']<=0
print('dH_rel_max:',m['dH_rel_max'],'baseline_drift:',m['baseline_rnn_drift'],'r_mea
n:',m['r_mean'])</pre>
```

#### NDA & ProofKit

Full ProofKit (procedures, extended logs, replay script) available under NDA. We can run a 45-minute live verification and provide artifacts for your internal lab.

#### Contact

Jason Volk — jason@invariant.pro — https://invariant.pro/validation/

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