

1.4.7 Median filtering

Median filtering: image smoothing can eliminate salt pepper noise. The basic idea is to traverse the image through a filter and take the median of the pixel values of each filter area as the new pixel value.

The algorithm idea is as follows:

- (1) Input image and convert to grayscale image;
- (2) Add salt pepper noise to the grayscale image;
- (3) Traverse the pixels and put the pixel values in the filter area into a one-dimensional array;
- (4) Selectively sort a one-dimensional array, and assign the median value to the center of the filter, that is, change the pixels of the traversed original image to the median of the filter area;
- (5) Output the image after median filtering.

Path:

[/home/dofbot/Dofbot\4.opencv\4.image_beautification\07_Median_filtering.ipynb](#)

```
# Median filtering 3*3

import cv2

import numpy as np

import matplotlib.pyplot as plt

img = cv2.imread('yahboom.jpg',1)

imgInfo = img.shape

height = imgInfo[0]

width = imgInfo[1]

img = cv2.cvtColor(img,cv2.COLOR_RGB2GRAY)

# cv2.imshow('src',img)

dst = np.zeros((height,width,3),np.uint8)
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```

collect = np.zeros(9,np.uint8)

for i in range(1,height-1):

    for j in range(1,width-1):

        k = 0

        for m in range(-1,2):

            for n in range(-1,2):

                gray = img[i+m,j+n]

                collect[k] = gray

                k = k+1

# 0 1 2 3 4 5 6 7 8

#    1

for k in range(0,9):

    p1 = collect[k]

    for t in range(k+1,9):

        if p1<collect[t]:

            mid = collect[t]

            collect[t] = p1

            p1 = mid

    dst[i,j] = collect[4]

# cv2.imshow('dst',dst)

# cv2.waitKey(0)

img = cv2.cvtColor(img, cv2.COLOR_BGR2RGB)

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dst = cv2.cvtColor(dst, cv2.COLOR_BGR2RGB)

plt.figure(figsize=(14, 6), dpi=100) #Set the size and pixels of the drawing area

plt.subplot(121) # The first in a row and two columns

plt.imshow(img)

plt.subplot(122) # The second in a row and two columns

plt.imshow(dst)

plt.show()
```

After running the above program, two pictures will be displayed in the jupyterLab control interface, as shown below.

