Assignment 3 Due: Jun 11, 2019

Question1 (6 points)

Consider the following model

$$X_i \mid Y_i \quad \stackrel{i.i.d}{\sim} \quad \text{Poisson}(y_i)$$
 $Y_i \mid \alpha, \beta \quad \stackrel{i.i.d}{\sim} \quad \text{Gamma}(\alpha, \beta)$
 $\alpha \quad \sim \quad \text{Exp}(a)$
 $\beta \quad \sim \quad \text{Gamma}(b, c)$

where a, b and c are treated as fixed constants.

(a) (2 points) Let Y and X denote the following random vectors, respectively

$$\begin{bmatrix} Y_1 \\ Y_2 \\ \vdots \\ Y_n \end{bmatrix} \quad \text{and} \quad \begin{bmatrix} X_1 \\ X_2 \\ \vdots \\ X_n \end{bmatrix}$$

Write down the joint posterior $f_{\{\mathbf{Y},\alpha,\beta\}|\mathbf{X}}$ up to an multiplicative constant.

- (b) (1 point) State the assumption(s) of independence that you used in part (a).
- (c) (2 points) Find the conditional posterior $f_{\{\mathbf{Y},\beta\}|\{\mathbf{X},\alpha\}}$.
- (d) (1 point) Find the marginal posterior $f_{\{\alpha,\beta\}|\mathbf{X}}$ up to an multiplicative constant.

Question2 (4 points)

Suppose tiger groupers' length and weight follow a normal distribution with

$$\boldsymbol{\mu}_t = \begin{bmatrix} 3 \\ 6 \end{bmatrix}; \quad \boldsymbol{\Sigma}_t = \begin{bmatrix} 12 & 1 \\ 1 & 2 \end{bmatrix}$$

while greasy groupers' length and weight also follow a normal distributions but with

$$\boldsymbol{\mu}_g = \begin{bmatrix} 13 \\ 10 \end{bmatrix}; \quad \boldsymbol{\Sigma}_g = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$$

Given there are twice as many tiger groupers in the tank, and the loss function is

$$C = \begin{cases} 0.1, & \text{greasy grouper classified as tiger grouper,} \\ 0.9 & \text{tiger grouper classified as greasy grouper,} \\ 0 & \text{correctly classified.} \end{cases}$$

- (a) (2 points) Write down the optimal decision rule in terms of a pair of observed length and weight.
- (b) (1 point) Plot the decision boundary of the optimal decision rule under this loss function.
- (c) (1 point) Clearly state inside which region you would classify the fish as a tiger grouper and vice versa. Note the decision boundary is no longer a point in the real line.