Limits of Computation

II - Church-Turing Thesis

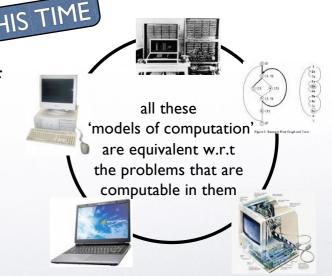
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The story so far

- We have found problems that cannot be solved by a WHILE program (Halting, Busy-Beaver, Tiling, Ambiguity of CFGs, etc).
- But this does not mean yet they could not be solved by a different machine model (different definition of "effective procedure").

More 'notions of computation'

- Evidence for the
 - Church-Turing Thesis
- by looking at other notions of computation:
 - Register machines
 - Counter machines
 - Turing machines
 - Goto language
 - Cellular Automata
- and showing (or stating) that they are all equivalent.





Church-Turing Thesis

reasonable formalisations of the intuitive notion of effective computability

All reasonable computation models are equivalent.

no restrictions on memory size and execution time are assumed

So it does not matter what model we use. It was alright to use WHILE.

We cannot prove this as it refers to informal entities (reasonable computation models). It is thus only a "thesis". But we provide some evidence for it.





Models of computation

- Random Access Machines (register machines): RAM
- Turing machines: TM
- Counter machines: CM
- Flowchart language: GOTO
- Cellular Automata: CA
- While language: WHILE ✓
- Church's λ-Calculus (see course Comparative Prog. Languages)

Machine instructions

- TM, GOTO, CM, RAM have the following in common:
- A program is a sequence of instructions with labels

 $\ell_1: I_1; \ell_2: I_2; ... \ell_n: I_n$

• a state or configuration during execution of the program is of the form (ℓ, σ) where ℓ is the current instruction's label and σ is the "store" which varies from machine to machine.

WHILE does not have 'machine flavour', it's more abstract

CA quite different

Semantic Framework for Machines

- definition of store
- function Readin producing initial store
- function Readout producing output
- description of semantics of the instructions,

$$p \vdash s o s'$$
 program p transits form configuration s into s' in one step

Semantic Framework for machines

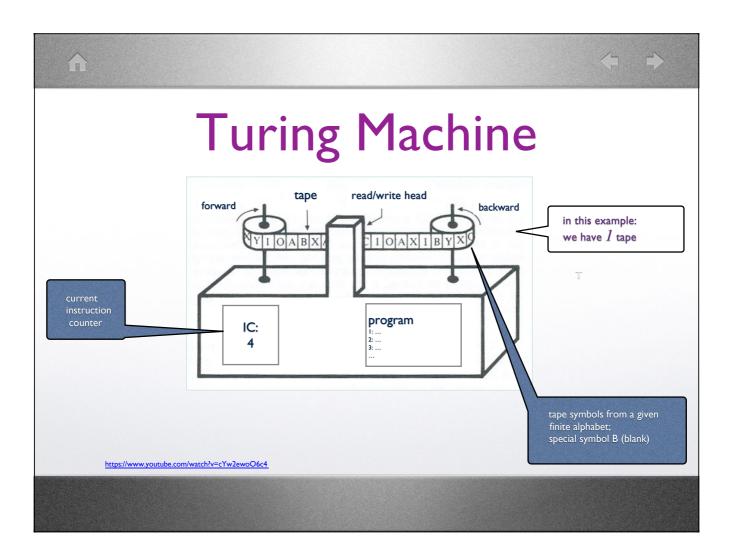
Definition (General framework for machine model semantics). Let p be a machine program with m instructions.

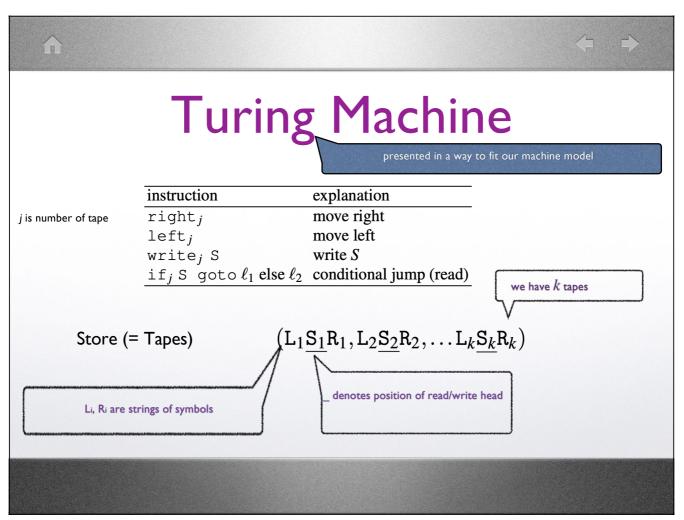
$$\llbracket \mathtt{p} \rrbracket(d) = e \text{ iff } \sigma_0 = Readin(d) \quad \text{and} \quad \mathtt{p} \vdash (1, \sigma_0) \to^* (m+1, \sigma) \quad \text{and} \quad e = Readout(\sigma)$$

$$p \vdash s \rightarrow^* s'$$

"many-step" operational semantics for machine language, zero, one, or several steps of the "one-step" semantics

We will now show how semantics of other languages/machines are an instance of this framework.





Turing Machine

Readin (input)

$$Readin(x) = (Bx, B, B, \dots, B)$$

in both cases: non-blank string right of head on tape I

Readout (output)

$$Readout(L_1S_1R_1, L_2S_2R_2, \dots L_kS_kR_k) = Prefix(R_1)$$

where $Prefix(R_1BR_2) = R_1$ provided that R_1 does not contain any blank symbols

One-step operational semantics for **I-tape** machine (no subscripts)

 ℓ -th instruction

$$\begin{array}{ll} \mathbf{p} \vdash (\ell, \mathbf{L}\underline{\mathbf{S}}\mathbf{S'R}) \to (\ell+1, \mathbf{LS}\underline{\mathbf{S'}}\mathbf{R}) & \text{if } \mathbf{p}(\ell) = \mathbf{right} \\ \mathbf{p} \vdash (\ell, \mathbf{L}\underline{\mathbf{S}}) & \to (\ell+1, \mathbf{LS}\underline{\mathbf{B}}) & \text{if } \mathbf{p}(\ell) = \mathbf{right} \\ \mathbf{p} \vdash (\ell, \mathbf{LS'}\underline{\mathbf{S}}\mathbf{R}) \to (\ell+1, \mathbf{L}\underline{\mathbf{S'}}\mathbf{S}\mathbf{R}) & \text{if } \mathbf{p}(\ell) = \mathbf{left} \\ \mathbf{p} \vdash (\ell, \underline{\mathbf{S}}\mathbf{R}) & \to (\ell+1, \underline{\mathbf{B}}\mathbf{S}\mathbf{R}) & \text{if } \mathbf{p}(\ell) = \mathbf{left} \\ \mathbf{p} \vdash (\ell, \mathbf{L}\underline{\mathbf{S}}\mathbf{R}) & \to (\ell+1, \mathbf{L}\underline{\mathbf{S'}}\mathbf{R}) & \text{if } \mathbf{p}(\ell) = \mathbf{write} \ \mathbf{S'} \\ \mathbf{p} \vdash (\ell, \mathbf{L}\underline{\mathbf{S}}\mathbf{R}) & \to (\ell_1, \mathbf{L}\underline{\mathbf{S}}\mathbf{R}) & \text{if } \mathbf{p}(\ell) = \mathbf{if} \ \mathbf{S} \ \mathbf{goto} \ \ell_1 \ \mathbf{else} \ \ell_2 \\ \mathbf{p} \vdash (\ell, \mathbf{L}\underline{\mathbf{S'}}\mathbf{R}) & \to (\ell_2, \mathbf{L}\underline{\mathbf{S'}}\mathbf{R}) & \text{if } \mathbf{p}(\ell) = \mathbf{if} \ \mathbf{S} \ \mathbf{goto} \ \ell_1 \ \mathbf{else} \ \ell_2 \ \mathbf{and} \ \mathbf{S} \neq \mathbf{S'} \end{array}$$

GOTO

instruction	explanation
X := nil	assign nil
X := Y	assign variable
X := hd Y	assign hd Y
X := tl Y	assign tl Y
X := cons Y Z	assign cons Y Z
if X goto ℓ_1 else ℓ_2	conditional jump

Unconditional jump can be expressed as well



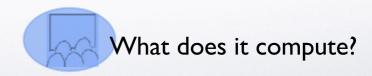
- uses the tree data type we know from WHILE
- does only permit operations on variables
- ullet if X tests whether X is not nil and then jumps according to a label
- store as for WHILE, ReadIn and Readout like in WHILE semantics of programs.

Sample Program

```
1: if X goto 2 else 6;
2: Y := hd X;
3: R := cons Y R;
4: X := tl X;
5: if R goto 1 else 1;
```

6: X := R;

GOTO programs not as readable as WHILE programs



Semantics of GOTO

(cont'd)

store σ (sigma) where variable X is assigned

 ℓ -th instruction

```
if p(\ell) = X := nil
p \vdash (\ell, \sigma) \rightarrow (\ell + 1, \sigma[X := nil])
p \vdash (\ell, \sigma) \rightarrow (\ell + 1, \sigma[X := \sigma(Y)])
                                                                   if p(\ell) = X := Y
p \vdash (\ell, \sigma) \rightarrow (\ell + 1, \sigma[X := d])
                                                                    if p(\ell) = X := hd Y \text{ and } \sigma(Y) = \langle d.e \rangle
p \vdash (\ell, \sigma) \rightarrow (\ell + 1, \sigma[X := nil])
                                                                    if p(\ell) = X := hd Y \text{ and } \sigma(Y) = nil
p \vdash (\ell, \sigma) \rightarrow (\ell + 1, \sigma[X := e])
                                                                    if p(\ell) = X := t1 Y \text{ and } \sigma(Y) = \langle d.e \rangle
p \vdash (\ell, \sigma) \rightarrow (\ell + 1, \sigma[X := nil])
                                                                    if p(\ell) = X := t1 Y \text{ and } \sigma(Y) = nil
p \vdash (\ell, \sigma) \rightarrow (\ell + 1, \sigma[X := \langle d.e \rangle]) if p(\ell) = X := cons Y Z and \sigma(Y) = d and \sigma(Z) = e
p \vdash (\ell, \sigma) \rightarrow (\ell_1, \sigma)
                                                                    if p(\ell) = \text{if } X \text{ goto } \ell_1 \text{ else } \ell_2 \text{ and } \sigma(X) \neq \text{nil}
p \vdash (\ell, \sigma) \rightarrow (\ell_2, \sigma)
                                                                    if p(\ell) = \text{if } X \text{ goto } \ell_1 \text{ else } \ell_2 \text{ and } \sigma(X) = \text{nil}
```

RAM model

• uses arbitrarily many registers containing arbitrarily big numbers.

(S)RAM instruction set

Successor RAM is like RAM but without binary operations

instruction	explanation
Xi := 0	reset register value
Xi := Xi+1	increment register value
Xi := Xi∸1	decrement register value
Xi := Xj	move register value
Xi := <xj> indirect addressing</xj>	move content of register addressed by X j
<xi> := Xj</xi>	move into register addressed by Xi
if Xi=0 goto ℓ_1 else ℓ_2	conditional jump
availabl	e only in RAM
Xi := Xj + Xk	addition of register values
Xi := Xj * Xk	multiplication of register values

- data type of natural numbers
- angle brackets < > indirect addressing
- if-goto-else tests whether
 X is 0 and then jumps accordingly.

Semantics SRAM

```
SRAM-store = { \sigma | \sigma : IN \rightarrow IN }
                 Readin(\mathbf{x})
                                         = \{0:x, 1:0, 2:0,...\}
                                                                                       Input in register X0
                 Readout(\sigma) = \sigma(0)
                                                                                       From register X0
|\mathbf{p} \vdash (\ell, \sigma) \rightarrow (\ell + 1, \sigma[i := \sigma(i) + 1])|
                                                                              if p(\ell) = Xi := Xi + 1
|\mathbf{p} \vdash (\ell, \sigma) \rightarrow (\ell+1, \sigma[i := \sigma(i)-1])|
                                                                              if p(\ell) = Xi := Xi - 1 and \sigma(i) > 0
|\mathbf{p} \vdash (\ell, \boldsymbol{\sigma}) \rightarrow (\ell+1, \boldsymbol{\sigma}[i := 0])|
                                                                               if p(\ell) = Xi := Xi - 1 and \sigma(i) = 0
|\mathbf{p} \vdash (\ell, \sigma) \rightarrow (\ell + 1, \sigma[i := \sigma(j)])|
                                                                               if p(\ell) = Xi := Xj
|\mathbf{p} \vdash (\ell, \sigma) \rightarrow (\ell+1, \sigma[i := 0])|
                                                                              if p(\ell) = Xi := 0
                                                                              if p(\ell) = \text{if Xi} = 0 goto \ell_1 else \ell_2 and \sigma(\text{Xi}) = 0
|\mathbf{p} \vdash (\ell, \boldsymbol{\sigma}) \rightarrow (\ell_1, \boldsymbol{\sigma})|
|\mathbf{p} \vdash (\ell, \sigma) \rightarrow (\ell_2, \sigma)|
                                                                               if p(\ell) = if Xi = 0 goto \ell_1 else \ell_2 and \sigma(Xi) \neq 0
|\mathbf{p} \vdash (\ell, \sigma) \rightarrow (\ell + 1, \sigma[i := \sigma(\sigma(j))])|
                                                                              if p(\ell) = Xi := \langle Xj \rangle
|\mathbf{p} \vdash (\ell, \sigma) \rightarrow (\ell + 1, \sigma[\sigma(i) := \sigma(j)])
                                                                              if p(\ell) = \langle Xi \rangle : = Xj
```

Counter Machine CM

I ::= Xi := Xi + 1 | Xi := Xi $\dot{-}$ 1 | if Xi=0 goto ℓ else ℓ'

- Counter machines are much simpler than register machines.
- They contain several registers, called counters as they can only be incremented or decremented and tested for zero.
- 2CM is like CM but with 2 counters only.
- Semantics as for register machines.





Cellular Automata CA

we just focus one specific version the famous 2-dimensional CA called (Conway's) Game of Life



John Conway (Cambridge Mathematician)

neighbourhood of (m,n) = 8 cells

the value of a cell changes every "time tick" and the new value is determined only by the values of the neighbourhood cells

(m-1,n+1)	(m,n+1)	(m+1,n+1)	
(m-1,n)	(m,n)	(m+1,n)	
(m-1,n-1)	(m,n-1)	(m+1,n-1)	

cell lattice (grid)

each cell contains 0

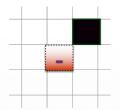


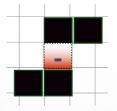


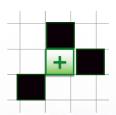


Rules of Game of Life

alive = I (solid line/filled) dead = 0 (no colour)







Underpopulation

die if fewer than two neighbours are alive

Survival

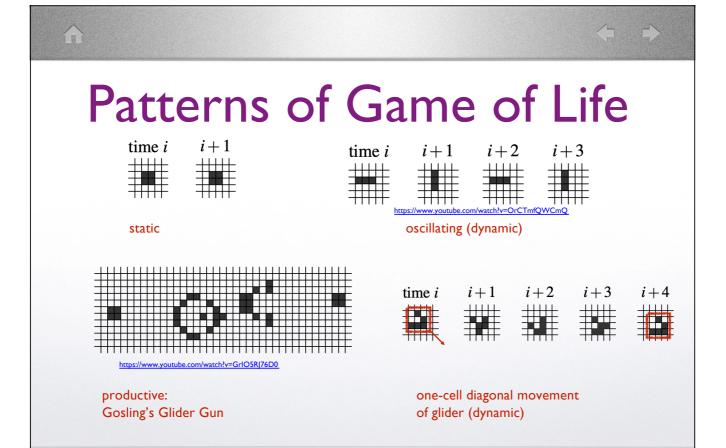
survive (stay alive) if two or three neighbours are alive

Overcrowding

die if more than three neighbours are alive

Reproduction

become alive if exactly three neighbours are alive



Cellular Automata

- Fun, but can they compute in our sense?
- Yes, one has to:
 - encode input as starting grid
 - result if a predefined cell changes its state to a predefined "accepting state"
 - "accepting state" must be left alone in further grid changes.

Robustness of Computability Thesis

Robustness of Computability

- We justify the Church-Turing thesis ...
- ... by showing that all the above notions of computation are equivalent to WHILE.
- Proof technique:
 - compile one program of language X into an equivalent one of language Y ...
 - ... if X is not a sub-language of Y anyway.
 - compose compilers appropriately to avoid having to write n^2 compilers:

