# RDBMS Design Using RAM and NVRAM: A Hybrid Architecture



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# Non-Volatile Random Access Memory (NVRAM)



- ▶ **Definition**: A type of non-volatile memory that combines the speed of RAM with the persistence of storage (e.g., Intel Optane, 3D XPoint).
- ► Key Characteristics:
  - ► **Low Latency**: Significantly faster than traditional disk I/O (nanoseconds vs. milliseconds).
  - ▶ **Persistence**: Data remains intact even after power loss, unlike volatile RAM.
  - ▶ Write Endurance: Higher than SSDs but lower than DRAM.
  - Byte-Addressability: Unlike block-based storage, allows fine-grained memory access.
- ► Relevance to RDBMS: Enables fast, durable storage for databases, bridging RAM and disk performance gaps.

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# Why RAM and NVRAM Are Better Than RAM and Disk I/O



- ▶ **Performance**: NVRAM offers latency closer to RAM (nanoseconds vs. milliseconds for disks), reducing I/O bottlenecks.
- ▶ Persistence: Unlike RAM, NVRAM retains data without power, eliminating the need for frequent disk writes.
- ➤ Scalability: By using RAM for fast indexing (e.g., B+ Trees, hash tables) and NVRAM for persistent storage, the system minimizes disk I/O delays. This allows efficient handling of growing datasets without significantly increasing query response times.
- ▶ Cost-Effectiveness: NVRAM reduces reliance on slow, power-intensive disk storage while maintaining persistence. This lowers the need for large amounts of RAM or frequent disk access, optimizing both hardware costs and energy consumption.

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# Architecture of the Project



- ► **Hybrid Design**: Uses RAM for fast indexing and processing, while NVRAM ensures persistence and durability.
- ▶ **Software Emulation**: Since true NVRAM (e.g., Intel Optane) is unavailable, we use mmap() to simulate persistent memory by mapping a file into virtual memory.
- ▶ Reserving RAM at Boot Time: Using the memmap boot parameter in Linux (through Grub), a portion of main memory is reserved for use of NVRAM. This RAM becomes accessible as a device file which is then mmap'ed to a user process.
- ► Multi-threaded Environment: Supports concurrent operations with thread-safe data structures and logging mechanisms.
- ► Goal: Achieve low-latency reads/writes, ACID compliance, and scalability for modern database workloads.

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# Keys and Values



- Each row of a table is represented by a **key-value pair**.
  - ► The **key** is the primary key used for the table.
  - ► The **value** is the contents of the row (including the primary key).
- ► Each key is composed of two parts: <table\_id, row\_id>.
- There is an index stored for each table based on the primary key.
- A hash table is used to point to the index of each table.
- ► Given a key:
  - ► The table\_id component is used to access the hash table to obtain a pointer to the root of the index.
  - ► The row\_id component of the key is then used to search the index to obtain a pointer to the row contents.

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# Overview of RAM and NVRAM: Data Structures and Design



#### ► RAM:

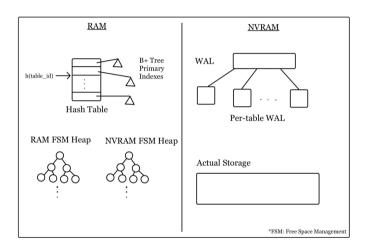
- ► Hash table maps table\_id to roots of B+ Tree indexes for fast lookups.
- ▶ B+ Trees index tables use row\_id as key to search for pointer to row contents.
- Secondary indexes for optimized queries.
- ► Free space management for both, B+ Tree and data storage in NVRAM.

#### ► NVRAM:

- Write-Ahead Logs (WALs) ensure durability for table and multi-table transactions.
- ► Stores actual data (larger values linked from B+ Tree leaf nodes).

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#### What Is Stored in RAM



- ► **Hash Table**: Maps table\_id to pointers of root of B+ Tree index for fast lookups (create\_table, get\_row, put\_row, del\_row, get\_nxt\_row).
- ▶ **B+ Trees**: Per-table indexing with row\_id as key; leaf nodes store small data or pointers to NVRAM.
- Secondary Indexes: Application-defined indexes for optimized queries on non-primary key attributes.
- ► Free Space Management: Utilizes a heap-based structure to efficiently track and allocate free space for B+ Tree nodes and data stored in NVRAM, minimizing fragmentation.

▶ **Purpose**: Supports low-latency, in-memory indexing and querying.

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# Key Table & Row Operations



- ► Create Table (create\_table): Compute hash, initialize B+ Tree, store root in hash table.
- ► Retrieve Row (get\_row): Get B+ Tree root via hash, search for row\_id, fetch from RAM/NVRAM.
- ▶ Insert/Update Row (put\_row): Search B+ Tree, update if exists, else allocate space and insert.
- Delete Row (del\_row): Find row\_id, remove from B+ Tree, free NVRAM if needed.
- ▶ Next Row (get\_nxt\_row): Find next row\_id in B+ Tree, return data or NULL.

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# Heap-Based Free Space Management



- ▶ **Objective**: Efficiently manage free space using a max heap for fast allocation and deallocation, providing near O(1) operations, efficient merging, and reduced fragmentation.
- ► Free space management will be done for both RAM and NVRAM, with the data structures for both stored in RAM.

#### Structure Maintained:

- ► Tracking of total available space and a pointer to the max heap.
- ► Each node in max heap represents a block of free memory and stores a pointer to the free memory location in NVRAM and its size.
- ▶ Metadata in free blocks is stored at both start and end of each block.
- ► Each block of memory has a 1 bit long allocation status (0 for free/1 for filled).

▶ If free, contains a pointer back to the heap node.

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#### What Is Stored in NVRAM

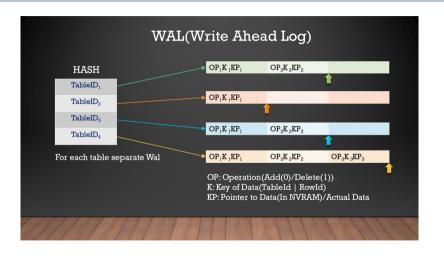


- ► Write-Ahead Logs (WALs):
  - ▶ Per-table WALs for individual table operations (ensuring durability).
- ► Actual Data Values: Data stored in NVRAM, with pointers in RAM from the indexes, for access.
- ▶ Purpose: Ensure data durability, support crash recovery, and handle persistent storage for large datasets.

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#### Row Data Format





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# Write-Ahead Log (WAL) in NVRAM



- ▶ **Purpose**: Ensures durability and crash recovery by logging changes before applying them to the database.
- ► Key Features:
  - ► Table-Wise WAL: Each table has a separate WAL, hashed by table key for fast access.
  - Stored in NVRAM: Eliminates disk I/O bottlenecks and removes the need for explicit flushing.
- ► WAL Entry Structure:
  - ► Commit Bit (1-bit): Indicates commit status.
  - ► Add/Delete Flag (1-bit): Specifies insertion or deletion.
  - ▶ Data Key: Composite key (table\_id | row\_id).
  - ▶ Pointer to Data: Reference to actual data in main storage.

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### Example



- ▶ Dummy Database: A table Users with columns row\_id (primary key), name, and age.
- ► Read Operation (get\_row):
  - Client issues get\_row(table\_id | row\_id).
  - ▶ Hash table in RAM finds the B+ Tree root for Users.
  - ▶ B+ Tree in RAM searches for the key:
    - ▶ If the data is in RAM, return it directly.
    - ► If a pointer to NVRAM exists, retrieve the data from there.
  - Return data to client with low latency.

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#### Example



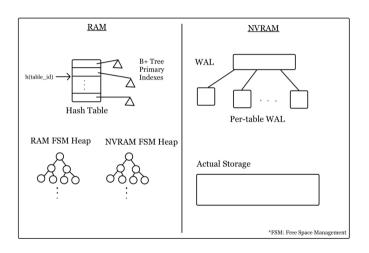
#### ► Write Operation (put\_row):

- ► Client issues put\_row(table\_id | row\_id, {name: "Alice", age: 30}).
- ► Hash table in RAM locates the B+ Tree root for Users.
- ▶ B+ Tree in RAM invokes the free space manager:
  - ▶ If sufficient space is available in the leaf node, data is stored in RAM.
  - ▶ If not, a pointer to a new allocated NVRAM space is stored instead.
- ► WAL in NVRAM logs the operation before applying changes (ensuring durability and atomicity).
- ▶ Data (or pointer) is written to RAM B+ Tree or NVRAM.
- Upon commit, the WAL entry is marked as committed.

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# Example





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### Planned Shutdown Algorithm



▶ **Objective**: Ensure a smooth shutdown by persisting RAM structures (B+ Trees, free space heaps) to NVRAM, reducing recovery time.

#### ► Steps:

- 1. Pause incoming transactions and complete or rollback any active ones.
- 2. Copy the latest RAM-based B+ Trees and free space heaps to NVRAM.
- 3. Write a checkpoint to NVRAM, marking a stable state of all tables and indexes.
- 4. Flush remaining WAL entries and finalize them to maintain data integrity.
- 5. Safely release resources, close NVRAM connections, and shut down the system.
- ▶ **Benefits**: Minimizes uncommitted WAL entries, making recovery nearly instantaneous.

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# Recovery Algorithm



▶ **Objective**: Restore RAM data structures (B+ Trees, free space heaps) from NVRAM for fast recovery and ensure data consistency.

#### Steps:

- 1. On restart, load the latest B+ Trees and free space heaps from NVRAM into RAM.
- 2. Read all WALs (per-table and multi-table transaction logs) from NVRAM.
- 3. Identify and apply only committed transactions based on commit markers.
- Replay WAL entries to reconstruct changes in B+ Trees and persist values back to NVRAM.
- 5. Verify integrity using checksums or hash-based validation techniques.
- 6. Clear WALs after successful recovery to start with a clean state.
- ▶ **Advantages**: Faster recovery by leveraging stored B+ Trees instead of reconstructing from scratch.

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#### Issues and Planned Solutions for Next Phase



#### ► Issues:

- Concurrency Control: Race conditions in multi-threaded operations on RAM structures and NVRAM WALs.
- Transaction Management: Ensuring atomicity and consistency across multi-table transactions.

#### ► Planned Solutions (Next Phase):

- ▶ Implement thread-safe locking or lock-free data structures (e.g., atomic operations) for concurrency control.
- Design transaction managers with two-phase commit or similar for multi-table operations.

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# Questions?



Thank you for your attention! Any questions or feedback?

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