JASWANTH V. GURUDEV

INDIAN INSTITUTE OF TECHNOLOGY MADRAS

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EDUCATION

Program
B.Tech Metallurgical and Materials Engineering + M.Tech Computational Engineering (Inter-Disciplinary Dual Degree)

Institution
S.92/10.0
2026

Research Interests

Convex Optimization, Architected Materials, ML-Assisted Mechanical Design

RELEVANT COURSES

- Deformation and Failure of Materials
- Machine Learning Techniques
- Foundations of Computational Fluid Dynamics
- Materials Characterization
- Computational Materials Engineering Lab
- Engineering Design of Additively Manufactured Components
- Numerical Methods for Metallurgists
- Optimisation Methods for Mechanical Design
- Biofluid Mechanics
- Computational Laboratory
- Fundamentals of Finite Element Analysis*
- Constitutive Modeling in Continuum Mechanics*
- Advanced Solid Mechanics*

RESEARCH PROJECTS

GRADED BCC LATTICE STRUCTURES FOR CRASHWORTHINESS AND HEAT DISSIPATION

MAR'25 - PRESENT

Advisor: Prof. Ratna Kumar Annabattula, Mechanics of Mechanics Group, IIT Madras

- Abstracts accepted at the IMPLAST'25 and ICCMS'25 conferences, to be held at IIT-R and IIT-BBS, respectively
- Utilized Latin Hypercube Sampling (LHS) to generate datapoints for multi-objective optimisation
- Surrogate Modelling with goal programming was used to identify the optimal design variables
- The optimal BCC lattice resulted in a 115% increase in absorbed energy and a 31% decrease in pressure drop

BIOMIMETIC HIERARCHICAL CELLULAR STRUCTURES FOR IMPACT ABSORPTION

DEC'24 - MAR'25

Advisor: Prof. Ratna Kumar Annabattula, Mechanics of Mechanics Group, IIT Madras

- Performed high strain-rate impact simulations of regular and auxetic honeycomb structures in Abaqus/Explicit
- Developed Python scripts to generate Voronoi substructures within each honeycomb unit cell for hierarchy
- Achieved a 2x improvement in overall energy absorbed per unit mass during low velocity impacts

PARTICLE ANISOTROPY CORRELATION WITH SLM POWDER SPREADING DIRECTION Personal Project, Mechanics of Mechanics Group, IIT Madras

Mar'25 - June'25

- Exploited Voro++ to generate Voronoi tessellations of monodispersed and polydispersed packings
- Developed C++ script to calculate Minkowski tensors for quantifying anisotropy index
- Developed a Python script to generate .vtk files to visualise the generated Voronoi tesselations in Paraview

MECHANICAL DESIGN OPTIMISATION AND FABRICATION

JULY'22- JAN'24

Team Anveshak, Mars Rover Team, IIT Madras

- Performed analysis of the **rocker-bogie** suspension kinematics in MATLAB for tuning geometric parameters
- Designed and fabricated a revamped rocker-bogie system, including chassis and bar-differential-based components
- Developed a 3D-printed gearbox with a 57:1 reduction, with a planetary (3:1) and a dual-stage cycloidal (19:1).
- Designed and fabricated lightweight **3D-printed wheels**, optimized for traction
- Ideated the next-gen four-wheeled independent-steering system with a double-pivoted rear-mounted differential

STUDY AND PREDICTION OF STEEL MELTING SHOP DEFECTS IN TI-STABILIZED SS COILS MAY'24 - JULY'24 Summer Internship, Jindal Stainless Ltd., Odisha

- Investigated seven frequent inclusion-based and surface defects in Ti-stabilized grades 416L, 439, and 441
- Developed a **classification model** to predict the defect probability and identified the top five influencing factors
- Built and tuned Random Forest and LightGBM models, with accuracy scores of 94.12% and 93.73%, respectively

DESIGN AND DEVELOPMENT OF AN ELECTRO-MECHANICAL TESTBED FOR HES SYSTEMSMAY'23- AUG'24 *Advisor: Prof. Tiju Thomas, Metallurgical and Materials Engineering, IIT Madras*

- Fabricated an electro-mechanical testbed for **simulating real-life EV** functions of a Battery-Supercapacitor system
- Implemented remote monitoring of real-time voltage, current, and power readings via ESP32 microcontroller
- Conducted stress testing on Li-ion and HES systems and fabricated 3D-printed enclosures for supercapacitors
- Tailored the testbed to **measure capacitance** above 100mF (accuracy: ±10%) for stress-tested supercapacitors

eYantra 2023 Robotics Competition, IIT Bombay

- Implemented **OpenCV** for ArUCo detection to facilitate package identification in a virtual extraterrestrial setup
- Integrated a UR5 robotic arm with a depth camera and used ROS2 (MoveIt, RViZ) for pick-and-place operations
- Programmed a virtual autonomous ground vehicle to navigate and deliver packages within a simulated environment
- Utilized Nav2 for mapping, localisation, and path planning, leveraging LiDAR data to optimize movement in Gazebo

COURSE PROJECTS

PROCESS PARAMETERS OF AN ADDITIVELY MANUFACTURED HEAT EXCHANGER

APRIL'24

(Course Instructor: Prof. Gnanamoorthy, Mechanical Engineering, IIT Madras)

- Designed a **shell-and-tube heat exchanger** that requires minimal support structures for manufacturing via L-PBF
- Identified process parameters from literature to minimize surface roughness and porosity

3D CONVEX HULL CONSTRUCTION

Nov'24

(Course Instructor: Prof. Prasad Patnaik, Applied Mechanics, IIT Madras)

- Developed a Python script uses the Gift-Wrapping algorithm to construct a 3D convex hull from random points
- Visualized the 3D convex hull using the PyQt library for an interactive graphical representation

2D LID DRIVEN CAVITY FLOW AND ANALYSIS OF NUMERICAL SCHEMES

Nov'24

(Course Instructor: Prof. Arul Prakash, Applied Mechanics, IIT Madras)

- Coded Python solvers for Navier-Stokes and 2D Laplace equations using the Finite Difference Method (FDM)
- Applied psi-omega formulation with Upwind schemes and compared Gauss-Seidel, SOR, and ADI methods
- Generated visualisations for a Re = 100 flow and validated the flow results against ghia et al. (1982)

ACHIEVEMENTS AND AWARDS

- Secured 99.35 percentile in JEE Mains B.E/B.Tech and 99.74 percentile in JEE Mains B.Arch in 2021
- Recipient of Visweswariah Scholarship for Excellence in Technology, awarded full tuition waiver in 2021
- Received the NTSE Scholarship, an academic excellence scholarship awarded to 2,103 high school students in 2019
- 2nd place, CAD Design Challenge, AIRSS 2024 Ideation and modelling of a three-component stair-climbing bot
- 2nd overall, International Rover Challenge 2024, Space Robotics Society

SKILLS

- Modeling and Simulation: Ansys, Abagus, Autodesk Inventor, AutoCAD, Solidworks, Gazebo
- Programming languages: MATLAB, Python, C, LaTeX, Arduino IDE
- Lab: FT-IR Spectroscopy, Optical Microscopy, Rheometry, Contact-angle Goniometry

Positions of Responsibility

HEAD OF OPERATIONS - TEAM ANVESHAK

JAN'24 - JUL'24

- Led a team of over 40 students in international competitions by managing logistics and technical strategies, resulting in podium ranks.
- Scheduled inter-module meetings to facilitate team bonding and streamlined deliverables for upcoming competitions

DESIGN ENGINEER (MECHANICAL MODULE) - TEAM ANVESHAK

July'22 - Jan'24

- Responsible for **Design**, **Manufacturing**, **Assembly**, **Testing and Validation** of the traversal system
- Responsible for Project Division and Management of 4-member subsystem with adherence to Overall Project Timeline

SCHOOL PUPIL LEADER - HIGHER SECONDARY SCHOOL

May'20 - Oct'21

- Organized annual events and represented the student body to improve faculty-student interaction
- Represented the school in inter-school sports and cultural competitions
- Played a pivotal role in organising the annual Tech Fest