```
!pip install -U --pre tensorflow=="2.*"
!pip install tf_slim
```

 \Box

```
ssd mobileNet.ipynb - Colaboratory
Collecting tensorflow==2.*
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Collecting tensorflow-estimator<2.5.0,>=2.4.0rc0

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     Descriptment already entirified element ungrader importable metadatar methon vancion / "2 0" in /ucn/local/lib/methon?
# Python API that helps in loading, parsing and visualizing the annotations in COCO(image dataset)
!pip install pycocotools
     Requirement already satisfied: pycocotools in /usr/local/lib/python3.6/dist-packages (2.0.2)
     Requirement already satisfied: setuptools>=18.0 in /usr/local/lib/python3.6/dist-packages (from pycocotools) (50.3.2)
     Requirement already satisfied: cython>=0.27.3 in /usr/local/lib/python3.6/dist-packages (from pycocotools) (0.29.21)
     Requirement already satisfied: matplotlib>=2.1.0 in /usr/local/lib/python3.6/dist-packages (from pycocotools) (3.2.2)
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     Requirement already satisfied: cycler>=0.10 in /usr/local/lib/python3.6/dist-packages (from matplotlib>=2.1.0->pycocot
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     Requirement already satisfied: numpy>=1.11 in /usr/local/lib/python3.6/dist-packages (from matplotlib>=2.1.0->pycocoto
     Requirement already satisfied: pyparsing!=2.0.4,!=2.1.2,!=2.1.6,>=2.0.1 in /usr/local/lib/python3.6/dist-packages (fro
     Requirement already satisfied: six>=1.5 in /usr/local/lib/python3.6/dist-packages (from python-dateutil>=2.1->matplot1
         Uninstalling tensorboard-2.3.0:
import os
import pathlib
if "models" in pathlib.Path.cwd().parts:
  while "models" in pathlib.Path.cwd().parts:
    os.chdir('...')
elif not pathlib.Path('models').exists():
  !git clone --depth 1 https://github.com/tensorflow/models
     Cloning into 'models'...
     remote: Enumerating objects: 2305, done.
     remote: Counting objects: 100% (2305/2305), done.
     remote: Compressing objects: 100% (2000/2000), done.
     remote: Total 2305 (delta 563), reused 941 (delta 282), pack-reused 0
     Receiving objects: 100% (2305/2305), 30.59 MiB | 30.92 MiB/s, done.
     Resolving deltas: 100% (563/563), done.
```

```
%%bash
cd models/research/
protoc object detection/protos/*.proto --python out=.
%%bash
cd models/research
pip install .
     Processing /content/models/research
     Requirement already satisfied: Pillow>=1.0 in /usr/local/lib/python3.6/dist-packages (from object-detection==0.1) (7.0
    Requirement already satisfied: Matplotlib>=2.1 in /usr/local/lib/python3.6/dist-packages (from object-detection==0.1)
    Requirement already satisfied: Cython>=0.28.1 in /usr/local/lib/python3.6/dist-packages (from object-detection==0.1) (
    Requirement already satisfied: cycler>=0.10 in /usr/local/lib/python3.6/dist-packages (from Matplotlib>=2.1->object-de
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    Requirement already satisfied: six in /usr/local/lib/python3.6/dist-packages (from cycler>=0.10->Matplotlib>=2.1->obje
    Building wheels for collected packages: object-detection
      Building wheel for object-detection (setup.py): started
      Building wheel for object-detection (setup.py): finished with status 'done'
      Created wheel for object-detection: filename=object detection-0.1-cp36-none-any.whl size=1368699 sha256=9f843e405d82
      Stored in directory: /tmp/pip-ephem-wheel-cache-ve1thhh3/wheels/94/49/4b/39b051683087a22ef7e80ec52152a27249d1a644ccf
     Successfully built object-detection
    Installing collected packages: object-detection
    Successfully installed object-detection-0.1
import numpy as np
import os
import six.moves.urllib as urllib
import sys
import tarfile
```

import tensorflow as tf

import zipfile

```
from collections import defaultdict
from io import StringIO
from matplotlib import pyplot as plt
from PIL import Image
from IPython.display import display
from object detection.utils import ops as utils ops
from object detection.utils import label map util
from object detection.utils import visualization utils as vis util
# patch tf1 into `utils.ops`
utils ops.tf = tf.compat.v1
# Patch the location of gfile
tf.gfile = tf.io.gfile
def load model(model name):
  base url = 'http://download.tensorflow.org/models/object detection/'
  model file = model name + '.tar.gz'
  model dir = tf.keras.utils.get file(
   fname=model name,
    origin=base url + model file,
    untar=True)
  model dir = pathlib.Path(model dir)/"saved model"
  model = tf.saved model.load(str(model dir))
  return model
# List of the strings that is used to add correct label for each box.
PATH TO LABELS = 'models/research/object detection/data/mscoco label map.pbtxt'
category index = label map util.create category index from labelmap(PATH TO LABELS, use display name=True)
```

```
# If you want to test the code with your images, just add path to the images to the TEST IMAGE PATHS.
PATH TO TEST IMAGES DIR = pathlib.Path('models/research/object detection/test images')
TEST IMAGE PATHS = sorted(list(PATH TO TEST IMAGES DIR.glob("*.jpg")))
TEST IMAGE PATHS
     [PosixPath('models/research/object detection/test images/image1.jpg'),
      PosixPath('models/research/object detection/test images/image2.jpg')]
#Loading an object detection model
model name = 'ssd mobilenet v1 coco 2017 11 17'
detection model = load model(model name)
     INFO:tensorflow:Saver not created because there are no variables in the graph to restore
print(detection model.signatures['serving default'].inputs)
     [<tf.Tensor 'image tensor:0' shape=(None, None, 3) dtype=uint8>]
detection model.signatures['serving default'].output dtypes
     {'detection boxes': tf.float32,
      'detection classes': tf.float32,
      'detection scores': tf.float32,
      'num detections': tf.float32}
detection model.signatures['serving default'].output shapes
     {'detection boxes': TensorShape([None, 100, 4]),
      'detection classes': TensorShape([None, 100]),
      'detection scores': TensorShape([None, 100]),
      'num detections': TensorShape([None])}
```

```
def run inference for single image(model, image):
 image = np.asarray(image)
 # The input needs to be a tensor, convert it using `tf.convert_to_tensor`.
 input tensor = tf.convert to tensor(image)
 # The model expects a batch of images, so add an axis with `tf.newaxis`.
 input tensor = input tensor[tf.newaxis,...]
 # Run inference
 model_fn = model.signatures['serving_default']
 output dict = model fn(input tensor)
 # All outputs are batches tensors.
 # Convert to numpy arrays, and take index [0] to remove the batch dimension.
 # We're only interested in the first num detections.
 num detections = int(output dict.pop('num detections'))
 output dict = {key:value[0, :num detections].numpy()
                 for key,value in output dict.items()}
 output dict['num detections'] = num detections
 # detection classes should be ints.
 output dict['detection classes'] = output dict['detection classes'].astype(np.int64)
 # Handle models with masks:
 if 'detection masks' in output dict:
   # Reframe the the bbox mask to the image size.
   detection_masks_reframed = utils_ops.reframe_box_masks_to_image_masks(
             output_dict['detection_masks'], output_dict['detection_boxes'],
               image.shape[0], image.shape[1])
   detection_masks_reframed = tf.cast(detection_masks_reframed > 0.5,
                                       tf.uint8)
   output dict['detection masks reframed'] = detection masks reframed.numpy()
 return output dict
def show inference(model, image path):
 # the array based representation of the image will be used later in order to prepare the
 # result image with boxes and labels on it.
 image np = np.array(Image.open(image path))
```

```
# Actual detection.
output_dict = run_inference_for_single_image(model, image_np)
# Visualization of the results of a detection.
vis_util.visualize_boxes_and_labels_on_image_array(
    image_np,
    output_dict['detection_boxes'],
    output_dict['detection_classes'],
    output_dict['detection_scores'],
    category_index,
    instance_masks=output_dict.get('detection_masks_reframed', None),
    use_normalized_coordinates=True,
    line_thickness=8)

display(Image.fromarray(image_np))

for image_path in TEST_IMAGE_PATHS:
    show inference(detection model, image_path)
```



