

## Weekly report

### 1 My Goals from last week

- Literature review
- Platform setup
  - Install Windows
  - Debug Henry's program

### 2 My Accomplishments this week

More details of our schedule and accomplishment are available at [https://docs.google.com/document/d/1DhvBMiaWoIwedYeeiF\\_WC4yBT6tN3jgArNQboucNOvI/edit?usp=sharing](https://docs.google.com/document/d/1DhvBMiaWoIwedYeeiF_WC4yBT6tN3jgArNQboucNOvI/edit?usp=sharing)

#### 2.1 Platform setup

- Tried to figure out hardware connection on Ubuntu
- Installed MATLAB on lihuang account on Linux Ubuntu
  - `sudo su -c find / — grep jre` to find out the right path similar to `/usr/lib/jvm/java-7-openjdk/jre/`
  - Run the following command in MATLAB top layer folder `./install-javadir /usr/lib/jvm/java-7-openjdk/jre/`
  - Installed Arduino support package
  - Installed IEEE1394 support package
  - Updated all drivers on Ubuntu
- Map `ttyACM0` to `ttyS101` before starting MATLAB (available in Henry's program)
- Installed Windows 8.1 Pro on the desktop

#### 2.2 Git branch Tutorial

Summarized a brief tutorial for git branch and workflow, available at [https://docs.google.com/document/d/1DhvBMiaWoIwedYeeiF\\_WC4yBT6tN3jgArNQboucNOvI/edit?usp=sharing](https://docs.google.com/document/d/1DhvBMiaWoIwedYeeiF_WC4yBT6tN3jgArNQboucNOvI/edit?usp=sharing)

#### 2.3 Literature review

- Becker, A., Demaine, E. D., Fekete, S. P., & McLurkin, J. (2014, May). Particle computation: Designing worlds to control robot swarms with only global signals. In Robotics and Automation (ICRA), 2014 IEEE International Conference on (pp. 6751-6756). IEEE.

#### 2.4 Programming

- Try to program a particle swarms animation m file without particle overlap in a binary image.