Progress Report

1. Goal from last week
    ○ Read chapters 1 to 7 (Part I) of *Programming Robots with ROS*
2. Accomplishments this week
    ○ Read chapter 11
    ○ Read chapter 18
    ○ Model and Configure a robot arm
    ○ Created a node subscribed to *turtle1/cmd_vel* and used the *turtlesim turtle_teleop_key* node to moves the hip joint and shoulder joint of the robot arm.
3. Goal for next week
    ○ Create a node to control all the joints from the keyboard
    ○ Research on *OWI Robotic Arm Edge*
    ○ Model *OWI Robotic Arm Edge*
4. Dr. Becker needs to