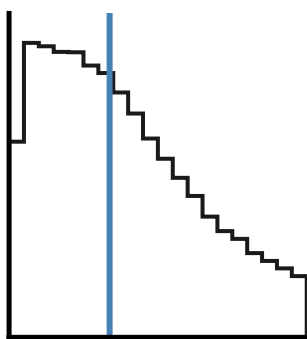
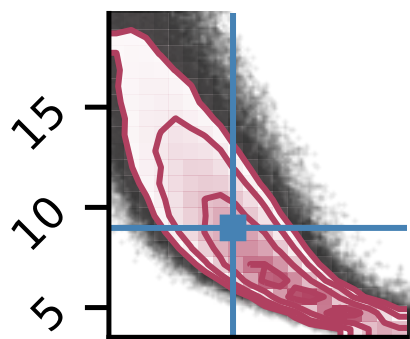
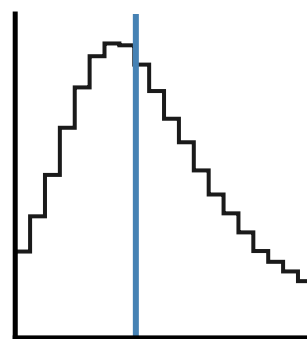
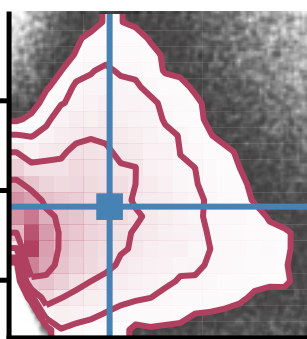
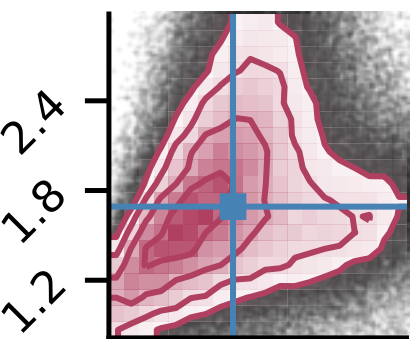


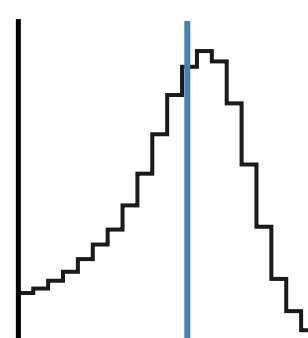
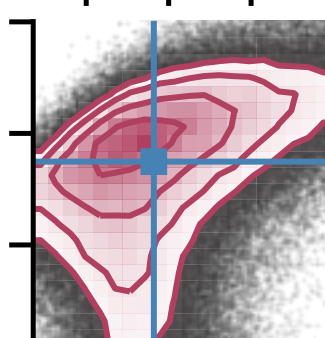
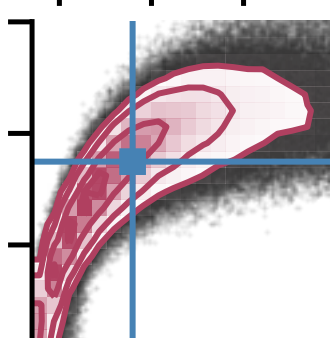
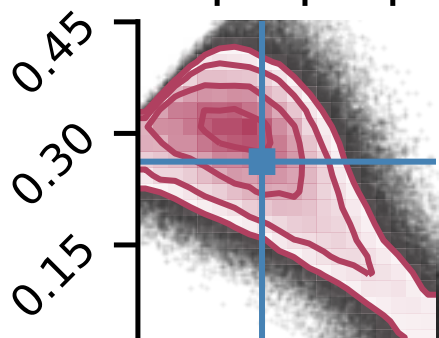
Vel. variance:  
 $\sigma^2$  [km<sup>2</sup> s<sup>-1</sup>]



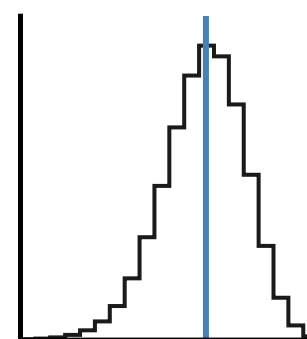
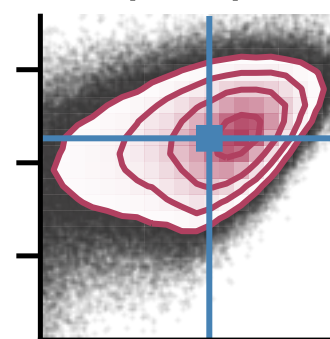
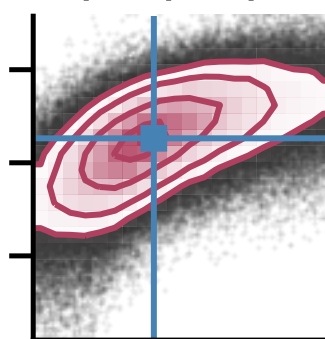
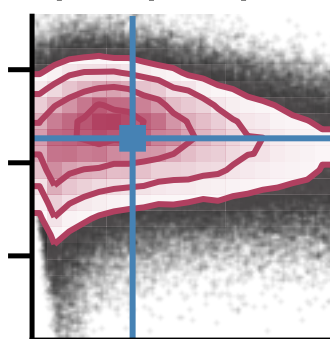
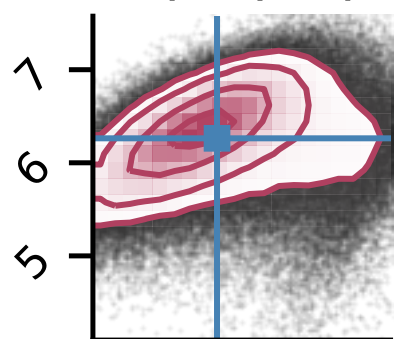
Power-law  
slope:  $m$



RMS seeing:  
 $s_0$  [parsec]



Noise:  
[km<sup>2</sup> s<sup>-1</sup>]



Corr. length:  
 $r_0$  [parsec]

Vel. variance:  
 $\sigma^2$  [km<sup>2</sup> s<sup>-1</sup>]

Power-law  
slope:  $m$

RMS seeing:  
 $s_0$  [parsec]

Noise:  
[km<sup>2</sup> s<sup>-1</sup>]