Automatic calculation of plane loci using Groebner bases and integration into a Dynamic Geometry System

Michael Gerhäuser, Alfred Wassermann

ord.createElement('slider' July 24, 2010 rd. createElement ('slider', [[1, notion (x) (return Math. sin (x) brd.createElement('slider' plot = brd.createElement('functiongraph', os = brd.createElement('riemannsum unction(){ return s.Value unction(){return a.Value

nction(){return b.Value





What is JSXGraph?

- ► A library implemented in JavaScript
- ▶ Runs in recent versions of all major browsers
- No plugins required
- ► LGPL-Licensed

Main features

- Dynamic Geometry
- Interactive function plotting
- Turtle Graphics
- Charts



unction() (return s.Value

Unction() (return a.Value

Unction() (return b.Value)

Supported Hardware

- ► PC (Windows, Linux, Mac)
- "Touchpads" like the Apple iPad
- Mobile phones, iPod
- Basically every device which runs at least one of the supported browsers
 - os = brd.createElement('riemannsum', unction() { return s.Value() unction(){return a.Value unction()(return b.Value(

Supported Browsers

- ► Firefox
- Chrome/Chromium
- Safari
- ▶ Internet Explorer
- Opera

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f = function(x) { return Math.sin(x); }
s = brd.createElement('slider', [[1,1], [
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f = function(x) { return Math.sin(x); }
s = brd.createElement('functiongraph')
function() { return s.Value function() { return a.Value function() { return b.Value function()

Example/Input

```
<link rel="stylesheet" type="text/css" href="css/jsxgraph.css" />
<script type="text/javascript" src="js/jsxgraphcore.js">/script>
<div id="jxgbox" class="jxgbox" style="width:500px; height:500px;"></fi>
<script type="text/javascript">
  board = JXG.JSXGraph.initBoard('jxgbox', {boundingbox: [-2, 20, 20, -2], axis:}
        true, grid: false, keepaspectratio: true});
  A = board.create('point', [8, 3]);
 B = board.create('point', [8, 8]);
  c1 = board.create('circle', [B, 4]);
 D = board.create('glider', [0, 0, c1], \{name: 'D'\});
  g = board.create('line', [A, D]);
  c2 = board.create('circle', [D, 3]);
  T = board.create('intersection', [c2,g,0], {name: 'T'});
</script>
                                                         serement('slider',[[1,1],[5,
                                              Lunction(x) { return Math.sin(x);
```

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os = brd.createElement('functiongraph',
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JSXGraph Example/Output Element('slider',[[1,2], lement('slider',[[1,1],[5, teElement('functiongraph', unction() { return s.Value() createElement('riemannsum', [f unction(){return a.Value unction() (return b. Value(

Supported file formats

- ▶ GEONE_xT
- GeoGebra
- Intergeo
- Cinderella (small feature subset)

brd.createElement('slider',[[1,2],[5 os = brd.createElement('riemannsum') unction() { return s.Value() unction(){return a.Value unction() {return b.Value(

Example/Input

```
<!iink rel="stylesheet" type="text/css" href="css/jsxgraph.css" />
<script type="text/javascript" src="js/jsxgraphcore.js"></script>
<script type="text/javascript" src="js/CinderellaReader.js"></script>
...
<div id="jxgbox" class="jxgbox" style="width:500px; height:500px;"></div>
<script type="text/javascript">
board = JXG.JSXGraph.loadBoardFromFile('jxgbox', 'watt.cdy', 'cinderella');

function computeLocus() {
   board.create('locus', [JXG.getRef('E')]);
}
</script>
```

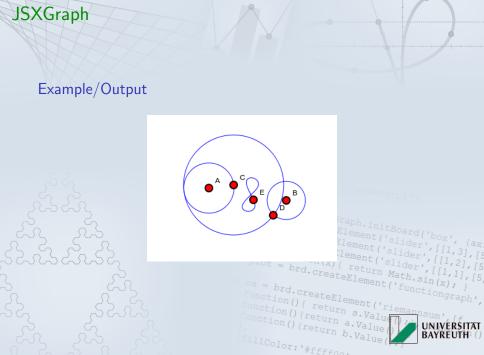
b = brd.createElement('slider', [[1,3], [5]])

f = function(x) { return Math.sin(x); }

plot = brd.createElement('functiongraph', [1,1], [5], [5]])

os = brd.createElement('functiongraph', [1,1], [5], [5]])

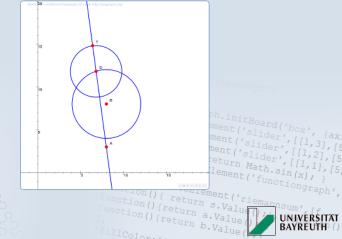
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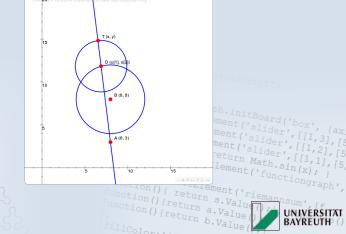
Computing plane loci using Groebner bases (in a nutshell)

```
## Septiment of the state of th
```

Given a set of free and dependent points,



we first choose a coordinate system,



- translate geometric constraints into an algebraic form,
 - $(u[1] 8)^2 + (u[2] 8)^2 16 = 0$
 - $(x u[1])^2 + (y u[2])^2 9 = 0$
 - 3x 3u[1] + yu[1] 8y + 8u[2] xu[2] = 0

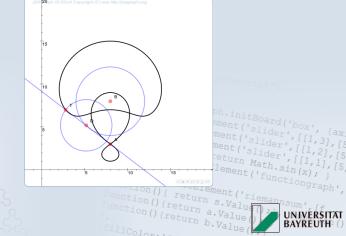
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- calculate the Gröbner basis of the given ideal,
 - $x^6 + 3x^4y^2 + 3x^2y^4 + y^6 48x^5 38x^4y 96x^3y^2 76x^2y^3$ $48xv^4 - 38v^5 + 1047x^4 + 1216x^3v + 1774x^2v^2 + 1216xv^3 +$ $727y^4 - 13024x^3 - 16596x^2y - 16096xy^2 - 8404y^3 + 97395x^2 +$ $109888xy + 63535y^2 - 415536x - 300806y + 790009 = 0$

eateElement('slider' os = brd.createElement('riemannsum unction() { return s.Value()

unction(){return a.Value nction(){return b.Value(

and finally plot the calculated implicit equation.



Implementing this algorithm in JSXGraph

Problems

- ▶ No JavaScript implementation of any Gröbner basis algorithm
- Can't use C-libraries directly in JavaScript
- No implicit plotting in JSXGraph by now

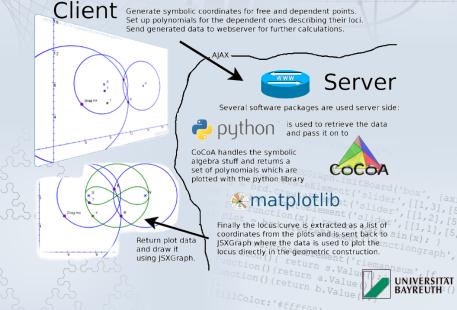


AJAX

► Transfer data (a)synchronously via HTTP with JavaScript

This enables us to

- use a computer algebra system on a (web) server for the expensive Gröbner basis calculations are a plotting tool/library for implicit plotting ment ('slider') tunction(x) (restriction(x) (restrict



Example/Input

os = brd.createElement ('function(x),')
function() { return s.Value | UNIVERSITAT BAYREUTH: ()
fillColor: '#ffsson

Implementation Example/Output JSX 20 ph v0.82rc4 Copyright (C) see http://jsxgraph.org 15 10 urn Math.sin(x); ment('functiongraph', 10 t('riemannsum',[f return b. Value (

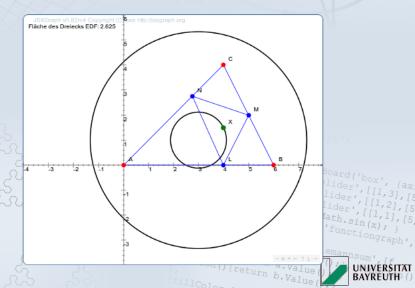
Ready-to-use elements

- Glider on circle and line
- Intersection points (circle/circle, circle/line, line/line)
- Midpoint
- Parallel line and point
- Perpendicular line and point
- Circumcircle and circumcenter

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brd.createElement('slider', [[1,3], [
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Easy to extend



```
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<script type="text/javascript">
  board = JXG.JSXGraph.initBoard('jxgbox', {boundingbox: [-4, 6, 8, -4], axis:}
       true, grid: false, keepaspectratio: true});
  A = board.create('point', [0, 0]);
  B = board.create('point', [6, 0]);
  C = board.create('point', [4, 4]);
  t1 = board.create('triangle', [A, B, C], {strokeWidth: '1px'});
  X = board.create('point', [4, 1.5], {name:"X"});
  L = board.create('perpendicularpoint', [X, t1.c]);
  M = board.create('perpendicularpoint', [X, t1.a]);
  N = board.create('perpendicularpoint', [X, t1.b]);
  t2 = board.create('triangle', [L, M, N], {strokeWidth: '1px'});
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                                         os = brd.createElement('riemannsum',[f
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X.ancestors[L.id] = L;
              X. ancestors [M. id ] = M:
              X.ancestors[N.id] = N;
              X.ancestors[A.id] = A;
              X. ancestors [B. id ] = B:
              X.ancestors[C.id] = C;
               X.generatePolynomial = function () {
                               var as16 = getTriangleArea(L, M, N),
                               as = ((('+M. symbolic.x+')-('+N. symbolic.x+'))^2+(('+M. symbolic.y+')-('+N.
                                                                     symbolic.y+'))^2)'
                               bs = '((('+L.symbolic.x+')-('+N.symbolic.x+'))^2+(('+L.symbolic.y+')-('+N.symbolic.x+'))^2+(('+L.symbolic.y+')-('+N.symbolic.x+'))^2+(('+L.symbolic.y+')-('+N.symbolic.x+'))^2+(('+L.symbolic.y+')-('+N.symbolic.x+'))^2+(('+L.symbolic.y+')-('+N.symbolic.x+'))^2+(('+L.symbolic.y+')-('+N.symbolic.x+'))^2+(('+L.symbolic.y+')-('+N.symbolic.x+'))^2+(('+L.symbolic.y+')-('+N.symbolic.x+'))^2+(('+L.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('+N.symbolic.y+')-('N.symbolic.y+')-('N.symbolic.y+')-('N.symbolic.y+')-('N.symbolic.y+')-('N.symbolic.y+')-('N.symbolic.y+')-('N.symbolic.y+')-('N.symbolic.y+')-('N.symbolic.y+')-('N.symbolic.y+')-('N.symbolic.y+')-('N.symbolic.y+')-('N.symbolic.y+')-('N.symbolic.y+')-('N.symbolic.y+')-('N.symbolic.y+')-('N.symbolic.y+')-('N.symbolic.y+')-('N.symbolic.y+')-('N.symbolic.y+')-('N.symbolic.y+')-('N.symbolic.y+')-('N.symbolic.y+')-('N.symbolic.y+')-('N.symbolic.y+')-('N.symbolic.y+')-('N.symbolic.y+')-('N.symbolic.y+')-('N.symbolic.y+')-('N.symbolic.y+')-('N.symbolic.y+')-('N.symbolic.y+')-('N.symbolic.y+')-('N.symbolic.y+')-('N.symbolic.y+')-('N.symbolic.y+')-('N.symbolic.y+')-('N.symbolic.y+')-('N.s
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                               cs = '((('+M.symbolic.x+')-('+L.symbolic.x+'))^2+(('+M.symbolic.y+')-('+L.symbolic.x+'))^2+(('+M.symbolic.y+')-('+L.symbolic.x+'))^2+(('+M.symbolic.y+')-('+L.symbolic.x+'))^2+(('+M.symbolic.y+')-('+L.symbolic.x+'))^2+(('+M.symbolic.y+')-('+L.symbolic.x+'))^2+(('+M.symbolic.y+')-('+L.symbolic.x+'))^2+(('+M.symbolic.y+')-('+L.symbolic.x+'))^2+(('+M.symbolic.y+')-('+L.symbolic.x+'))^2+(('+M.symbolic.y+')-('+L.symbolic.x+'))^2+(('+M.symbolic.y+')-('+L.symbolic.x+'))^2+(('+M.symbolic.y+')-('+L.symbolic.y+')-('+L.symbolic.x+'))^2+(('+M.symbolic.y+')-('+L.symbolic.x+'))^2+(('+M.symbolic.y+')-('+L.symbolic.x+'))^2+(('+M.symbolic.y+')-('+L.symbolic.x+'))^2+(('+M.symbolic.y+')-('+L.symbolic.x+'))^2+(('+M.symbolic.y+')-('+L.symbolic.x+'))^2+(('+M.symbolic.x+')-('+L.symbolic.x+'))^2+(('+M.symbolic.x+')-('+L.symbolic.x+'))^2+(('+M.symbolic.x+')-('+L.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M.symbolic.x+'))^2+(('+M
                                                                     symbolic.y+'))^2)'.
                               return ['4*'+as+'*'+cs+'-('+as+'+'+cs+'-'+bs+')*('+as+'+'+cs+'-'+bs+')-('+
                                                                     as16+')'l:
                };
                locus = board.create('locus', [X], {strokeColor: 'red'});
</script>
```



Re-using locus data: Discovered loci can be

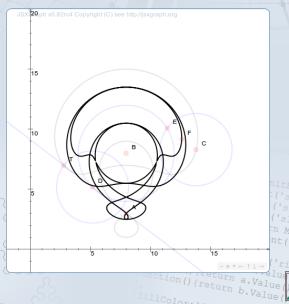
- ▶ intersected with circles, lines, other curves, ...
- used as a base object for gliding points
- used for the discovery of other loci

a = brd.createElement('slider', [1,3], [b = brd.createElement('slider', [1,3], [f = function(x) { return Math.sin(x); }]

so = brd.createElement('slider', [1,1],

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To Solve of Michael Congregate (C) and International Congregate (C
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```
C = board.create('glider', [loc]);
c2 = board.create('circle', [C, 3]);
E = board.create('intersection', [c1, c2, 0]);
F = board.create('midpoint', [C, E]);
```



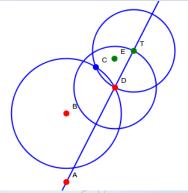
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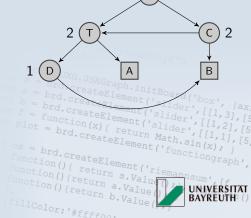
Optimization

brd = JXG.JSXGraph.initBoard('box', [ax a = brd.createElement('slider', [l1,3], [ax f = brd.createElement('slider', [l1,2], [ax f = function(x) { return Math.sin(x); } plot = brd.createElement('slider', [l1,2], [ax f = function() { return Math.sin(x); } function() { return s.Value function() { return s.Value function() { return a.Value function() { return b.Value function() { return b.Value

Optimization

Idea: Divide and conquer





Optimization

Transformations

- ightharpoonup Translate the construction moving one point to (0,0)
- ▶ Rotate the construction moving another point onto the x-axis
- ► After the Gröbner basis is calculated, the result is retransformed
- User can choose the two points or



Examples

Last slide

Thank You

- http://jsxgraph.org/
- http://jsxgraph.uni-bayreuth.de/wiki/

os = brd.createElement('functiongrap function()(return s.Value function() (return a.Value function() (return b.Value)

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