JSXGraph Reference Card

Include JSXGraph in HTML

Three parts are needed: Include files containing the software, an HTML element, and JavaScript code.

Include files:

Two files have to be included: jsxgraph.css, and jsxgraph-core.js.

src="domain/jsxgraphcore.js"></script>

domain is the location of the files. This can be a local directory
or http://jsxgraph.uni-bayreuth.de/distrib/

HTML element containing the construction:

```
<div id="box" class="jxgbox"
style="width:600px; height:600px;"></div>
```

JavaScript code:

```
<script type="text/javascript">
  var brd = JXG.JSXGraph.initBoard('box',{axis:true});
<script>
```

Initializing the board

```
- Attributes of the board boundingbox: [x_1,y_1,x_2,y_2] user coordinates of the upper left and bottom right corner keepaspectratio:true/false default: false zoomX,zoomY: zoom factor in x/y-axis direction zoomfactor: overall zoom factor in both directions axis,grid,showNavigation,showCopyright: true/false
```

var brd = JXG.JSXGraph.initBoard('box',{attributes});

Properties and methods of the board:

show axis, grid, zoom/navigation buttons, display copyright

Basic commands

```
var el = brd.create('type',[parents],{attributes});
el.setProperty({key1:value1,key2:value2,...});
```

Point

```
brd.create('point',[parents],{attributes});
```

Parent elements:

```
[x,y] Euclidean coordinates [z,x,y] Homogeneous coordinates (z in first place) [function(){return p1.X();}, function(){return p2.Y();}] Functions for x, y, (and z) [function(){return [a,b];}] Function returning array [function(){return new JXG.Coords(...);}]
```

Function returning Coords object

Methods

```
\begin{array}{ll} \texttt{p.X(),p.Y()} & x\text{-coordinate, }y\text{-coordinate} \\ \texttt{p.Z()} & (\text{Homogeneous}) \ z\text{-coordinate} \\ \texttt{p.Dist(q)} & \text{Distance from } p \text{ to point } q \end{array}
```

Glider

```
Point on circle, line, curve, or turtle.
```

```
brd.create('glider',[parents],{attributes});
```

Parent elements:

```
[x,y,c] Initial coordinates and object to glide on [c] Object to glide on (initially at origin)
```

Coordinates may also be defined by functions, see Point.

Line

```
brd.create('line',[parents],{attributes});
```

Parent elements:

In case of coordinates as parents, the line is the set of solutions of the equation $a \cdot x + b \cdot y + c \cdot z = 0$.

Circle

```
brd.create('circle',[parents],{attributes});
```

Parent elements:

[p1,p2]	2 points: center and point on circle line
[p,r]	center, radius (constant or function)
[p,c],[c,p]	center, circle from which the radius is taken
[p,1],[1,p]	center, line segment for the radius
[p1,p2,p3]	circle through 3 points
Points may also	be specified as array of coordinates.

Polygon

```
brd.create('polygon',[p1,p2,...],{attributes});
[p1,p2,...] The array of points
is connected by line segments and the inner area is filled.
brd.create('regularpolygon',[p1,p2,n],{attributes});
```

Slider

```
\begin{array}{lll} \text{var s = brd.create('slider',[[a,b],[c,d],[e,f,g]],\{atts\});} \\ \text{[a,b],[c,d]:} & \text{visual start and end position of the slider} \\ \text{[e,f,g]:} & \text{the slider returns values between $e$ and $g$,} \\ & \text{the initial position is at value $f$} \\ \text{snapWidth:num} & \text{minimum distance between 2 values} \\ \text{s.Value():} & \text{returns the position of the slider} \in [e,g] \\ \end{array}
```

Group

```
brd.create('group',[p1,p2,...],{attributes});
[p1,p2,...] array of points
Invisible grouping of points. If one point is moved, the others
are transformed accordingly.
```

Curve

```
- brd.create('functiongraph',[parents],{atts});
                                   Function graph, x \mapsto f(x)
[function(x){return x*x:}.-1.1]
                                         function term
                                         optional: start, end
-brd.create('curve',[parents],{attributes});
· Parameter curve, t \mapsto (f(t), q(t)):
[function(t){return 5*t;},function(t){return t*t;},0,2]
                   x function, y function, optional: start, end
· Polar curve: Defined by the equation r = f(\phi).
[function(phi){return 5*phi;},[1,2],0,Math.PI]
                Defining function, optional: center, start, end
· Data plot:
[[1,2,3],[4,-2,3]]
                            array of x- and y-coordinates, or
[[1,2,3],function(x){return x*x;}]
                        array of x-coordinates, function term
- brd.create('spline',[p1,p2,...],{attributes});
                                Cubic spline: array of points
[p1, p2, ...]
-brd.create('riemannsum',[f,n,type],{atts});
Riemann sum of type 'left', 'right', 'middle', 'trapezodial', 'up-
per', or 'lower'
- brd.create('integral',[[a,b],f],{atts});
Display the area \int_a^b f(x)dx.
```

Tangent, normal

Conic sections

```
- ellipse, hyperbola: defined by the two foci points and
a point on the conic section or the length of the major axis.
brd.create('ellipse',[p1,p2,p3],{attributes});
brd.create('ellipse',[p1,p2,a],{attributes});
brd.create('hyperbola',[p1,p2,p3],{attributes});
brd.create('hyperbola',[p1,p2,a],{attributes});
- parabola: defined by the focus and the directrix (line).
brd.create('parabola',[p1,line],{attributes});
- conic section: defined by 5 points or by the (symmetric) quadratic form
```

$$(x,y,z)\begin{pmatrix} a_{00} & a_{01} & a_{02} \\ a_{01} & a_{11} & a_{12} \\ a_{02} & a_{12} & a_{22} \end{pmatrix} (x,y,z)^{\top}$$

```
brd.create('conic',[p1,...,p5],{atts});
brd.create('conic',[a<sub>00</sub>,a<sub>11</sub>,a<sub>22</sub>,a<sub>01</sub>,a<sub>02</sub>,a<sub>12</sub>],{atts});
```

Turtle

```
var t = brd.create('turtle',[parents],{atts});
                                position, direction (degrees).
t.X(), t.Y(), t.dir
Parent elements:
[x,v,angle]
                 Optional start values for x, y, and direction
Methods:
t.back(len); or t.bk(len);
t.clean(); erase the turtle lines without resetting the turtle
t.clearScreen(); or t.cs(); call t.home() and t.clean()
t.forward(len): t.fd(len):
t.hideTurtle(); or t.ht();
                   Set the turtle to [0,0] and direction to 90.
t.home();
t.left(angle); or t.lt(angle);
t.lookTo(t2.pos);
                                Turtle looks to the turtle t2
t.lookTo([x,y]);
                           Turtle looks to a coordinate pair
                              Move the turtle with drawing
t.moveTo([x,y]);
t.penDown(); or t.pd();
t.penUp(); or t.pu();
t.popTurtle();
                                pop turtle status from stack
t.pushTurtle();
                                 push turtle status on stack
t.right(angle); or t.rt(angle);
t.setPos(x.v):
                           Move the turtle without drawing
t.setPenColor(col); col: colorString, e.g. 'red' or '#ff0000'
t.setPenSize(size);
                                       size: number
t.showTurtle(); or t.st();
```

Text

Display static or dynamic texts.

```
el = brd.create('text',[x,y,"Hello"]);
el = brd.create('text',[x,y,f]); where
f = function(){ return p.X(); }
Example for a dynamic text: f returns the x coordinate of the
point p.
```

Image

Display bitmap image (also as data uri).

```
el = brd.create('image',[uri-string,[x,y],[w,h]]);
    [x,y]: position of lower left corner, [w,h]: width, height
```

Other geometric elements

```
- angle:
                               filled area defined by 3 points
el = brd.create('angle',[A,B,C],{attributes});
- arc:
                             circular arc defined by 3 points
el = brd.create('arc',[A,B,C],{attributes});
                       line through 2 points with arrow head
el = brd.create('arrow',[A,B],{attributes});
- arrowparallel: arrow parallel to arrow a starting at point P
el = brd.create('arrowparallel',[a,P],{atts}); or [P,a]
- bisector: angular bisector defined by 3 points, returns line
el = brd.create('bisector',[A,B,C],{atts});
            angular bisector defined by 2 lines, returns 2 lines
el = brd.create('bisectorlines',[11,12],{atts});
                         circle through 3 points (deprecated)
- circumcircle:
el = brd.create('circumcircle',[A,B,C],{atts});
                            center of circle through 3 points
- circumcirclemidpoint:
el = brd.create('circumcirclemidpoint',[A,B,C]);
- midpoint: midpoint between 2 points or the 2 points defined
by a line
el = brd.create('midpoint', [A,B], {atts}); or [line]
- mirrorpoint:
                     rotate point B around point A by 180^{\circ}
el = brd.create('mirrorpoint', [A,B], {atts});
                       line parallel to line l through point P
el = brd.create('parallel',[1,P],{atts}); or [P,1]
- parallelpoint: point D such that ABCD from a parallelogram
el = brd.create('parallelpoint', [A,B,C], {atts});
- perpendicular: line perpendicular to line l through point P
el = brd.create('perpendicular',[1,P],{atts}); or [P,1]
- perpendicular point: point defining a perpendicular line to
line l through point P
el = brd.create('perpendicularpoint',[1,P],{}); or [P,1]
- reflection: reflection of point P over the line l. Superseded
by transformations
el = brd.create('reflection',[1,P],{atts}); or [P,1]
                                                        ???
                 circle sector defined by 3 points
- sector:
el = brd.create('sector', [A,B,C], {atts});
- semi circle:
                              defined by 2 points p_1 and p_2.
brd.create('semicircle',[p1,p2],{atts});
- intersection:
                               of 2 objects (lines or circles).
Returns array of length 2 with first and second intersection
point (also for line/line intersection).
brd.create('intersection',[o1,o2,n],{atts});
```

```
Transform
Affine transformation of objects.
t = brd.create('transform',[data,base],{type:'type'});
base: the transformation is applied to the coordinates of this
object.
Possible types:
- translate: data=[x,y]
- scale: data=[x,y]
- reflect: data=[line] or [x1,y1,x2,y2]
- rotate: data=[angle,point] or [angle,x,y]
- shear: data=[angle]
- generic: data=[v11.v12.v13.v21....v33] 3 × 3 matrix
Methods:
t.bindTo(p)
                        the coordinates of p are defined by t
t.applyOnce(p)
                              apply the transformation once
               combine two transformations to one: t := t \cdot s
t.melt(s)
p2 = brd.create('point',[p1,t],{fixed:true});
                               Point p_2: apply t on point p_1
Attributes of geometric elements
Generic attributes:
strokeWidth:
                                        number
strokeColor,fillColor,highlightFillColor,
highlightStrokeColor,labelColor:
                                        color string
strokeOpacity,fillOpacity,highlightFillOpacity,
highlightStrokeOpacity:
                                      value between 0 and 1
                                        true, false
visible.trace.draft:
dash:
                              dash style for lines: 0, 1, \dots, 6
infoboxtext:
                                        string
Attributes for point elements:
face:
          possible point faces: '[]', 'o', 'x', '+', '<', '>', 'A', 'v'
size:
                                        number
fixed:
                                        true, false
Attributes for line elements:
straightFirst, straightLast, withTicks: true, false
Attributes for line, arc and curve elements:
```

true, false

true, false

'html', 'internal'

0 < h < 360, 0 < s, v < 1

returns RGB color string.

firstArrow,lastArrow:

withLines:

display:

Color string:

JXG.hsv2rgb(h,s,v)

Attributes for polygon elements:

HTML color definition or HSV color scheme:

Attributes for text elements:

Mathematical functions

```
Functions of the intrinsic JavaScript object Math:

Math.abs,Math.acos,Math.asin,Math.atan,Math.ceil,

Math.cos,Math.exp,Math.floor,Math.log,Math.max,

Math.min,Math.random,Math.sin,Math.sqrt,Math.tan

(number).toFixed(3): Rounding a number to fixed precision
```

Additional mathematical functions are methods of JXG.Board. angle ABCbrd.angle(A,B,C) brd.cosh(x), board.sinh(x) brd.pow(a,b) compute $\frac{d}{dx}f$ numerically brd.D(f,x) compute $\int_a^b f(x)dx$ numerically brd.I([a,b],f) root of the function f. brd.root(f,x) Uses Newton method with start value x brd.factorial(n) computes $n! = 1 \cdot 2 \cdot 3 \cdot \cdots n$ computes $\binom{n}{k}$ brd.binomial(n,k) Euclidean distance brd.distance(arr1,arr2) brd.lagrangePolynomial([p1,p2,...])

returns a polynomial through the given points brd.neville([p1,p2,...]) polynomial curve interpolation c = JXG.Math.Numerics.bezier([p1,p2,...]) Bezier curve p2,p3,p5,p6,... are control points. brd.create('curve',c); f = JXG.Math.Numerics.regressionPolynomial(n,xArr,yArr) Regression pol. of deg. n: brd.create('functiongraph',f); brd.riemannsum(f,n,type,start,end) Volume of Riemann sum, see Curves

- Intersection of objects:

brd.intersection(el1,el2,i,j) intersection of the elements el_1 and el_2 which can be lines, circles or curves

In case of circle and line intersection, $i \in \{0,1\}$ denotes the first or second intersection. In case of an intersection with a curve, i and j are floats which are the start values for the path positions in the Newton method for el_1 and el_2 , resp.

Todo list

'axis', 'ticks'.

Chart

To do \dots

Links

Help pages are available at http://jsxgraph.org