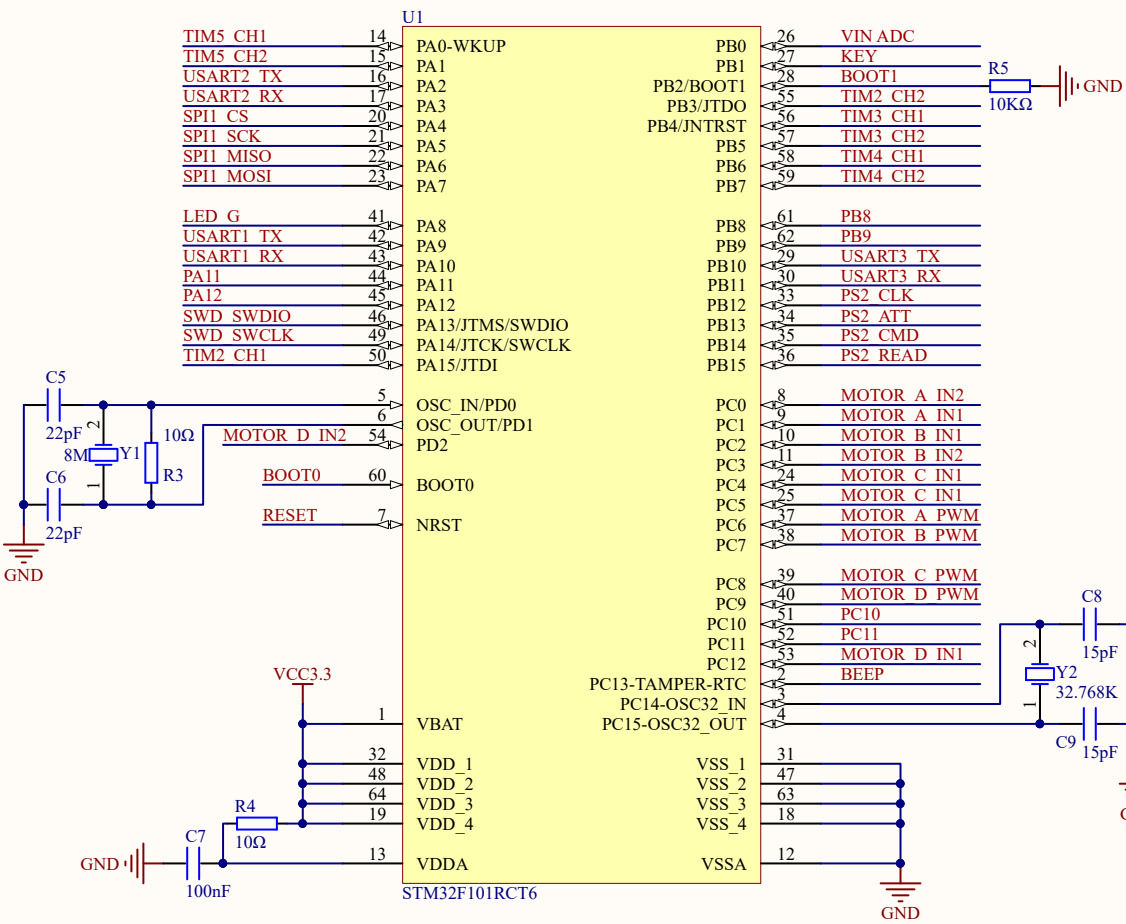
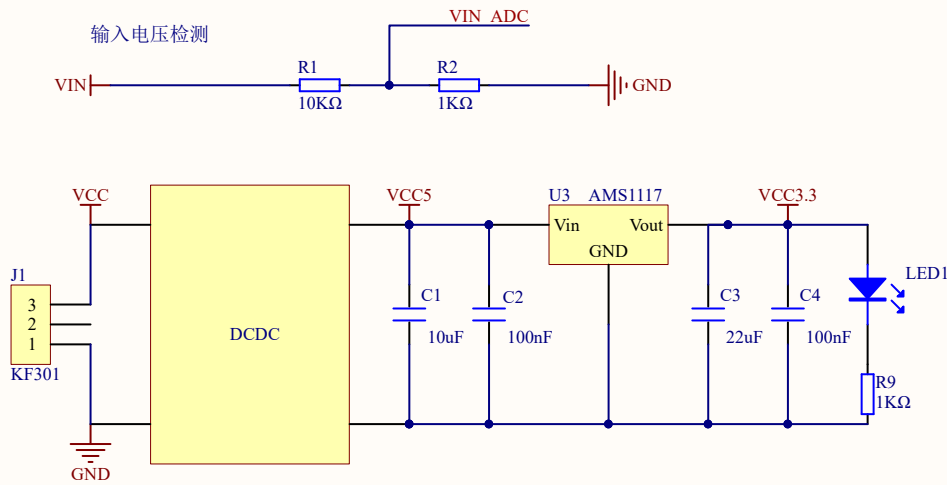


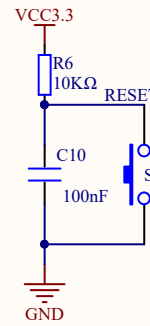
## 下位机主控



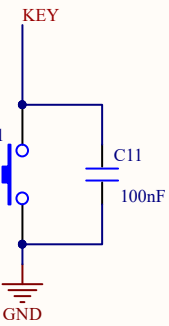
## 电源12V转5V 3.3V



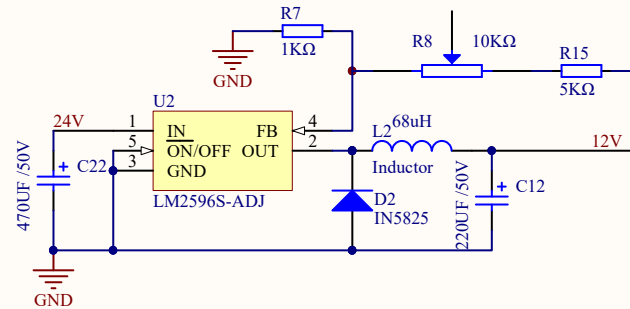
## 复位



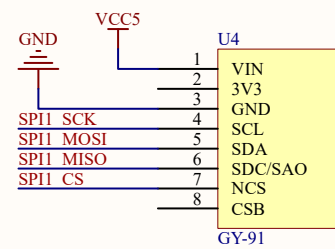
## 按键



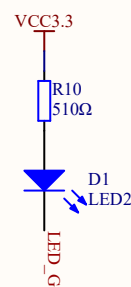
## 电源24V转12V



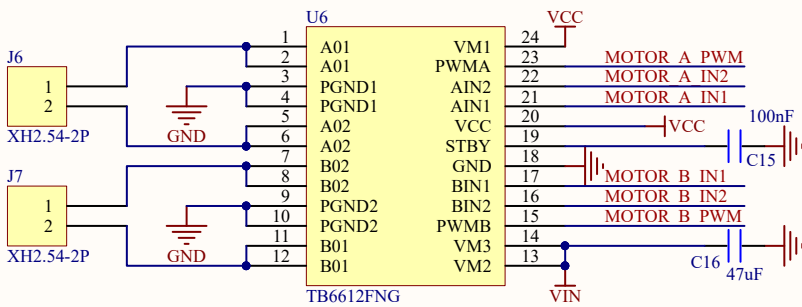
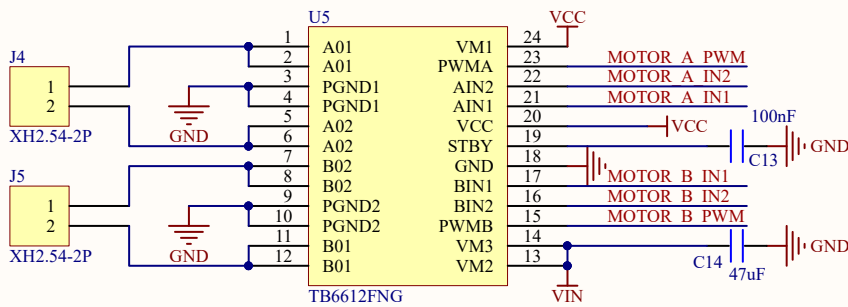
## 姿态测量模块



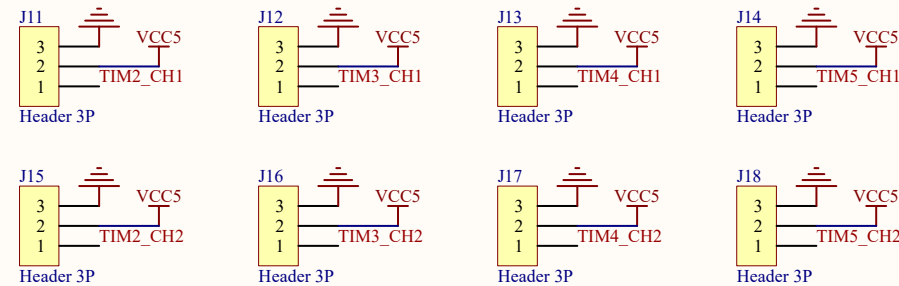
## LED



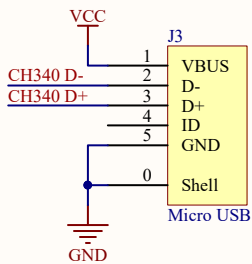
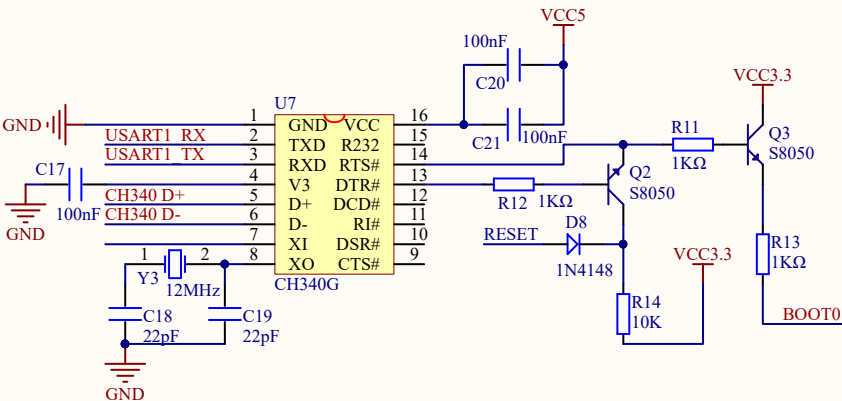
## 电机驱动



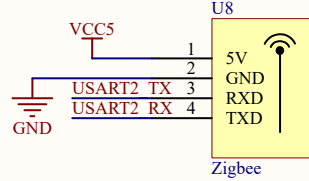
## PWM接口 编码器输入捕获



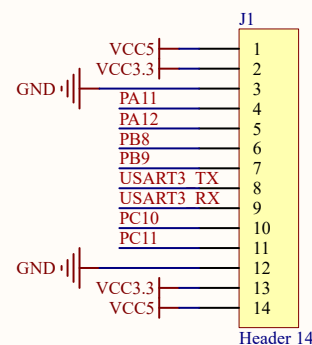
## USB串口



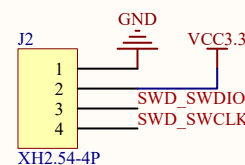
## 无线通信模块



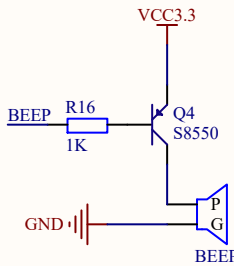
## 通用I/O接口



## SWD接口

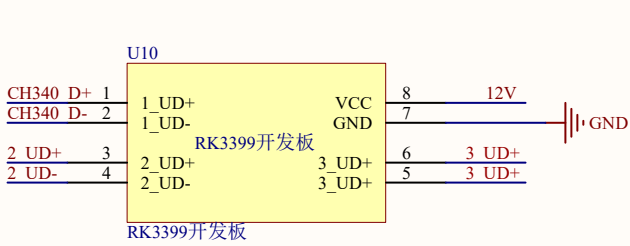


## 蜂鸣器

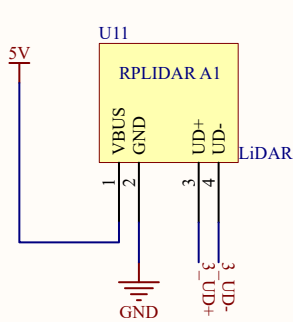


Title: RoboCar 电路原理图	Project: 基于SLAM的机器人自主导航算法		
File: RoboCar_2.SchDoc	Vision: V1.0	Author: 席佳伟 Javid	
Date: 2020/5/6	Size: A3	个人网站: <a href="https://javid.cn">https://javid.cn</a>	

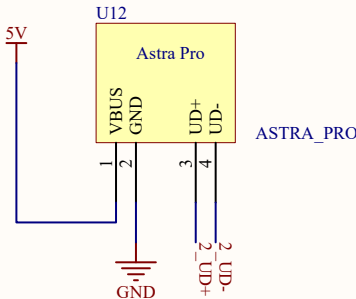
上位机主控



激光雷达模组



深度视觉模组



PS2遥控器

