



Building Simulation Testbed Development for RLC

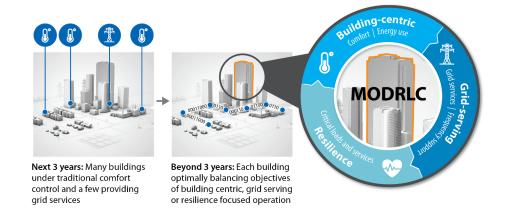
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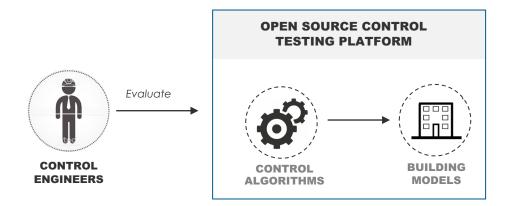
IBPSA Project 1 - WP1.2 - BOPTEST and MPC

October 14, 2020

OBJECTIVES

- DOE BTO Project: Multi-Objective Deep Reinforcement Learning Control for GEB
- Build testbed capabilities using open-source software for long-term relevance and benefit of building controls community
- Develop standard prototype building models with realistic controls implemented in Spawn
- Provide reproducible results evaluated against accepted key performance indicators (KPIs)
- Compare conventional, enhanced rule based, and model predictive control (MPC) against reinforcement learning based (RL) building control algorithms
- Validate transfer learning to arrive at recommendations for most suitable control approaches for implementation at scale





DEVELOPMENT ROADMAP

1. ACTB
DEVELOPMENT

- Development of Spawn models
- Test of Advanced Controls Testbed



2. EVALUATION OF CONTROL STRATEGIES

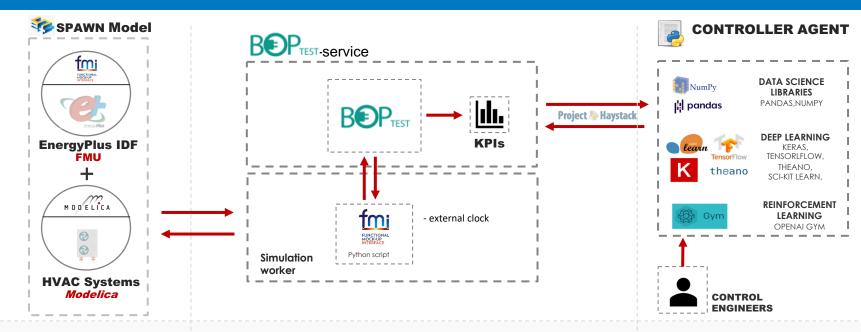
- Development of rule-based, MPC and RL control
- Evaluation of KPIs with BOPTEST
- Evaluation of RL control strategies with ACTB



3. FIELD IMPLEMENTATION

- · Identification of a suitable real building
- Development of a finely-granular Spawn model
- Application of RL control strategies and transfer learning

PROPOSED ARCHITECTURE



SPAWN OF ENERGYPLUS

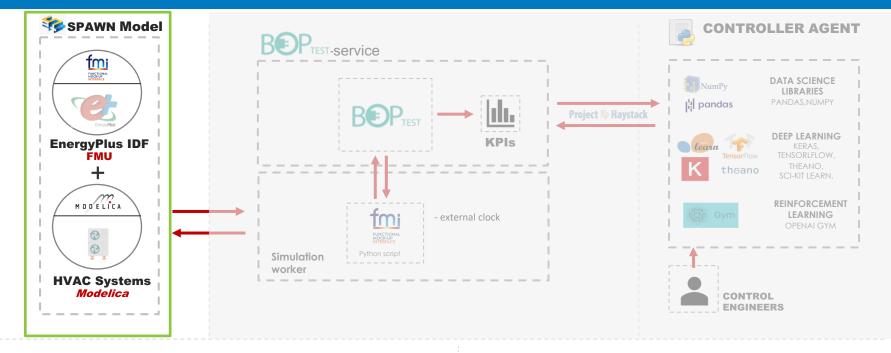
- EnergyPlus thermal zone balance & load model
- Modelica HVAC and controls model using Modelica Buildings Library
- Bridges gap between BEM & control workflows

BOPTEST

- Signal override & measurement points
- Control of EnergyPlus & Modelica simulations
- Haystack API for point mapping
- · Management of FMU simulations
- Python controller interface
- User-side client for control & KPIs output
- Parallel simulation of multiple BEM test-cases

PYTHON AGENT

- Implementation of control agents pursuing a variety of strategies
- Flexibility
- Availability of proven deep learning and RL libraries

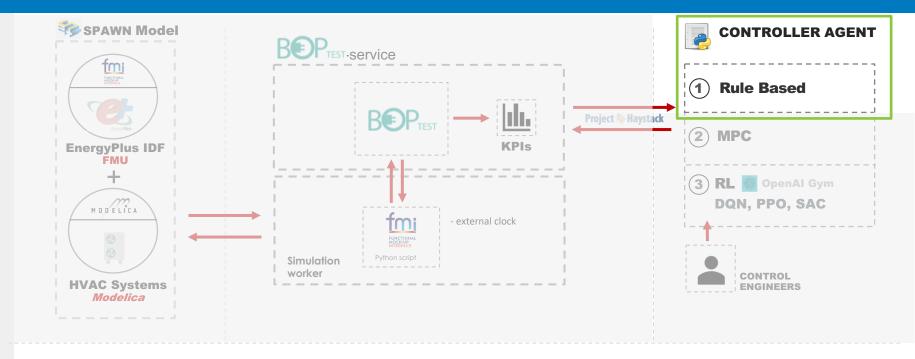


1. Development of a Spawn model

- A detailed building envelope model is developed in EnergyPlus
- A detailed HVAC model is developed in Modelica
- Envelope and HVAC models are packaged into a Spawn model

Advantages:

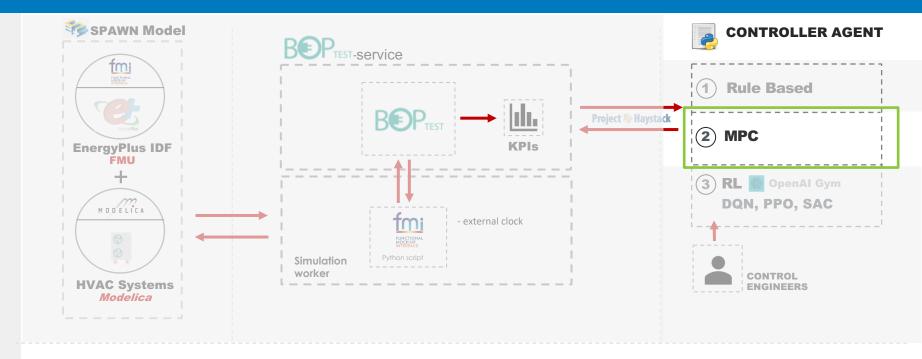
- Leverage EnergyPlus sensible and latent load modeling capabilities and Modelica's flexibility
- Decouple building envelope model from HVAC system models
- Enable the development of vendor-specific detailed HVAC models



BOPTEST Python controller interface:

Development of three types of control strategies:

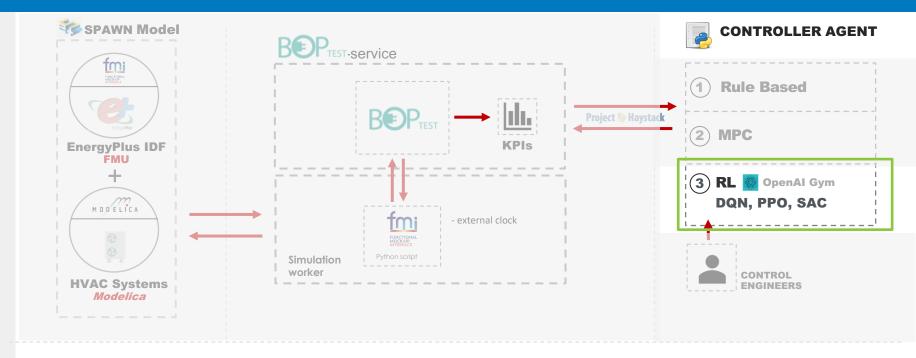
• Rule-based controls, to serve as a baseline



BOPTEST Python controller interface:

Development of three types of control strategies:

- Rule-based controls, to serve as a baseline
- MPC strategies

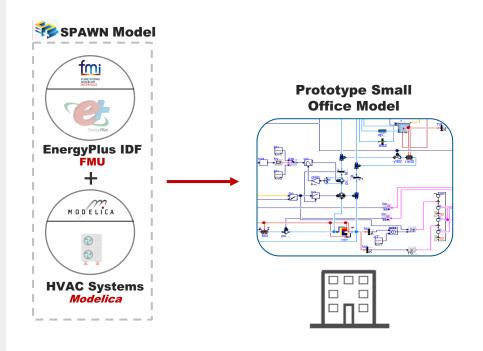


BOPTEST Python controller interface:

Development of three types of control strategies:

- Rule-based controls, to serve as a baseline
- MPC strategies
- Reinforcement Learning with OpenAl Gym: Deep Q Learning (DQN), Proximal Policy Optimization (PPO) and Soft Actor Critic (SAC)

PROPOSED TESTCASE



- **5 Zone** Building
- Single zone packaged RTU
- Control sequences (ASHRAE GL 36 where appropriate)
- HVAC using MBL components
- HVAC Derived from DOE Small Office Prototype
- Rule-based, MPC, and RL controls evaluation using BOPTEST KPIs

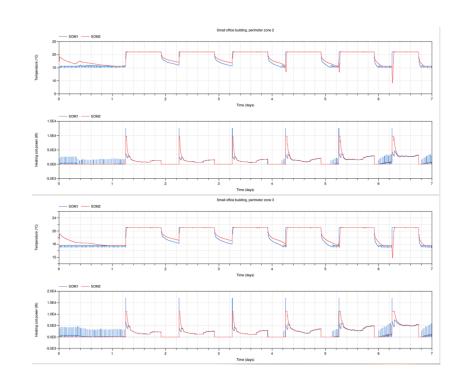
SUMMARY & FUTURE WORK

Work to date:

- Verified that EnergyPlus models and their FMU equivalent have the same performance characteristics.
- Developed a Spawn model of a DOE prototype small office building, embedded into an FMU.
- Exposed sensors and setpoints of the Spawn model in BOPTEST using the SignalExchange components.

Future work:

- Test Advanced Controls Testbed leveraging BOPTEST framework.
- Debug and refine the integration of the testbed tools.
- **Develop** and **evaluate** advanced control strategies.







Thank you!

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