### Iterative Methods

Part 3: Arnold: for Linear Sys. (GMRES)

Reurf Arnold: generates ONB Qn s.t.

Substitute  $\begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 \\ 2 & 2 & 2 \\ 1 & 1 & 1 \end{bmatrix}$   $\begin{bmatrix} 1 & 1 & 1 \\ 2 & 2 & 2 \\ 1 & 1 & 1 \end{bmatrix}$   $\begin{bmatrix} 1 & 1 & 1 \\ 2 & 2 & 2 \\ 1 & 1 & 1 \end{bmatrix}$   $\begin{bmatrix} 1 & 1 & 1 \\ 2 & 2 & 2 \\ 1 & 1 & 1 \end{bmatrix}$   $\begin{bmatrix} 1 & 1 & 1 \\ 2 & 2 & 2 \\ 1 & 1 & 1 \end{bmatrix}$   $\begin{bmatrix} 1 & 1 & 1 \\ 2 & 2 & 2 \\ 1 & 1 & 1 \end{bmatrix}$   $\begin{bmatrix} 1 & 1 & 1 \\ 2 & 2 & 2 \\ 1 & 1 & 1 \end{bmatrix}$   $\begin{bmatrix} 1 & 1 & 1 \\ 2 & 2 & 2 \\ 1 & 1 & 1 \end{bmatrix}$   $\begin{bmatrix} 1 & 1 & 1 \\ 2 & 2 & 2 \\ 1 & 1 & 1 \end{bmatrix}$   $\begin{bmatrix} 1 & 1 & 1 \\ 2 & 2 & 2 \\ 1 & 1 & 1 \end{bmatrix}$ 

Arnshib Decomp.  $A \begin{bmatrix} 1 & 1 \\ q_1 - q_n \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ q_1 - q_n \end{bmatrix} \begin{bmatrix} 1 & 1 \\ q_1 - q_n \end{bmatrix} + h q_{n+1} e_n^T$   $Q_n \qquad Q_n \qquad H_n$ 

=> Hn = Qn\*AQn

## Approximating Eigenvalues

O,,.., On eigenvalues of the are roots of the minimizing polynomial

Ilpa(A) xII2 = minimum over

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pa e pa deg. n po by is

- As a increases, pa tends to place roots near extremel eigenvalues of A.
- => Can be much more efficient them
  power iterations/simultaneous iterations.

# Generalized Minimal Residuals (GMRES)

The Arabli iteration also produces powerful approximations to the solus of linear systems.

Solve Ax=b => X4 = A-1b Exact

Krylov Subspace K, (A, b) = span {b, Ab, A2b, ..., And b}

Idea: choose  $X_n \in K_n(A,b)$  to minimize the residual norm

X. = argmin ||Ax-b||<sub>2</sub> xeK\_(4,b)

=> This is sust a Leust-Squares problem!

Amsteli! Leust-Squares

Approach 1: write  $AK_{nC}$  to get  $x \in K_{n}(A,b)$   $X_{n} = argmin 11AK_{nC} - b11_{z}$   $C \in \mathbb{R}^{n}$ 

Solve w/QR fecherication of tall skinny met

 $\begin{bmatrix} \dot{A}_{x} & \dot{A}_{x}^{2} & -\dot{A}_{x}^{4} \\ \dot{I} & \dot{I} \end{bmatrix}$ 

=> ill-conclitioneel Leust-Symres problem

Approach 2: write A Quy to get xEKn (A,b)

Xn 2 argmin 1/A Qny-bl/2 QyelR"

Use Arnoldi decomp Alla: Que Ha

11AQ - 4112 = 11Q - Hay - 51/2

b/c and Hay-bekn(A,b) - = 11 Any - Qn b//

Since q= b/11611, we need to solve

=> Special structure of Hu allows us to update Least-Squares solu. Yn forst as we build up Hu column-by-column with Arnoldi iterations.

#### GMRES (Psendscode)

q = 6/11611 for k=1,2,3,--

· Step n of Arnoldi adels kt column to Hk, Qk

· solve is problem y a arguin littery-11/2 using fust UR update.

· Compute Xx = Qx Yx

## GMRES : Polynomial Approx

Since  $x_n \in K_n(A,b) = span \{b, Ab, A^2b, -, A^{n-1}b\}$ ,  $x_n = g_{n-1}(A)b = c_nb + c_nAb + \cdots + c_{n-1}A^{n-1}b$  We minimize the residual

(n = b-Axn = b- A(wb+aAb+ -- + an An-16)

50 ra=p(A)b -here pa(z)=1-zqua(z)

is a degree a polynomial -/pn(0)=1.

The Over all degree a polynomichs
with p(o)=1, GMRES constructs Pn(2)

s.b. Ilpa(A) bllz z minimum.

#### Convergence

First, note that Ilranil \$ Ilrall for all n>1 b/c Kn(A,b) c Knn(A,b).

Second, note that IIImII=0 since  $K_m(A,b) = IR^m$  and A is invertible: A'b &  $K_m(A,b)$ 

So II all - DO monobonically (nonincreesing)
in no more than m steps.

We need neem, so key question is hor fast does IITall decreese?

Extremal problems in polynomial approx

Denste Pi = {set of deg. ~ poly with P(0):1}

II Tall = min II p(A) bll & II p(A) II II bll my
repi 

II Tall & inf II p(A) II

II to II feli

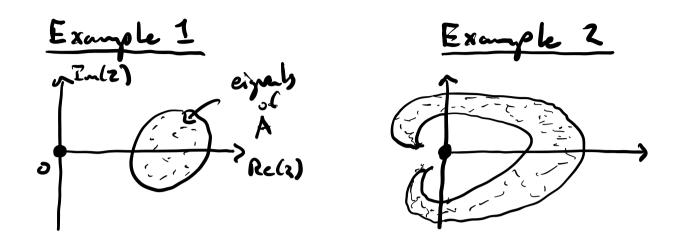
 $A = V \perp V'$  diagonalizable, Hen  $p(A) = Vp(A) V'' \Rightarrow ||p(A)|| \leq ||V|||V'|| ||p(A)||$   $\times (V) = \sum_{1 \leq i \leq r} p(i)$ 

IIIall & K(V) min max p();)
per: 15 isn

Min-mar problem on spectrum of A.

Note: Non-normality (large K(V)) can degrade convergence of iterative methods like

Arnold: 6 MRES.



P(0) = 1, how smell can p(2) be on spectrum of A?