

## Randomized Algorithms

### Low-Rank Approximation

Recap

Direct Methods: Compute the core matrix factorizations to reach back. error:

$\Rightarrow$  LU

$\Rightarrow$  QR

$\Rightarrow$  Eigenvalue decomposition

$\Rightarrow$  SVD

Typically  $O(m^3)$  for  $m \times m$  matrix.

Iterative Methods: Compute an approximate soln to tol.  $\delta$  in  $N(\delta)$  iterations:

$\Rightarrow$  Arnoldi

$\Rightarrow$  GMRES

$\Rightarrow$  Lanczos

$\Rightarrow$  CG

$\left. \begin{array}{l} \text{Arnoldi} \\ \text{GMRES} \\ \text{Lanczos} \\ \text{CG} \end{array} \right\} \begin{array}{l} \text{Eigenvalues} \\ \text{linear systems} \end{array}$

Trade off accuracy and computational cost.  
Usually want fast  $x \rightarrow Ax$ , e.g.,  $O(m \log(m))$ .

Many applications, but historically these are closely associated w/ solving PDE discretizations.

## Low-rank Structure in Data

Relatively new feature of applied math is sheer volume of data available.

⇒ Need to work with high-dim data sets/matrices.

⇒ Often less explicit structure than, e.g., PDE discretizations.

⇒ Presence of noise and corruption in matrix entries.

How do we deal with high-dim data?

Observation: high-dim data can often be approximated with low-rank matrices.

$$\begin{matrix} & A \approx QB \\ \begin{matrix} n \\ \left[ \right] \\ n \end{matrix} & \approx \begin{matrix} n \\ \left[ \right] \\ r \end{matrix} \end{matrix} \begin{matrix} n \\ \left[ \right] \\ r \end{matrix}$$

column/row spaces are low-dimensional

Idea: Project data onto low-dim subspace and do direct NLA there.

Stage A: Compute ONB  $Q$  whose span approximates  $\text{span}(A)$ .

$$\Rightarrow A \approx \underbrace{QQ^*A}_B \text{ and } Q^*Q = I$$

Stage B: Compute  $B = Q^*A$  and factor  $B$  with a direct method

$$\Rightarrow B = U \Sigma V^*, \quad A \approx (QU) \Sigma V^*$$

How do we find such a  $Q$ ?

### Low-Rank Approximation

Fixed Precision Problem: Given  $m \times n$   $A$  and tolerance  $\epsilon > 0$ , find  $m \times k$   $Q$  s.t.

$$(*) \quad \|A - \underbrace{QQ^*A}_B\|_2 < \epsilon \text{ and } Q^*Q = I.$$

The SVD of  $A$  tells us how to pick  $Q$ .

$$\begin{array}{c} \begin{bmatrix} | & & | \\ a_1 & \dots & a_n \\ | & & | \end{bmatrix} = \begin{bmatrix} | & & | \\ u_1 & \dots & u_n \\ | & & | \end{bmatrix} \begin{bmatrix} \sigma_1 & & \\ & \ddots & \\ & & \sigma_n \end{bmatrix} \begin{bmatrix} - & v_1^* & - \\ & \vdots & \\ - & v_n^* & - \end{bmatrix} \\ A \qquad \qquad U \qquad \qquad \Sigma \qquad \qquad V^* \end{array}$$

$$\begin{aligned}
&= \sum_{j=1}^n \sigma_j u_j v_j^* = \sum_{j=1}^k \sigma_j u_j v_j^* + \sum_{j=k+1}^n \sigma_j u_j v_j^* \\
&= \underbrace{\begin{bmatrix} 1 & & \\ & \ddots & \\ & & 1 \\ & & & 0 \end{bmatrix} \begin{bmatrix} \sigma_1 & & \\ & \ddots & \\ & & \sigma_k \end{bmatrix} \begin{bmatrix} -v_1^* & \\ & \ddots & \\ & & -v_k^* \end{bmatrix}}_{A_k} + \underbrace{\begin{bmatrix} u_{k+1} & \dots & u_n \end{bmatrix} \begin{bmatrix} \sigma_{k+1} & & \\ & \ddots & \\ & & \sigma_n \end{bmatrix} \begin{bmatrix} -v_{k+1}^* & \\ & \ddots & \\ & & -v_n^* \end{bmatrix}}_E
\end{aligned}$$

Thm (Eckart-Young, see L.N.T. lecture 5)

For any  $0 \leq k \leq r$ , we have that

$$\|A - A_k\|_2 = \inf_{\text{rank}(X) \leq k} \|A - X\|_2 = \sigma_{k+1}$$

"Best rank  $k$  approximation of  $A$  is given by  $k$ -truncated SVD of  $A$ ."

$\Rightarrow$  To solve (\*), choose  $k$  s.t.  $\sigma_{k+1} < \varepsilon$  and set

$$Q = \begin{bmatrix} u_1 & \dots & u_k \end{bmatrix} = U_k$$

Then  $QQ^*A = A_k$ , so

$$\|A - QQ^*A\|_2 = \sigma_{k+1} < \varepsilon. \quad \checkmark$$

## Randomized "Sketch"

Truncated SVD of  $A$  is best low-rank approx, but too expensive to compute.

Idea: Try to approximate  $\text{span}(U_k)$ , the dominant singular vectors of  $A$ , with a single power iteration.

Intuition 1: Suppose  $A$  has exactly rank  $k$ , so that  $A = A_k$  and  $\epsilon_k > 0$ .

$$\begin{matrix} W \\ \left[ \begin{array}{c} | \\ w_1 \dots w_k \\ | \end{array} \right] = \left[ \begin{array}{c} | \\ u_1 \dots u_k \\ | \end{array} \right] \left[ \begin{array}{c} G_1 \dots G_k \end{array} \right] \left[ \begin{array}{c} - \\ v_1^* \\ \vdots \\ v_k^* \\ - \end{array} \right] \left[ \begin{array}{c} X \\ | \\ x_1 \dots x_k \\ | \end{array} \right] \\ \uparrow \qquad \qquad \qquad U_k \qquad \qquad \qquad \Sigma_k \qquad \qquad \qquad V_k \qquad \qquad \qquad \uparrow \\ \text{random} \qquad \qquad \qquad \qquad \qquad \qquad \qquad \qquad \qquad \text{random} \\ \text{samples} \qquad \qquad \qquad \qquad \qquad \qquad \qquad \qquad \qquad \text{vectors} \\ \text{from } \text{span}\{u_1, \dots, u_k\} \end{matrix}$$

W has lin. indep. columns as long as

$$V_k^* X \text{ has full rank, } \text{rank}(V_k^* X) = k.$$

$\Rightarrow$  for i.i.d. normal entries of  $X$ , this happens almost surely.

To get a ONB, we orthonormalize

$\Rightarrow$  compute  $W = QR$

$$\therefore \|A - QQ^*A\|_2 = \sigma_{k+1} = 0 \quad \text{a.s.}$$

Intuition 2: Now, let  $A = A_k + E$  as before  
so that  $\|E\|_2 = \sigma_{k+1} < \epsilon$ .

$$\tilde{W}_i = Ax_i = A_k x_i + E x_i$$

$$\tilde{W} = W + EX$$

$\uparrow$  basis for span( $A_k$ ) as before       $\uparrow$  small perturbation

The span of  $\tilde{W}$  is a good approx to  $W$   
with high probability as long as we  
oversample, taking  $x_i$  for  $1 \leq i \leq k + p$   
 $\uparrow$   
oversampling  
param.