

Optimization

Part 1: Steepest Descent : Conjugate Gradients

Recap

CG Iteration (Symmetric Positive Definite A)

$$x_0 = 0, r_0 = b, p_0 = r_0$$

for $n = 1, 2, 3, \dots$

$$\alpha_n = (r_n^T r_n) / (p_n^T A p_n)$$

step size

$$x_n = x_{n-1} + \alpha_n p_{n-1}$$

approx. soln.

$$r_n = r_{n-1} - \alpha_n A p_{n-1}$$

residual

$$\beta_n = (r_n^T r_n) / (r_{n-1}^T r_{n-1})$$

improvement

$$p_n = r_n + \beta_n p_{n-1}$$

search direction

Residuals r_0, r_1, \dots, r_{n-1} form ONB for $K_n(A, b)$

Directions p_0, p_1, \dots, p_{n-1} form A-ONB for $K_n(A, b)$

x_n minimizes $\|e\|_A = \sqrt{(x - x_n)^T A (x - x_n)}$ over $K_n(A, b)$

Distinct from GMRES (in part) because

- a) builds ONBs using short recurrences (symmetry of A)
- b) minimizes $\|e\|_A$ instead of $\|e\|_2$ (SPD)

CG and Polynomial Approximation

Like Arnoldi, GMRES, Lanczos: CG convergence closely linked to polynomial approximation.

$$e_n = p_n(A)e_0 \quad \text{for degree } n \text{ poly with } \overbrace{p_n(0)=1}^{P_n}.$$

$$(*) \quad \|p_n(A)e_0\|_A = \text{minimum over all } p_n \in P_n$$

Thm 1 If A is SPD and $\alpha_1 \neq 0$, then $(*)$ has a unique soln $p_n \in P_n$, and

$$\frac{\|e_n\|_A}{\|e_0\|_A} = \inf_{p \in P_n} \frac{\|p(A)e_0\|_A}{\|e_0\|_A} \leq \inf_{p \in P_n} \max_{\lambda \in \Lambda(A)} |p(\lambda)|$$

where $\Lambda(A)$ is the spectrum of A .

Sketch PF / SPD A has $A = V\Lambda V^*$ with $V^*V = I$.

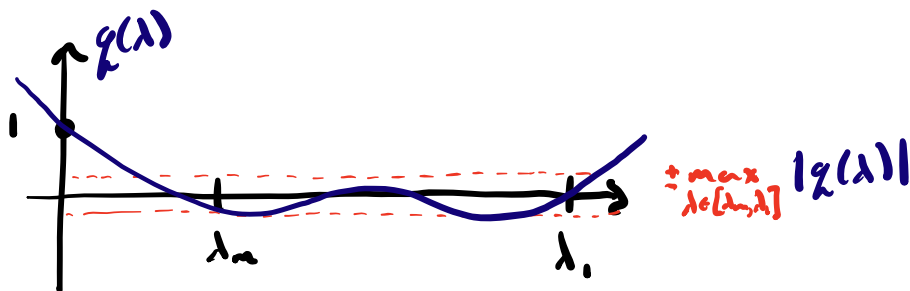
Plug in eigendecomposition to $(*)$ and simplify

Rate of Convergence

Since $\Lambda(A) \subset [\lambda_n, \lambda_1] \subset \{x \in \mathbb{R} : x > 0\}$, we can develop explicit bounds on the rate of convergence $\|e_n\|_A / \|e_0\|_A$.

Idea: look for polynomial $q_n(x)$ that is small on $[\lambda_n, \lambda_1]$ and has $q_n(0)=1$.

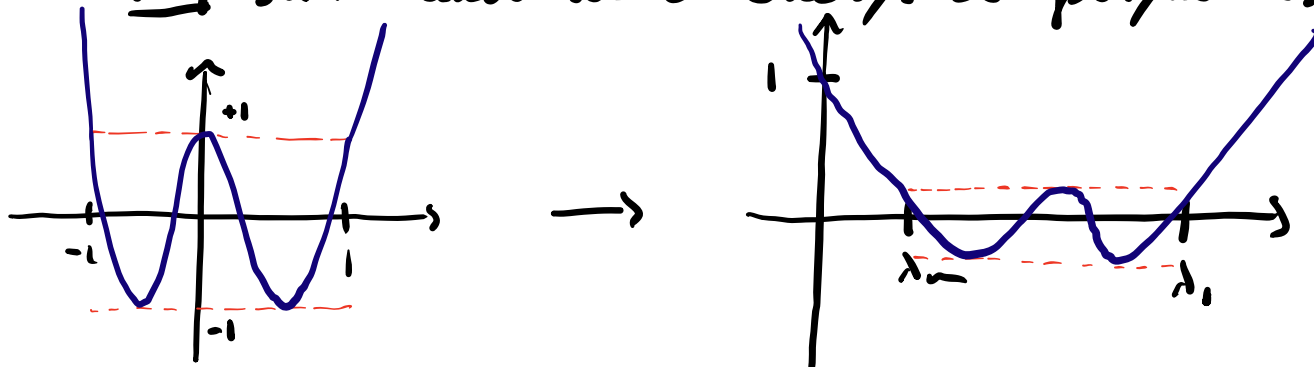
$$\Rightarrow \frac{\|e_n\|_A}{\|e_0\|_A} \leq \inf_{p \in \mathcal{P}_n} \max_{\lambda \in \Lambda(A)} |p(\lambda)| \leq \max_{\lambda \in [\lambda_n, \lambda_1]} |q_n(\lambda)|$$



Thm 2 Let SPD A have 2-norm condition number $\kappa = \lambda_1/\lambda_n$. Then CG A -norm error after n iterations satisfy

$$\frac{\|e_n\|_A}{\|e_0\|_A} \leq \frac{2}{\left[\left(\frac{\sqrt{\kappa}+1}{\sqrt{\kappa}-1} \right)^n + \left(\frac{\sqrt{\kappa}-1}{\sqrt{\kappa}+1} \right)^n \right]} \leq 2 \left(\frac{\sqrt{\kappa}-1}{\sqrt{\kappa}+1} \right)^n$$

Sketch PF Shift and scale Chebyshev polynomials



Note: for moderately ill-conditioned matrices

$$\# \text{ iterations} = \mathcal{O}(\sqrt{\kappa} \log \varepsilon_{\text{mach}})$$

to reach $\|e_n\|_A / \|e_0\|_A \leq \varepsilon_{\text{mach}}$.

CG : Optimization

CG Iterations can also be understood as an improved first-order (gradient based) optimization routine. CG minimizes

$$\begin{aligned} \|e_n\|_A^2 &= (x - x_n)^* A (x - x_n) \\ &= x_n^* A x_n - 2x_n^* A x + x^* A x \\ &= \underbrace{x_n^* A x_n - 2x_n^* b}_{\varphi(x_n)} + \underbrace{x^* b}_{\text{const}} \end{aligned}$$

CG minimizes $\varphi(x) = \frac{1}{2} x^* A x - x^* b$

over $K_n(A, b)$, by taking "steps" in

the search direction p_{n-1} , of length α_n .

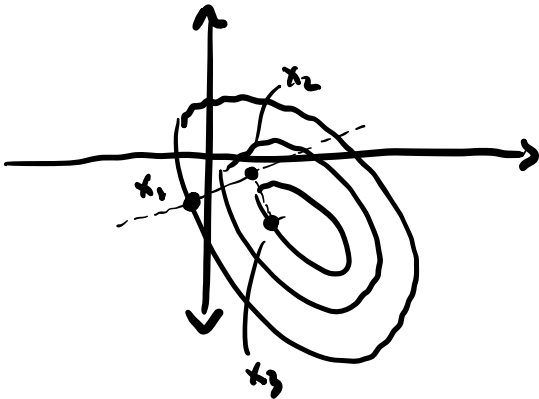
Steepest Descent (Gradient Descent)

Task: minimize smooth function $\phi: \mathbb{R}^d \rightarrow \mathbb{R}$.

Idea: starting from point x , walk "downhill" along the steepest slope.

The direction of steepest slope at point $x \in \mathbb{R}^d$ is given by $-\nabla \phi|_{x=x}$.

E.g. $\phi(x) = \frac{1}{2}x^T A x - x^T b$



$$\begin{aligned}\nabla \phi(x) &= \frac{1}{2} A^T x + \frac{1}{2} A x - b \\ &= A x - b \\ &= r\end{aligned}$$

To minimize $\phi(x)$ along line $x - \alpha r$

need $\alpha = \frac{r^T r}{r^T A r}$.

Steepest Descent for $\mathcal{D}(x)$

1. Compute $r_n = b - Ax_n$
 $= r_{n-1} - \alpha_{n-1} Ar_{n-1}$

Gradient

2. $\alpha_n = r_n^T r_n / r_n^T A r_n$

step length

3. $x_{n+1} = x_n + \alpha_n r_n$

update