



Translational Neuromodeling Unit



University of
Zurich^{UZH}

ETH

Eidgenössische Technische Hochschule Zürich
Swiss Federal Institute of Technology Zurich

GENERATIVE MODELS OF FMRI DATA: DCM WITH A SPECIAL INTRO TO RDCM

JAKOB HEINZLE + STEFAN FRÄSSEL

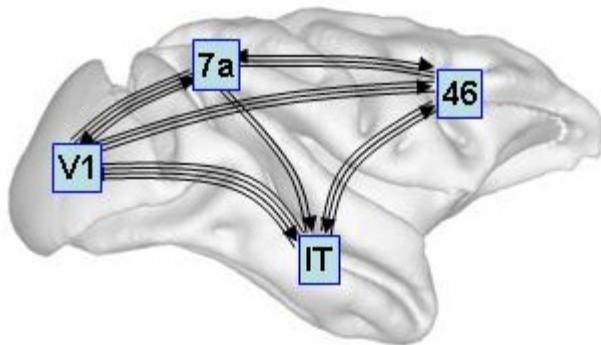
TRANSLATIONAL NEUROMODELING UNIT (TNU)
UNIVERSITY OF ZURICH & ETH ZURICH

Translational Neuromodeling (FS 2021)

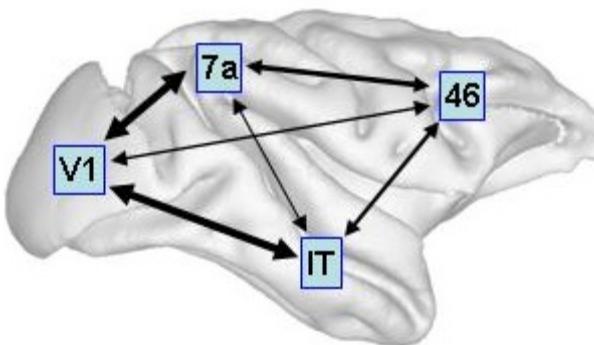
Zurich, 30 March, 2021

DIFFERENT FORMS OF BRAIN CONNECTIVITY

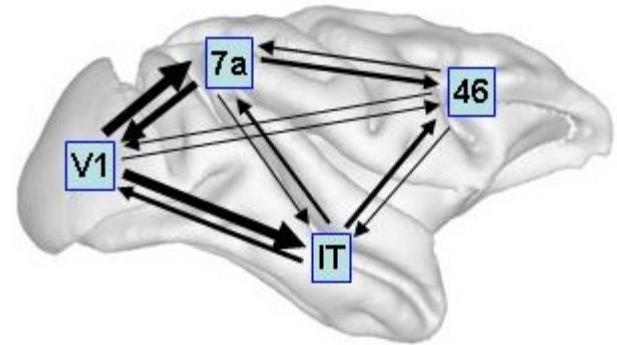
structural connectivity



functional connectivity



effective connectivity



- presence of physical connections
- Diffusion weighted imaging (DWI), tractography, tracer studies

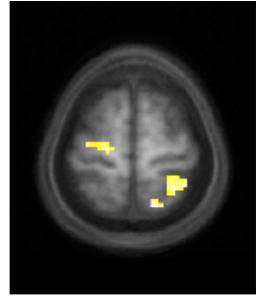
- statistical dependencies between regional time series
- correlations, Independent Component Analysis (ICA)

Ideally, we would like to have:
Parameters of an underlying network model, including directed connectivity.

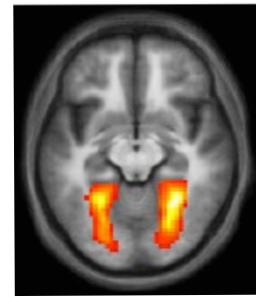
Sporns, 2007, Scholarpedia

FROM FUNCTIONAL SEGREGATION TO FUNCTIONAL INTEGRATION

localizing brain activity:
functional segregation

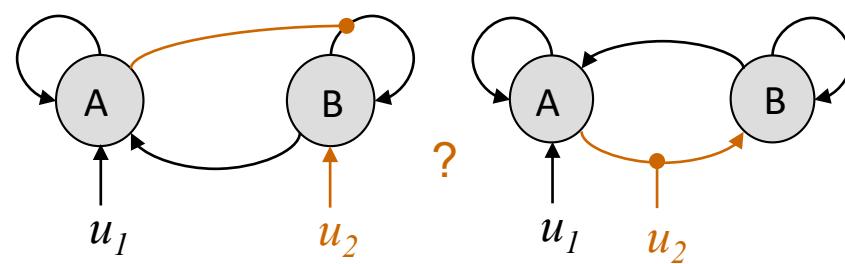


u_1



$u_1 \times u_2$

effective connectivity analysis:
functional integration



« Where, in the brain, did
my experimental manipulation
have an effect? »

« How did my experimental manipulation
propagate through the network? »

DYNAMIC CAUSAL MODELING



ACADEMIC
PRESS

Available online at www.sciencedirect.com



NeuroImage 19 (2003) 1273–1302

NeuroImage

www.elsevier.com/locate/ynimng

Dynamic causal modelling

K.J. Friston,* L. Harrison, and W. Penny

The Wellcome Department of Imaging Neuroscience, Institute of Neurology, Queen Square, London WC1N 3BG, UK

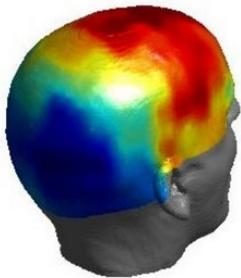
Received 18 October 2002; revised 7 March 2003; accepted 2 April 2003

- Dynamic causal modeling (DCM) for functional magnetic resonance imaging (fMRI) data was introduced in 2003 by Karl Friston, Lee Harrison and Will Penny (*NeuroImage* 19:1273–1302)

Friston et al., 2003, *NeuroImage*

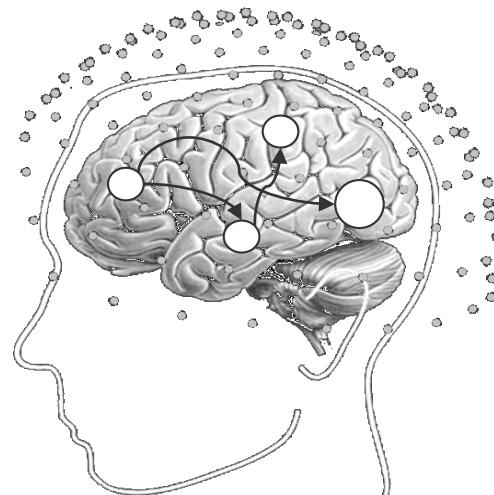
DYNAMIC CAUSAL MODELING

EEG, MEG

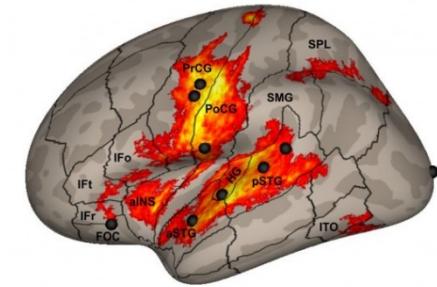


Forward model:
Predicting measured
activity

$$y = g(x, \theta) + \varepsilon$$



fMRI



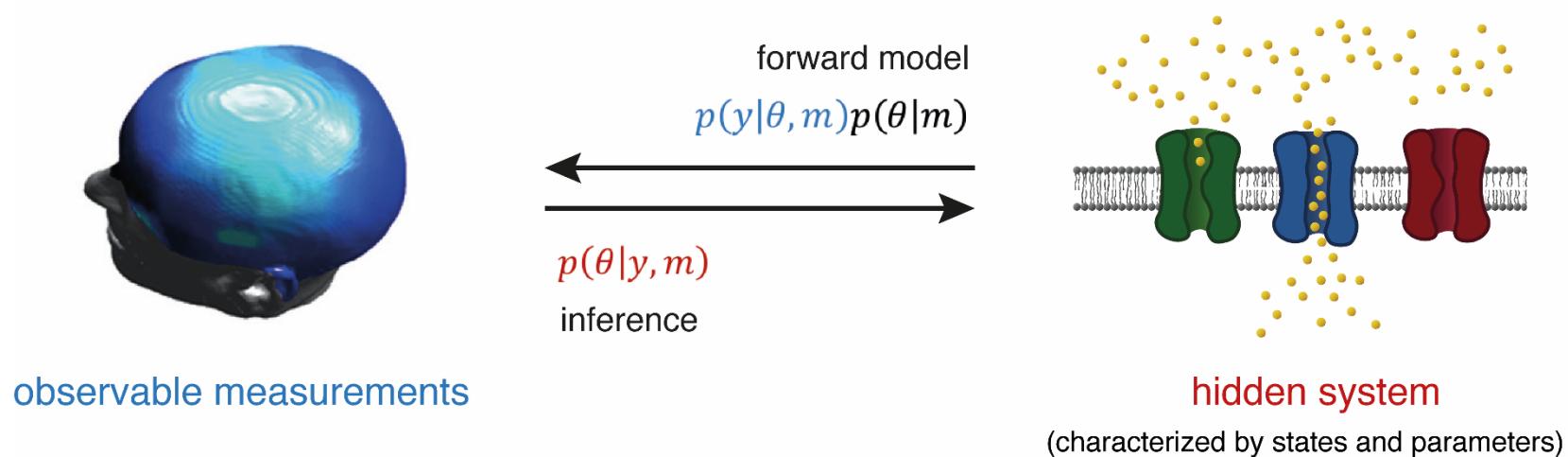
<http://sites.bu.edu/guentherlab/>

Model inversion:
Estimating neuronal
mechanisms

$$\frac{dx}{dt} = f(x, u, \theta) + \omega$$

Friston et al., 2003, *NeuroImage*; David et al., 2006, *NeuroImage*

GENERATIVE MODEL



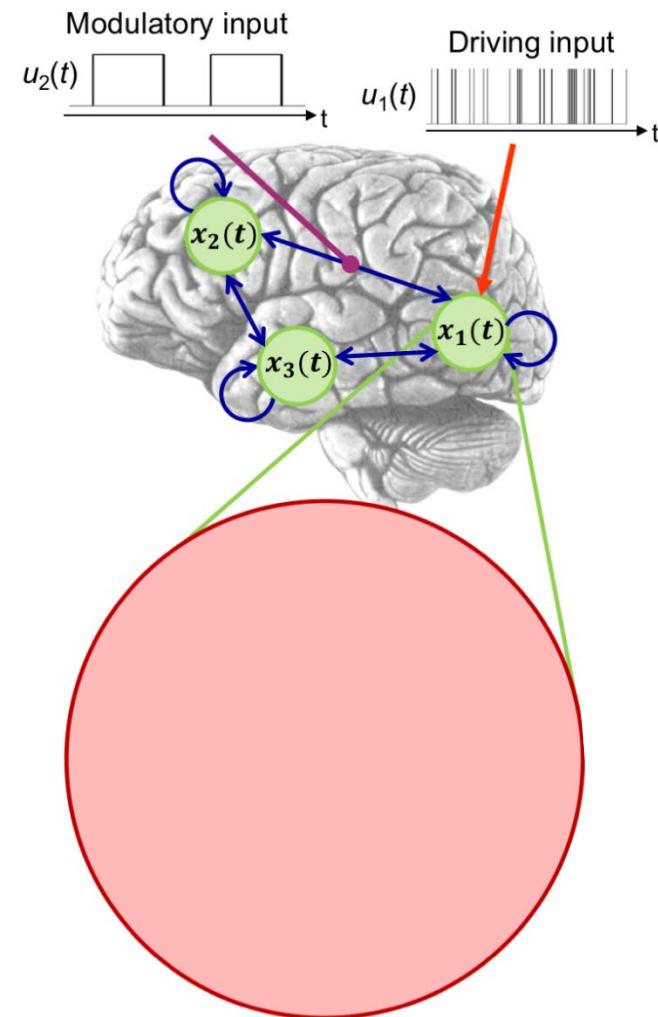
1. enforces mechanistic thinking: how could the data have been caused?
2. generate synthetic data (observations) by sampling from the prior – can the model explain certain phenomena at all?
3. inference about model structure: formal approach to disambiguating mechanisms → $p(m|y)$
4. inference about model parameters → $p(\theta|y, m)$

Stephan et al., 2016, *Front. Hum. Neurosci.*; Frässle et al., in press, *Wiley Interdiscip. Rev. Cogn. Sci.*

THEORY



DCM FOR FMRI (OVERVIEW)



Neural state equation

$$\dot{x} = \left(A + \sum u_j B^{(j)} \right) x + Cu$$

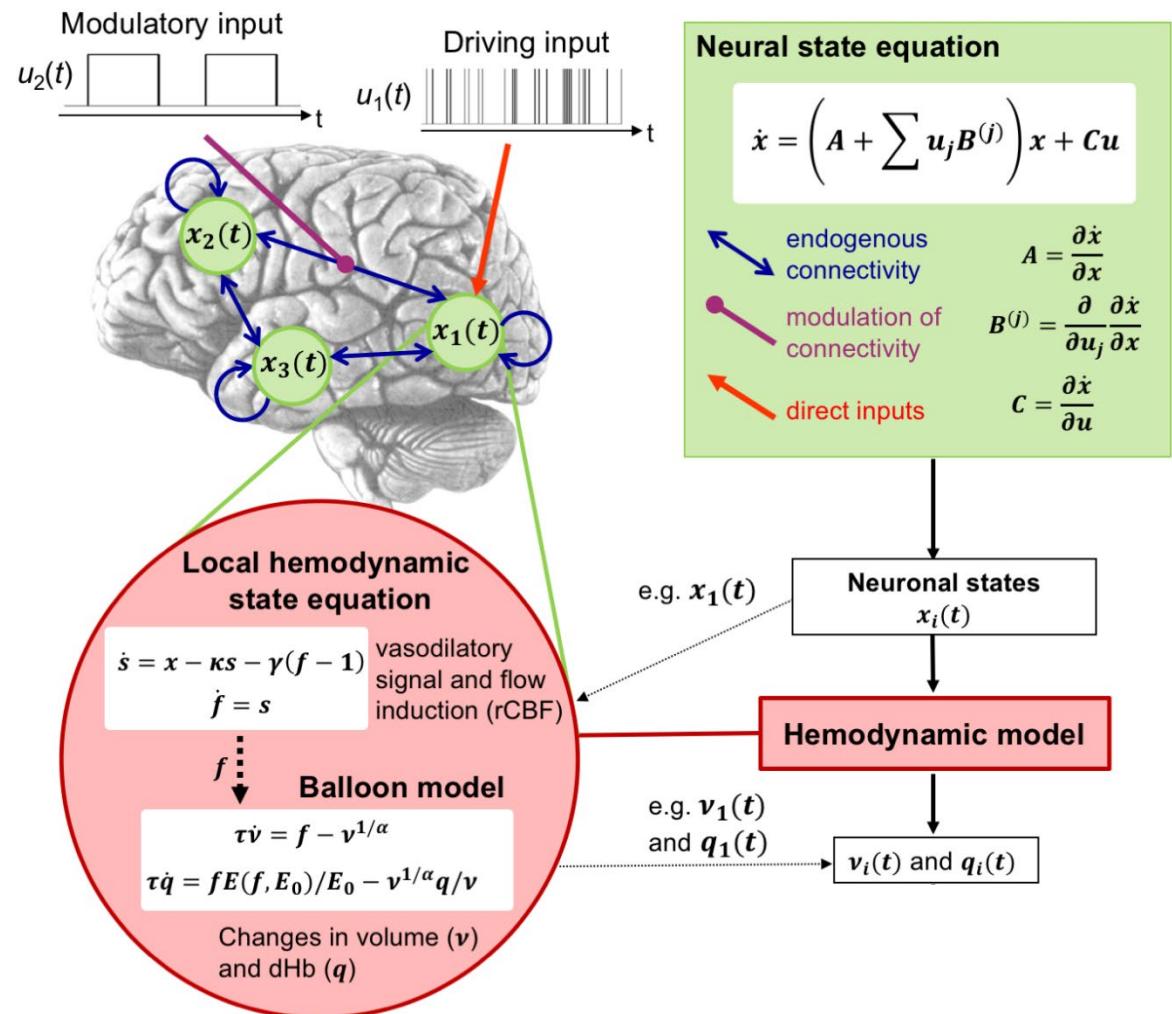
- endogenous connectivity
- modulation of connectivity
- direct inputs

$$A = \frac{\partial \dot{x}}{\partial x}$$
$$B^{(j)} = \frac{\partial \dot{x}}{\partial u_j \partial x}$$
$$C = \frac{\partial \dot{x}}{\partial u}$$

↓
Neuronal states
 $x_i(t)$

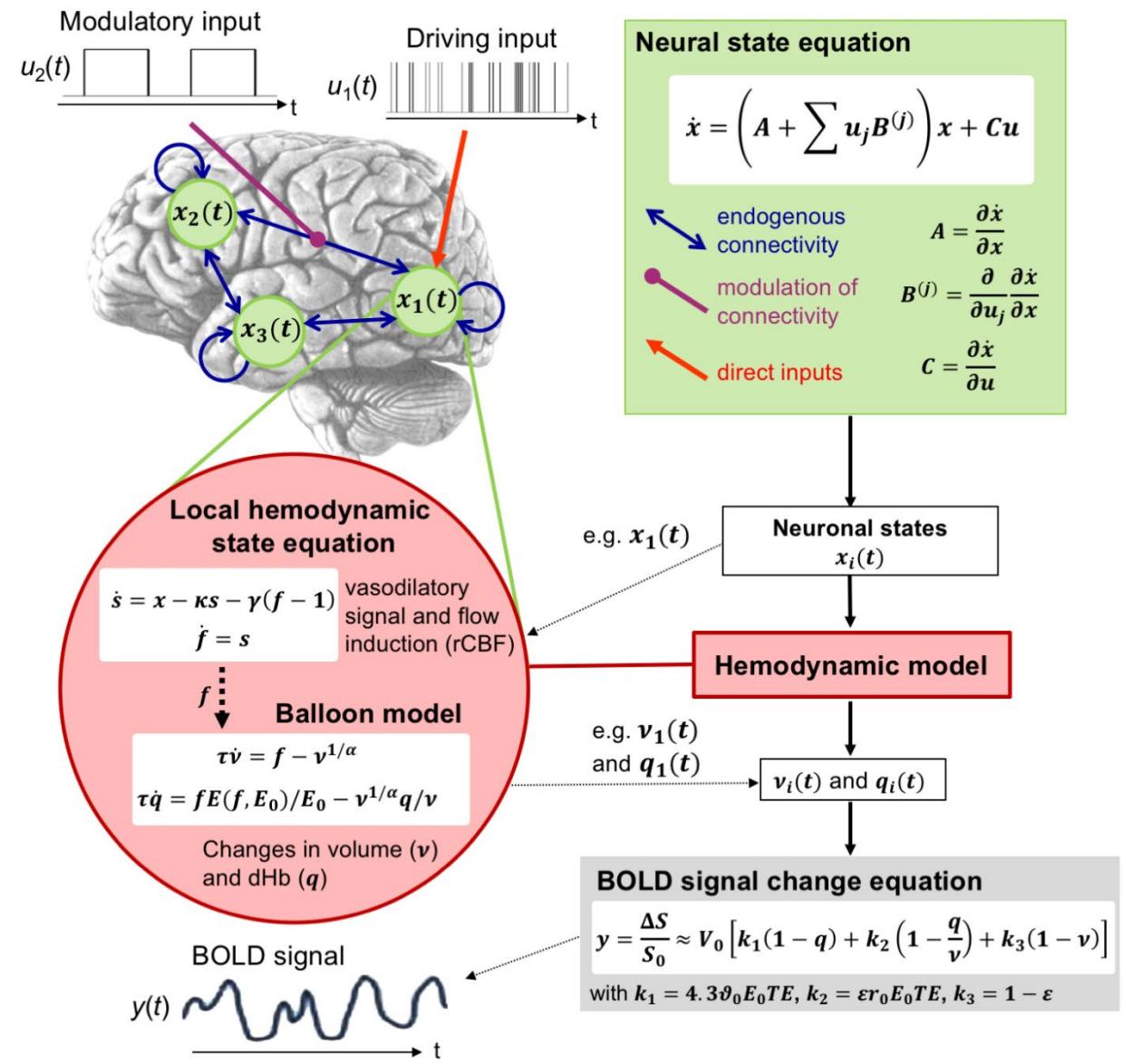
Friston et al., 2003, *NeuroImage*; Stephan et al., 2015, *Neuron*

DCM FOR FMRI (OVERVIEW)



Friston et al., 2003, *NeuroImage*; Stephan et al., 2015, *Neuron*

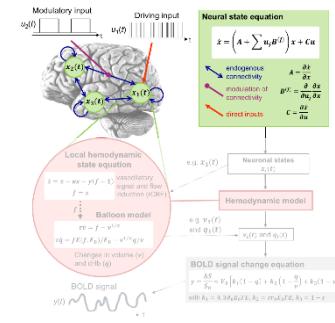
DCM FOR FMRI (OVERVIEW)



Friston et al., 2003, *NeuroImage*; Stephan et al., 2015, *Neuron*

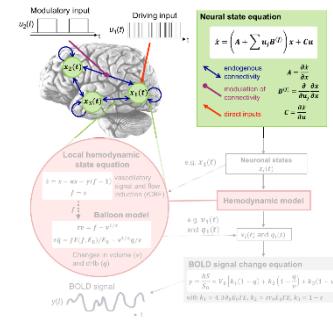
NEURONAL STATE EQUATION

$$\frac{dx}{dt} = f(x, u)$$



Friston et al., 2003, *NeuroImage*; Stephan et al., 2008, *NeuroImage*

NEURONAL STATE EQUATION

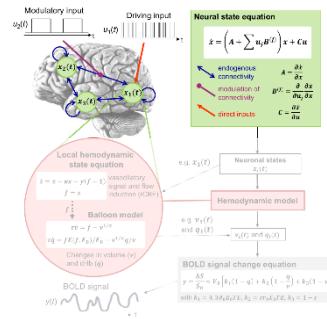


$$\frac{dx}{dt} = f(x, u) \approx f(x_0, 0) + \frac{\partial f}{\partial x} x + \frac{\partial f}{\partial u} u + \frac{\partial^2 f}{\partial x \partial u} ux + \frac{\partial^2 f}{\partial x^2} \frac{x^2}{2} + \dots$$

bilinear model

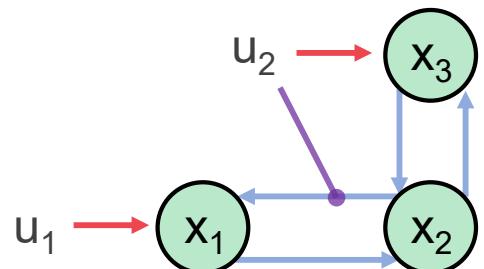
Friston et al., 2003, *NeuroImage*; Stephan et al., 2008, *NeuroImage*

NEURONAL STATE EQUATION

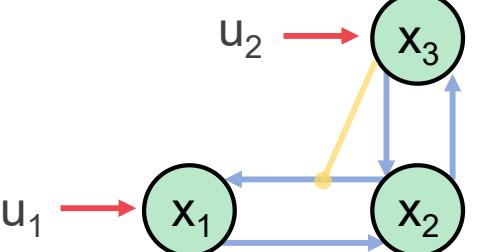


$$\frac{dx}{dt} = f(x, u) \approx f(x_0, 0) + \frac{\partial f}{\partial x} x + \frac{\partial f}{\partial u} u + \frac{\partial^2 f}{\partial x \partial u} u x + \frac{\partial^2 f}{\partial x^2} \frac{x^2}{2} + \dots$$

bilinear model



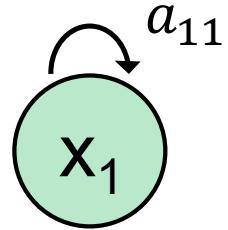
nonlinear model



Friston et al., 2003, *NeuroImage*; Stephan et al., 2008, *NeuroImage*

NEURONAL STATE EQUATION

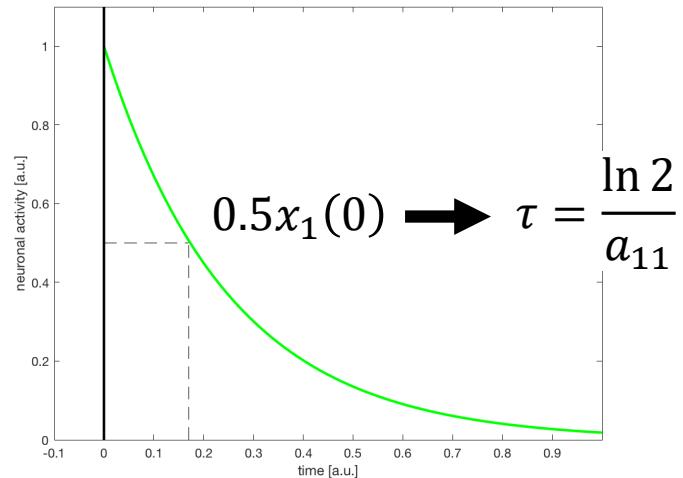
DCM effective connectivity parameters are rate constants



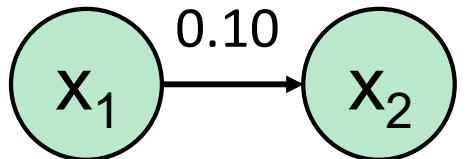
$$\frac{dx_1}{dt} = a_{11}x_1$$



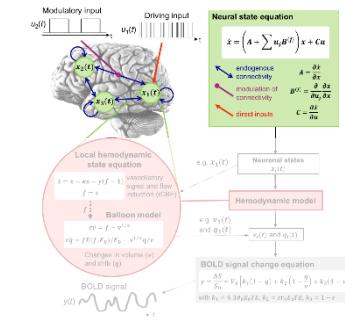
$$x_1(t) = x_1(0) \cdot \exp(a_{11}t)$$



Friston et al., 2003, *NeuroImage*

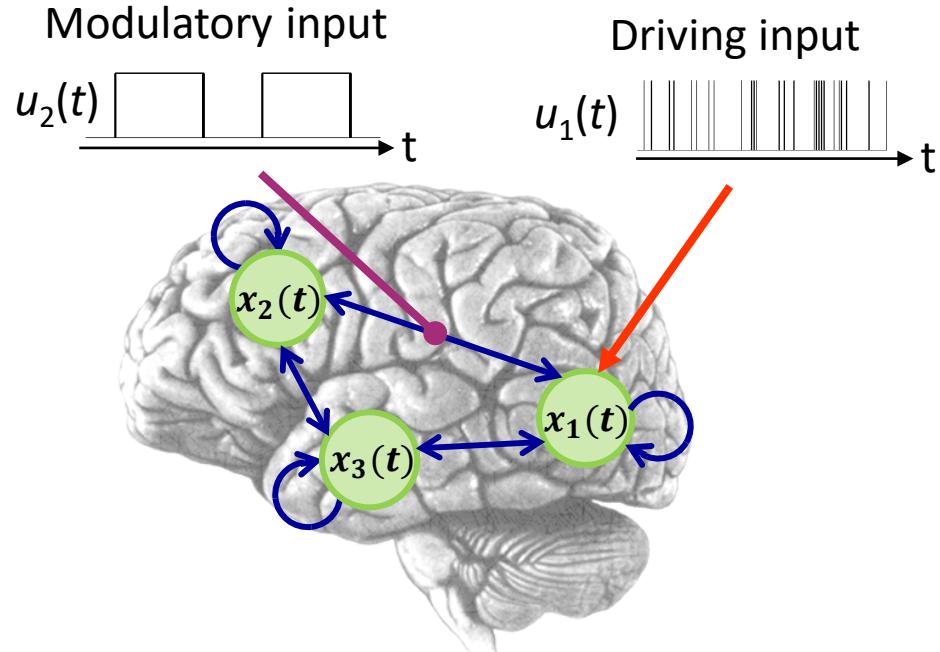


If $x_1 \rightarrow x_2$ is 0.10s^{-1} , this means that, per unit time, the increase in activity in x_2 corresponds to 10% of the current activity in x_1



NEURONAL STATE EQUATION

Interim summary: bilinear neuronal state equation



Friston et al., 2003, *NeuroImage*

$$\frac{dx}{dt} = \left(A + \sum_{j=1}^m u_j B^{(j)} \right) x + Cu$$

State change

Current state

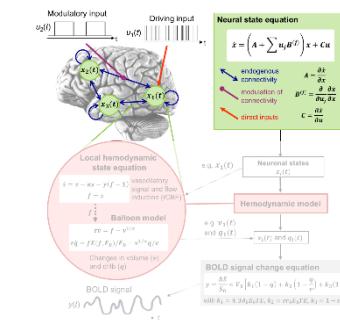
External inputs

$\theta = \{A, B^{(1)}, \dots, B^{(m)}, C\}$

Endogenous connectivity

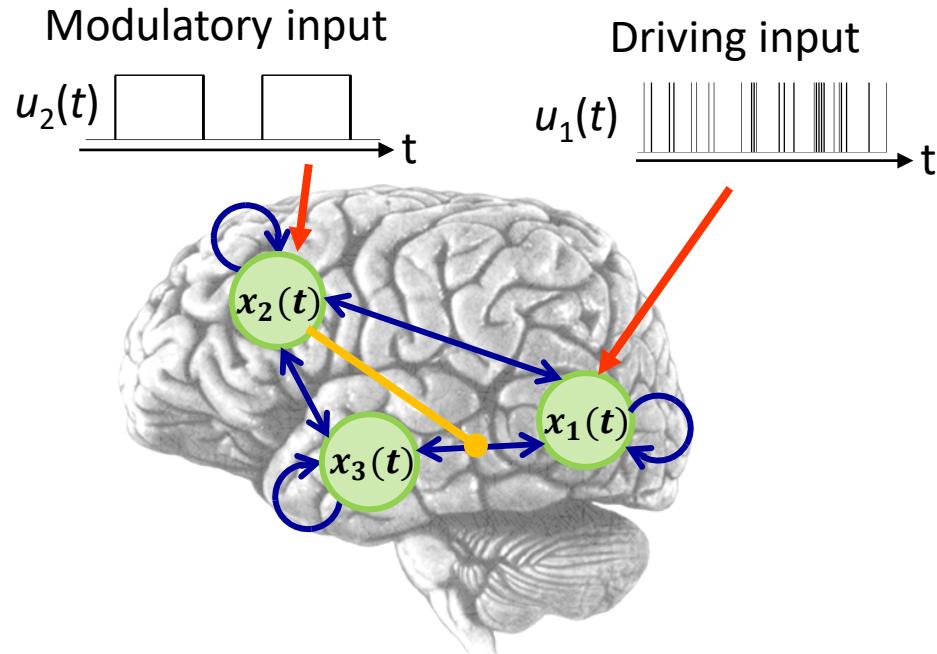
Modulatory connectivity

Driving inputs



NEURONAL STATE EQUATION

Interim summary: non-linear neuronal state equation



Friston et al., 2003, *NeuroImage*

State change

$$\frac{dx}{dt} = \left(A + \sum_{j=1}^m u_j B^{(j)} + \sum_{i=1}^n x_i D^{(i)} \right)$$

Current state

External inputs

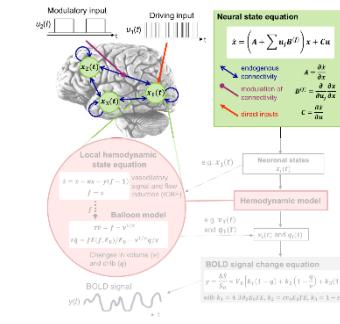
$\theta = \{A, B^{(1)}, \dots, B^{(m)}, C, D^{(1)}, \dots, D^{(n)}\}$

Endogenous connectivity

Modulatory connectivity

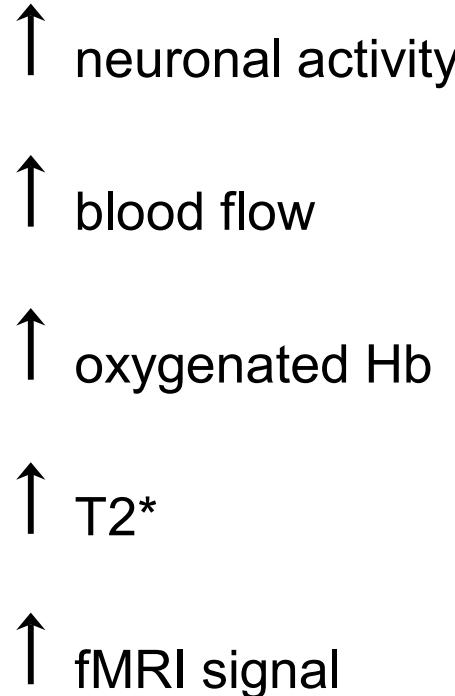
Driving inputs

Modulatory connectivity (non-linear)

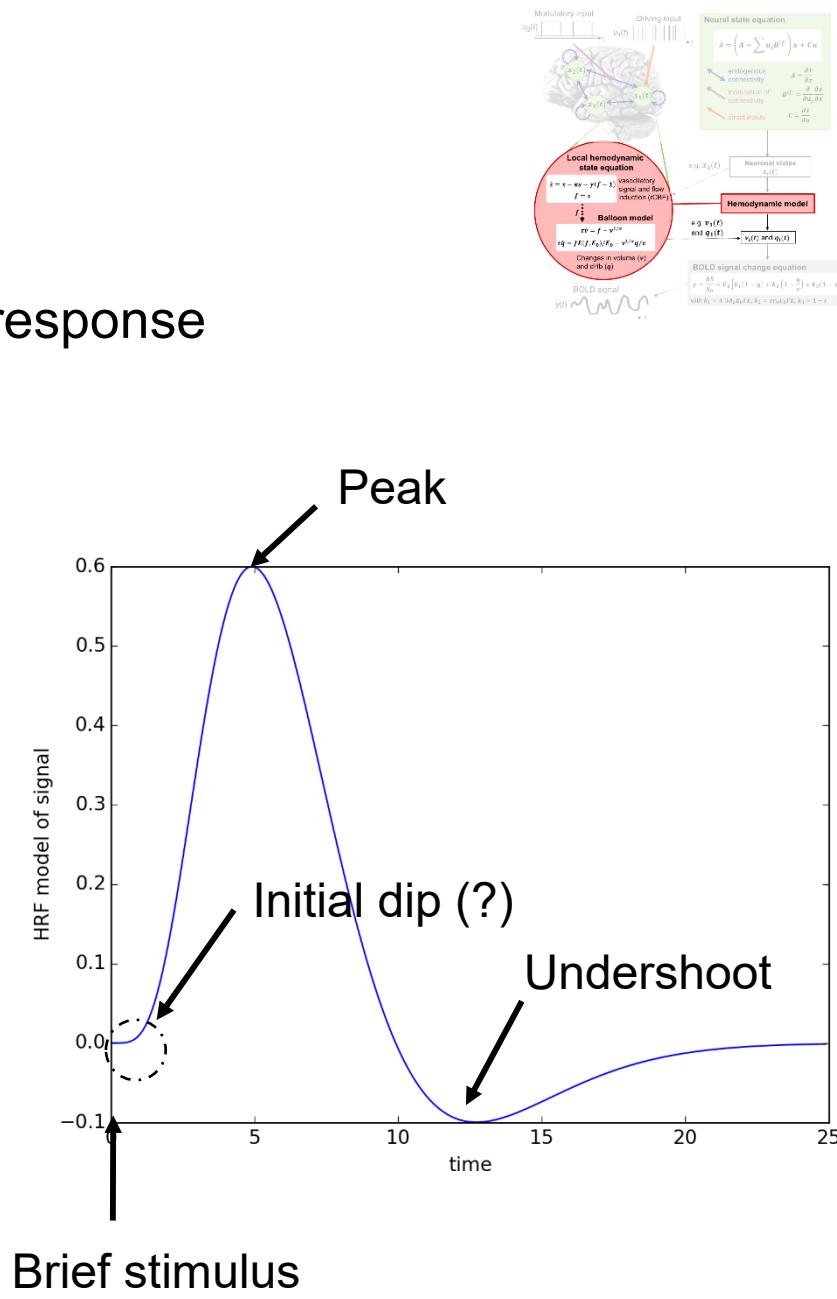
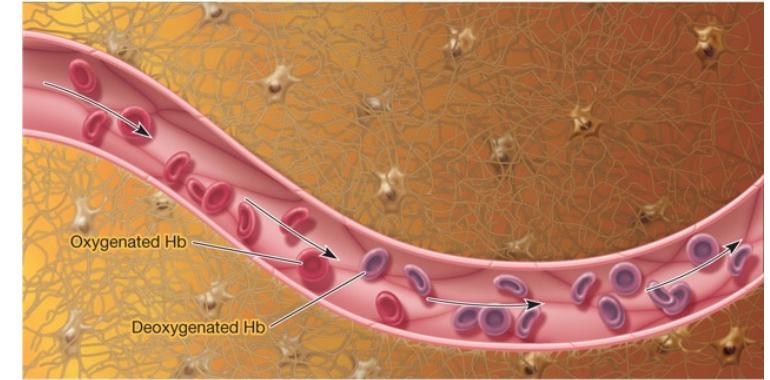


HEMODYNAMIC MODEL

Neuronal dynamics only indirectly observable via hemodynamic response



Huettel et al., 2004, *NeuroImage*



HEMODYNAMIC MODEL

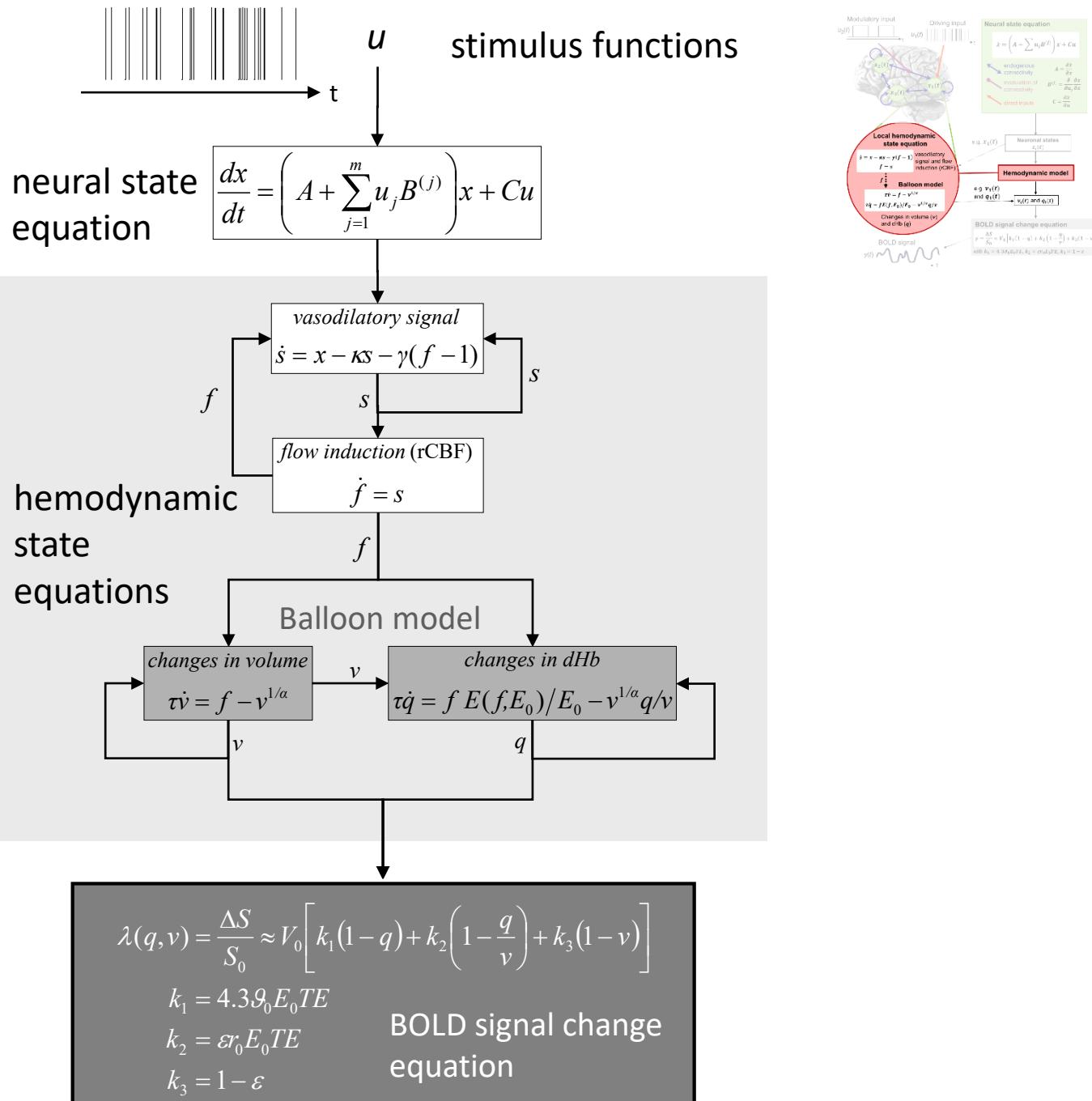
6 hemodynamic parameters:

$$\theta^h = \{\kappa, \gamma, \tau, \alpha, \rho, \varepsilon\}$$

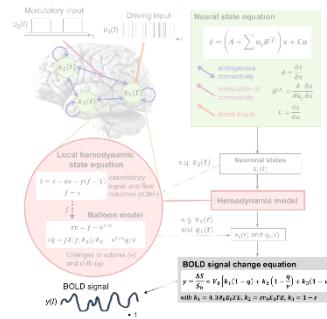
Important for model fitting, but typically of no interest for statistical inference.

Parameters (κ, τ and ε) are computed separately for each region → region specific HRFs!

Friston et al., 2003, *NeuroImage*; Stephan et al., 2007, *NeuroImage*



BOLD SIGNAL CHANGE EQUATION



Resting blood volume Deoxyhemoglobin content Blood volume

$$\lambda(q, v) = \frac{\Delta S}{S_0} \approx V_0 \left[k_1(1 - q) + k_2 \left(1 - \frac{q}{v} \right) + k_3(1 - v) \right]$$

Parameters

$$k_1 = 4.3\vartheta_0 E_0 TE$$

$$k_2 = \varepsilon r_0 E_0 TE$$

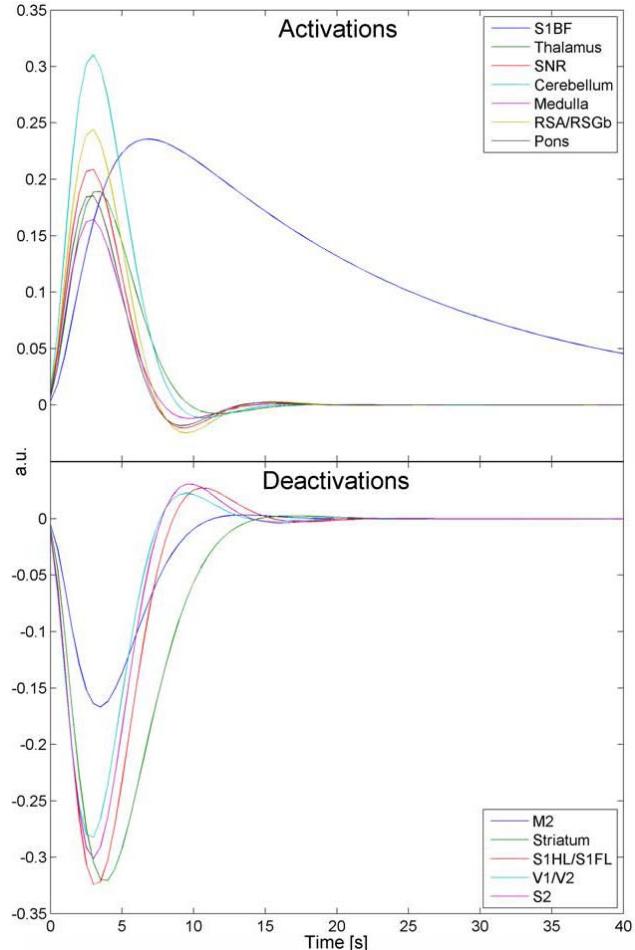
$$k_3 = 1 - \varepsilon$$

Friston et al., 2003, *NeuroImage*; Stephan et al., 2007, *NeuroImage*

$$V_0 = 0.04 \quad E_0 = 0.4$$

At 1.5 Tesla	At 3 Tesla	At 7 Tesla
$\vartheta_0 \approx 40.3 \text{ s}^{-1}$	$\vartheta_0 \approx 80.6 \text{ s}^{-1}$	$\vartheta_0 \approx 188 \text{ s}^{-1}$
$r_0 \approx 25 \text{ s}^{-1}$	$r_0 \approx 110 \text{ s}^{-1}$	$r_0 \approx 340 \text{ s}^{-1}$
$TE \approx 0.04 \text{ s}$	$TE \approx 0.035 \text{ s}$	$TE \approx 0.025 \text{ s}$
$\varepsilon \approx 1.28$	$\varepsilon \approx 0.47$	$\varepsilon \approx 0.026$

HEMODYNAMICS ARE IMPORTANT

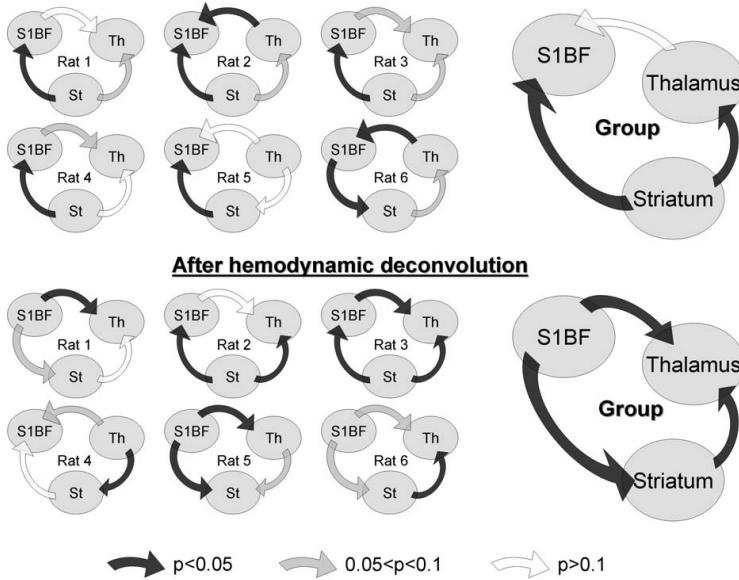


David et al., 2008, *PLoS Biol.*

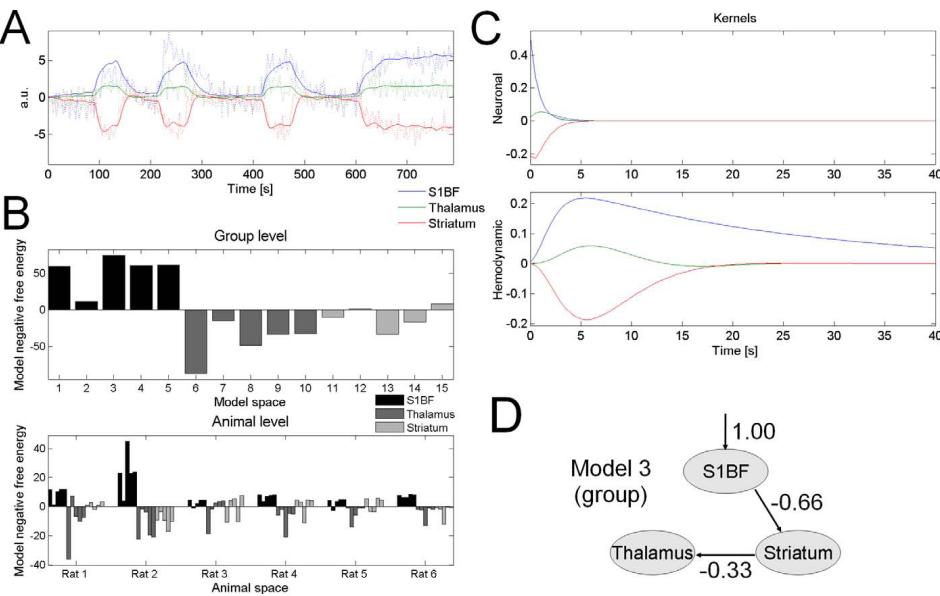
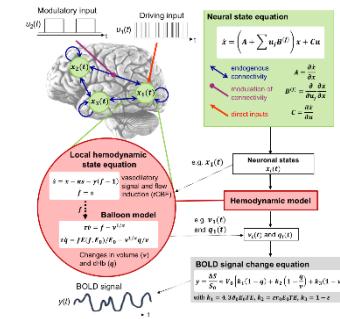
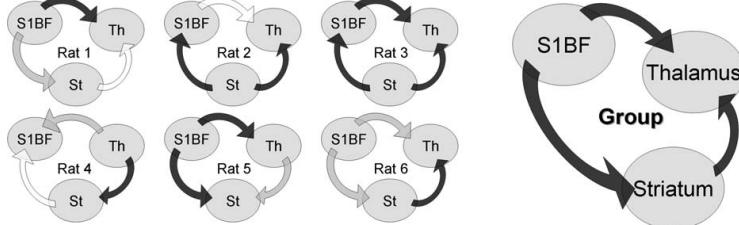
Granger causality

DCM

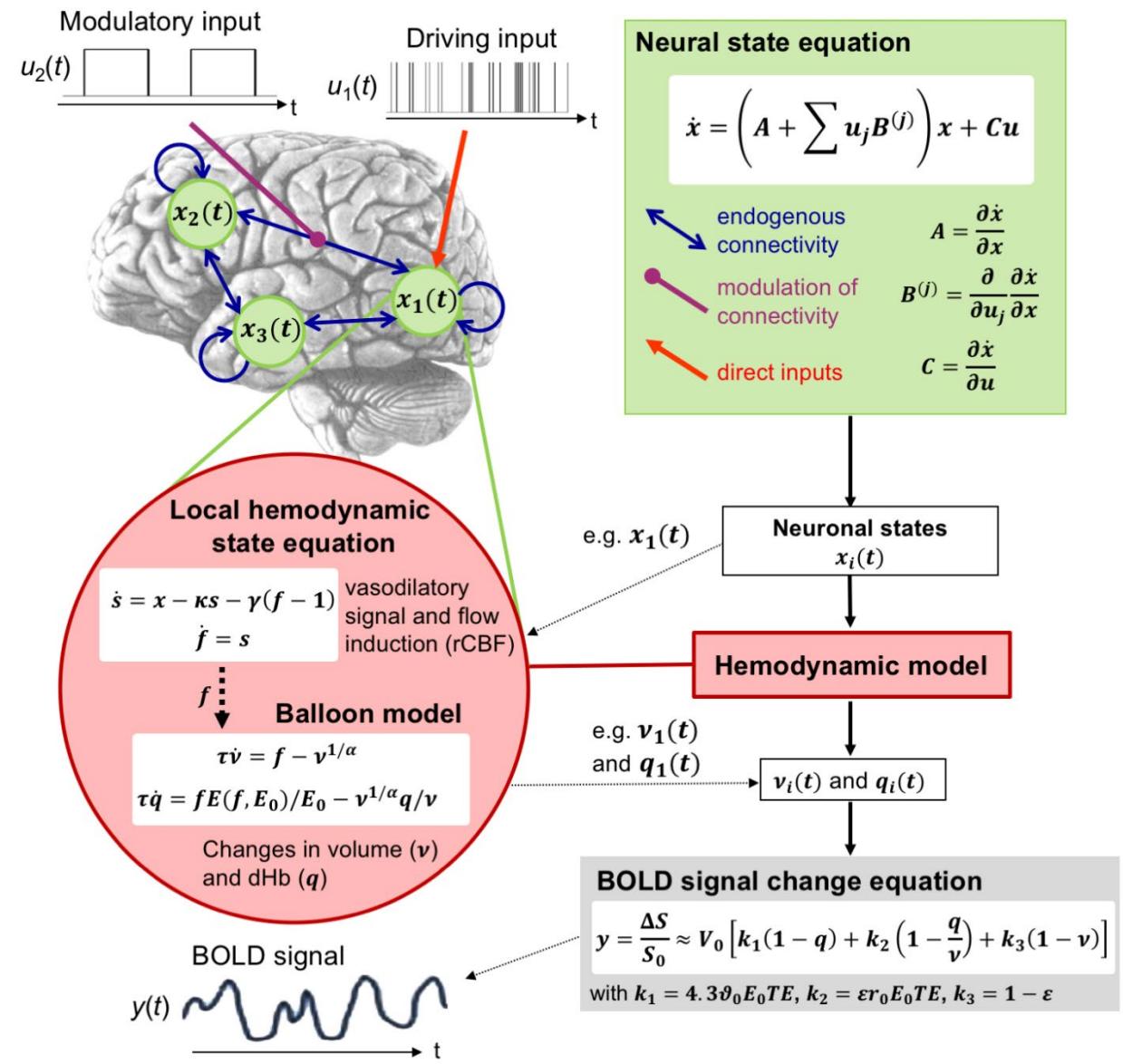
Without hemodynamic deconvolution



After hemodynamic deconvolution



DCM FOR FMRI (OVERVIEW)

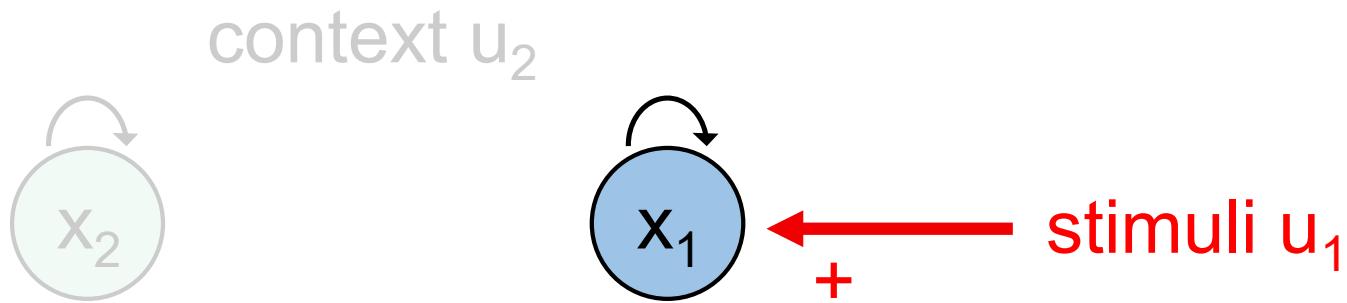


Friston et al., 2003, *NeuroImage*; Stephan et al., 2015, *Neuron*

SIMULATIONS

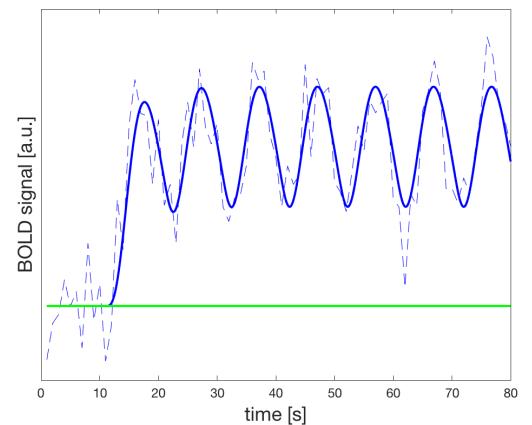
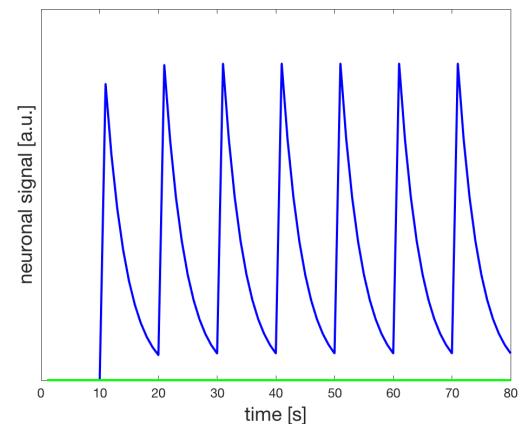
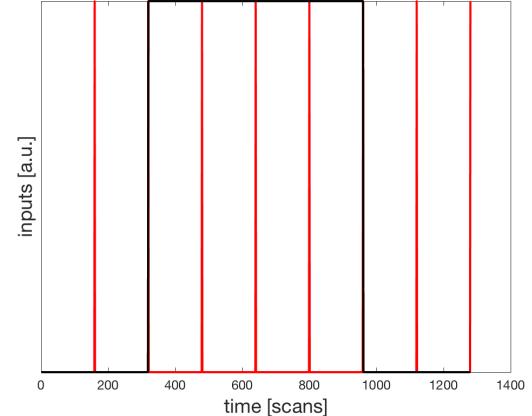
WHAT CAN DCM EXPLAIN?

Example: single node



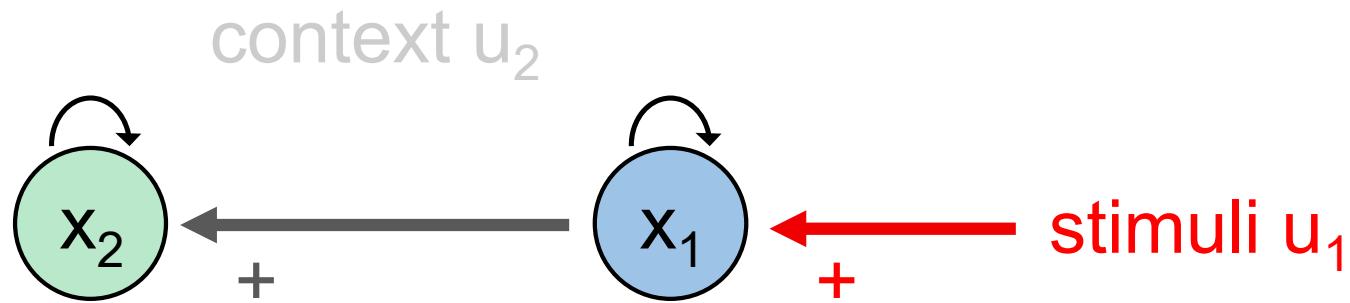
$$\frac{dx}{dt} = Ax + u_2 B^{(2)}x + Cu_1$$

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} a_{11} & 0 \\ 0 & a_{22} \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + u_2 \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} c_{11} & 0 \\ 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$



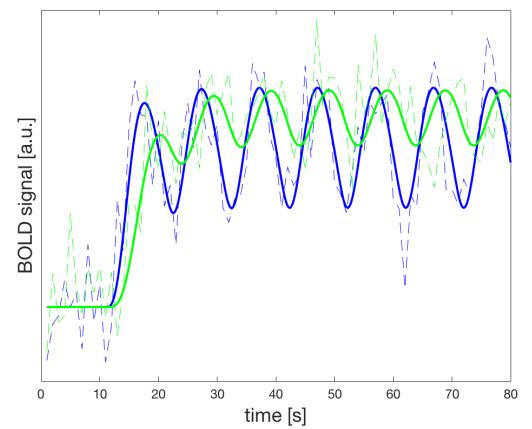
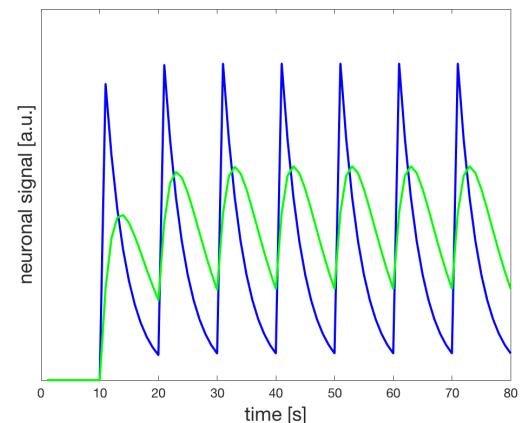
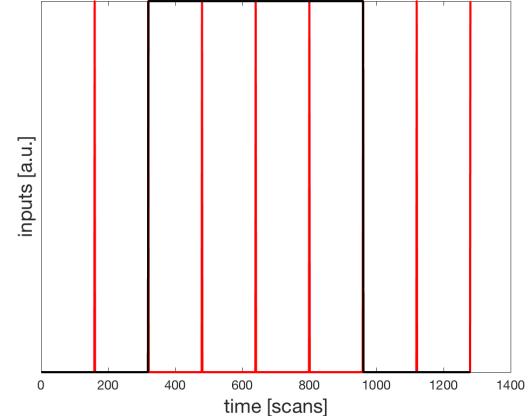
WHAT CAN DCM EXPLAIN?

Example: two connected node



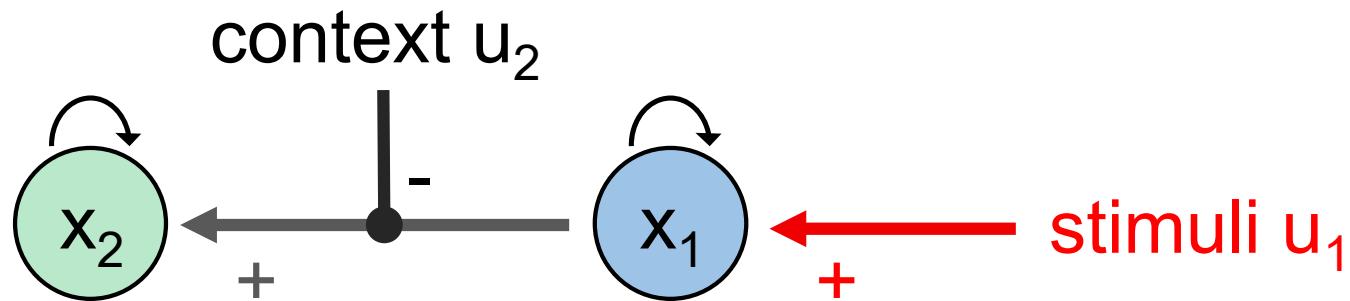
$$\frac{dx}{dt} = Ax + u_2 B^{(2)}x + Cu_1$$

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} a_{11} & 0 \\ a_{21} & a_{22} \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + u_2 \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} c_{11} & 0 \\ 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$



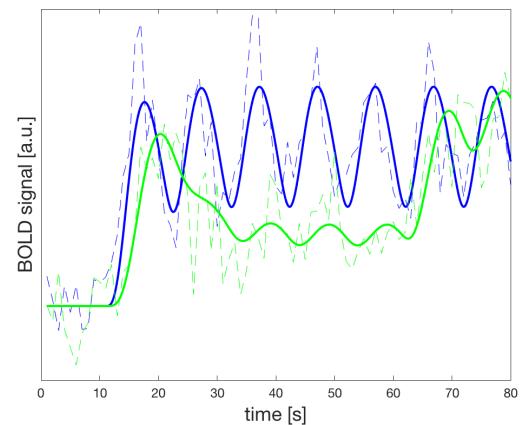
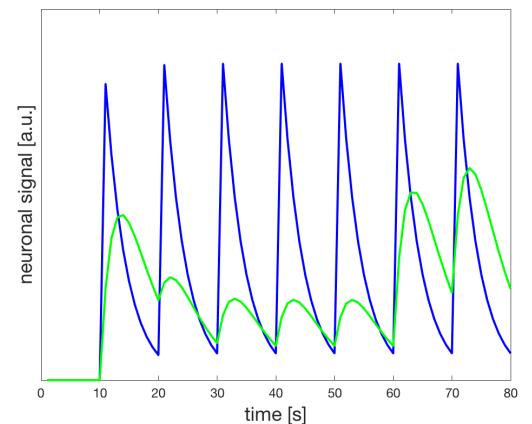
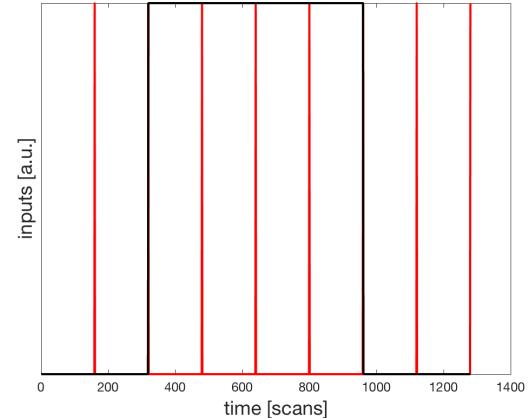
WHAT CAN DCM EXPLAIN?

Example: modulation of connection



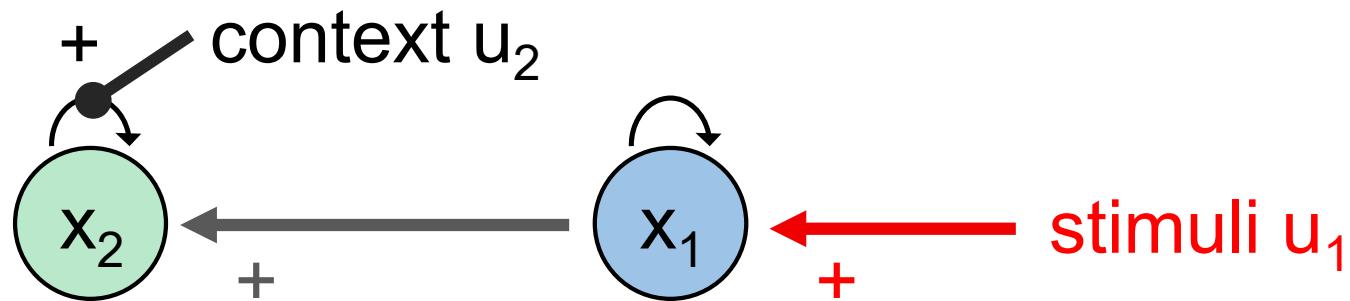
$$\frac{dx}{dt} = Ax + u_2 B^{(2)}x + Cu_1$$

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} a_{11} & 0 \\ a_{21} & a_{22} \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + u_2 \begin{bmatrix} 0 & 0 \\ b_{21}^{(2)} & 0 \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} c_{11} & 0 \\ 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$



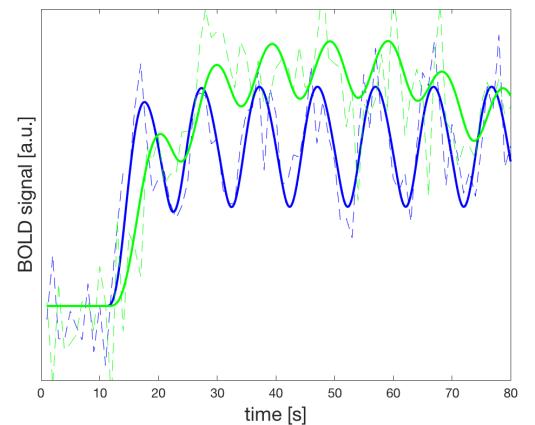
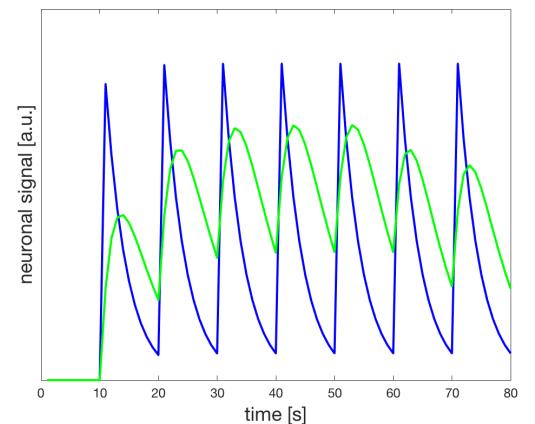
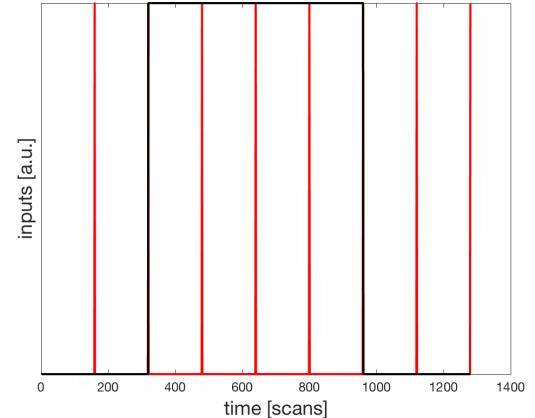
WHAT CAN DCM EXPLAIN?

Example: modulation of inhibitory self-connection



$$\frac{dx}{dt} = Ax + u_2 B^{(2)}x + Cu_1$$

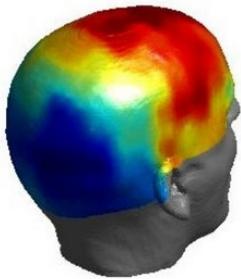
$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} a_{11} & 0 \\ a_{21} & a_{22} \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + u_2 \begin{bmatrix} 0 & 0 \\ 0 & b_{22}^{(2)} \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} c_{11} & 0 \\ 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$



MODEL INVERSION / INFERENCE

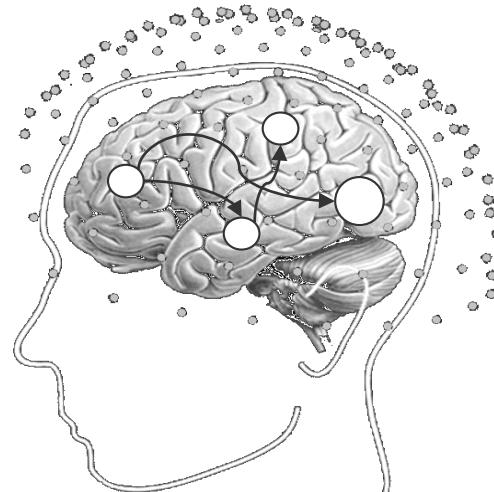
DYNAMIC CAUSAL MODELING

EEG, MEG

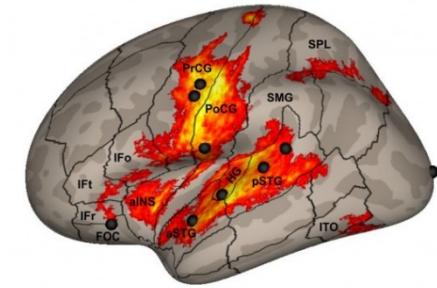


Forward model:
Predicting measured
activity

$$y = g(x, \theta) + \varepsilon$$



fMRI



<http://sites.bu.edu/guentherlab/>

Model inversion:
Estimating neuronal
mechanisms

$$\frac{dx}{dt} = f(x, u, \theta) + \omega$$

Friston et al., 2003, *NeuroImage*; David et al., 2006, *NeuroImage*

BAYES THEOREM

Bayes theorem gives a recipe for evaluating the posterior density by combining new data (likelihood) and prior knowledge



Reverend Thomas Bayes
(1702-1761)

$$p(\theta|y, m) = \frac{p(y|\theta, m)p(\theta|m)}{p(y|m)}$$

The posterior probability of the parameters is an optimal combination of our prior knowledge and the new data that we have acquired

BAYES THEOREM

Bayes theorem gives a recipe for evaluating the posterior density by combining new data (likelihood) and prior knowledge

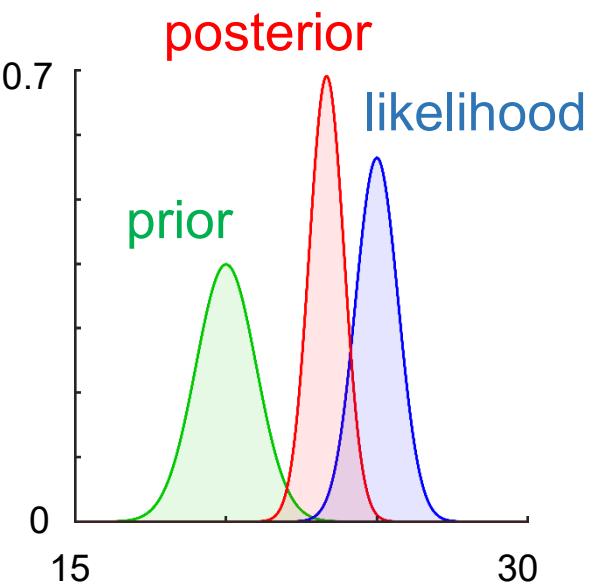
$$p(\theta|y, m) = \frac{p(y|\theta, m)p(\theta|m)}{p(y|m)}$$

posterior likelihood prior
model evidence

The posterior probability of the parameters is an optimal combination of our prior knowledge and the new data that we have acquired



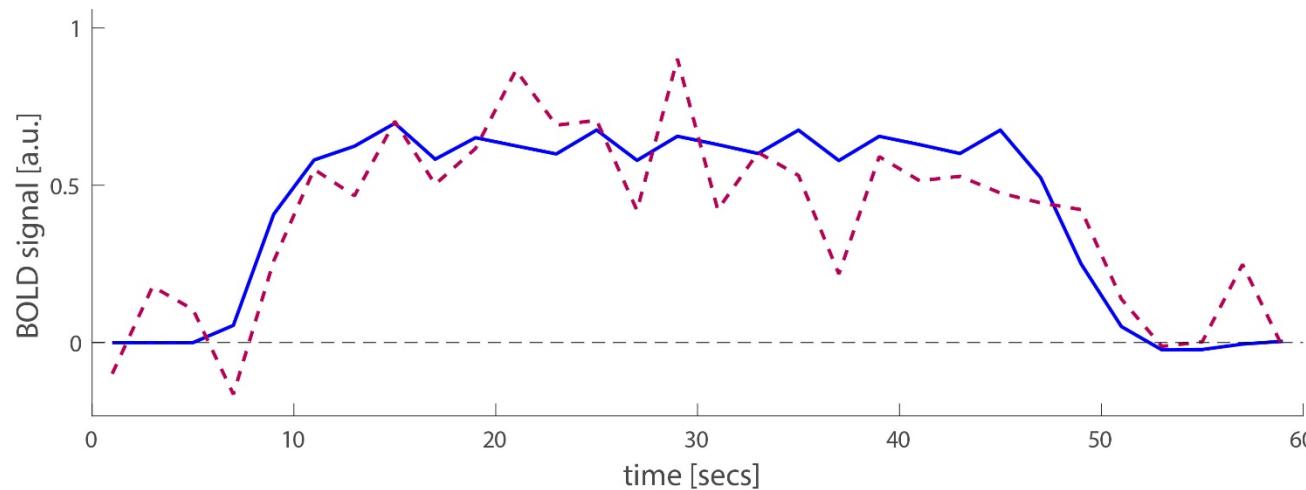
Reverend Thomas Bayes
(1702-1761)



LIKELIHOOD FUNCTION

$$p(y(t)|\theta, m) = \mathcal{N}(y(t); g(\theta^n, \theta^h, u), \theta^\sigma)$$

likelihood

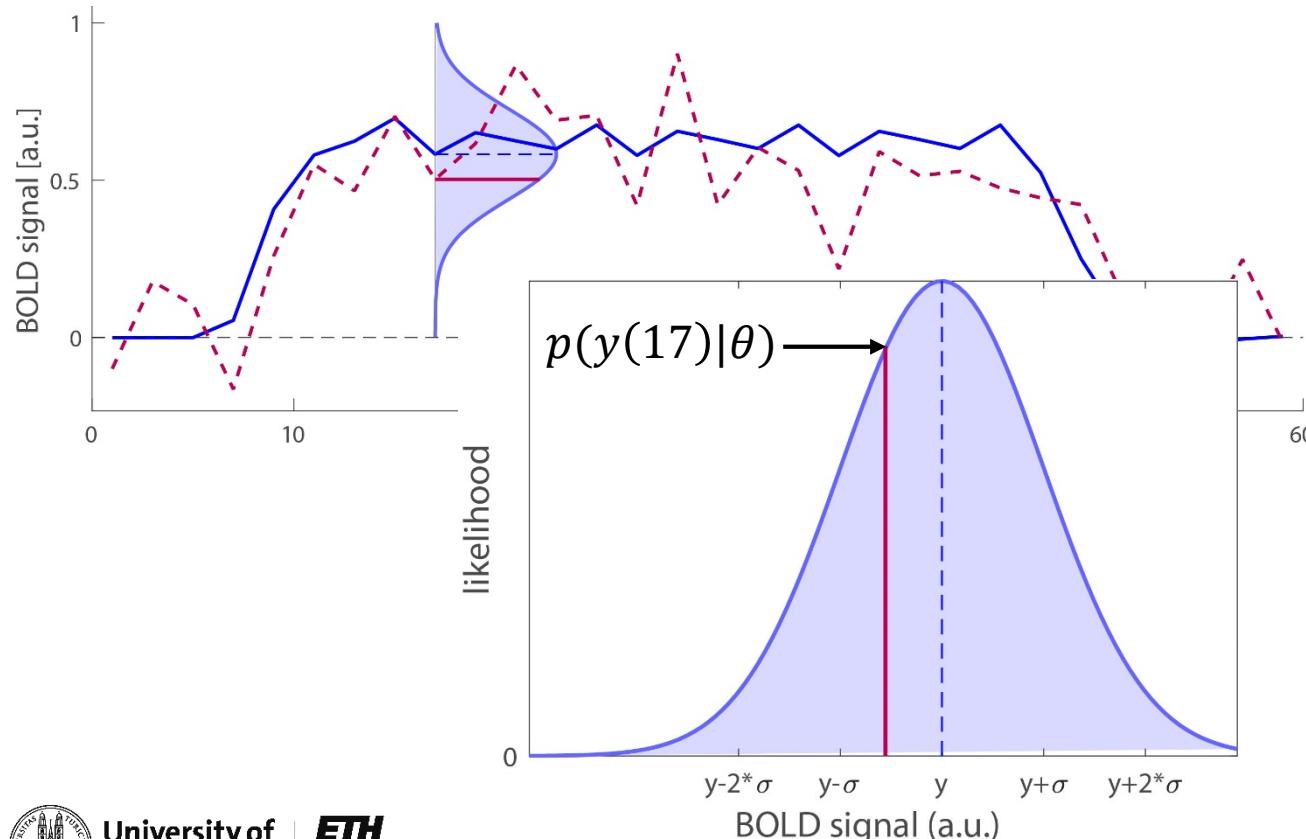


Assume data is normally distributed around the prediction from the dynamical model (Gaussian noise):

LIKELIHOOD FUNCTION

$$p(y(t)|\theta, m) = \mathcal{N}(y(t); g(\theta^n, \theta^h, u), \theta^\sigma)$$

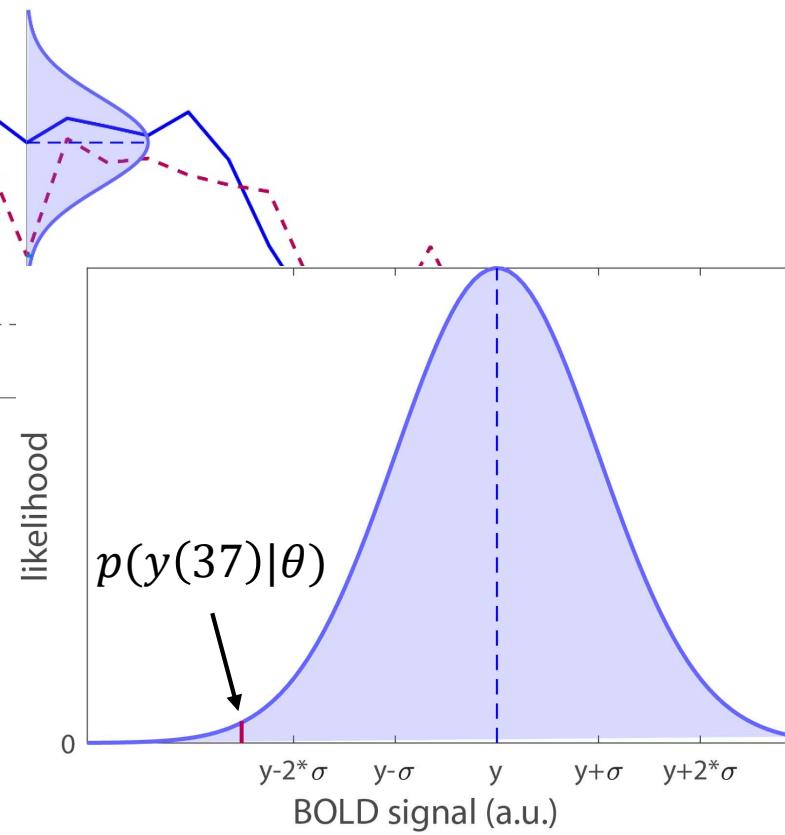
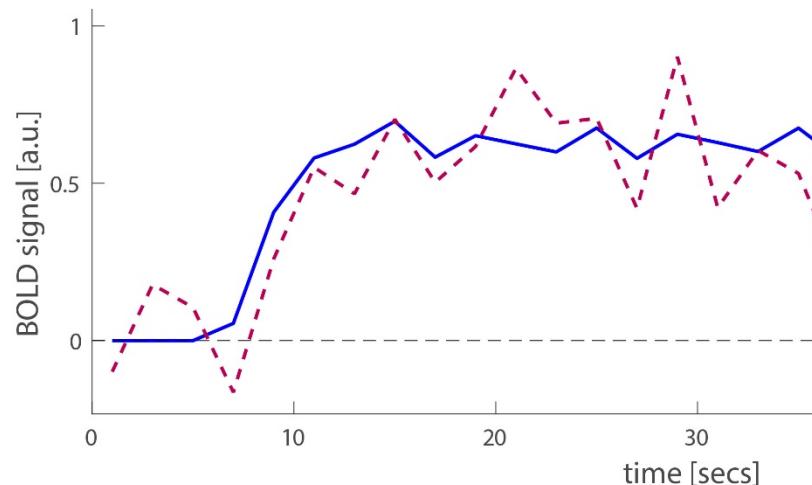
likelihood



LIKELIHOOD FUNCTION

$$p(y(t)|\theta, m) = \mathcal{N}(y(t); g(\theta^n, \theta^h, u), \theta^\sigma)$$

likelihood



PRIORS

Bayes theorem gives a recipe for evaluating the posterior density by combining new data (likelihood) and prior knowledge

$$p(\theta|y, m) = \frac{p(y|\theta, m)p(\theta|m)}{p(y|m)}$$

prior

Neuronal parameters:

- self-connections: principled (to ensure that the system is stable)
- other parameters (between—region connections, modulation, inputs): shrinkage priors

Hemodynamic parameters:

- empirical

PRIORS

Types of priors:

- Explicit priors on *model parameters* (e.g., connection strengths)
- Implicit priors on *model functional form* (e.g., system dynamics)
- Choice of “interesting” *data features* (e.g., regional time-series vs. ICA analysis)

Role of priors (on model parameters):

- Resolving the *ill-posedness* of the inverse problem
- Avoiding *overfitting* (cf. generalization error)

Impact of priors:

- On parameter posterior distributions (cf. “shrinkage to the mean” effect)
- On model evidence (cf. “Occam’s razor”)
- On free-energy landscape (cf. Laplace approximation)

BAYES THEOREM

Bayes theorem gives a recipe for evaluating the posterior density by combining new data (likelihood) and prior knowledge

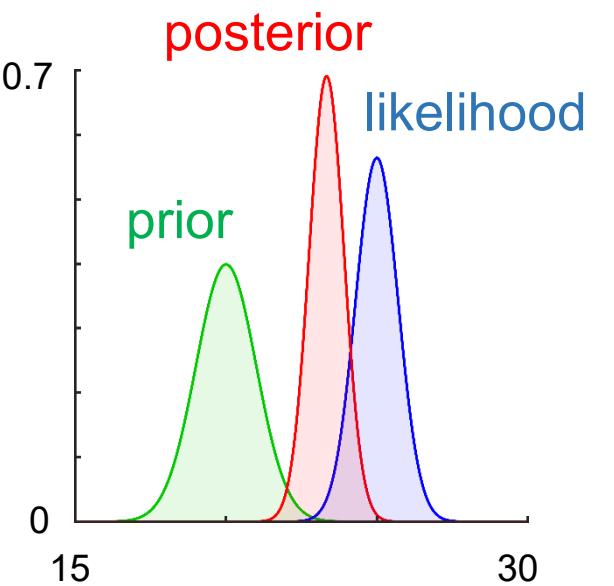
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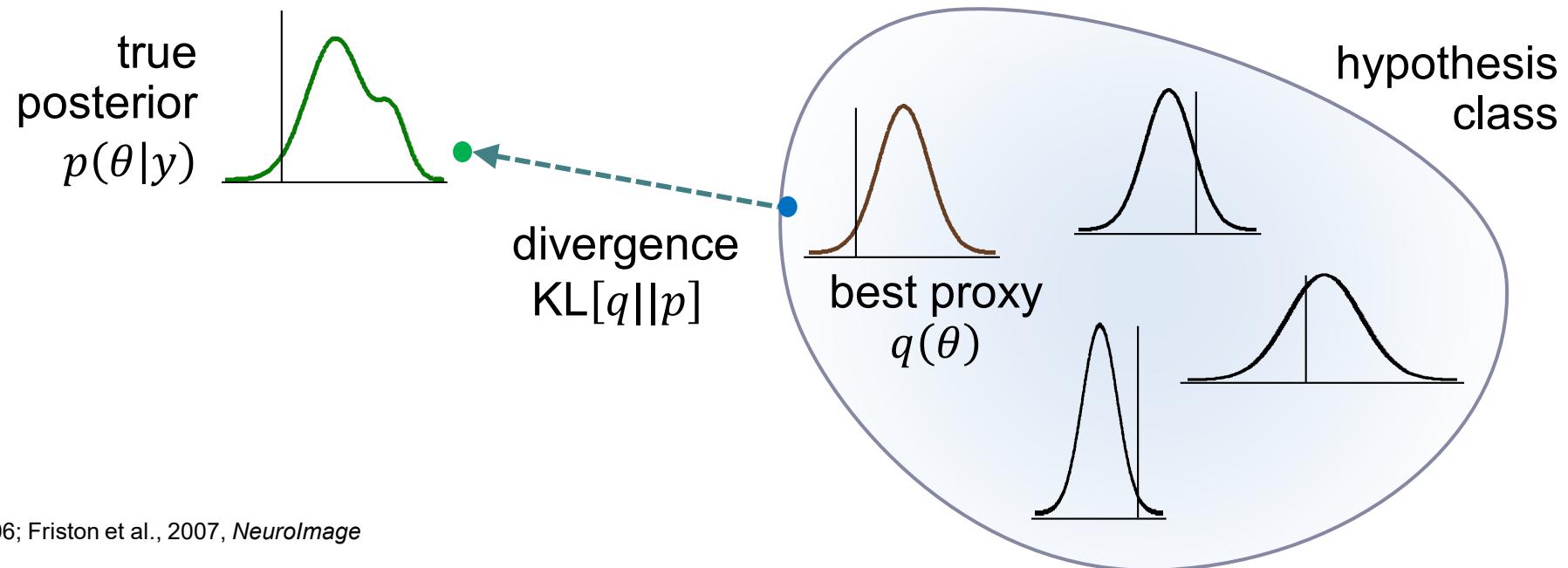


Reverend Thomas Bayes
(1702-1761)



VARIATIONAL BAYES (VB)

Idea: find an approximate density $q(\theta)$ that is maximally similar to the true posterior $p(\theta|y)$. This is often done by assuming a particular form for q (fixed form VB) and then optimizing its sufficient statistics.



Bishop, 2006; Friston et al., 2007, *NeuroImage*

NEGATIVE FREE ENERGY

$$\ln p(y) = \underbrace{\text{KL}[q||p]}_{\text{divergence} \geq 0 \text{ (unknown)}} + \underbrace{F(q, y)}_{\text{neg. free energy (easy to evaluate for a given } q)}$$

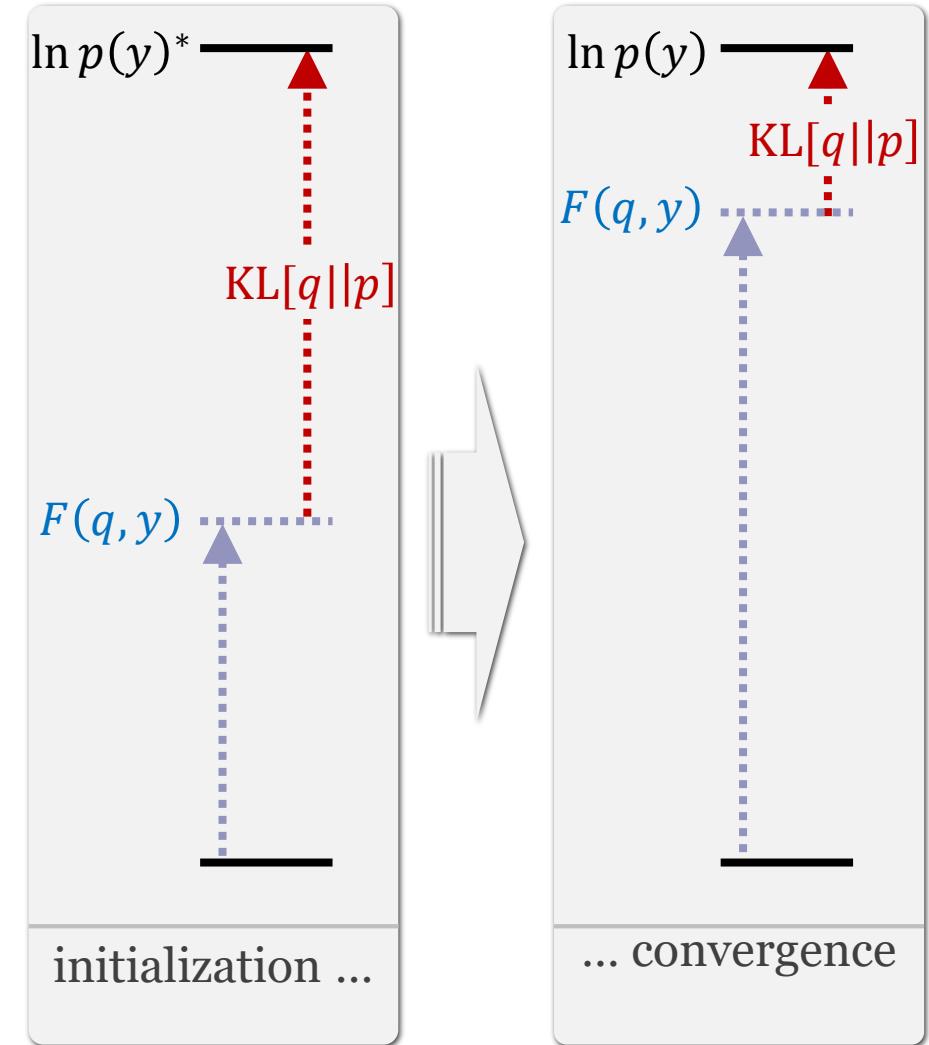
$F(q, y)$ is a functional with respect to the approximate posterior $q(\theta)$.

Maximizing $F(q, y)$ is equivalent to:

- minimizing $\text{KL}[q||p]$
- tightening $F(q, y)$ as a lower bound on the log model evidence

When $F(q, y)$ is maximized, $q(\theta)$ is our best estimate of the true posterior.

Bishop, 2006; Friston et al., 2007, *NeuroImage*



NEGATIVE FREE ENERGY – A CLOSER LOOK

The **negative free energy** represents a trade-off between the accuracy and complexity of a model:

$$F = \langle \log p(y|\theta, m) \rangle_q - KL[q(\theta)||p(\theta|m)]$$

Bishop, 2006; Friston et al., 2007, *NeuroImage*

NEGATIVE FREE ENERGY – A CLOSER LOOK

The **negative free energy** represents a trade-off between the accuracy and complexity of a model:

$$F = \langle \log p(y|\theta, m) \rangle_q - KL[q(\theta)||p(\theta|m)]$$

accuracy
(expected log likelihood)

complexity
(KL divergence between
approximate posterior and prior)

Bishop, 2006; Friston et al., 2007, *NeuroImage*

NEGATIVE FREE ENERGY – A CLOSER LOOK

The **negative free energy** represents a trade-off between the accuracy and complexity of a model:

$$F = \langle \log p(y|\theta, m) \rangle_q - KL[q(\theta)||p(\theta|m)]$$

In contrast to “simple” criteria (e.g., AIC & BIC), the complexity term of the negative free energy accounts for parameter interdependencies and is a much richer description:

$$KL[q(\theta)||p(\theta|m)] = \frac{1}{2} \ln|C_\theta| - \frac{1}{2} \ln|C_{\theta|y}| + \frac{1}{2} (\mu_{\theta|y} - \mu_\theta)^T C_\theta^{-1} (\mu_{\theta|y} - \mu_\theta)$$

Bishop, 2006; Friston et al., 2007, *NeuroImage*

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complexity **higher** the more independent prior parameters

Bishop, 2006; Friston et al., 2007, *NeuroImage*

NEGATIVE FREE ENERGY – A CLOSER LOOK

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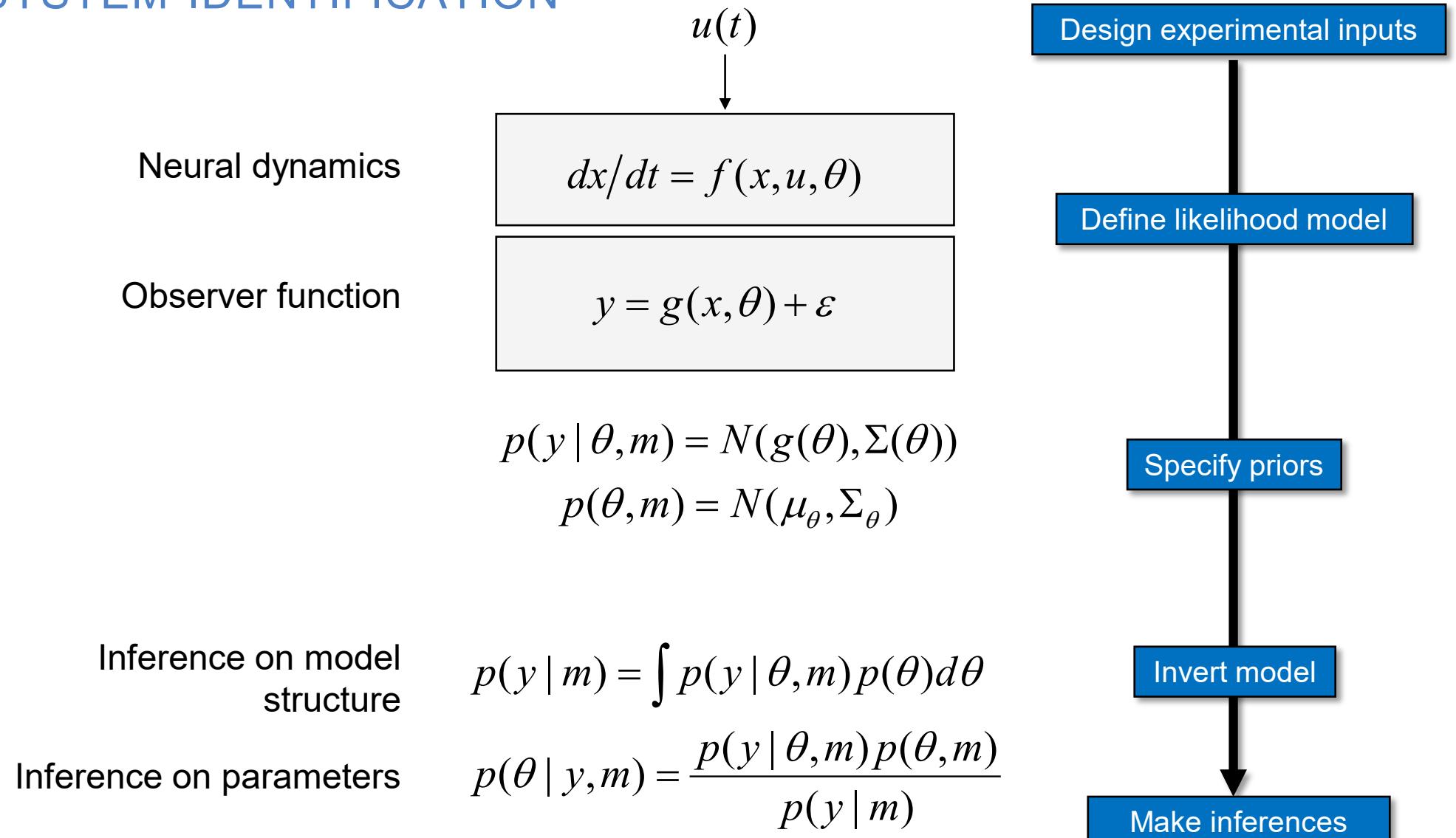
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complexity **higher** the more posterior deviates from prior mean

Bishop, 2006; Friston et al., 2007, *NeuroImage*

BAYESIAN SYSTEM IDENTIFICATION



BAYESIAN MODEL SELECTION (BMS)

The **negative free energy** as a lower bound approximation to the log model evidence is the current gold standard for Bayesian model selection (BMS).

Generative modeling: comparing competing hypotheses about the mechanisms underlying observed data.

- *a priori* definition of hypothesis set (model space) is crucial
- determine the most plausible hypothesis (model), given the data

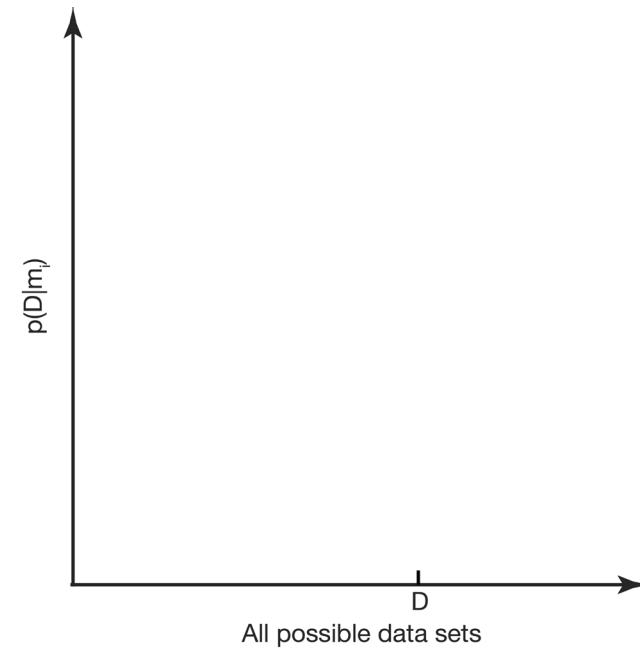
Note: **Model selection is not equal to model validation** and only allows to compare the relative goodness of competing hypotheses within the pre-specified model space!

→ Model validation requires external criteria (external to the measured data).

OVERFITTING AT THE LEVEL OF MODELS

But: There is a very large number of possible models for a given dataset. Wouldn't we need to search the entire model space and test all possible models?

No! With more models included in the model space, the risk of overfitting (at the level of models) increases, too.

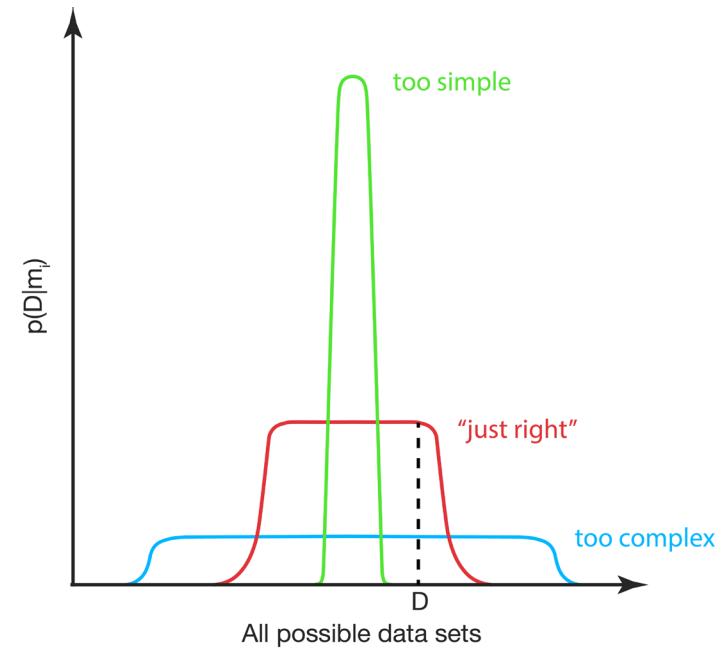


Ghahramani, 2004

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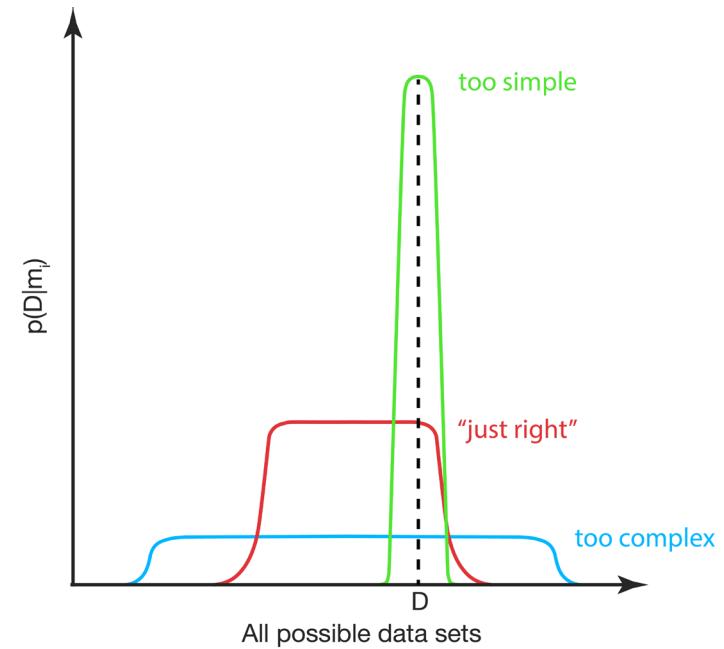


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No! With more models included in the model space, the risk of overfitting (at the level of models) increases, too.

Solutions:

- regularization: definition of model space (i.e., specify priors $p(m)$ over models)
- family-level Bayesian model selection
- Bayesian model averaging (BMA)

Ghahramani, 2004

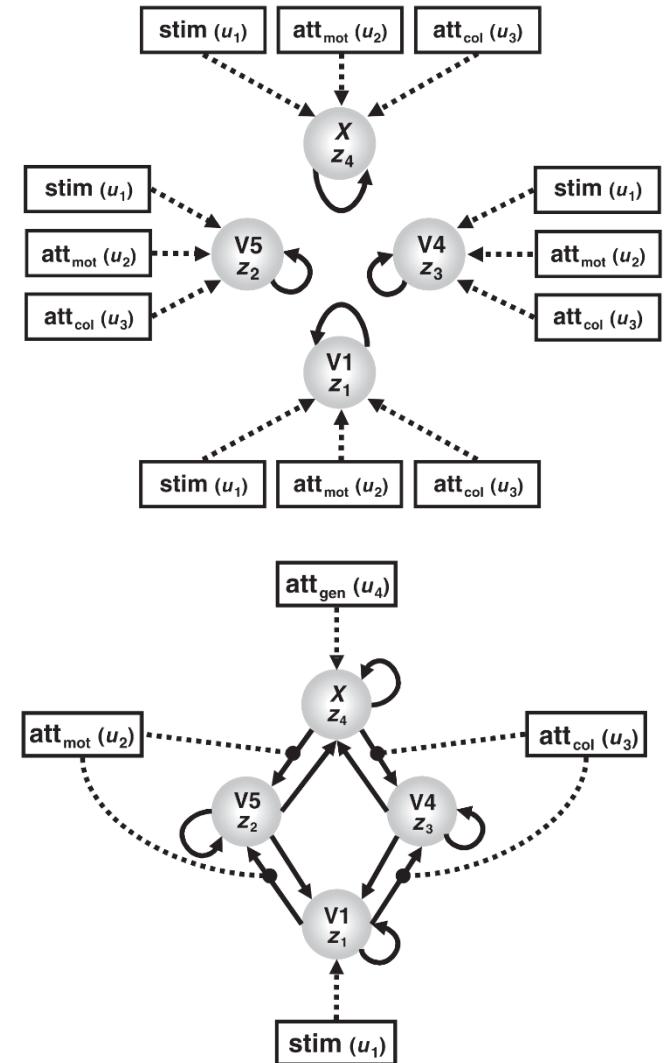
NOTE: GLM vs. DCM

DCM tries to model the same phenomena (i.e., local BOLD responses) as a GLM, just in a different way (via connectivity and its modulations).

No activation detected by a GLM → no motivation to include this region in a deterministic DCM.

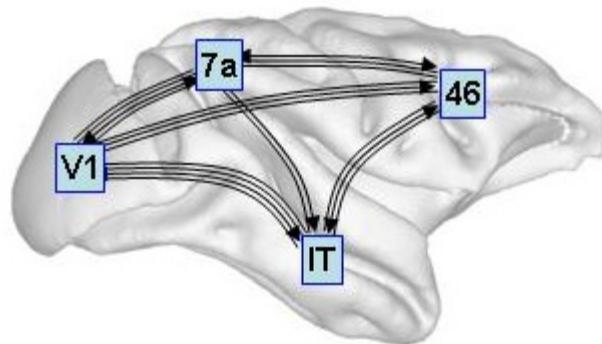
However, a stochastic DCM (that incorporates a noise term in the neuronal state equation and can thus account for endogenous fluctuations) could be applied in the absence of a local activation.

Stephan, 2004, *J. Anat.*



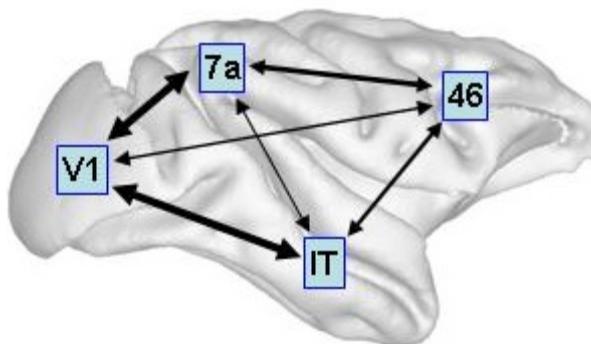
INTERPRETATION: DIFFERENT FORMS OF BRAIN CONNECTIVITY

structural connectivity



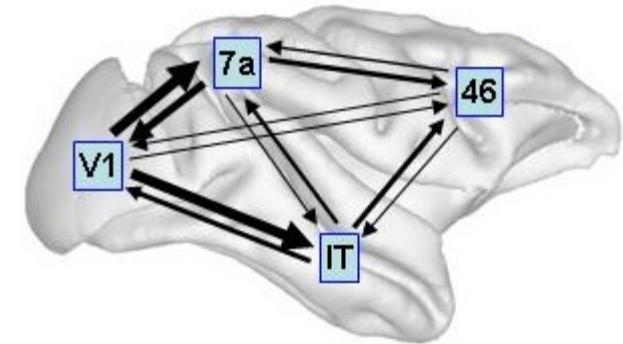
- presence of physical connections
- Diffusion weighted imaging (DWI), tractography, tracer studies

functional connectivity



- statistical dependencies between regional time series
- correlations, Independent Component Analysis (ICA)

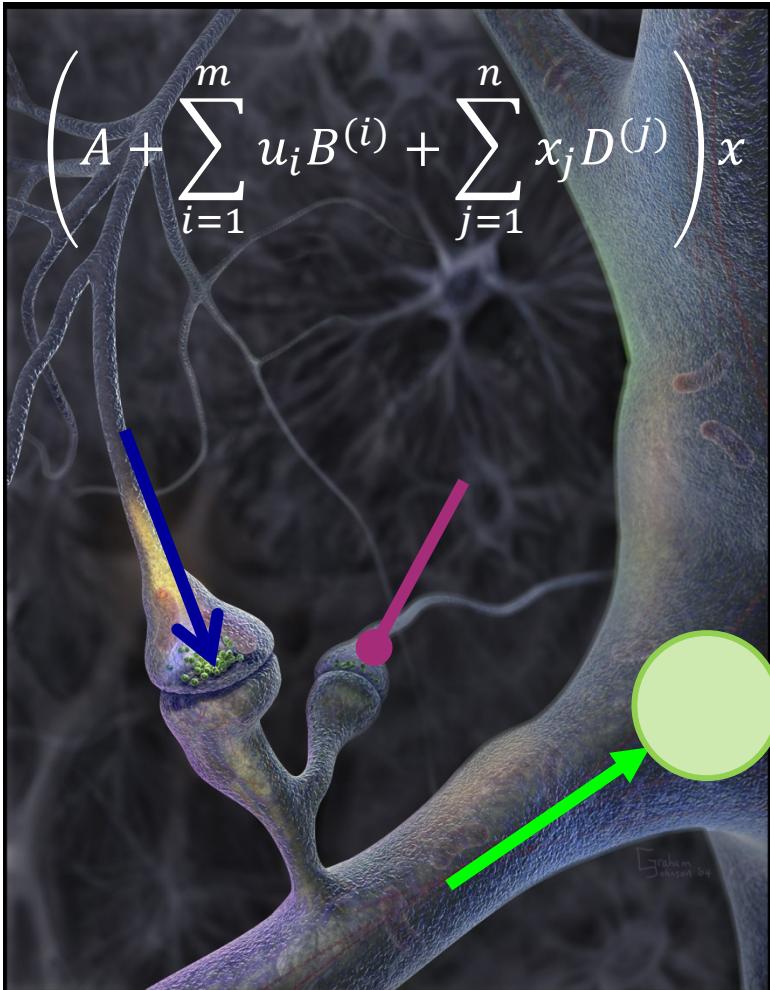
effective connectivity



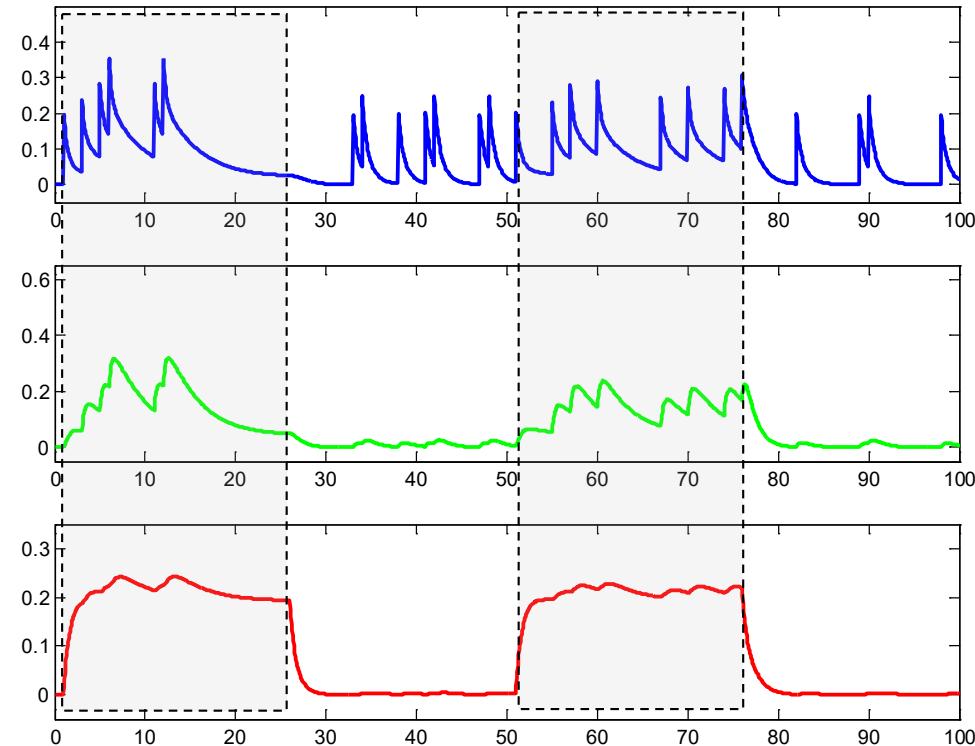
- (causal) directed influences between neuronal populations
- Dynamic causal modeling (DCM)

Sporns, 2007, Scholarpedia

INTERPRETATION: NEUROMODULATION



Stephan et al, 2008, *Neuroimage*

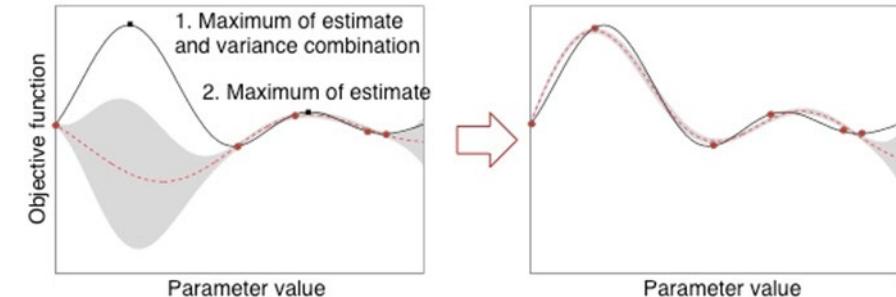


Synaptic strengths are context-sensitive:
They depend on spatio-temporal patterns of network activity.

METHODOLOGICAL DEVELOPMENTS OF DCM

Global optimization schemes for model inversion

- Markov Chain Monte Carlo (MCMC) sampling (Sengupta et al., 2015, *NeuroImage*)
- Gaussian process (GP) regression (Lomakina et al., 2015, *NeuroImage*)

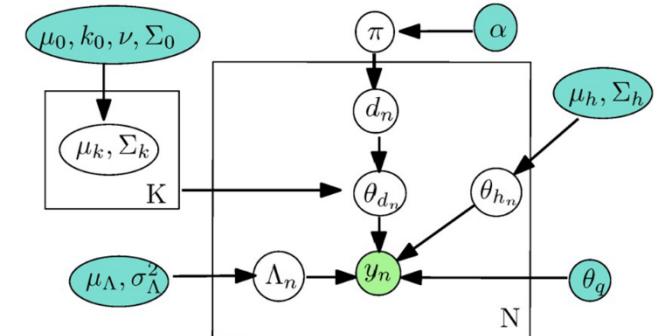


Sampling-based estimates of model evidence

- Aponte et al. 2016, *J. Neurosci. Meth.*
- Raman et al., 2016, *J. Neurosci. Meth.*

Choice of priors → empirical Bayes

- Friston et al. 2016, *NeuroImage*
- Raman et al. 2016 and 2018, *J. Neurosci. Meth.*
- Yao et al. 2018, *Neuroimage*



Sengupta et al, 2015, *NeuroImage*; Lomakina et al., 2015, *NeuroImage*; Aponte et al., 2016, *J. Neurosci. Meth.*; Friston et al., 2016, *NeuroImage*; Raman et al., 2016, *J. Neurosci. Meth.*; Raman et al., 2018, *J. Neurosci. Meth.*; Yao et al., 2018, *Neuroimage*

APPLICATIONS



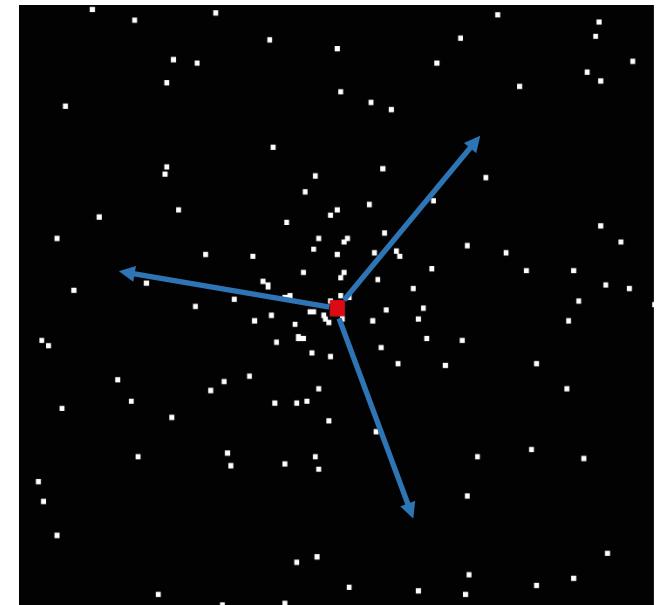
SIMPLE EXAMPLE: ATTENTION TO MOTION

Stimuli: radially moving dots were presented.

Pre-scanning: 5x30s trials with 5 speed changes.
Subjects were asked to detect the change in radial velocity.

Scanning: No actual speed changes. Conditions:

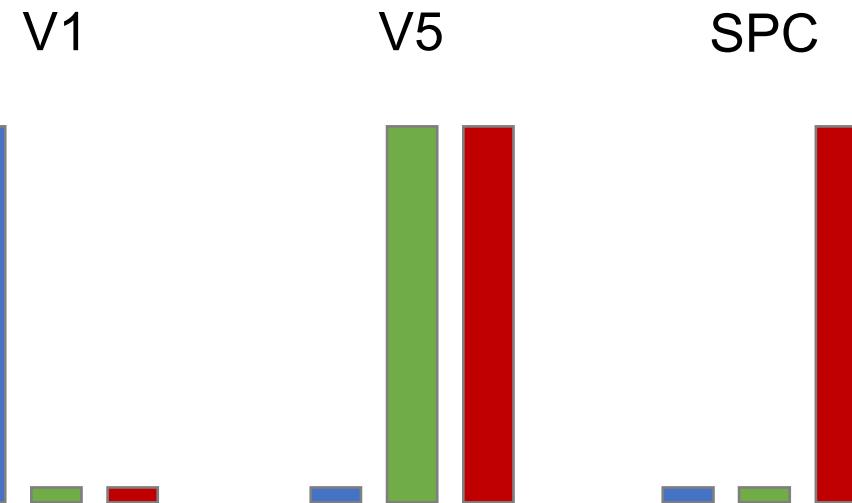
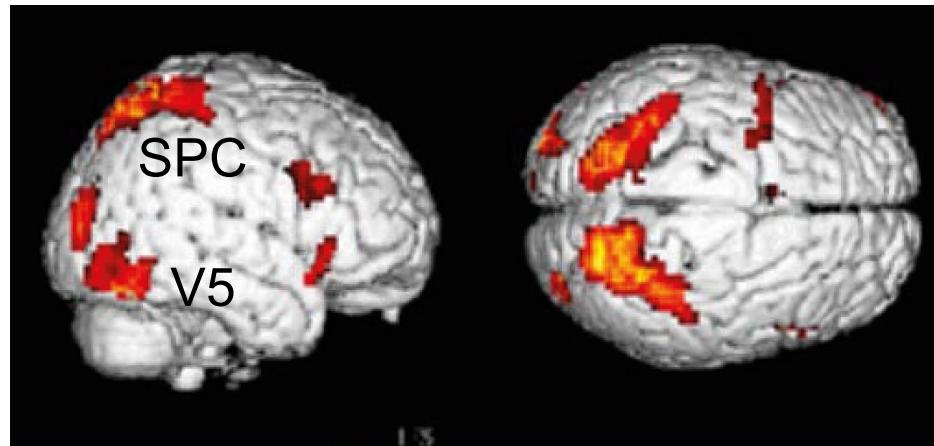
- F: fixation
- S: static dots
- M: moving dots
- A: attend moving dots



Büchel and Friston, 1997, *Cerebral Cortex*; Friston et al., 2003, *NeuroImage*

SIMPLE EXAMPLE: ATTENTION TO MOTION

Single-subject results: BOLD activation patterns

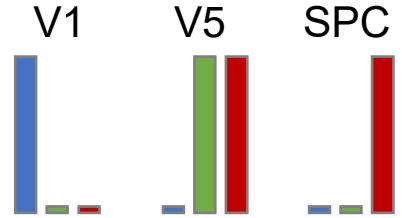


Linear contrast: attention > no attention

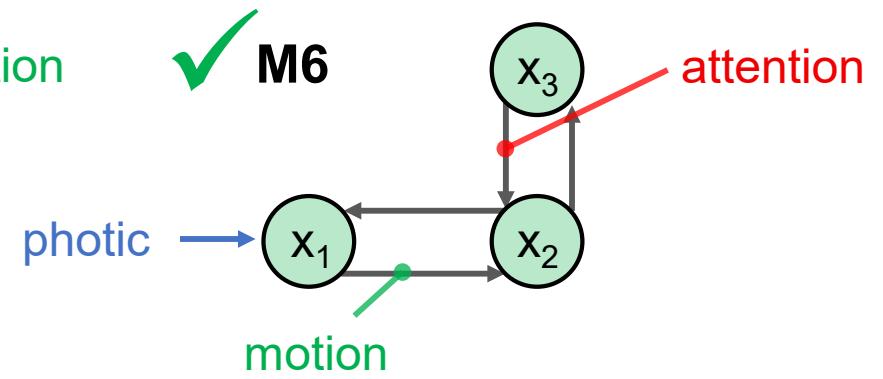
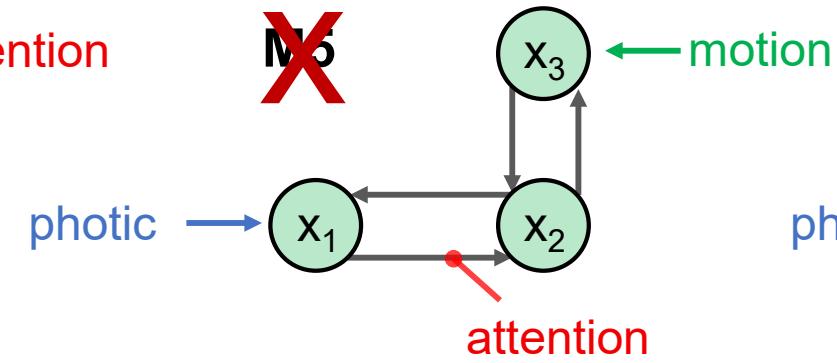
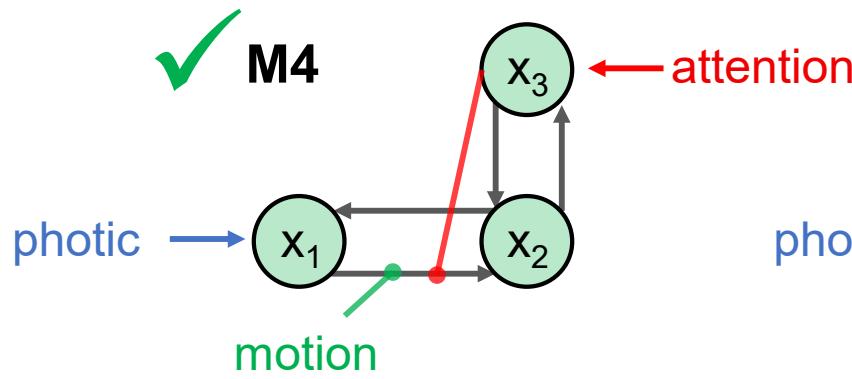
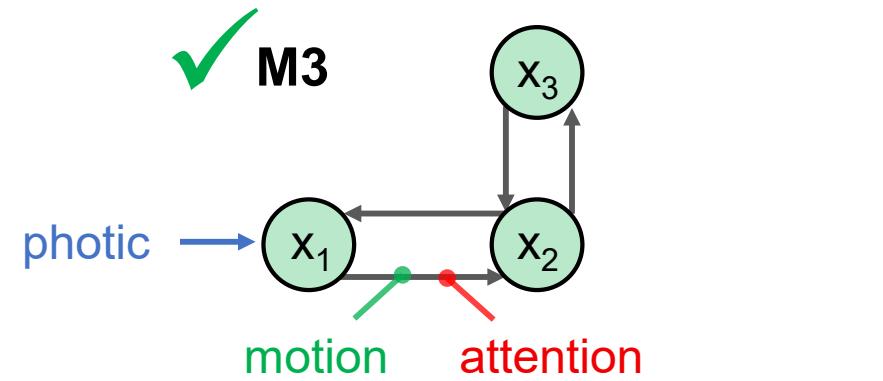
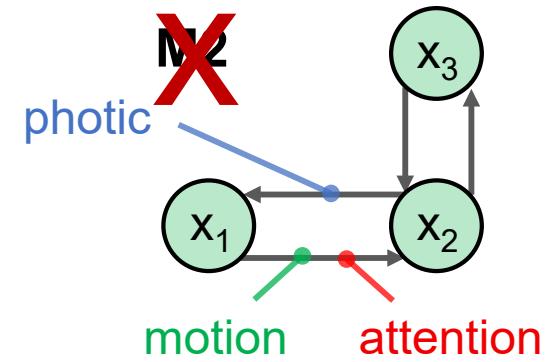
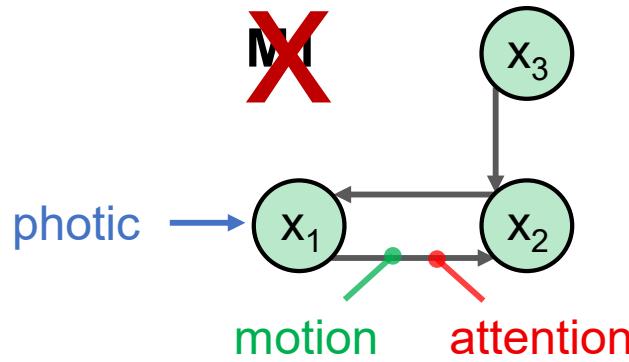
- photic
- motion
- attention

Büchel and Friston, 1997, *Cerebral Cortex*; Friston et al., 2003, *NeuroImage*

SIMPLE EXAMPLE: ATTENTION TO MOTION



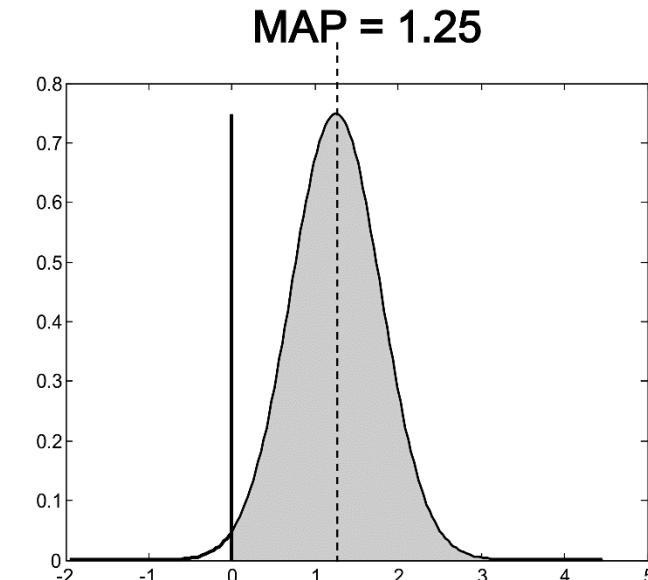
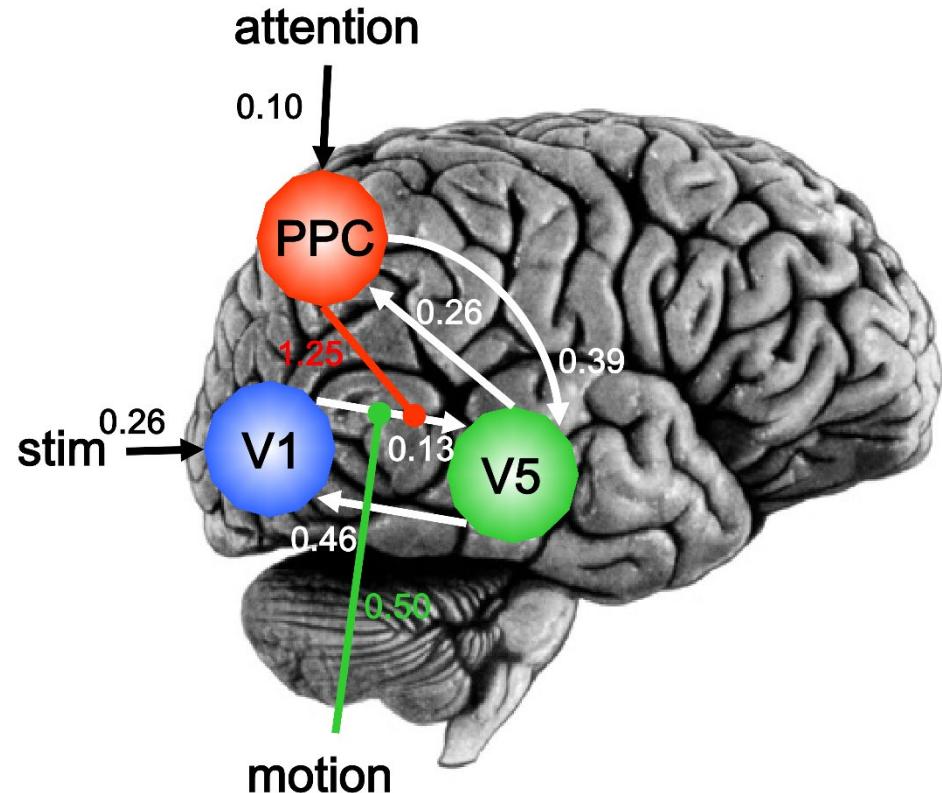
Model space definition – which models can explain the data (Quiz)?



Büchel and Friston, 1997, *Cerebral Cortex*; Friston et al., 2003, *NeuroImage*

SIMPLE EXAMPLE: ATTENTION TO MOTION

Single-subject results: DCM effective connectivity



$$p(D_{V5,V1}^{PPC} > 0 \mid y) = 99.1\%$$

Büchel and Friston, 1997, *Cerebral Cortex*; Friston et al., 2003, *NeuroImage*; Stephan et al., 2008, *NeuroImage*

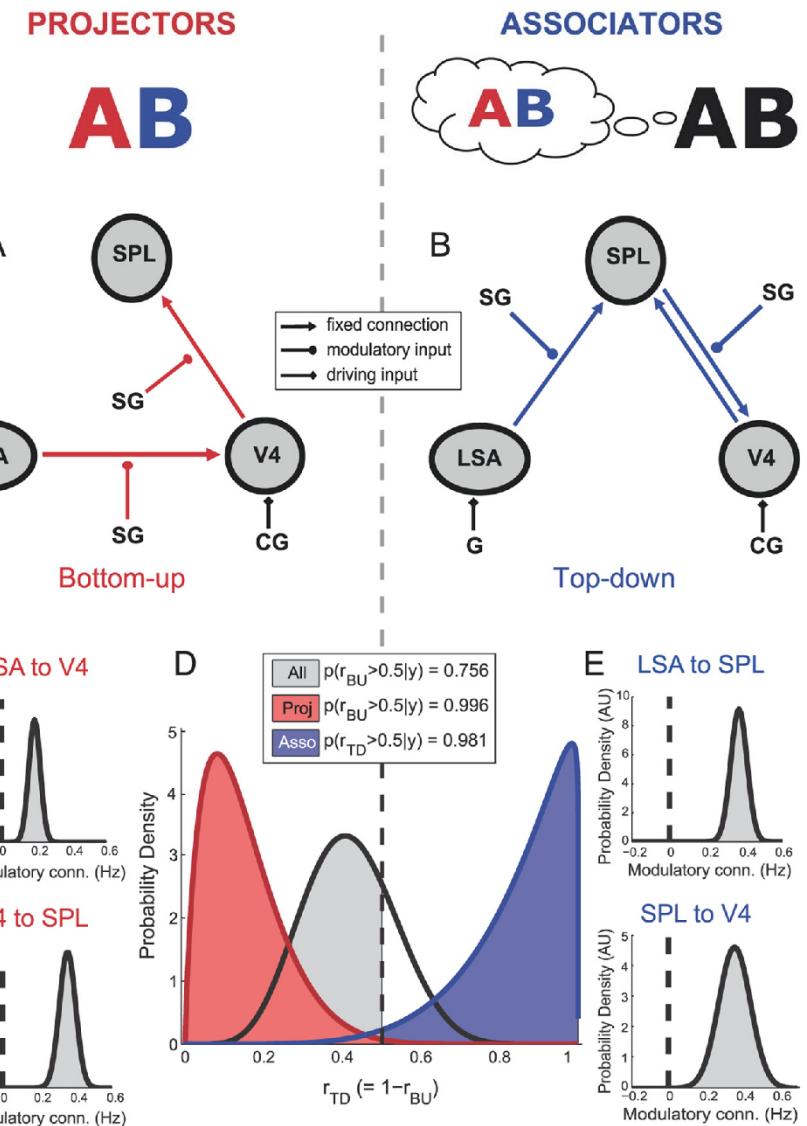
BAYESIAN MODEL SELECTION: SYNESTHESIA (SUPPLEMENTAL INFO)

Individuals with different forms of color-grapheme synesthesia were tested and effective connectivity in the relevant neural circuits was assessed using DCM.

Bayesian model selection (BMS) as a formal approach to differential diagnosis in clinical applications

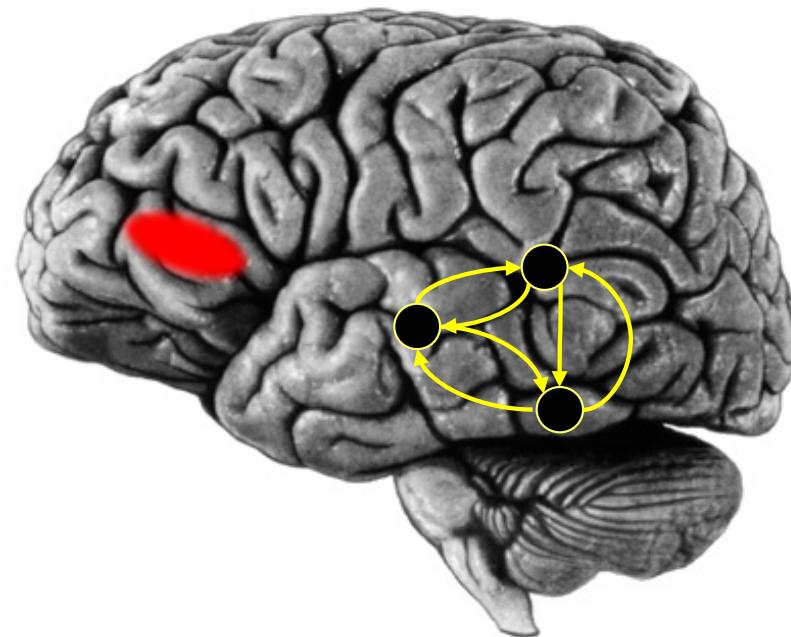
(Note: Here, different forms of synesthesia were tested. This is not a clinical condition, but simply a specific cognitive trait.)

Van Leeuwen et al., 2011, J. Neurosci.



GENERATIVE EMBEDDING: APHASIA

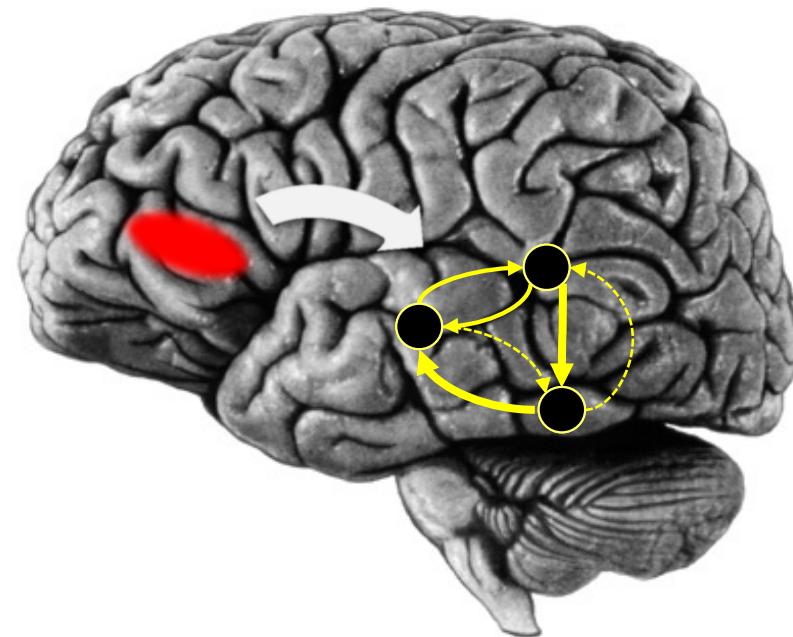
Dissociating aphasic patients (N=11) and healthy controls (N=26)



Schofield et al., 2012, *J. Neurosci.*; Brodersen et al., 2011, *PLoS Comp. Biol.*

GENERATIVE EMBEDDING: APHASIA

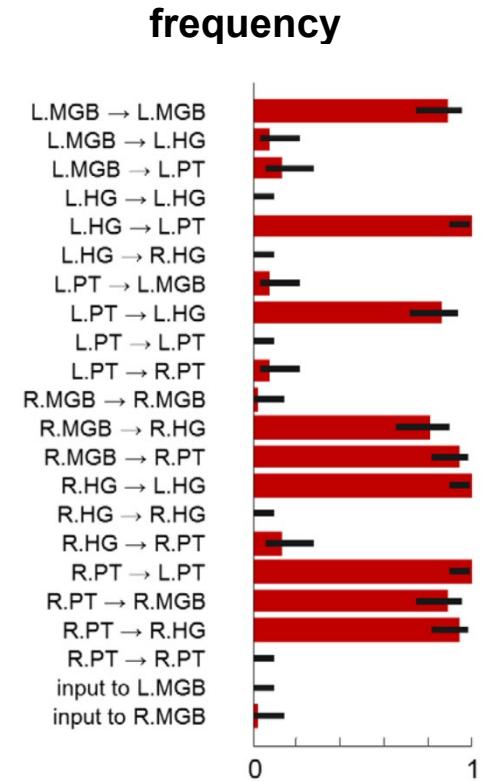
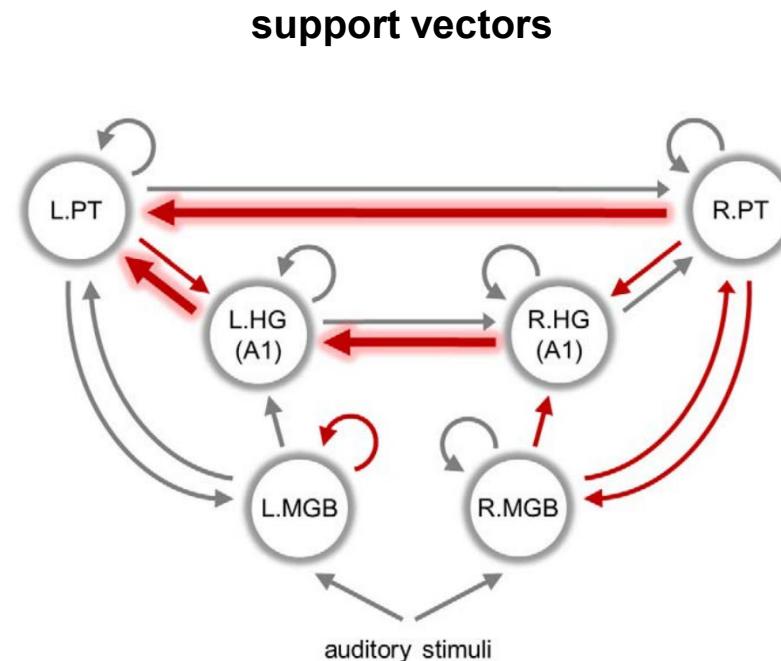
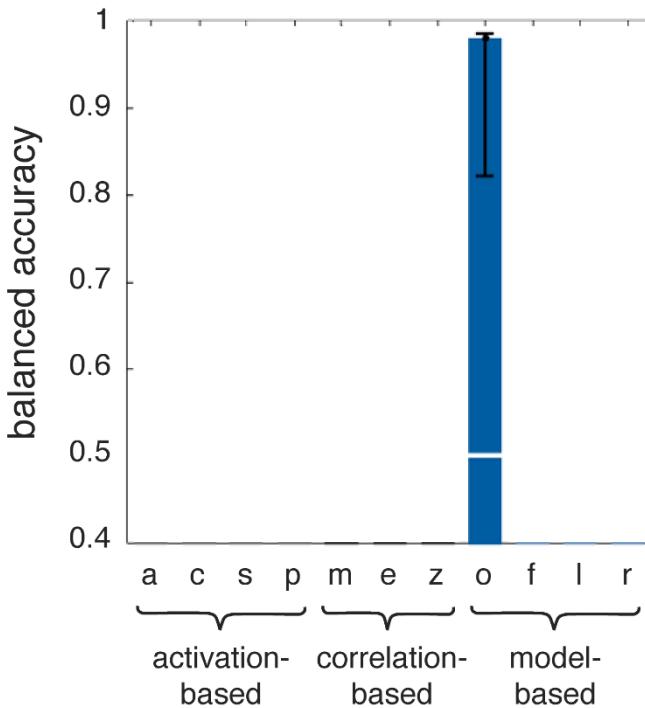
Dissociating aphasic patients (N=11) and healthy controls (N=26)



Schofield et al., 2012, *J. Neurosci.*; Brodersen et al., 2011, *PLoS Comp. Biol.*

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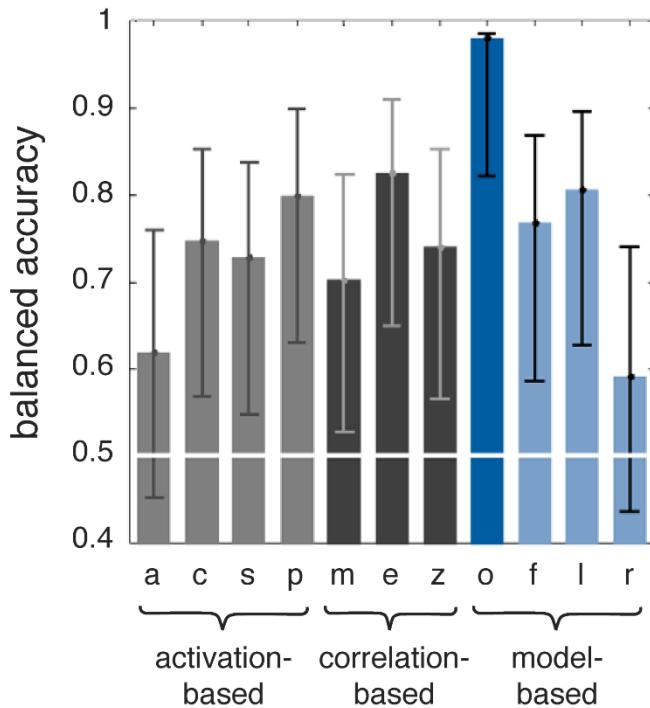
Dissociating aphasic patients (N=11) and healthy controls (N=26)



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GENERATIVE EMBEDDING: APHASIA

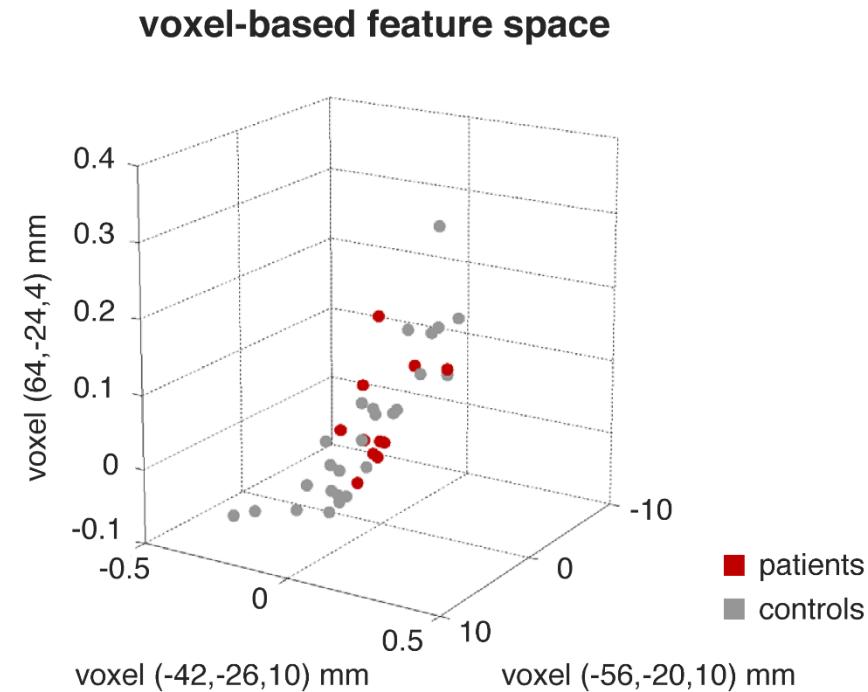
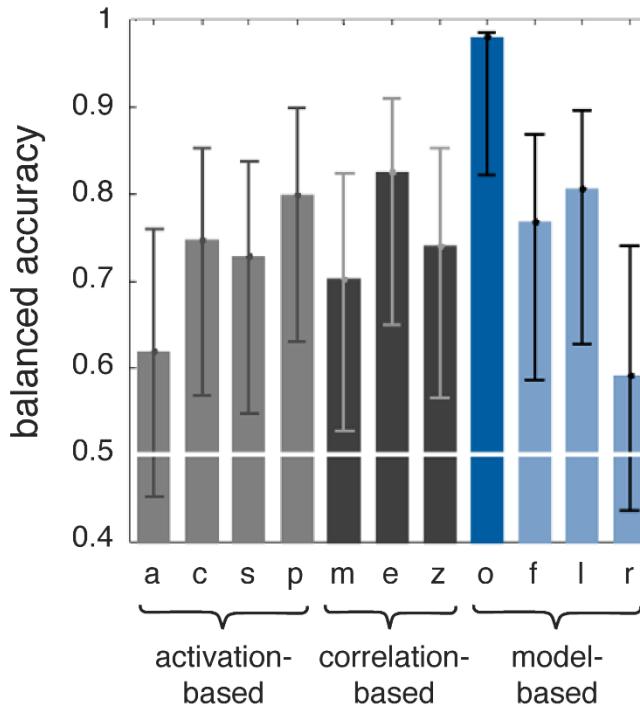
Dissociating aphasic patients (N=11) and healthy controls (N=26)



Schofield et al., 2012, *J. Neurosci.*; Brodersen et al., 2011, *PLoS Comp. Biol.*

GENERATIVE EMBEDDING: APHASIA

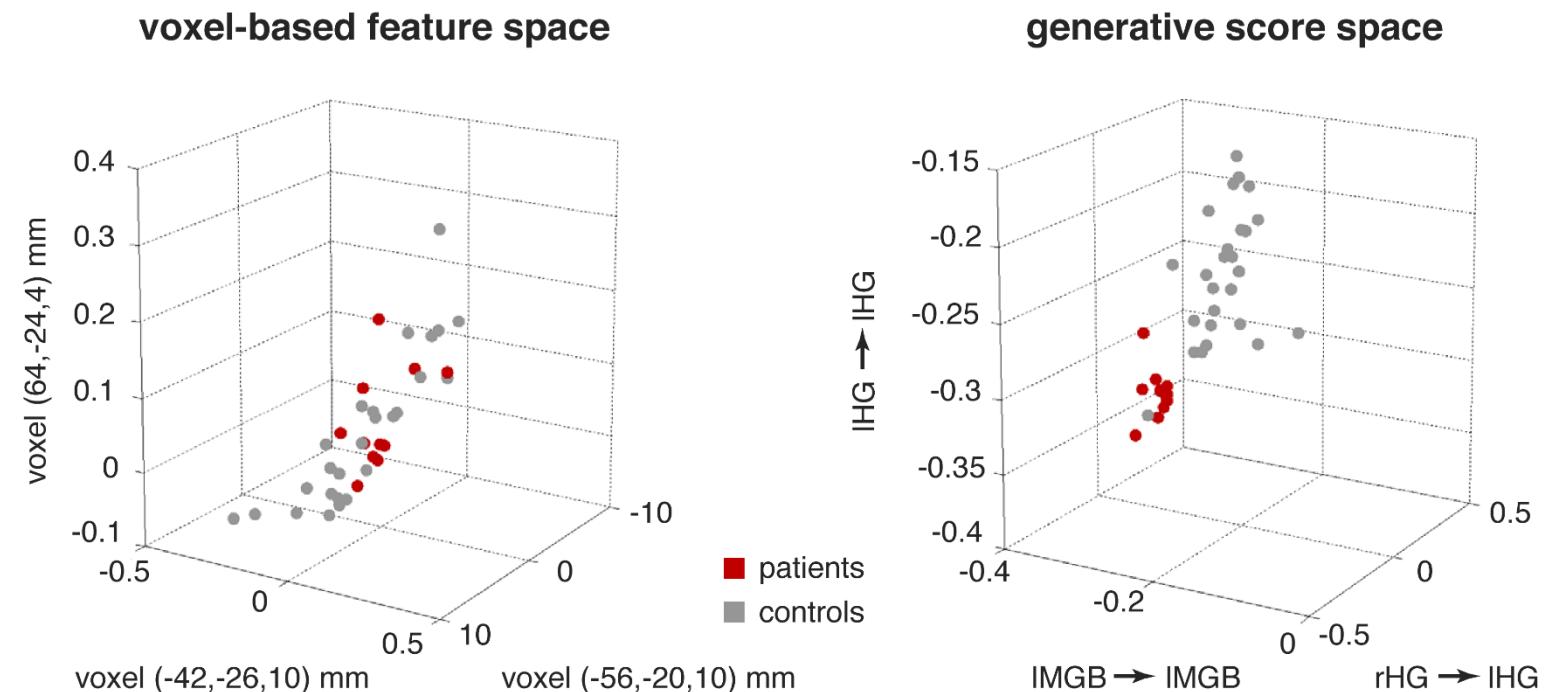
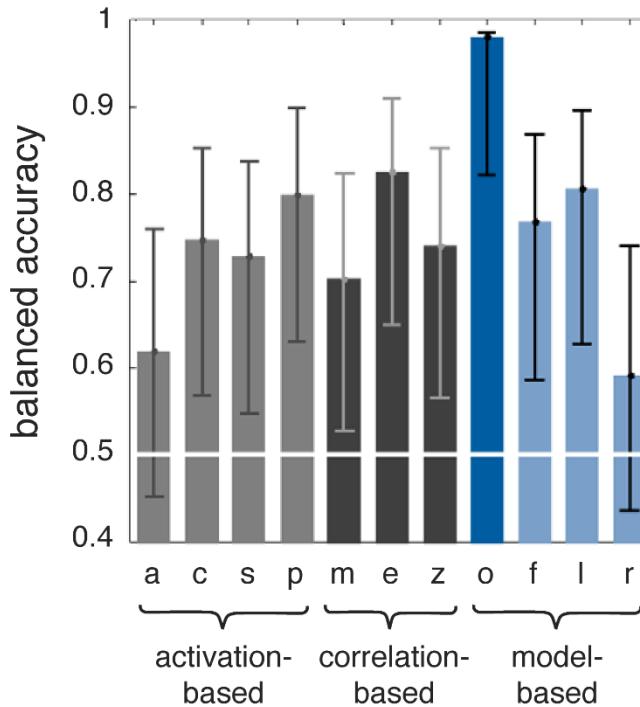
Dissociating aphasic patients (N=11) and healthy controls (N=26)



Schofield et al., 2012, *J. Neurosci.*; Brodersen et al., 2011, *PLoS Comp. Biol.*

GENERATIVE EMBEDDING: APHASIA

Dissociating aphasic patients (N=11) and healthy controls (N=26)

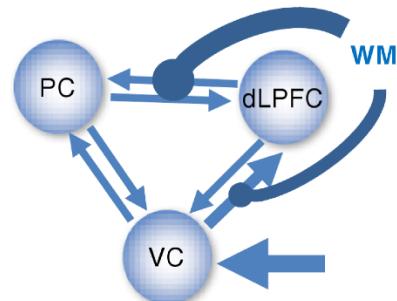


Schofield et al., 2012, *J. Neurosci.*; Brodersen et al., 2011, *PLoS Comp. Biol.*

GENERATIVE EMBEDDING: SCHIZOPHRENIA

Detecting subgroups of patients in schizophrenia (N=41)

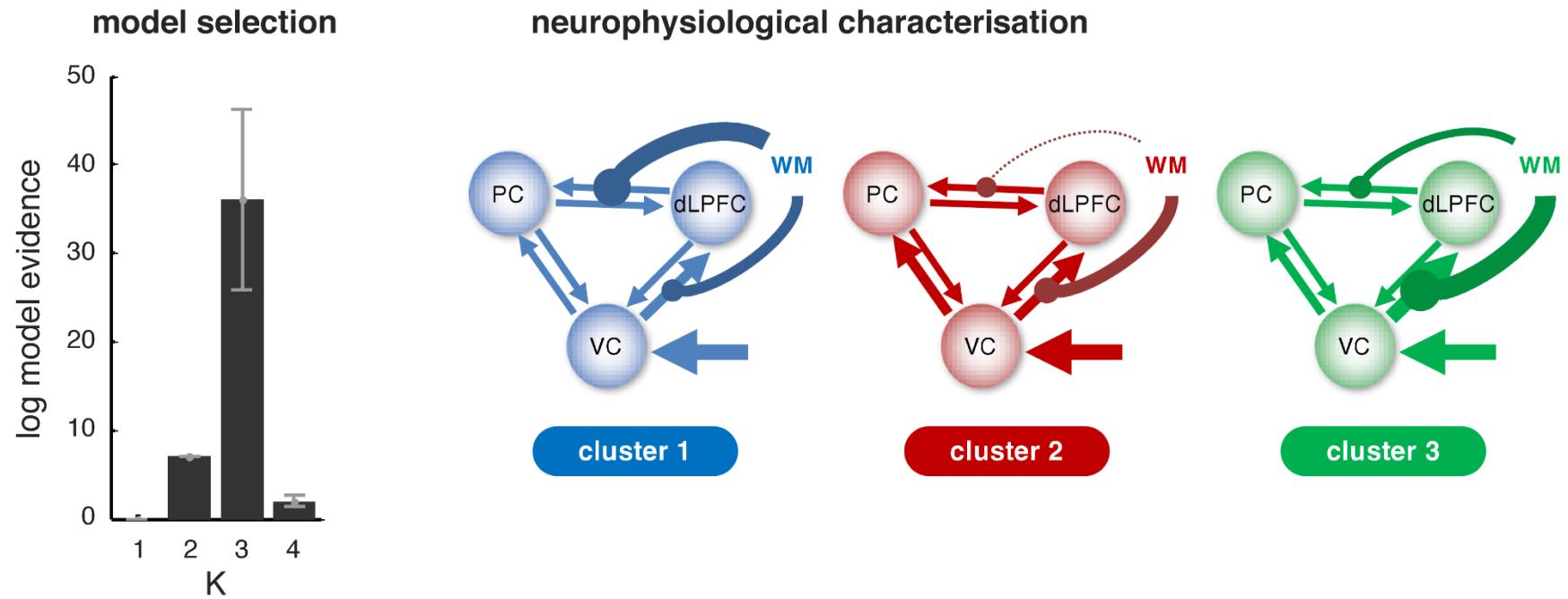
neurophysiological characterisation



Deserno et al., 2012, *J. Neurosci.*; Brodersen et al., 2014, *NeuroImage: Clinical*

GENERATIVE EMBEDDING: SCHIZOPHRENIA

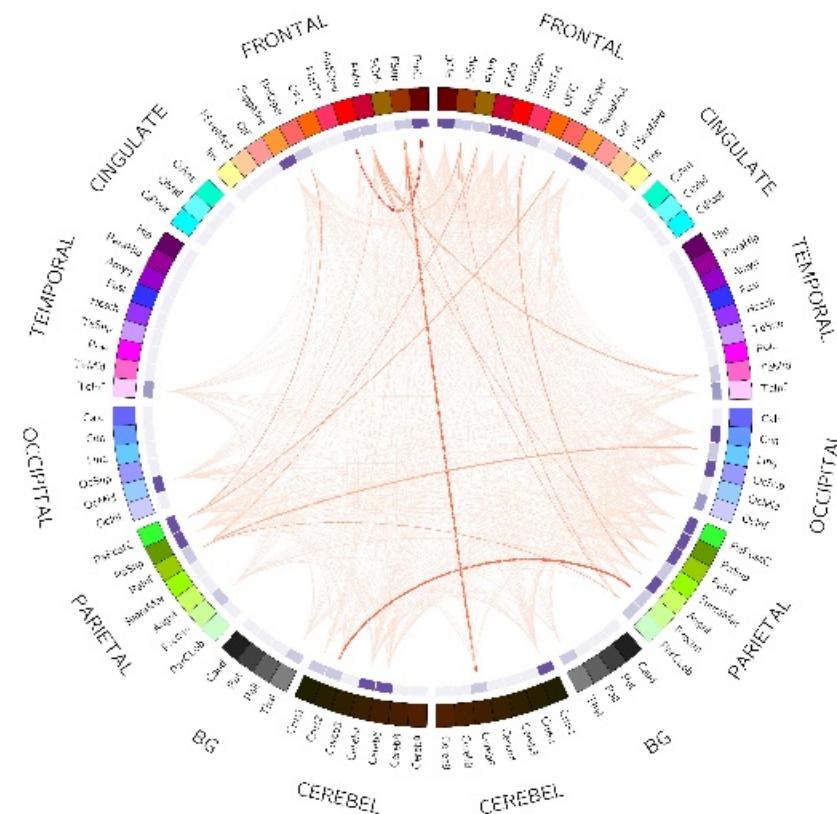
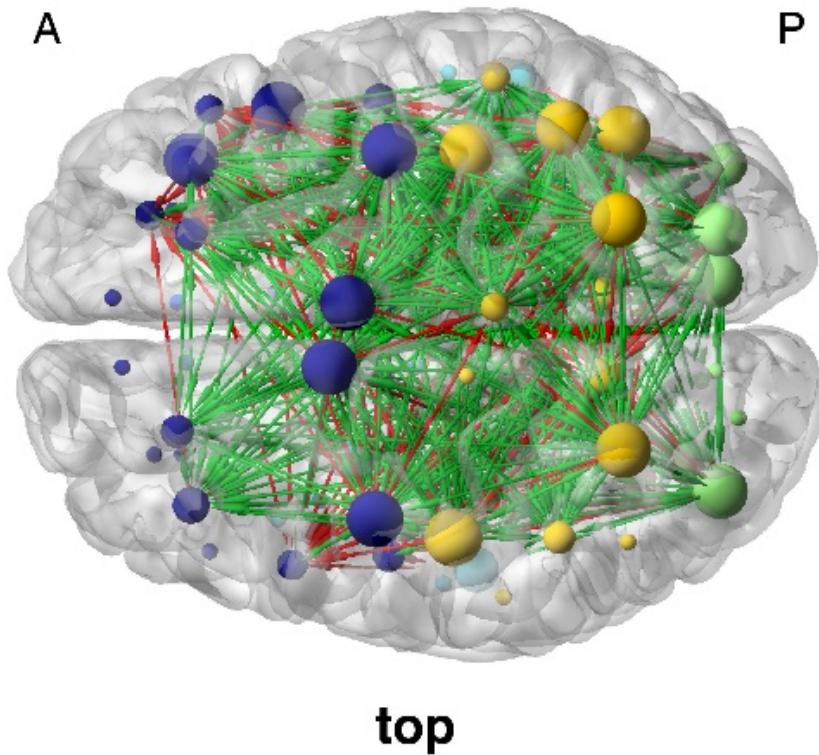
Detecting subgroups of patients in schizophrenia (N=41)



Deserno et al., 2012, *J. Neurosci.*; Brodersen et al., 2014, *NeuroImage: Clinical*

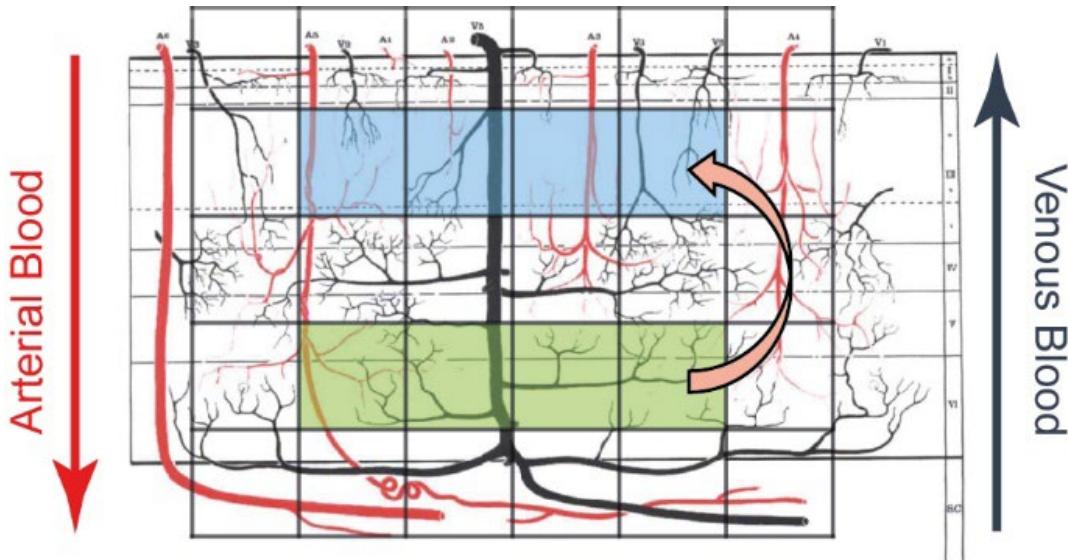
DCM EXTENSIONS

REGRESSION DCM

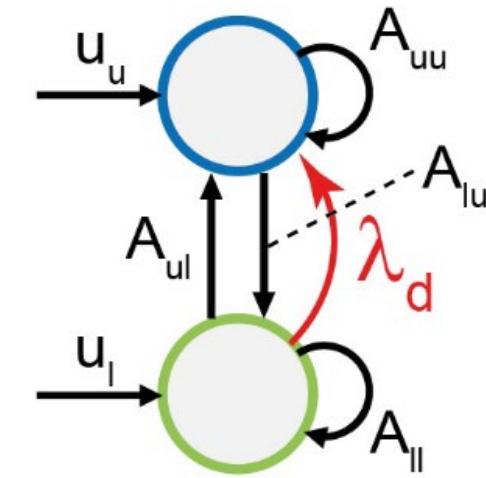


Frässle et al., 2017, *NeuroImage*; Frässle et al., 2018, *NeuroImage*

DCM FOR LAYERED FMRI



Heinze et al., 2017, *NeuroImage*



$$\tau_u \frac{dv_u}{dt} = f_u - v_u^{\frac{1}{\alpha_u}} + \lambda_d v_l^*$$

$$\tau_u \frac{dq_u}{dt} = f_u \frac{1 - (1 - E_0)^{1/f_u}}{E_0} - v_u^{1/\alpha_u} \frac{q_u}{v_u} + \lambda_d q_l^*$$

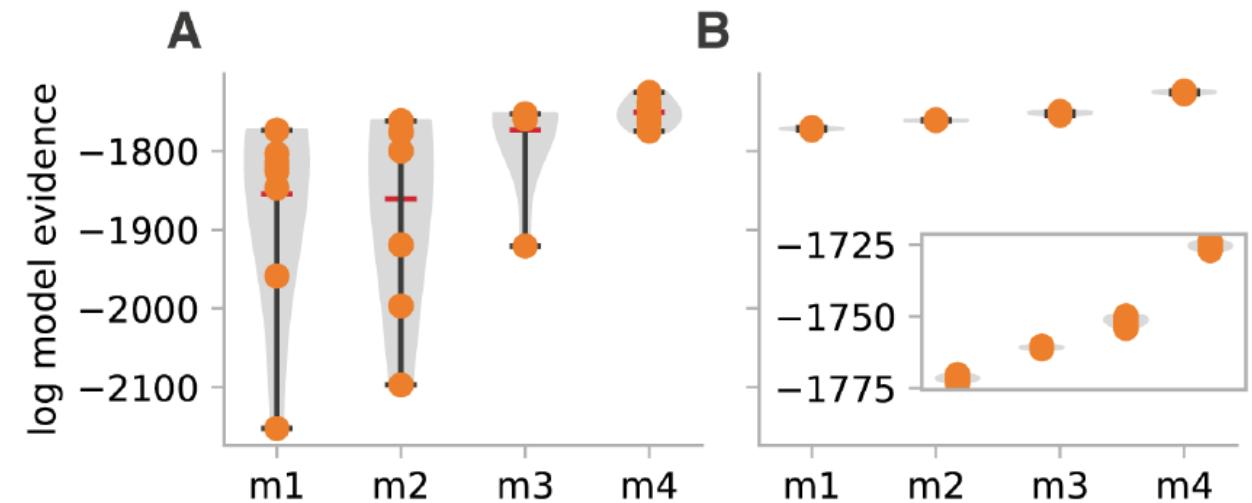
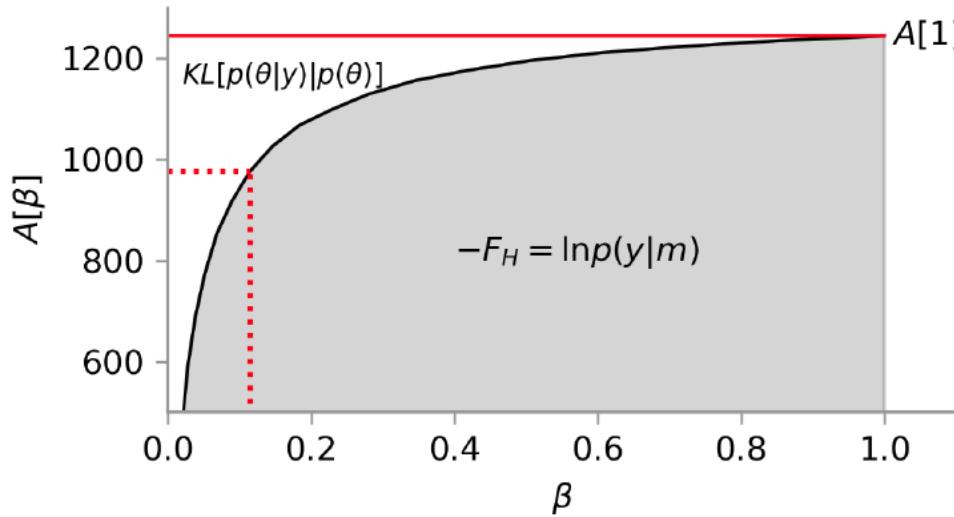
$$\tau_l \frac{dv_l}{dt} = f_l - v_l^{\frac{1}{\alpha_l}}$$

$$\tau_l \frac{dq_l}{dt} = f_l \frac{1 - (1 - E_0)^{1/f_l}}{E_0} - v_l^{1/\alpha_l} \frac{q_l}{v_l}$$

$$\tau_d \frac{dv_l^*}{dt} = -v_l^* + (v_l - 1)$$

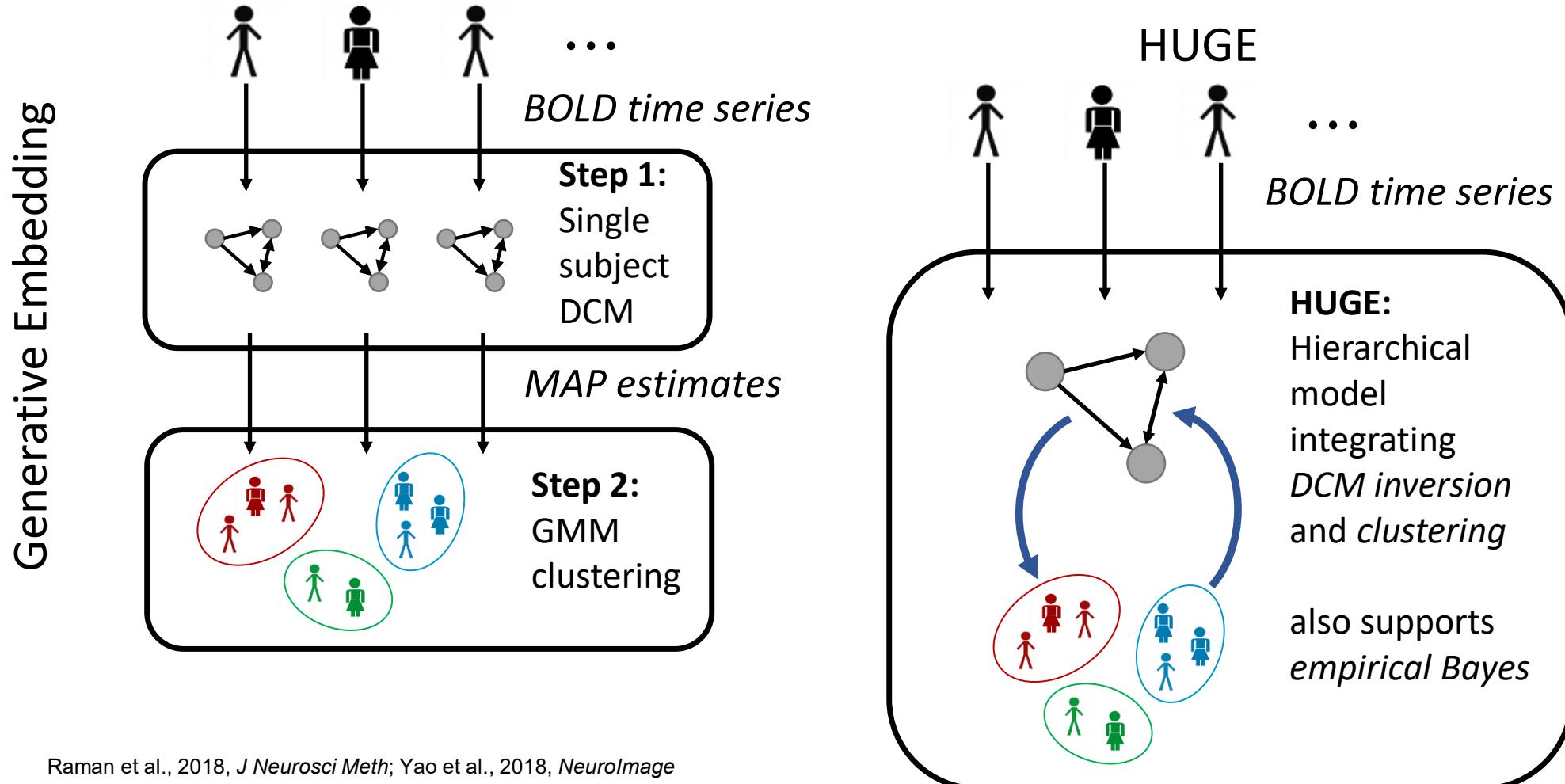
$$\tau_d \frac{dq_l^*}{dt} = -q_l^* + (q_l - 1)$$

THERMODYNAMIC INTEGRATION FOR DCM



Aponte et al., 2016, *J Neurosci Meth*; Aponte et al., 2018, *biorXiv*;

HUGE – HIERARCHICAL UNSUPERVISED GENERATIVE EMBEDDING



STOCHASTIC DCM

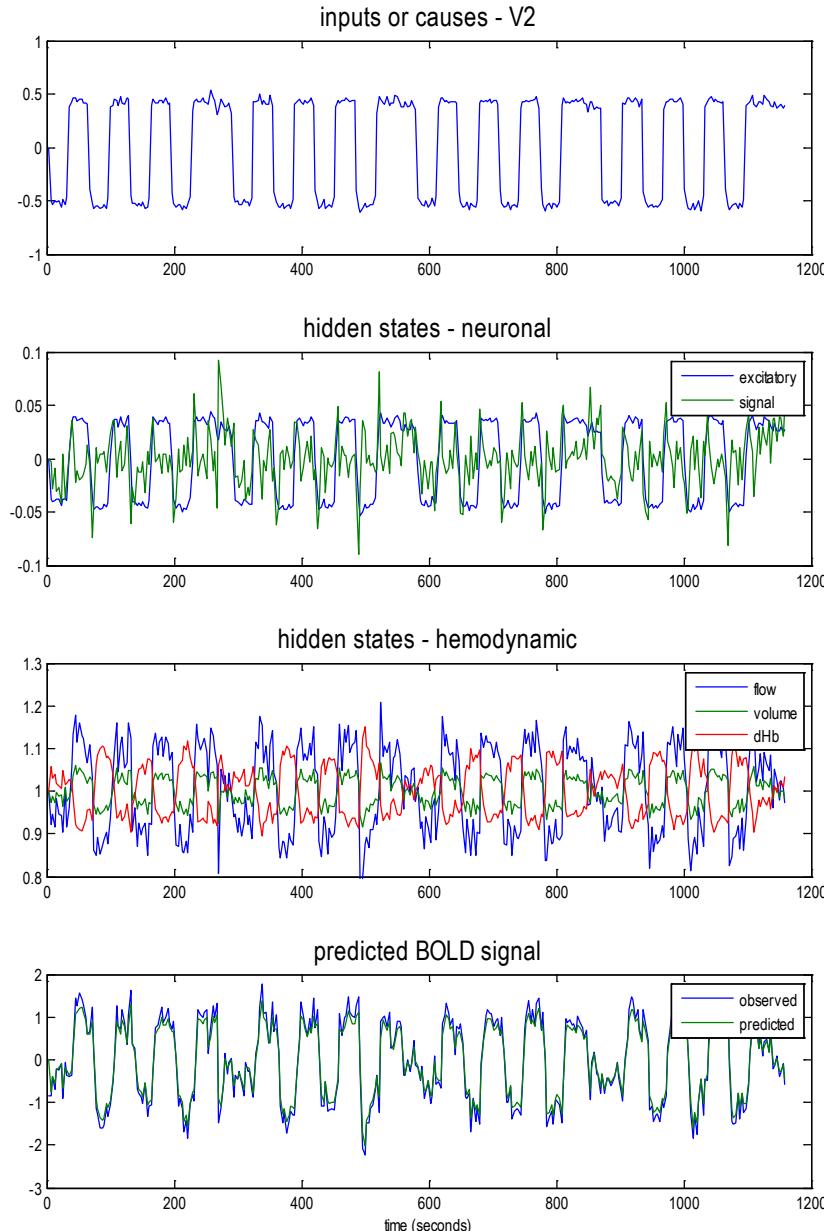
$$\frac{dx}{dt} = (A + \sum_j u_j B^{(j)})x + Cv + \omega^{(x)}$$

$$v = u + \omega^{(v)}$$

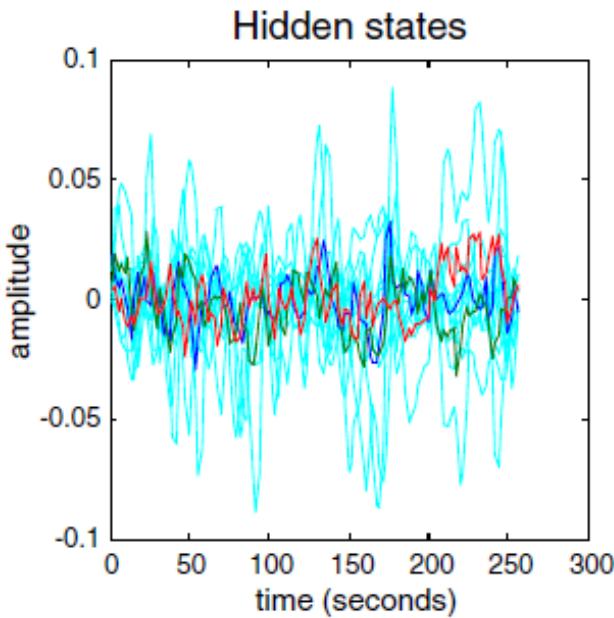
- all states are represented in generalised coordinates of motion
- random state fluctuations $\omega^{(x)}$ account for endogenous fluctuations, have unknown precision and smoothness
→ two hyperparameters
- fluctuations $\omega^{(v)}$ induce uncertainty about how inputs influence neuronal activity
- can be fitted to resting state data

Li et al., 2011, *NeuroImage*

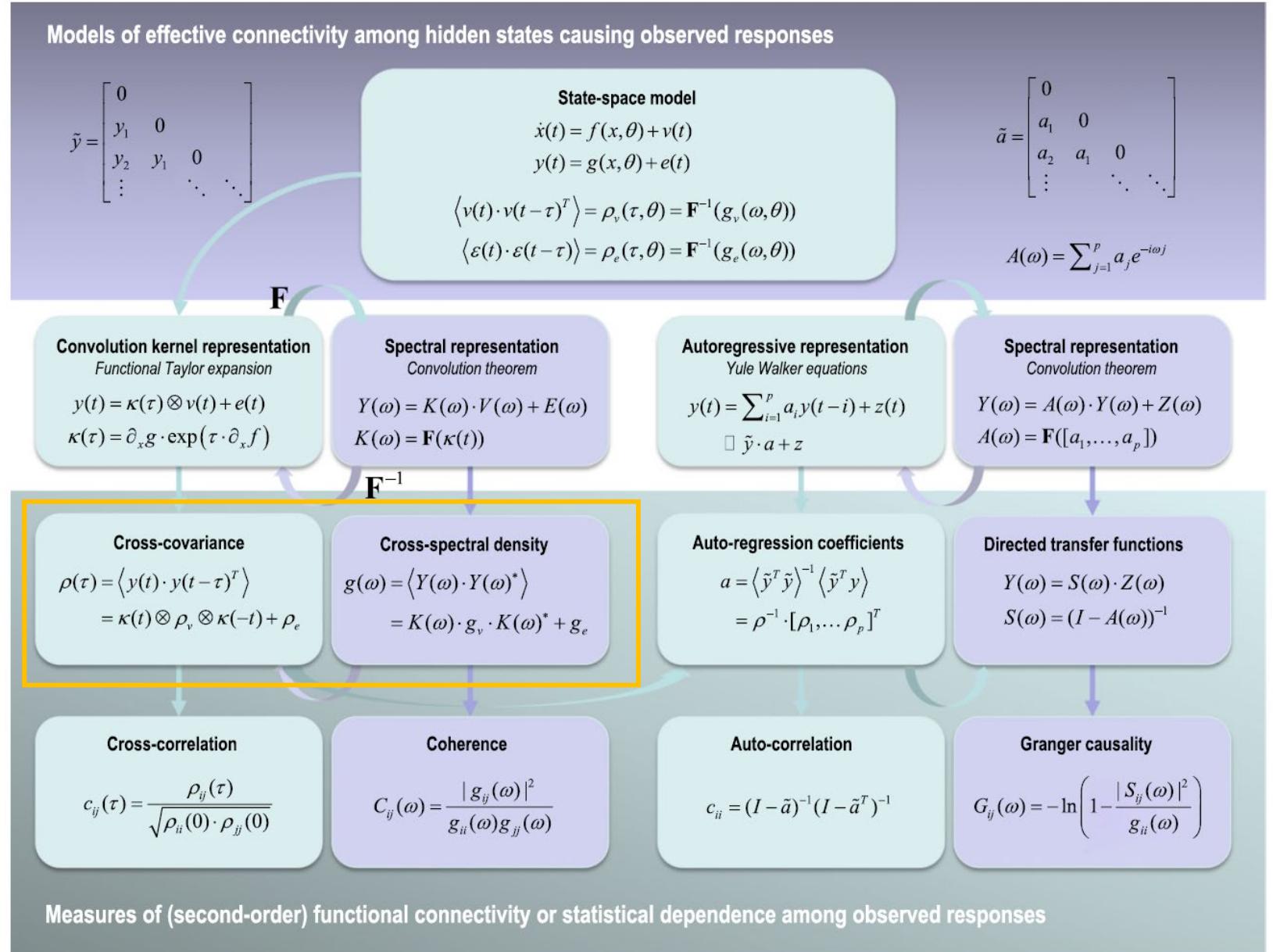
Estimates of hidden causes and states (Generalised filtering)



SPECTRAL DCM – RESTING STATE



Friston et al, 2014, *Neuroimage*



SPECTRAL DCM – RESTING STATE

Cross-covariance

$$\begin{aligned}\rho(\tau) &= \langle y(t) \cdot y(t - \tau)^T \rangle \\ &= \kappa(t) \otimes \rho_v \otimes \kappa(-t) + \rho_e\end{aligned}$$

Cross-spectral density

$$\begin{aligned}g(\omega) &= \langle Y(\omega) \cdot Y(\omega)^* \rangle \\ &= K(\omega) \cdot g_v \cdot K(\omega)^* + g_e\end{aligned}$$

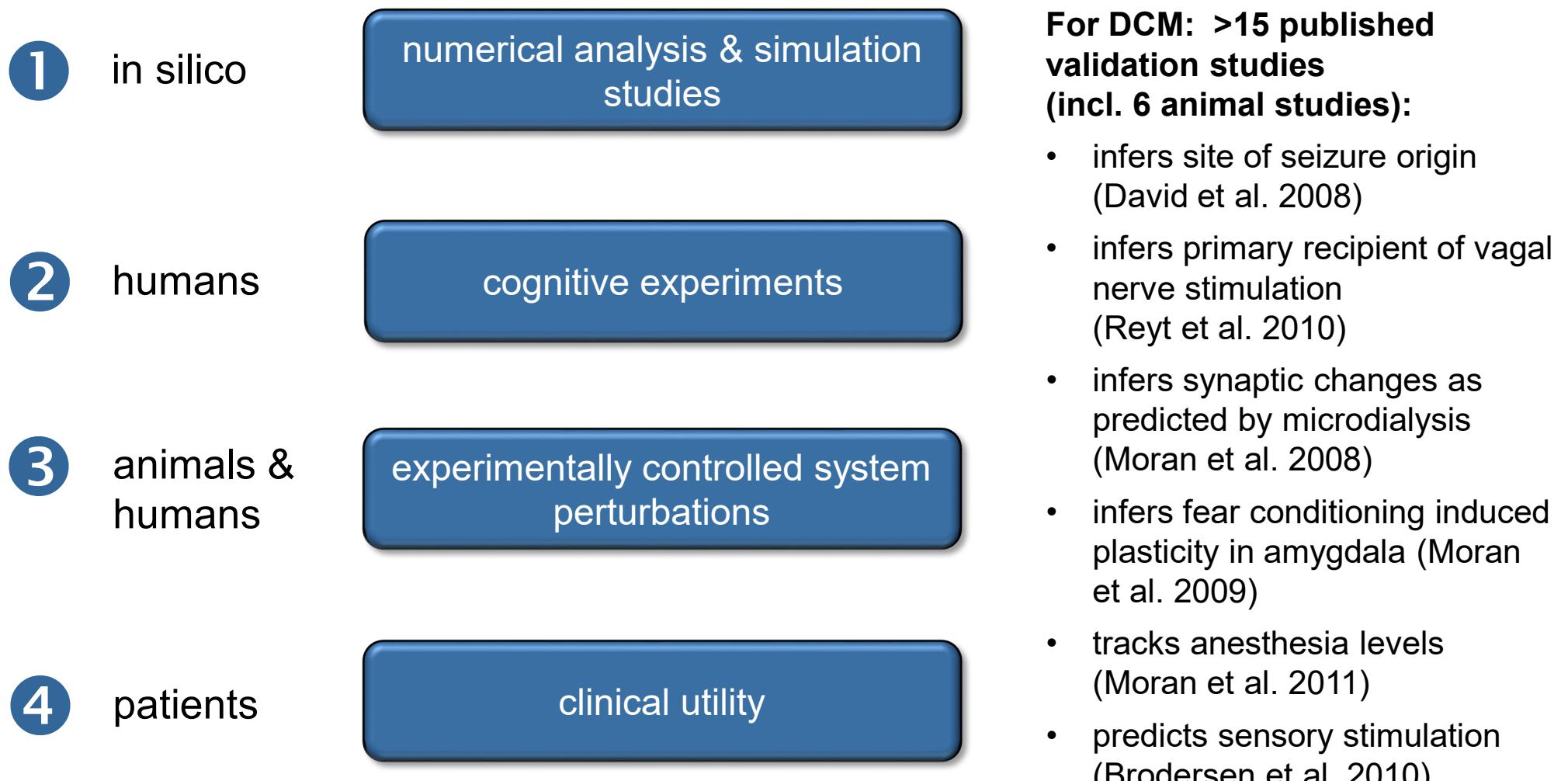
Friston et al, 2014, *Neuroimage*

ALL MODELS ARE WRONG BUT SOME ARE USEFUL

George Edward Pelham Box
(1919-2013)



HIERARCHICAL STRATEGY FOR MODEL VALIDATION



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