

# Signal Processing and Linear Systems I

## Lecture 3: Signal Models

January 7, 2013

## Models of Continuous Time Signals

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Today's topics:

- Sinuoidal signals
- Exponential signals
- Complex exponential signals
- Unit step and unit ramp
- Impulse functions

## Sinusoidal Signals

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- A sinusoidal signal is of the form

$$x(t) = \cos(\omega t + \theta).$$

where the *radian frequency* is  $\omega$ , which has the units of radians/s.

- Also very commonly written as

$$x(t) = A \cos(2\pi f t + \theta).$$

where  $f$  is the frequency in Hertz.

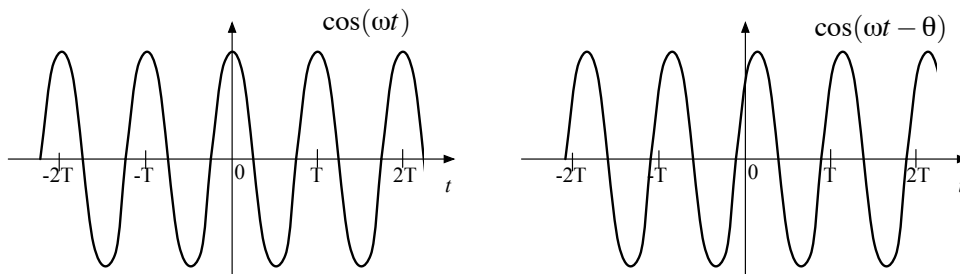
- We will often refer to  $\omega$  as the frequency, but it must be kept in mind that it is really the *radian frequency*, and the *frequency* is actually  $f$ .

- The (fundamental) period of the sinuoid is

$$T = \frac{1}{f} = \frac{2\pi}{\omega}$$

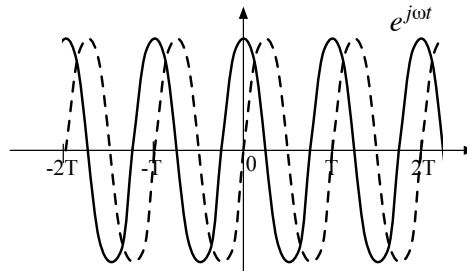
with the units of seconds.

- The *phase* or *phase angle* of the signal is  $\theta$ , given in radians.



## Complex Sinusoids

- The Euler relation defines  $e^{j\phi} = \underbrace{\cos \phi}_{\Re(e^{j\phi})} + j \underbrace{\sin \phi}_{\Im(e^{j\phi})}$ .
- A complex sinusoid is  $Ae^{j(\omega t + \theta)} = A \cos(\omega t + \theta) + jA \sin(\omega t + \theta)$ .



- Real sinusoid can be represented as the real part of a complex sinusoid

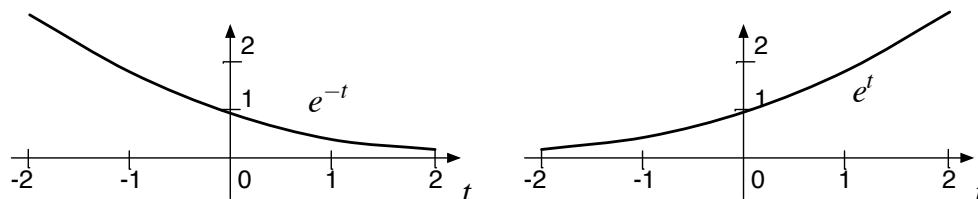
$$\Re\{Ae^{j(\omega t + \theta)}\} = A \cos(\omega t + \theta)$$

## Exponential Signals

- An exponential signal is given by

$$x(t) = e^{\sigma t}$$

- If  $\sigma < 0$  this is *exponential decay*.
- If  $\sigma > 0$  this is *exponential growth*.

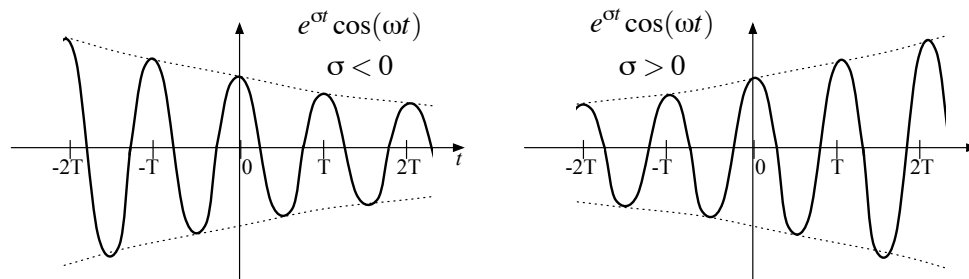


## Damped or Growing Sinusoids

- A damped or growing sinusoid is given by

$$x(t) = e^{\sigma t} \cos(\omega t + \theta)$$

- Exponential growth ( $\sigma > 0$ ) or decay ( $\sigma < 0$ ), modulated by a sinusoid.

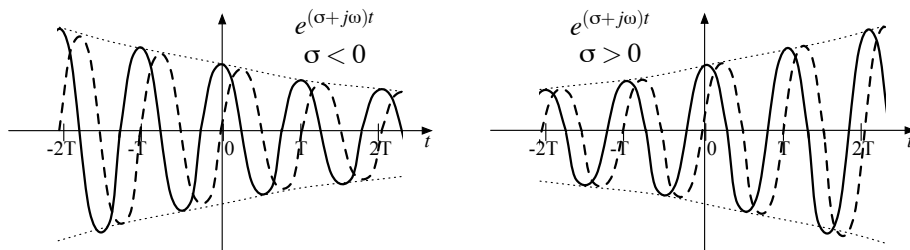


## Complex Exponential Signals

- A complex exponential signal is given by

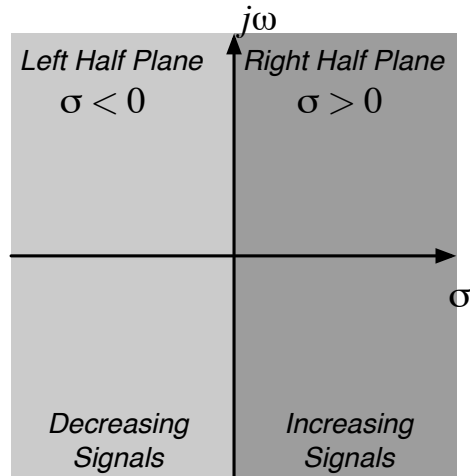
$$e^{(\sigma+j\omega)t+j\theta} = e^{\sigma t}(\cos(\omega t + \theta) + j \sin(\omega t + \theta))$$

- A exponential growth or decay, modulated by a complex sinusoid.
- Includes all of the previous signals as special cases.



## Complex Plane

Each complex frequency  $s = \sigma + j\omega$  corresponds to a position in the complex plane.

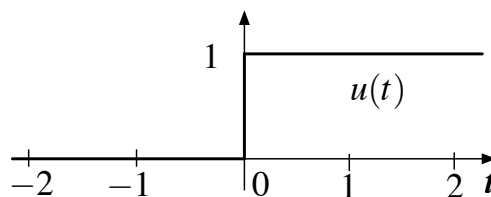


## Unit Step Functions

- The *unit step function*  $u(t)$  (or  $u_{-1}(t)$ ) is defined as

$$u(t) = \begin{cases} 1, & t \geq 0 \\ 0, & t < 0 \end{cases}$$

- Also known as the *Heaviside step function*.
- Alternate definitions of value exactly at zero, such as  $1/2$ .



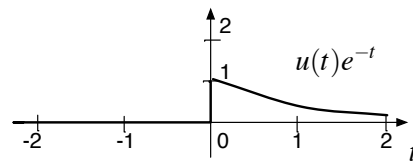
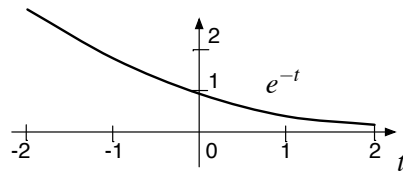
### Uses for the unit step:

- Extracting part of another signal. For example, the piecewise-defined signal

$$x(t) = \begin{cases} e^{-t}, & t \geq 0 \\ 0, & t < 0 \end{cases}$$

can be written as

$$x(t) = u(t)e^{-t}$$

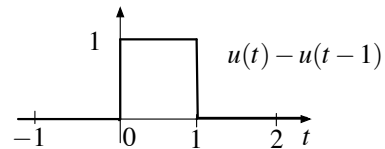
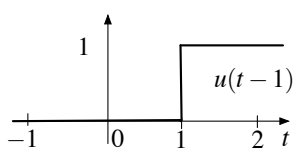
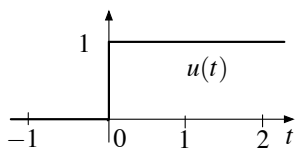


- Combinations of unit steps to create other signals. The offset rectangular signal

$$x(t) = \begin{cases} 0, & t \geq 1 \\ 1, & 0 \leq t < 1 \\ 0, & t < 0 \end{cases}$$

can be written as

$$x(t) = u(t) - u(t - 1).$$

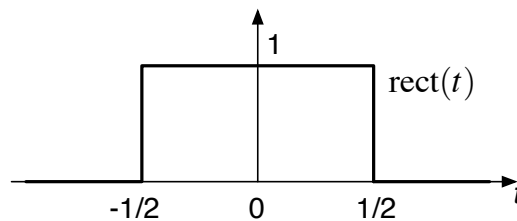


## Unit Rectangle

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Unit rectangle signal:

$$\text{rect}(t) = \begin{cases} 1 & \text{if } |t| \leq 1/2 \\ 0 & \text{otherwise.} \end{cases}$$



## Unit Ramp

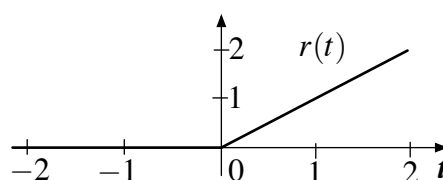
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- The *unit ramp* is defined as

$$r(t) = \begin{cases} t, & t \geq 0 \\ 0, & t < 0 \end{cases}$$

- The unit ramp is the integral of the unit step,

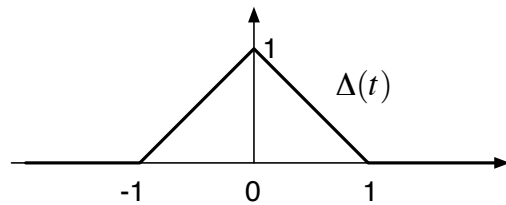
$$r(t) = \int_{-\infty}^t u(\tau) d\tau$$



## Unit Triangle

### Unit Triangle Signal

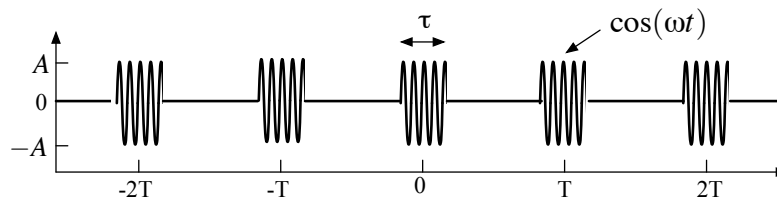
$$\Delta(t) = \begin{cases} 1 - |t| & \text{if } |t| < 1 \\ 0 & \text{otherwise.} \end{cases}$$



## More Complex Signals

Many more interesting signals can be made up by combining these elements.

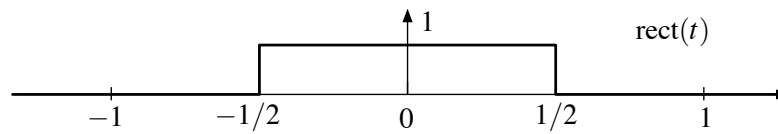
*Example:* Pulsed Doppler RF Waveform (we'll talk about this later!)



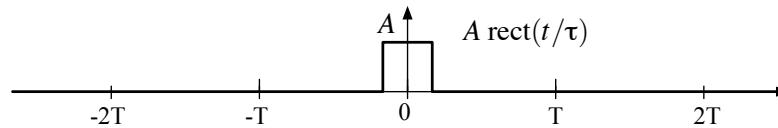
RF cosine gated on for  $\tau \mu\text{s}$ , repeated every  $T \mu\text{s}$ , for a total of  $N$  pulses.



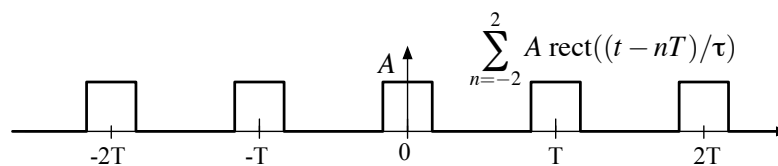
Start with a simple  $\text{rect}(t)$  pulse



Scale to the correct duration and amplitude for one subpulse

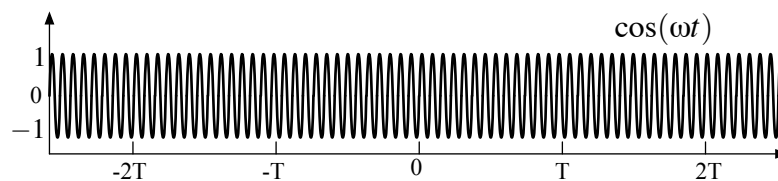


Combine shifted replicas

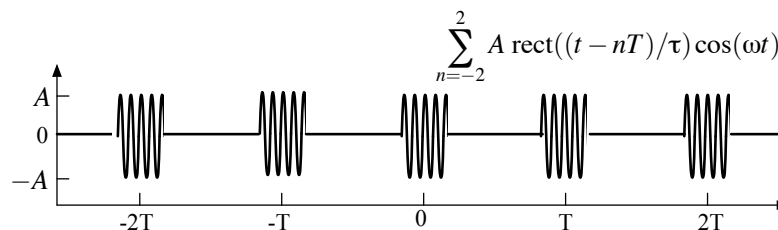


This is the *envelope* of the signal.

Then multiply by the RF carrier, shown below



to produce the pulsed Doppler waveform

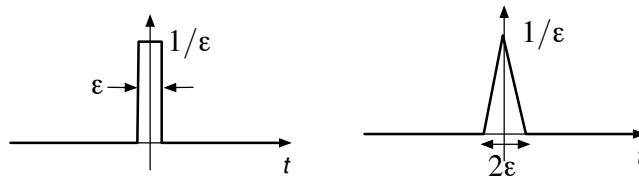


## Impulsive signals

(Dirac's) **delta function** or **unit impulse**  $\delta$  is an *idealization* of a signal that

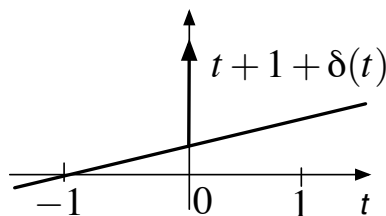
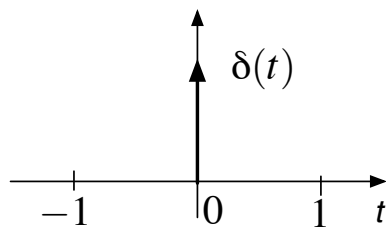
- is very large near  $t = 0$
- is very small away from  $t = 0$
- has integral 1

for example:



- the exact shape of the function doesn't matter
- $\epsilon$  is small (which depends on context)

On plots  $\delta$  is shown as a solid arrow:



## Formal properties

Formally we **define**  $\delta$  by the property that

$$\int_{-\infty}^{\infty} f(t)\delta(t) dt = f(0)$$

provided  $f$  is continuous at  $t = 0$

**Basic Idea:**  $\delta$  acts over a time interval very small, over which  $f(t) \approx f(0)$

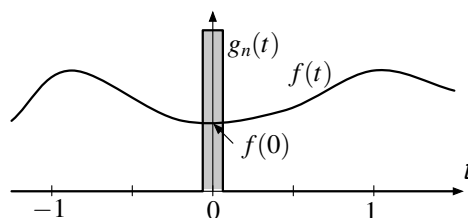
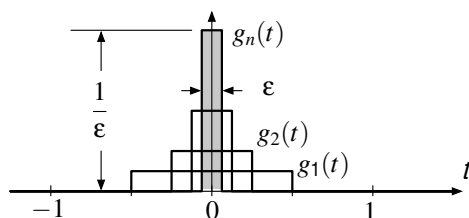
- $\delta(t)$  is not really defined for any  $t$ , only its behavior in an integral.
- Often described (incorrectly) as  $\delta(t) = 0$  for  $t \neq 0$ , infinite at  $t = 0$ . This is a valid (if bizarre) function, but it does *not* have unit integral! Its Riemann integral is 0!

**Example:** Model  $\delta(t)$  as

$$g_n(t) = n \operatorname{rect}(nt)$$

as  $n \rightarrow \infty$ . This has an area  $(n)(1/n) = 1$ . If  $f(t)$  is continuous at  $t = 0$ , then

$$\int_{-\infty}^{\infty} f(t)\delta(t) dt = \lim_{n \rightarrow \infty} \int_{-\infty}^{\infty} f(t)g_n(t) dt = f(0) \int_{-\infty}^{\infty} g_n(t) dt = f(0)$$



**Not true that  $\lim_{n \rightarrow \infty} g_n(t) = \delta(t)$ !!** Limit is *outside* the integral.

## Scaled impulses

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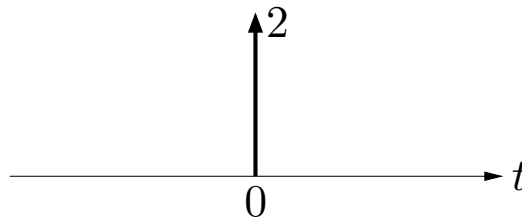
$\alpha\delta(t)$  is an impulse at time 0, with *magnitude* or *strength* or *area*  $\alpha$

We have

$$\int_{-\infty}^{\infty} \alpha\delta(t)f(t) dt = \alpha f(0)$$

provided  $f$  is continuous at 0

On plots: write area next to the arrow, e.g., for  $2\delta(t)$ ,



## Multiplication of a Function by an Impulse

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- Consider a function  $\phi(t)$  multiplied by an impulse  $\delta(t)$ ,

$$\phi(t)\delta(t)$$

If  $\phi(t)$  is continuous at  $t = 0$ , can this be simplified?

- Substitute into the formal definition with a continuous  $f(t)$  and evaluate,

$$\begin{aligned} \int_{-\infty}^{\infty} f(t) [\phi(t)\delta(t)] dt &= \int_{-\infty}^{\infty} [f(t)\phi(t)] \delta(t) dt \\ &= f(0)\phi(0) \end{aligned}$$

- Hence

$$\phi(t)\delta(t) = \phi(0)\delta(t)$$

is a scaled impulse, with strength  $\phi(0)$ .

## Sifting property

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- The signal  $x(t) = \delta(t - T)$  is an impulse function with impulse at  $t = T$ .
- For  $f$  continuous at  $t = T$ ,

$$\int_{-\infty}^{\infty} f(t)\delta(t - T) dt = f(T)$$

- Multiplying a function  $f(t)$  by an impulse at time  $T$  and integrating, extracts the value of  $f(T)$ .
- This will be important in modeling sampling later in the course.

## Limits of Integration

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The integral of a  $\delta$  is non-zero only if it is in the integration interval:

- If  $a < 0$  and  $b > 0$  then

$$\int_a^b \delta(t) dt = 1$$

because the  $\delta$  is within the limits.

- If  $a > 0$  or  $b < 0$ , and  $a < b$  then

$$\int_a^b \delta(t) dt = 0$$

because the  $\delta$  is outside the integration interval.

- **Ambiguous** if  $a = 0$  or  $b = 0$

Our convention: to avoid confusion we use limits such as  $a-$  or  $b+$  to denote whether we include the impulse or not.

$$\int_{0+}^1 \delta(t) dt = 0, \quad \int_{0-}^1 \delta(t) dt = 1, \quad \int_{-1}^{0-} \delta(t) dt = 0, \quad \int_{-1}^{0+} \delta(t) dt = 1$$

**Example:**

$$\begin{aligned} & \int_{-2}^3 f(t)(2 + \delta(t+1) - 3\delta(t-1) + 2\delta(t+3)) dt \\ &= 2 \int_{-2}^3 f(t) dt + \int_{-2}^3 f(t)\delta(t+1) dt - 3 \int_{-2}^3 f(t)\delta(t-1) dt \\ & \quad + 2 \int_{-2}^3 f(t)\delta(t+3) dt \\ &= 2 \int_{-2}^3 f(t) dt + f(-1) - 3f(1) \end{aligned}$$

## Physical interpretation

Impulse functions are used to model physical signals

- that act over short time intervals
- whose effect depends on integral of signal

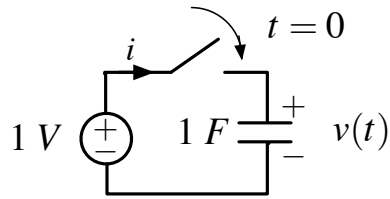
**Example:** hammer blow, or bat hitting ball, at  $t = 2$

- force  $f$  acts on mass  $m$  between  $t = 1.999$  sec and  $t = 2.001$  sec
- $\int_{1.999}^{2.001} f(t) dt = I$  (mechanical impulse, N · sec)
- blow induces change in velocity of

$$v(2.001) - v(1.999) = \frac{1}{m} \int_{1.999}^{2.001} f(\tau) d\tau = I/m$$

For most applications, model force as impulse at  $t = 2$ , with magnitude  $I$ .

**example:** rapid charging of capacitor

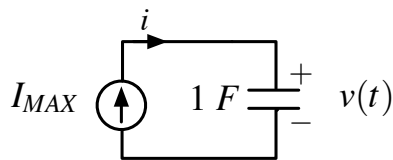


assuming  $v(0) = 0$ , what is  $v(t)$ ,  $i(t)$  for  $t > 0$ ?

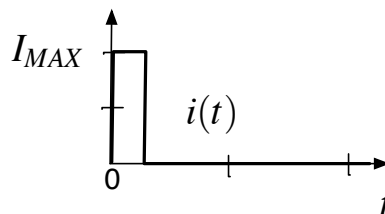
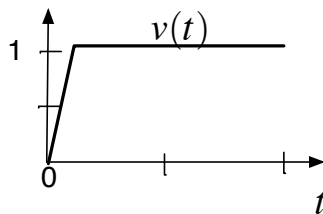
- $i(t)$  is very large, for a very short time
- a unit charge is transferred to the capacitor 'almost instantaneously'
- $v(t)$  increases to  $v(t) = 1$  'almost instantaneously'

To calculate  $i$ ,  $v$ , we need a more detailed model.

For example, assume the current delivered by the source is limited: if  $v(t) < 1$ , the source acts as a current source  $i(t) = I_{\max}$



$$i(t) = \frac{dv(t)}{dt} = I_{\max}, \quad v(0) = 0$$



As  $I_{\max} \rightarrow \infty$ ,  $i$  approaches an impulse,  $v$  approaches a unit step

In conclusion,

- large current  $i$  acts over very short time between  $t = 0$  and  $\epsilon$
- total charge transfer is  $\int_0^\epsilon i(t) dt = 1$
- resulting change in  $v(t)$  is  $v(\epsilon) - v(0) = 1$
- can approximate  $i$  as impulse at  $t = 0$  with magnitude 1

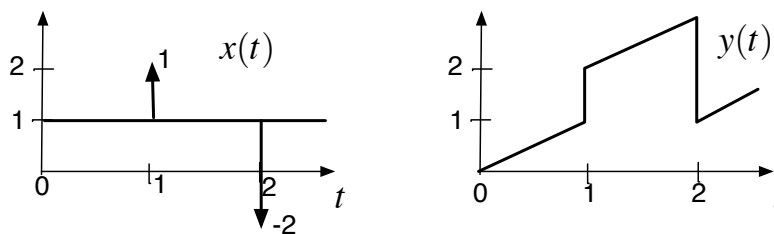
Modeling current as impulse

- obscures details of current signal
- obscures details of voltage change during the rapid charging
- preserves total change in charge, voltage
- is reasonable model for time scales  $\gg \epsilon$

## Integrals of impulsive functions

Integral of a function with impulses has jump at each impulse, equal to the magnitude of impulse

**example:**  $x(t) = 1 + \delta(t - 1) - 2\delta(t - 2)$ ; define  $y(t) = \int_0^t x(\tau) d\tau$



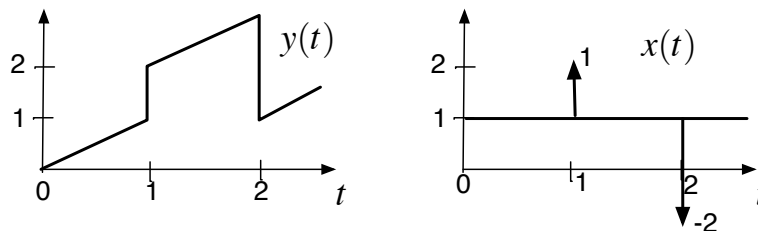


## Derivatives of discontinuous functions

Conversely, derivative of function with discontinuities has impulse at each jump in function

- Derivative of unit step function  $u(t)$  is  $\delta(t)$
- Signal  $y$  of previous page

$$y'(t) = 1 + \delta(t - 1) - 2\delta(t - 2)$$



## Derivatives of impulse functions

Integration by parts suggests we define

$$\int_{-\infty}^{\infty} \delta'(t) f(t) dt = \delta(t) f(t) \Big|_{-\infty}^{\infty} - \int_{-\infty}^{\infty} \delta(t) f'(t) dt = -f'(0)$$

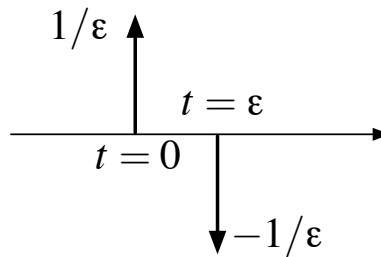
provided  $f'$  continuous at  $t = 0$

- $\delta'$  is called *doublet*
- $\delta'$ ,  $\delta''$ , etc. are called *higher-order impulses* (or singularity functions)
- Similar rules for higher-order impulses:

$$\int_{-\infty}^{\infty} \delta^{(k)}(t) f(t) dt = (-1)^k f^{(k)}(0)$$

if  $f^{(k)}$  continuous at  $t = 0$

**Interpretation** of doublet  $\delta'$ : take two impulses with magnitude  $\pm 1/\epsilon$ , a distance  $\epsilon$  apart, and let  $\epsilon \rightarrow 0$



Then

$$\int_{-\infty}^{\infty} f(t) \left( \frac{\delta(t)}{\epsilon} - \frac{\delta(t - \epsilon)}{\epsilon} \right) dt = \frac{f(0) - f(\epsilon)}{\epsilon}$$

converges to  $-f'(0)$  if  $\epsilon \rightarrow 0$

## Caveat

$\delta(t)$  is not a signal or function in the ordinary sense, it only makes mathematical sense when inside an integral sign

- We manipulate impulsive functions as if they were real functions, which they aren't
- It is safe to use impulsive functions in expressions like

$$\int_{-\infty}^{\infty} f(t) \delta(t - T) dt, \quad \int_{-\infty}^{\infty} f(t) \delta'(t - T) dt$$

provided  $f$  (resp,  $f'$ ) is continuous at  $t = T$ .

- Some innocent looking expressions don't make any sense at all (e.g.,  $\delta(t)^2$  or  $\delta(t^2)$ )