

STANFORD UNIVERSITY

EE 102B Spring-2013

Lecture 14

Discrete-Time Filtering of Continuous-Time Signals

May 1, 2013

ASSIGNMENTS

- Reading for this Lecture:
 - SPF: Section 12-3
 - S&S: Chapter 5
- HW#04 is due by 5pm today, May 1, in Packard 263.
- Lab #04 is due by 5pm, Friday, May 3, in Packard 263. Contact Keith Gaul for access to EE computer cluster if you need the signal processing toolbox. gaul@ee.stanford.edu

Office Hours for Course Staff – Come see us.

- Ron Schafer: Mon. 2:00-4:00 pm. Not available for office hours today.
- Dookun Park: Tues. 1:30 ~ 3:30 pm in Packard 107
- Ruo Yu Gu (Roy): Mon. 4:00 ~ 6:00 pm in Packard 106
- <https://class2go.stanford.edu/EE102B/Spring2013/pages/staff>

Lecture Objective

- Review sampling and reconstruction
 - C-to-D conversion
 - Relation of CTFT to DTFT
- A-to-D and D-to-A conversion
- Discrete-time filtering of continuous-time signals

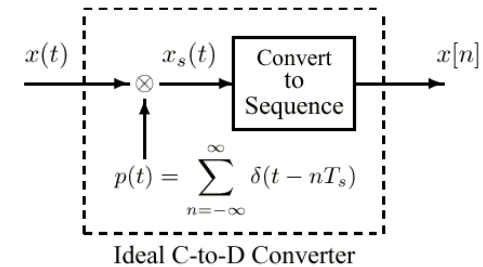
REVIEW OF SAMPLING AND RECONSTRUCTION

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Representing Sampling by Impulse Train Modulation



$$x_s(t) = x(t) \sum_{n=-\infty}^{\infty} \delta(t - nT_s) = \sum_{n=-\infty}^{\infty} \underline{x(t)\delta(t - nT_s)}$$

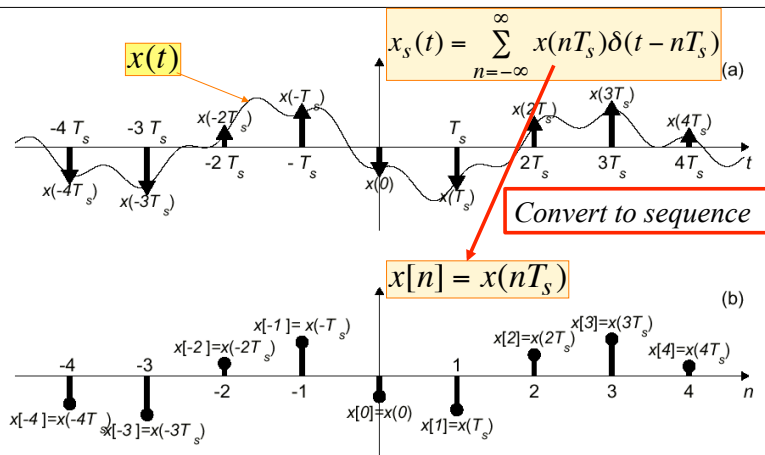
$$x_s(t) = \sum_{n=-\infty}^{\infty} \underline{x(nT_s)\delta(t - nT_s)}$$

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Illustration of Sampling



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Frequency-Domain Analysis

$$x_s(t) = x(t) \sum_{n=-\infty}^{\infty} \delta(t - nT_s) = \sum_{n=-\infty}^{\infty} x(nT_s)\delta(t - nT_s)$$

$$x_s(t) = x(t) \sum_{k=-\infty}^{\infty} \frac{1}{T_s} e^{jk\omega_s t} = \frac{1}{T_s} \sum_{k=-\infty}^{\infty} \underline{x(t)e^{jk\omega_s t}}$$

$$X_s(j\omega) = \frac{1}{T_s} \sum_{k=-\infty}^{\infty} \underline{X(j(\omega - k\omega_s))}$$

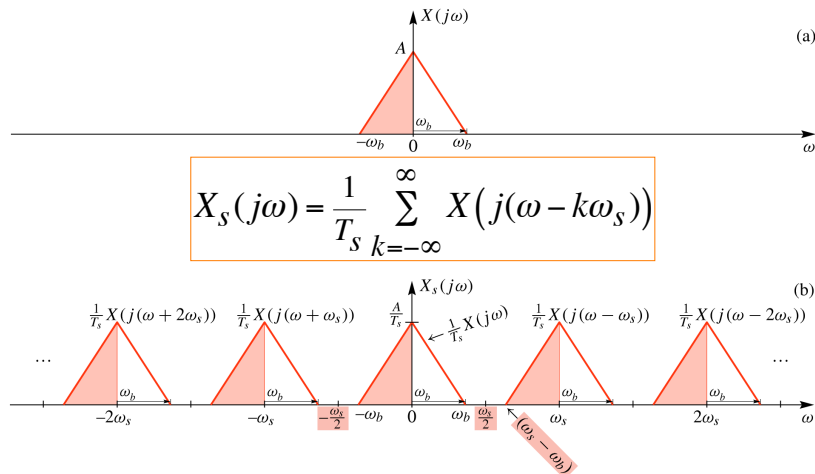
$$\omega_s = \frac{2\pi}{T_s}$$

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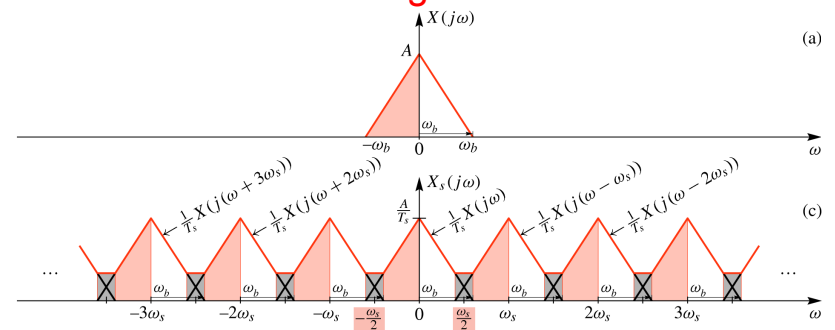
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Frequency-Domain Representation of Sampling



Aliasing Distortion

- If $\omega_s < 2\omega_b$, the copies of $X(j\omega)$ overlap, and we have **aliasing distortion**.



Relation to the DTFT

- Look at the CTFT of $x_s(t)$ in a different way

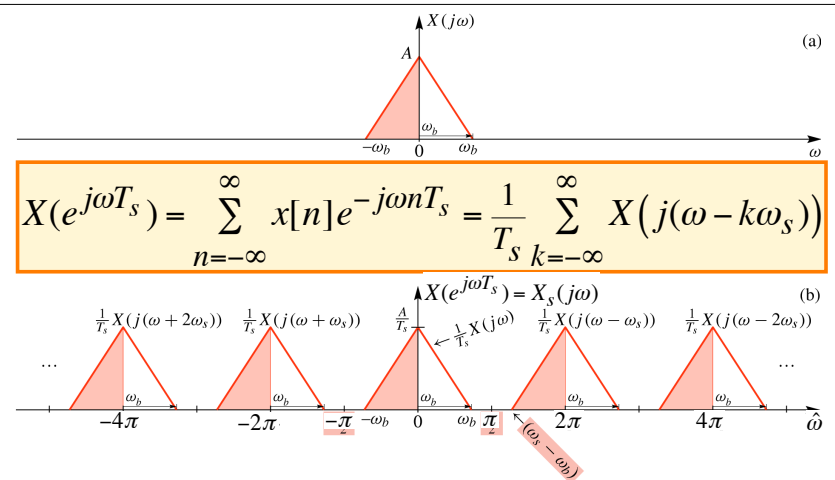
$$x_s(t) = \sum_{n=-\infty}^{\infty} x(nT_s) \delta(t - nT_s)$$

$$X_s(j\omega) = \sum_{n=-\infty}^{\infty} x(nT_s) e^{-j\omega nT_s} = X(e^{j\omega T_s})$$

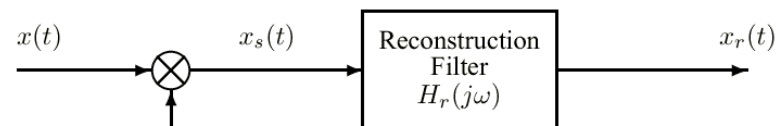
$$X(e^{j\omega T_s}) = \sum_{n=-\infty}^{\infty} x[n] e^{-j\omega nT_s} = \frac{1}{T_s} \sum_{k=-\infty}^{\infty} X(j(\omega - k\omega_s))$$

Recall that: $\hat{\omega} = \omega T_s$ $x[n] = x(nT_s)$ $\omega_s = \frac{2\pi}{T_s}$

Frequency-Domain Representation of Sampling



Reconstruction of $x(t)$



$$p(t) = \sum_{n=-\infty}^{\infty} \delta(t - nT_s)$$

$$x_s(t) = \sum_{n=-\infty}^{\infty} x(nT_s) \delta(t - nT_s) = \frac{1}{T_s} \sum_{k=-\infty}^{\infty} x(t) e^{jk\omega_s t}$$

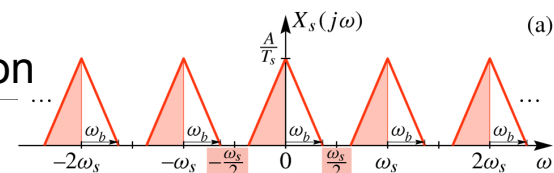
$$X_s(j\omega) = \frac{1}{T_s} \sum_{k=-\infty}^{\infty} X(j(\omega - k\omega_s))$$

$$X_r(j\omega) = H_r(j\omega) X_s(j\omega)$$

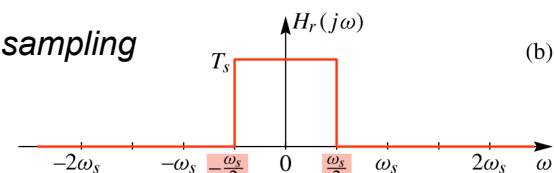
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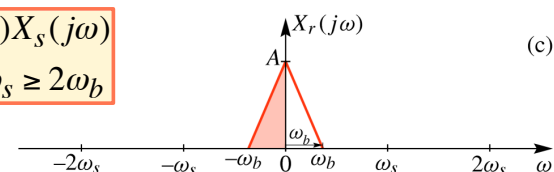
Bandlimited Reconstruction



This proves the sampling theorem.



$$X_r(j\omega) = H_r(j\omega) X_s(j\omega) \\ = X(j\omega) \text{ when } \omega_s \geq 2\omega_b$$



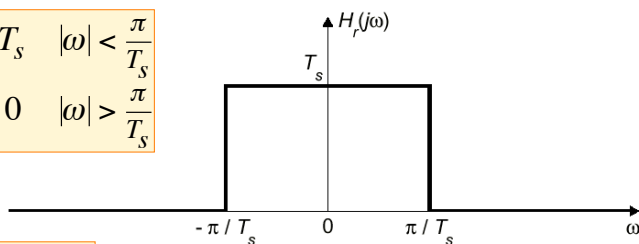
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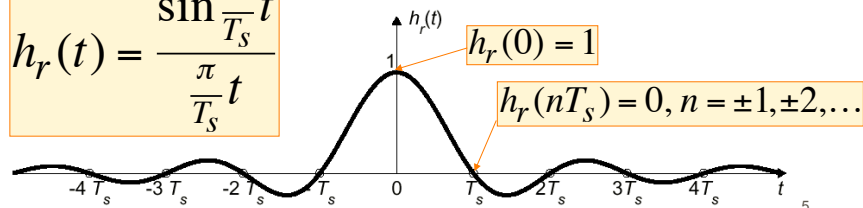
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Ideal Reconstruction Filter

$$H_r(j\omega) = \begin{cases} T_s & |\omega| < \frac{\pi}{T_s} \\ 0 & |\omega| > \frac{\pi}{T_s} \end{cases}$$



$$h_r(t) = \frac{\sin \frac{\pi}{T_s} t}{\frac{\pi}{T_s} t}$$



Signal Reconstruction

$$x_r(t) = h_r(t) * x_s(t) = h_r(t) * \sum_{n=-\infty}^{\infty} x(nT_s) \delta(t - nT_s)$$

$$x_r(t) = \sum_{n=-\infty}^{\infty} x(nT_s) h_r(t - nT_s)$$

$$x_r(t) = \sum_{n=-\infty}^{\infty} x(nT_s) \frac{\sin \frac{\pi}{T_s} (t - nT_s)}{\frac{\pi}{T_s} (t - nT_s)}$$

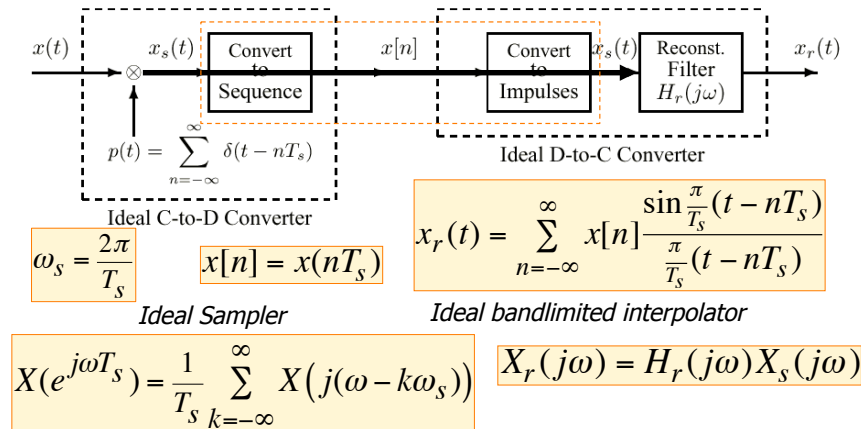
Ideal bandlimited interpolation formula

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Ideal C-to-D and D-to-C Back-to-Back



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Example of Sampling a Sinusoidal Signal (Ex. 12-6)

- Consider a signal of the form:

$$x(t) = \frac{1}{3\pi} + \frac{1}{3\pi} \cos(\pi t + \pi/2)$$

- Its CTFT is

$$X(j\omega) = \frac{2}{3} \delta(\omega) + \frac{j}{3} \delta(\omega - \pi) - \frac{j}{3} \delta(\omega + \pi)$$

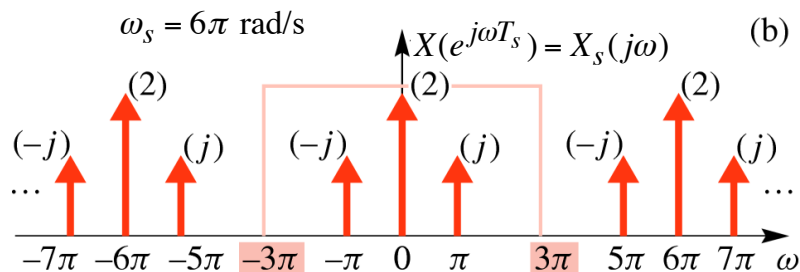
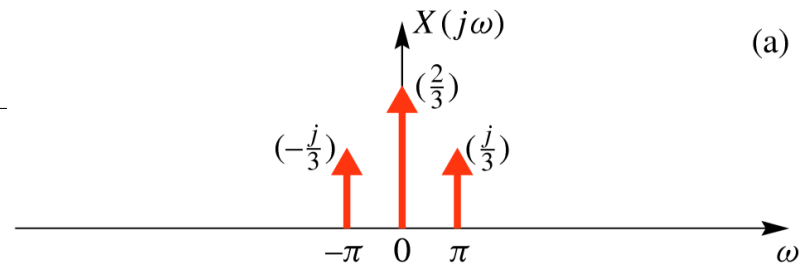
- The DTFT of $x[n]$ with $\omega_s = 6\pi$ ($T_s = 1/3$)

$$X(e^{j\omega T_s}) = 3 \left[\frac{2}{3} \delta(\omega) + \frac{j}{3} \delta(\omega - \pi) - \frac{j}{3} \delta(\omega + \pi) \right] \quad |\omega| \leq \frac{\pi}{T_s}$$

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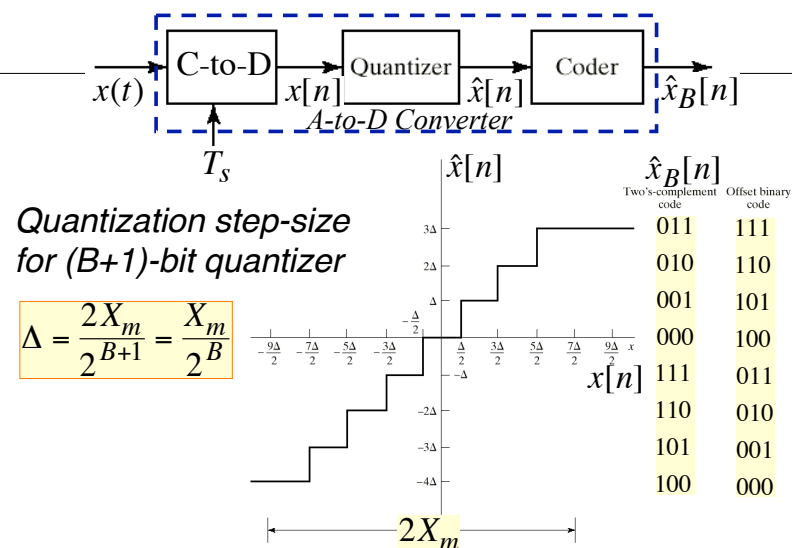
A-to-D CONVERSION

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Representation of A-to-D Converter



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Listening Experiment on the Effects of Quantization

	Signal	Error
"Unquantized" speech signal		
3-bit quantized Speech signal		
8-bit quantized speech signal		X32

$$\text{Bit rate} = B \cdot f_s$$

Quantization is perceived as "noise" in audio signals.
We study quantization noise in EE264.

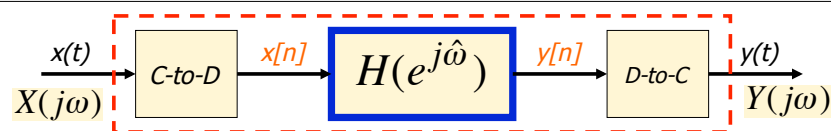
DISCRETE-TIME FILTERING OF CONTINUOUS-TIME SIGNALS

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DT Filtering of CT Signals



If no aliasing occurs in sampling $x(t)$, then

$$Y(j\omega) = H_{\text{eff}}(j\omega)X(j\omega)$$

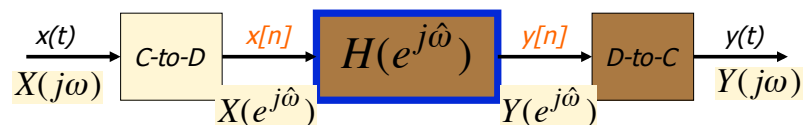
$$H_{\text{eff}}(j\omega) = \begin{cases} H(e^{j\omega T_s}) & |\omega| < \frac{1}{2}\omega_s \\ 0 & |\omega| > \frac{1}{2}\omega_s \end{cases}$$

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C-to-D Converter

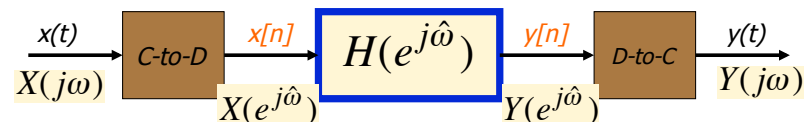


$$x[n] = x(nT_s)$$

$$X_s(j\omega) = \frac{1}{T_s} \sum_{k=-\infty}^{\infty} X(j(\omega - k\omega_s))$$

$$X(e^{j\omega T_s}) = X(e^{j\hat{\omega}}) \Big|_{\hat{\omega}=\omega T_s} = \sum_{n=-\infty}^{\infty} x[n] e^{-j\omega T_s n} = X_s(j\omega)$$

LTI DT System

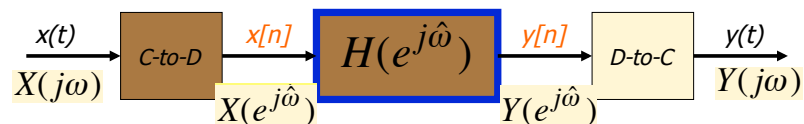


$$Y(e^{j\hat{\omega}}) = H(e^{j\hat{\omega}}) X(e^{j\hat{\omega}})$$

$$\hat{\omega} = \omega T_s = \frac{\omega}{f_s}$$

$$Y(e^{j\omega T_s}) = H(e^{j\omega T_s}) X(e^{j\omega T_s})$$

D-to-C Converter

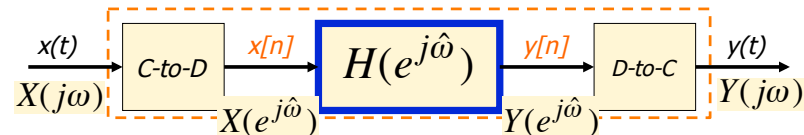


$$y(t) = \sum_{n=-\infty}^{\infty} y[n] h_r(t - nT_s)$$

$$Y(j\omega) = \sum_{n=-\infty}^{\infty} y[n] H_r(j\omega) e^{-j\omega T_s n} = H_r(j\omega) \sum_{n=-\infty}^{\infty} y[n] e^{-j\omega T_s n}$$

$$Y(j\omega) = H_r(j\omega) Y(e^{j\omega T_s})$$

Putting it All Together



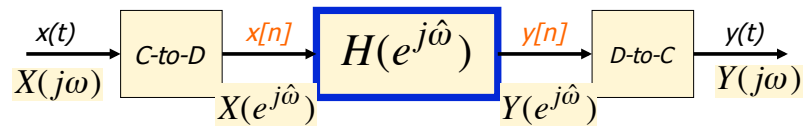
$$Y(j\omega) = H_r(j\omega) Y(e^{j\omega T_s}) = H_r(j\omega) H(e^{j\omega T_s}) X(e^{j\omega T_s})$$

$$Y(j\omega) = H_r(j\omega) H(e^{j\omega T_s}) \frac{1}{T_s} \sum_{k=-\infty}^{\infty} X(j(\omega - k\omega_s))$$

If no aliasing occurs in sampling $x(t)$, then it follows that

$$Y(j\omega) = H(e^{j\omega T_s}) X(j\omega) = H_{\text{eff}}(j\omega) X(j\omega)$$

DT Filtering of CT Signals



If no aliasing occurs in sampling $x(t)$, then it follows that

$$Y(j\omega) = H_{\text{eff}}(j\omega)X(j\omega)$$

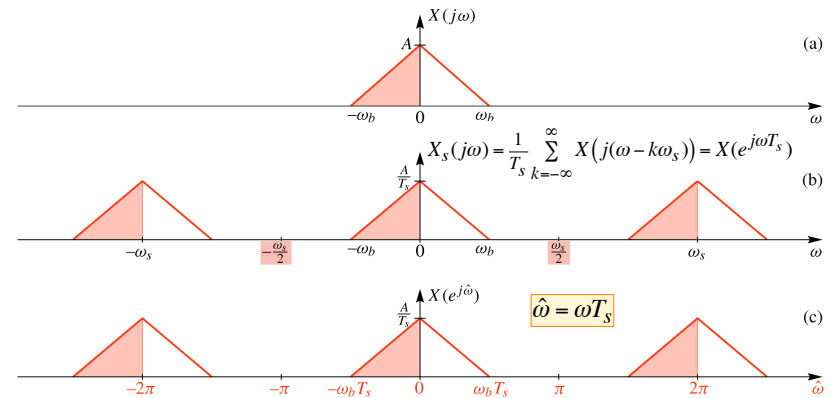
$$H_{\text{eff}}(j\omega) = \begin{cases} H(e^{j\omega T_s}) & |\omega| < \frac{1}{2}\omega_s \\ 0 & |\omega| > \frac{1}{2}\omega_s \end{cases}$$

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Sampling

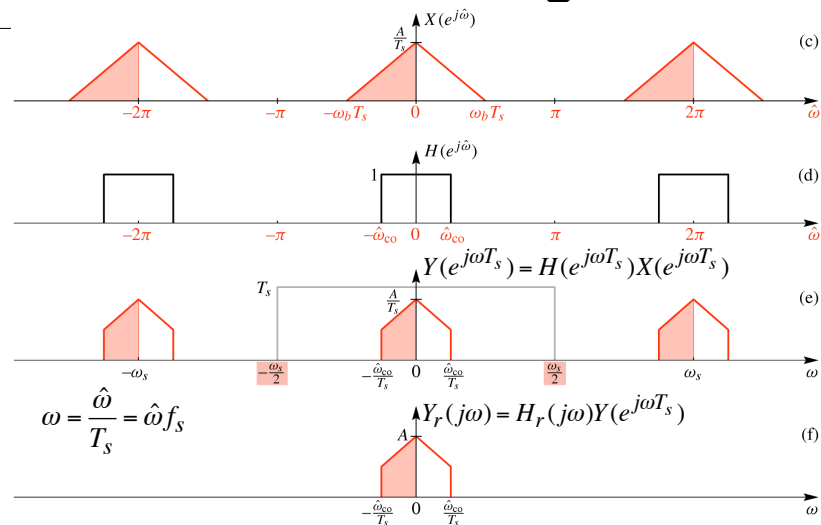


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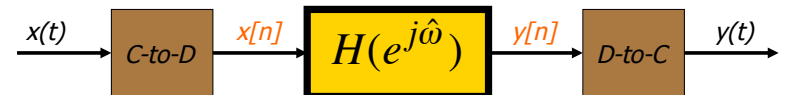
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Discrete-Time Filtering of Continuous-Time Signals



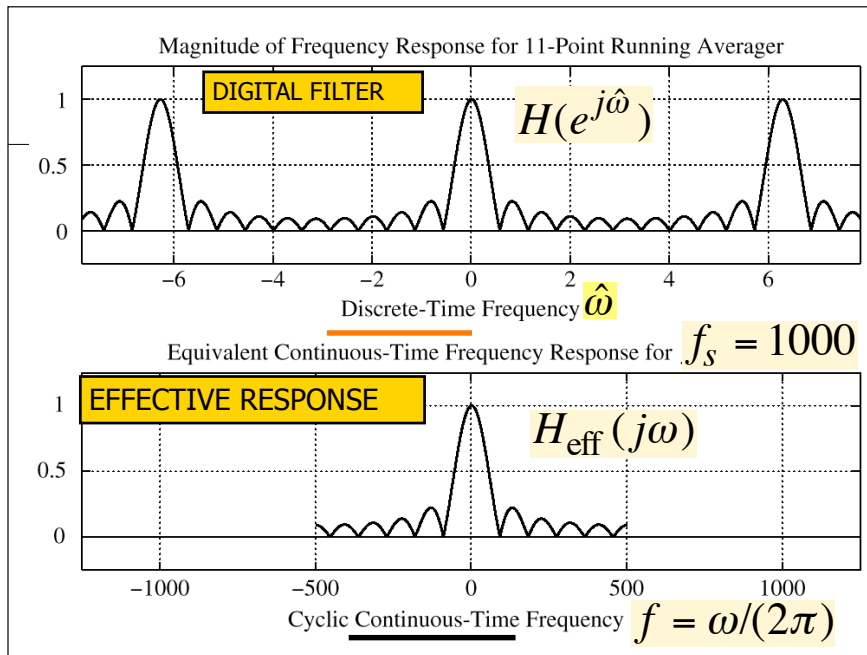
11-pt AVERAGER Example



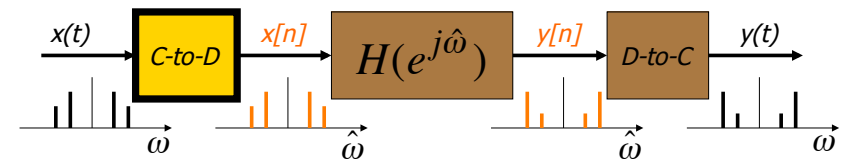
$$y[n] = \frac{1}{11} \sum_{k=0}^{10} x[n-k]$$

$$H(e^{j\hat{\omega}}) = \frac{1}{11} \sum_{k=0}^{10} e^{-j\hat{\omega}k} = \frac{\sin(\hat{\omega}11/2)}{11\sin(\hat{\omega}/2)} e^{-j\hat{\omega}5}$$

$$H_{\text{eff}}(j\omega) = \frac{\sin(\omega T_s 11/2)}{11\sin(\omega T_s/2)} e^{-j\omega T_s 5} \quad |\omega| < \frac{\pi}{T_s}$$



FREQUENCY SCALING



TIME SAMPLING:

IF NO ALIASING:

FREQUENCY SCALING

$$t = nT_s$$

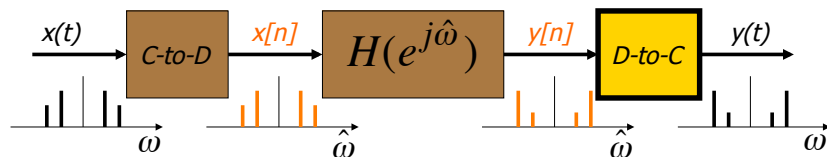
$$\hat{\omega} = \omega T_s = \frac{\omega}{f_s}$$

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D-A FREQUENCY SCALING



TIME SAMPLING:

$$t = nT_s \Rightarrow n \leftarrow t f_s$$

RECONSTRUCT up to $0.5f_s$

FREQUENCY SCALING

IDEAL LPF

$$\omega = \hat{\omega} f_s$$

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