

CS480 – ARTIFICIAL INTELLIGENCE

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TOPIC: CONSTRAINT SATISFACTION
CHAPTER: 6
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CHAPTER 6 – MOTIVATION

- Each state is described as a set of variables and their values
- There are constraints on which values can be assigned to which variables
- Examples
 - **Class scheduling:** Each room can host one class at a time, each instructor can be at one place at the same time, etc.
 - **Map coloring:** Adjacent states cannot have the same color
 - **Sudoku:** Numbers 1-9 must appear exactly once in a row, column, and block
- These are called Constraint Satisfaction Problems (CSP)
- We would like to develop general purpose and efficient solvers

OUTLINE

- Problem definition
- Constraint propagation
 - Node consistency
 - Arc consistency
 - Path consistency
 - K-consistency
 - Global constraints
- Backtracking search
 - Variable ordering
 - Value ordering
 - Forward checking
 - Maintaining arc consistency
- Local search

PROBLEM DEFINITION - CSP

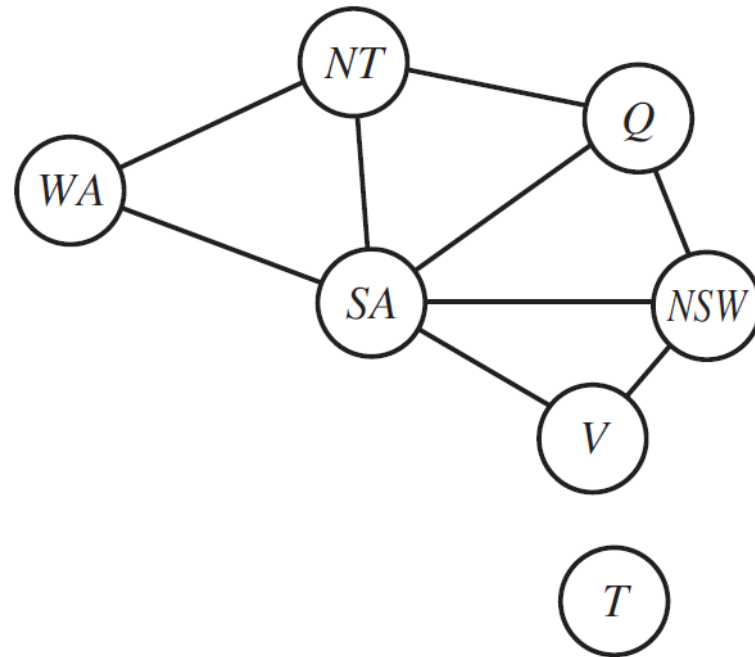
- \mathcal{X} is a set of variables: $\{X_1, X_2, \dots, X_n\}$
- \mathcal{D} is a set of domains: $\{D_1, D_2, \dots, D_n\}$, one for each variable
- C is a set of constraints on allowable combinations of values
- Definitions
 - **Assignment:** Some or all variables are assigned a value
 - **Consistent assignment:** No constraint is violated
 - **Complete assignment:** All variables are assigned
 - **Solution:** A consistent and complete assignment

EXAMPLE – MAP COLORING



- $X = \{WA, NT, SA, Q, NSW, V, T\}$
- $D_i = \{red, green, blue\}$
- $C = \{WA \neq NT, WA \neq SA, NT \neq SA, NT \neq Q, SA \neq Q, SA \neq NSW, SA \neq V, Q \neq NSW, NSW \neq V\}$

CONSTRAINT GRAPH



Variables are nodes. Two nodes are linked if they participate in a constraint.

TYPES OF CONSTRAINTS

- **Unary:** A variable cannot take on a value
- **Binary:** Constrains two variables
- **Global:** Constrains arbitrary number of variables
- We will consider binary CSPs
 - Unary: Modify the domain and remove the constraint
 - Global: Convert to binary constraint by introducing auxiliary variables

SOLVING CSPs

- A combination of
 - Search
 - Search for a value for a variable from its domain
 - Inference
 - Propagate constraints, reducing the domains of variables

INFERENCE: CONSTRAINT PROPAGATION

- **Node consistency**

- Unary constraints are enforced by altering the domains

- **Arc consistency**

- X_i is arc-consistent with respect to another variable X_j if for every value in the domain of D_i , there is some value in the domain of D_j that satisfies the binary constraint on the arc (X_i, X_j)

AC-3 ALGORITHM

- Put all arcs in a queue
- while queue is not empty
 - pick an arc (X_i, X_j)
 - make X_i arc consistent
 - if D_i is modified
 - if D_i is empty
 - return failure
 - else
 - Add all (X_k, X_i) to the queue, where X_k is a neighbor of X_i

AC-3

function AC-3(*csp*) **returns** false if an inconsistency is found and true otherwise

inputs: *csp*, a binary CSP with components (X , D , C)

local variables: *queue*, a queue of arcs, initially all the arcs in *csp*

while *queue* is not empty **do**

$(X_i, X_j) \leftarrow \text{REMOVE-FIRST}(\text{queue})$

if REVISE(*csp*, X_i , X_j) **then**

if size of $D_i = 0$ **then return** *false*

for each X_k **in** $X_i.\text{NEIGHBORS} - \{X_j\}$ **do**

 add (X_k, X_i) to *queue*

return *true*

function REVISE(*csp*, X_i , X_j) **returns** true iff we revise the domain of X_i

revised \leftarrow *false*

for each x **in** D_i **do**

if no value y in D_j allows (x, y) to satisfy the constraint between X_i and X_j **then**

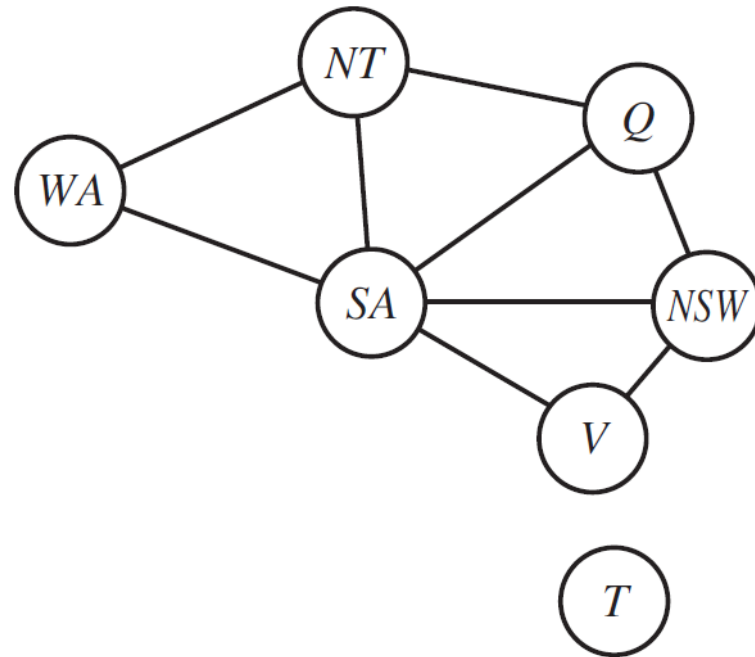
 delete x from D_i

revised \leftarrow *true*

return *revised*

EXAMPLE: AC-3 ON THE AUSTRALIA MAP

ASSUME $D_{WA} = \{R\}$, $D_V = \{G\}$



MORE CONSTRAINT PROPAGATION

- Arc consistency cannot detect all inconsistencies
- Consider coloring a map of three inter-connected states with two colors. They are arc-consistent.
- **Path consistency**
 - Triples of variables
 - A two-variable set $\{X_i, X_j\}$ is path-consistent with respect to a third variable X_m if, for every assignment $\{X_i=a, X_j=b\}$, there is an assignment to X_m that satisfies the constraints on $\{X_i, X_m\}$ and $\{X_m, X_j\}$.

MORE CONSTRAINT PROPAGATION

○ ***K*-consistency**

- A CSP is k -consistent if, for any set of $k-1$ variables and for any consistent assignment to those variables, a consistent value can always be assigned to any k^{th} variable.
- 1-consistency = node consistency
- 2-consistency = arc consistency
- 3-consistency = path consistency

BOUNDS CONSISTENCY

- A CSP is bounds consistent if for every variable X , and for every value between its lower and upper bounds, there exist some value for Y that satisfies the constraint between X and Y .
- Useful for variables with infinite or large domains
- Example
 - $D_X = [0, 200]$, $D_Y = [0, 300]$; $X + Y = 400$. After making X and Y bounds consistent, what are D_X and D_Y ?

SEARCHING FOR SOLUTIONS

- Rather than treating all of the variables as a single state, we will treat the variables as the nodes of the search tree
- Depth-first search: intuitively (the formal version is in the next slide)
 - Pick an unassigned variable *var*
 - for each *value* in the domain of *var*
 - Assign *value* to the *var*
 - Propagate constraints
 - If inconsistency is detected, backtrack

BACKTRACKING SEARCH

function BACKTRACKING-SEARCH(*csp*) **returns** a solution, or failure
 return BACKTRACK($\{ \}$, *csp*)

function BACKTRACK(*assignment*, *csp*) **returns** a solution, or failure
 if *assignment* is complete **then return** *assignment*
 var \leftarrow SELECT-UNASSIGNED-VARIABLE(*csp*)
 for each *value* **in** ORDER-DOMAIN-VALUES(*var*, *assignment*, *csp*) **do**
 if *value* is consistent with *assignment* **then**
 add $\{var = value\}$ to *assignment*
 inferences \leftarrow INFERENCE(*csp*, *var*, *value*)
 if *inferences* \neq failure **then**
 add *inferences* to *assignment*
 result \leftarrow BACKTRACK(*assignment*, *csp*)
 if *result* \neq failure **then**
 return *result*
 remove $\{var = value\}$ and *inferences* from *assignment*
 return failure

IMPORTANT CHOICES

1. Which variable to choose?
2. How to order its values?
3. What inference to use for propagating constraints?

VARIABLE ORDERING

○ **Minimum remaining values (MRV) heuristic**

- Also called “most-constrained” or “fail-first”
- Prunes early
- Might not help initially where domains are large

○ **Degree heuristic**

- Choose the variable that is involved in the most number of constraints with the remaining unassigned variables
- A good tie-breaker for MRV

VALUE ORDERING

- **Least-constraining value (LCV) heuristic**
 - Prefers the value that rules out the fewest choices for the neighboring variables
- **MRV chooses the most-constrained variable and LCV chooses the least-constraining value. Why?**

INTERLEAVING SEARCH AND INFERENCE

○ **Forward checking**

- When a variable X is assigned a value, make all the connected variables, Y , arc-consistent with X .
- Fast but does not detect all inconsistencies

○ **Maintaining arc consistency (MAC)**

- When a variable X_i is assigned a value, call AC-3 with the queue = (X_j, X_i) .

AN EXAMPLE

- The map coloring CSP with
 - MRV
 - Degree
 - Forward checking

CRYPTARITHMETIC

- TWO + TWO = FOUR
- Every letter represents a different digit
- Let's solve an easier version, where F=1, O is less than 5, and W is less than 5, and 1 removed from every variables' domains
 - F=1 (already assigned)
 - O: {0, 2, 3, 4}
 - R: {0, 2, 3, 4, 5, 6, 7, 8, 9}
 - T: {0, 2, 3, 4, 5, 6, 7, 8, 9}
 - U: {0, 2, 3, 4, 5, 6, 7, 8, 9}
 - W: {0, 2, 3, 4}

SUDOKU – AC-3 CAN SOLVE THIS

6						2	1	
		8		1				4
	5	4	6					
		7			9	8	2	
	4			5	1	9		3
9			3	7			5	
		9		8				
3		5		2			6	
7	8							

SUDOKU – AC-3 CAN ALMOST SOLVE THIS

6						2	1	
		8		1				4
	5	4	6					
		7			9	8	2	
	4			5	1	9		3
9			3	7			5	
		9		8				
3		5		2			6	
7								

SUDOKU – AC-3 CONVERTS THE PREVIOUS PROBLEM INTO THIS

6	9	3	8	4	7	2	1	5
2	7	8	5	1	3	6	9	4
1	5	4	6	9	2	3	8	7
5	3	7	4	6	9	8	2	1
8	4	6	2	5	1	9	7	3
9	{1,2}	{1,2}	3	7	8	4	5	6
4	{1,6}	9	{1,7}	8	{5,6}	{1,5,7}	3	2
3	{1,8}	5	{1,7,9}	2	4	{1,7}	6	{8,9}
7	{1,2,6,8}	{1,2}	{1,9}	3	{5,6}	{1,5}	4	{8,9}

NON-BINARY TO BINARY

- $a+b=2*c$
- $c+d=12$
- $a = \{0,1,2,3,4\}$
- $b = \{0,1,2\}$
- $c = \{0,1,2,3,4\}$
- $d = \{0..9\}$
- All are distinct

LOCAL SEARCH

- Start with an initial guess
- Pick a variable that violates constraints and choose a value for it
- Min-conflicts heuristic
 - Pick a value that results in the minimum number of conflicts with the other variables

MIN-CONFLICTS

function MIN-CONFLICTS(*csp*, *max_steps*) **returns** a solution or failure

inputs: *csp*, a constraint satisfaction problem

max_steps, the number of steps allowed before giving up

current \leftarrow an initial complete assignment for *csp*

for *i* = 1 to *max_steps* **do**

if *current* is a solution for *csp* **then return** *current*

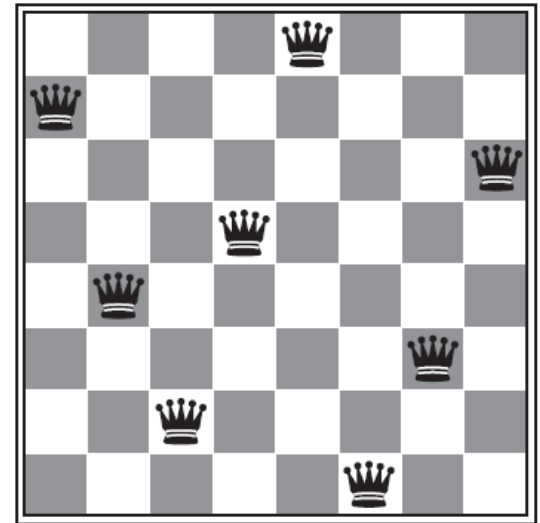
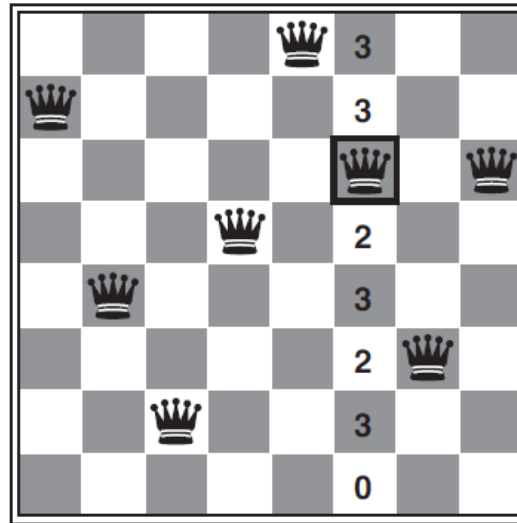
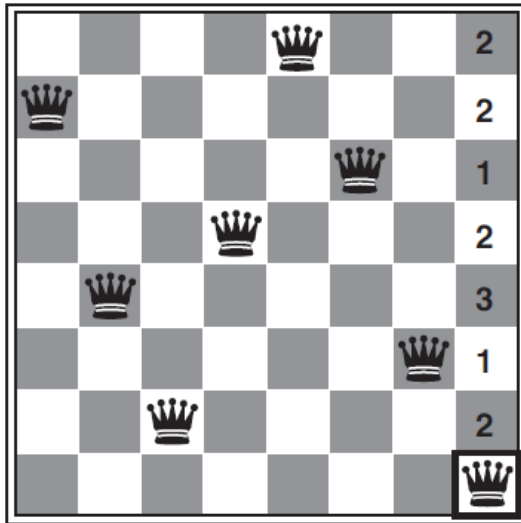
var \leftarrow a randomly chosen conflicted variable from *csp*.VARIABLES

value \leftarrow the value *v* for *var* that minimizes CONFLICTS(*var*, *v*, *current*, *csp*)

 set *var* = *value* in *current*

return *failure*

MIN-CONFLICTS EXAMPLE



SO FAR

- Agent-based modeling – Chapter 2
- Search for problem solving
 - Goal-based – Chapter 3
 - DFS, BFS, ..., A*
 - Utility-based – Chapter 5
 - Minimax, alpha-beta
 - Constraint satisfaction – Chapter 6
 - Backtracking

NEXT

- Knowledge Representation and Reasoning –
Logic
 - Chapters 7, 8, 9