

Weakly- and Semi-Supervised Learning of a DCNN for Semantic Image Segmentation (2015)

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Notes

1 Introduction

The authors in this paper study the problem of learning a DCNN for either (1) weakly annotated training data such as bounding boxes or image-level labels or (2) a combination of few strongly labeled and many weakly labeled images, sourced from one or multiple datasets.

The authors present an EM algorithm for training with image-level or bounding box annotation, applicable to both weakly-supervised and semi-supervised settings, this method achieves excellent performance when combining a small number of pixel-level annotated images with a large number of image-level or bounding box annotated images, nearly matching the results achieved when all training images have pixel-level annotations.

2 Method

The model is based on deeplab, with a DCNN for predicting image segmentation followed by a fully connected CRF for refinement, the results is $y_m \in \{0, \dots, L\}$ which is the label for a pixel at position $m \in \{1, \dots, M\}$ in the image.

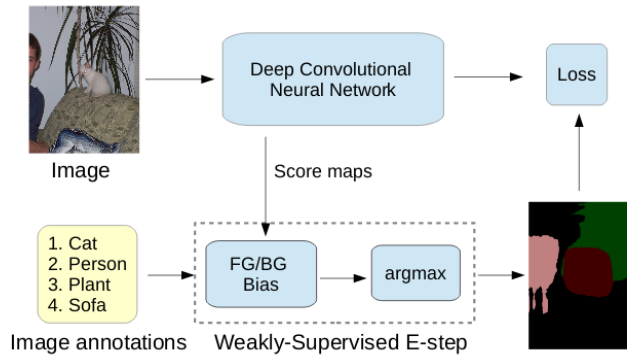


Figure 2. DeepLab model training using image-level labels.

Pixel-level annotations

In a fully supervised case, the training objective is a CE between the predicted labels and the ground truth:

$$J(\theta) = \log P(\mathbf{y}|\mathbf{x}; \theta) = \sum_{m=1}^M \log P(y_m|\mathbf{x}; \theta)$$

Image-level annotations

In this case, we can only observe the image x and the classes z but not pixel-wise labels, which are considered as latent variables y , we can then construct a graphical model:

$$P(\mathbf{x}, \mathbf{y}, \mathbf{z}; \boldsymbol{\theta}) = P(\mathbf{x}) \left(\prod_{m=1}^M P(y_m | \mathbf{x}; \boldsymbol{\theta}) \right) P(\mathbf{z} | \mathbf{y})$$

We can now train our model by applying E step and M step:

E-step : for the E step we want to maximize the segmentation mask predicted using the model and the input image $P(\mathbf{y} | \mathbf{x}; \boldsymbol{\theta}')$, so that the image class predicted from the mask will be correct $P(\mathbf{z} | \mathbf{y})$:

$$\begin{aligned} \hat{\mathbf{y}} &= \underset{\mathbf{y}}{\operatorname{argmax}} P(\mathbf{y} | \mathbf{x}; \boldsymbol{\theta}') P(\mathbf{z} | \mathbf{y}) \\ &= \underset{\mathbf{y}}{\operatorname{argmax}} \log P(\mathbf{y} | \mathbf{x}; \boldsymbol{\theta}') + \log P(\mathbf{z} | \mathbf{y}) \\ &= \underset{\mathbf{y}}{\operatorname{argmax}} \left(\sum_{m=1}^M f_m(y_m | \mathbf{x}; \boldsymbol{\theta}') + \log P(\mathbf{z} | \mathbf{y}) \right) \end{aligned}$$

But we also need to specify the observation model $P(\mathbf{z} | \mathbf{y})$, which is assumed that it is factorized over the pixel positions:

$$\log P(\mathbf{z} | \mathbf{y}) = \sum_{m=1}^M \phi(y_m, \mathbf{z}) + (\text{const})$$

Given that:

$$\phi(y_m = l, \mathbf{z}) = \begin{cases} b_l & \text{if } z_l = 1 \\ 0 & \text{if } z_l = 0 \end{cases}$$

M-step : Now in the M-step, we want to optimize the model so that its output is close to the prediction we obtained in the E step:

$$\sum_{\mathbf{y}} P(\mathbf{y} | \mathbf{x}, \mathbf{z}; \boldsymbol{\theta}') \log P(\mathbf{y} | \mathbf{x}; \boldsymbol{\theta}) \approx \log P(\hat{\mathbf{y}} | \mathbf{x}; \boldsymbol{\theta})$$

And this is summerized as follows:

Algorithm 1 Weakly-Supervised EM (fixed bias version)

Input: Initial CNN parameters $\boldsymbol{\theta}'$, potential parameters b_l , $l \in \{0, \dots, L\}$, image \mathbf{x} , image-level label set \mathbf{z} .

E-Step: For each image position m

- 1: $\hat{f}_m(l) = f_m(l | \mathbf{x}; \boldsymbol{\theta}') + b_l$, if $z_l = 1$
- 2: $\hat{f}_m(l) = f_m(l | \mathbf{x}; \boldsymbol{\theta}')$, if $z_l = 0$
- 3: $\hat{y}_m = \operatorname{argmax}_l \hat{f}_m(l)$

M-Step:

- 4: $Q(\boldsymbol{\theta}; \boldsymbol{\theta}') = \log P(\hat{\mathbf{y}} | \mathbf{x}, \boldsymbol{\theta}) = \sum_{m=1}^M \log P(\hat{y}_m | \mathbf{x}, \boldsymbol{\theta})$
- 5: Compute $\nabla_{\boldsymbol{\theta}} Q(\boldsymbol{\theta}; \boldsymbol{\theta}')$ and use SGD to update $\boldsymbol{\theta}'$.

Bounding Box Annotations

To construct masks using the bounding boxes, the authors try to use a simple method by considering all the pixels inside the box and positive and outside as negative, and in case of intersection of two bounding boxes, the pixel is assigned to the smallest one, but this gives a lot of false negative, so to refine these masks, they constrain the center pixel to the foreground and the pixels outside the

box to the background and use a CRF with the appropriate setting the unary terms to refine the masks per class and then take the argmax for the mask of all classes.

And here is an illustration of the process:

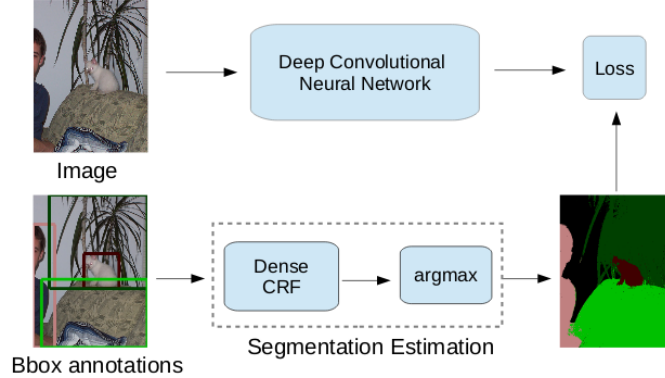


Figure 3. DeepLab model training from bounding boxes.

2.1 Mixed strong and weak annotations

When we have both strong and weakly annotated examples, we combine the two as follows, using the CE from the labeled examples, and EM for the weakly supervised examples:

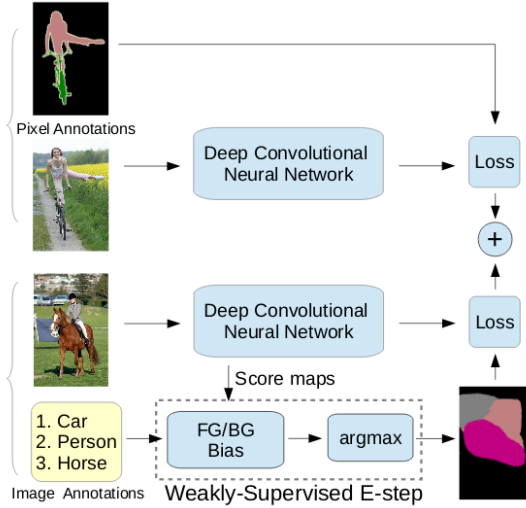


Figure 5. DeepLab model training on a union of full (strong labels) and image-level (weak labels) annotations.

3 Experiments

| Method | #Strong | #Weak | val IOU |
|-----------------|---------|--------|---------|
| EM-Fixed (Weak) | - | 10,582 | 20.8 |
| EM-Adapt (Weak) | - | 10,582 | 38.2 |
| EM-Fixed (Semi) | 200 | 10,382 | 47.6 |
| | 500 | 10,082 | 56.9 |
| | 750 | 9,832 | 59.8 |
| | 1,000 | 9,582 | 62.0 |
| | 1,464 | 5,000 | 63.2 |
| | 1,464 | 9,118 | 64.6 |
| Strong | 1,464 | - | 62.5 |
| | 10,582 | - | 67.6 |

Table 1. VOC 2012 *val* performance for varying number of pixel-level (strong) and image-level (weak) annotations (Sec. 4.3).

| Method | #Strong | #Weak | test IOU |
|-----------------|---------|-------|----------|
| MIL-FCN [31] | - | 10k | 25.7 |
| MIL-sppxl [32] | - | 760k | 35.8 |
| MIL-obj [32] | BING | 760k | 37.0 |
| MIL-seg [32] | MCG | 760k | 40.6 |
| EM-Adapt (Weak) | - | 12k | 39.6 |
| EM-Fixed (Semi) | 1.4k | 10k | 66.2 |
| | 2.9k | 9k | 68.5 |
| Strong [5] | 12k | - | 70.3 |

Table 2. VOC 2012 *test* performance for varying number of pixel-level (strong) and image-level (weak) annotations (Sec. 4.3).

| Method | #Strong | #Box | val IOU |
|----------------------|---------|--------|---------|
| Bbox-Rect (Weak) | - | 10,582 | 52.5 |
| Bbox-EM-Fixed (Weak) | - | 10,582 | 54.1 |
| Bbox-Seg (Weak) | - | 10,582 | 60.6 |
| Bbox-Rect (Semi) | 1,464 | 9,118 | 62.1 |
| Bbox-EM-Fixed (Semi) | 1,464 | 9,118 | 64.8 |
| Bbox-Seg (Semi) | 1,464 | 9,118 | 65.1 |
| Strong | 1,464 | - | 62.5 |
| | 10,582 | - | 67.6 |

Table 3. VOC 2012 *val* performance for varying number of pixel-level (strong) and bounding box (weak) annotations (Sec. 4.4).

| Method | #Strong | #Box | test IOU |
|----------------------|-------------|------|----------|
| BoxSup [9] | MCG | 10k | 64.6 |
| BoxSup [9] | 1.4k (+MCG) | 9k | 66.2 |
| Bbox-Rect (Weak) | - | 12k | 54.2 |
| Bbox-Seg (Weak) | - | 12k | 62.2 |
| Bbox-Seg (Semi) | 1.4k | 10k | 66.6 |
| Bbox-EM-Fixed (Semi) | 1.4k | 10k | 66.6 |
| Bbox-Seg (Semi) | 2.9k | 9k | 68.0 |
| Bbox-EM-Fixed (Semi) | 2.9k | 9k | 69.0 |
| Strong [5] | 12k | - | 70.3 |

Table 4. VOC 2012 *test* performance for varying number of pixel-level (strong) and bounding box (weak) annotations (Sec. 4.4).