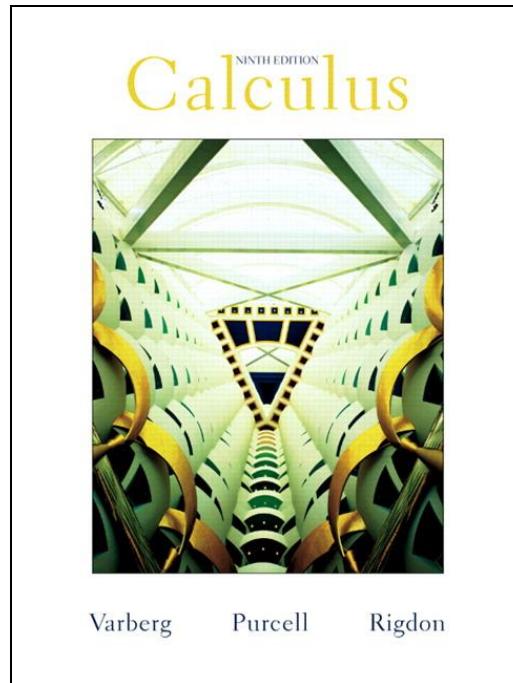


Varberg, Calculus 9e



Chapter 12

**Derivatives for Functions of Two
or More Variables**

Section 12.1

Functions of Two or More Variables

Function of Two or More Variables

- **Real-valued function of two real variables**, the is a function f the assigns to each ordered pair (x,y) in some set D of the plane a (unique) real number $f(x,y)$. Examples are

$$(1) \quad f(x, y) = x^2 + 3y^2$$

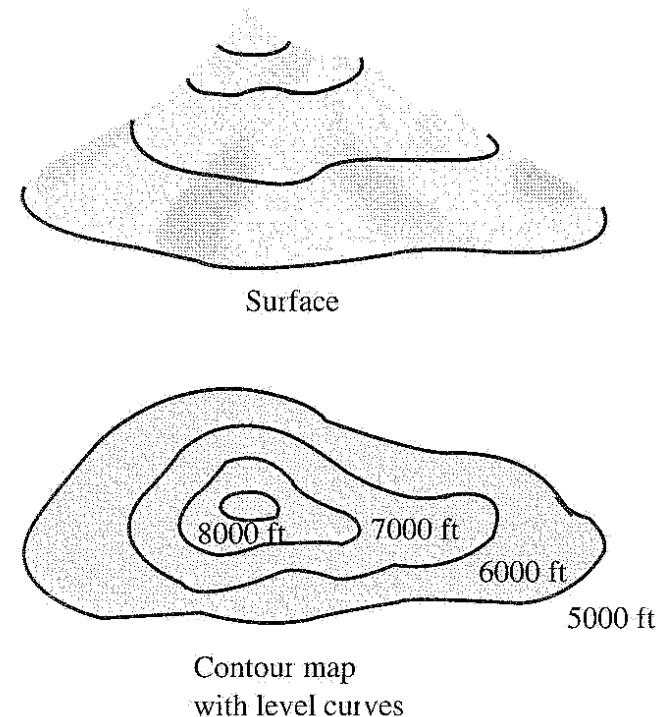
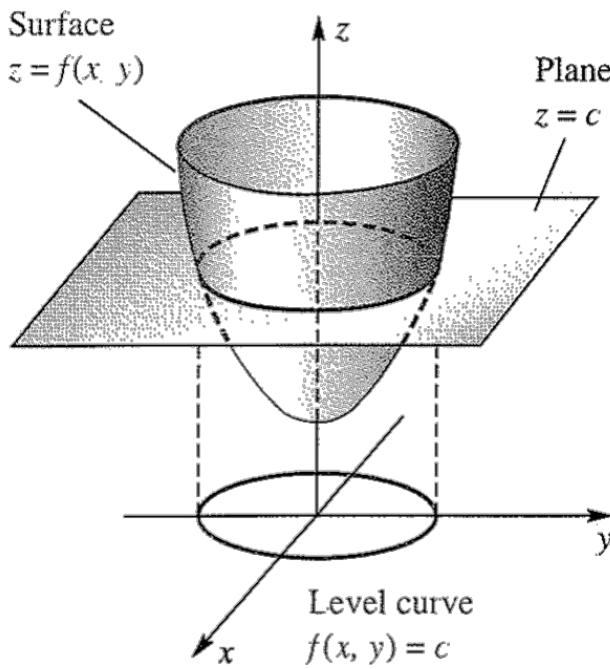
$$(2) \quad g(x, y) = 2x\sqrt{y}$$

Function of Two or More Variables

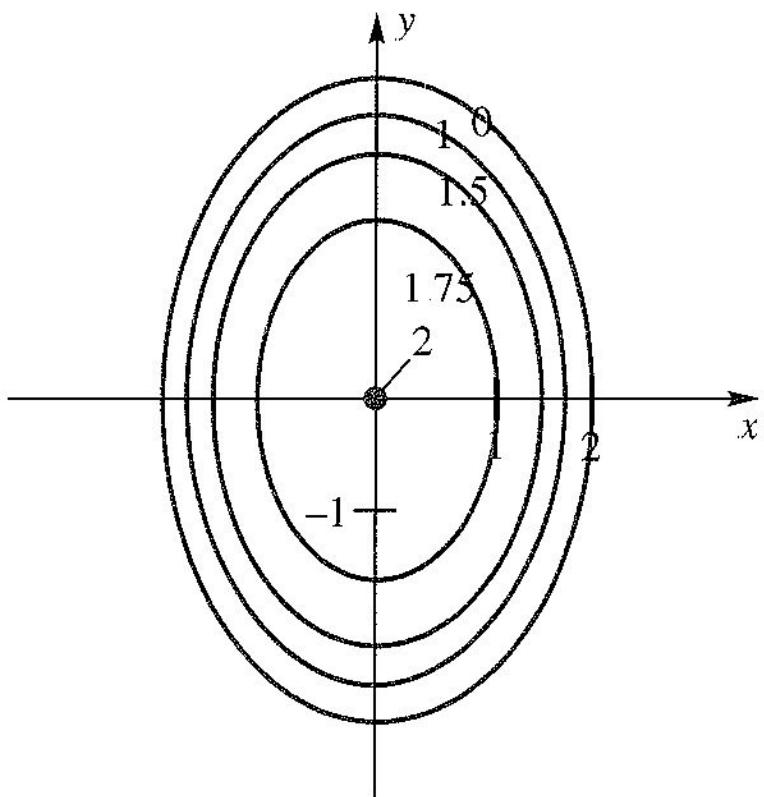
- The set D is called the **domain**, the set of all points (x,y) in the plane for which the function rule makes sense and gives a real number value.
- The **range** of a function is its set of values. If $z = f(x,y)$, we call x and y the **independent variables** and z the **dependent variable**.

Level Curves

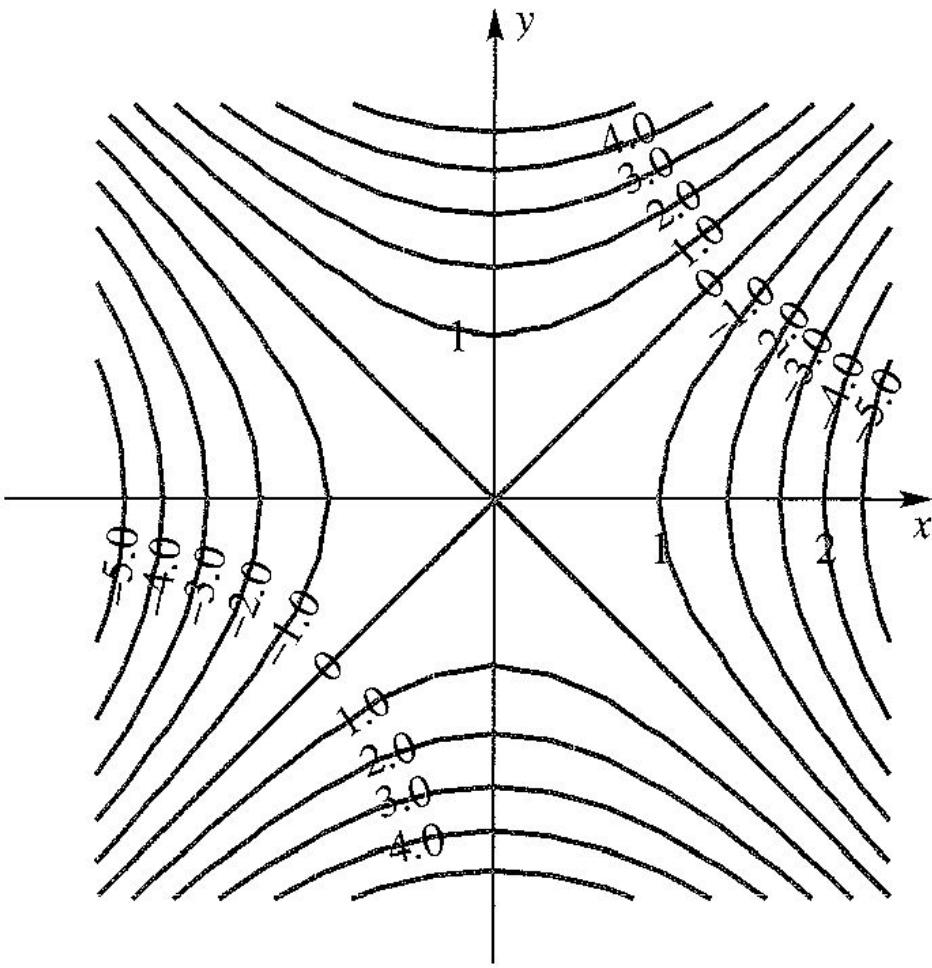
- The projection of the curve on the xy -plane is called a **level curve**, and a collection of such curves is a **contour plot** or a **contour map**.



Contour Map $z = \frac{1}{3} \sqrt{36 - 9x^2 - 4y^2}$



Contour Map $z = y^2 - x^2$



EXAMPLE 4 Draw contour maps for the surfaces corresponding to

$z = \frac{1}{3}\sqrt{36 - 9x^2 - 4y^2}$ and $z = y^2 - x^2$ (see Examples 2 and 3, and Figures 4 and 5).

SOLUTION The level curves of $z = \frac{1}{3}\sqrt{36 - 9x^2 - 4y^2}$ corresponding to $z = 0, 1, 1.5, 1.75, 2$ are shown in Figure 12. They are ellipses. Similarly, in Figure 13, we show the level curves of $z = y^2 - x^2$ for $z = -5, -4, -3, \dots, 2, 3, 4$. These curves are hyperbolas unless $z = 0$. The level curve for $z = 0$ is a pair of intersecting lines.



Computer Graphs and Level Curves

- In Figures 15 through 19, we have drawn five more surfaces

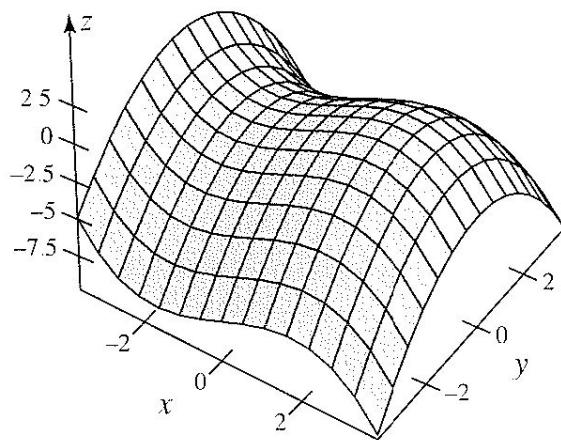
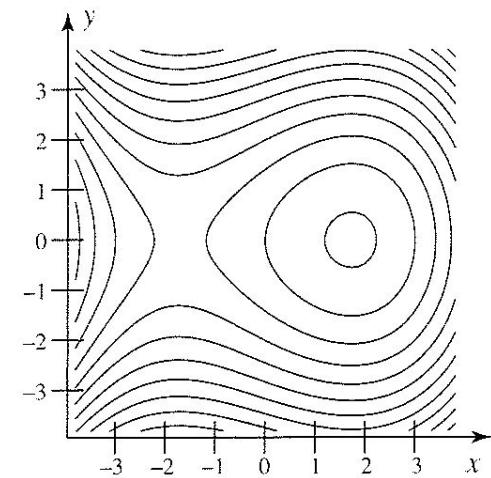
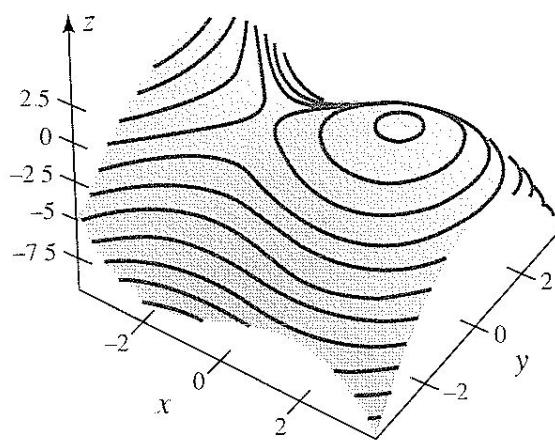


Figure 15



$$z = x - \left(\frac{1}{9}\right)x^3 - \left(\frac{1}{2}\right)y^2 \quad \begin{cases} -3.8 \leq x \leq 3.8 \\ -3.8 \leq y \leq 3.8 \end{cases}$$

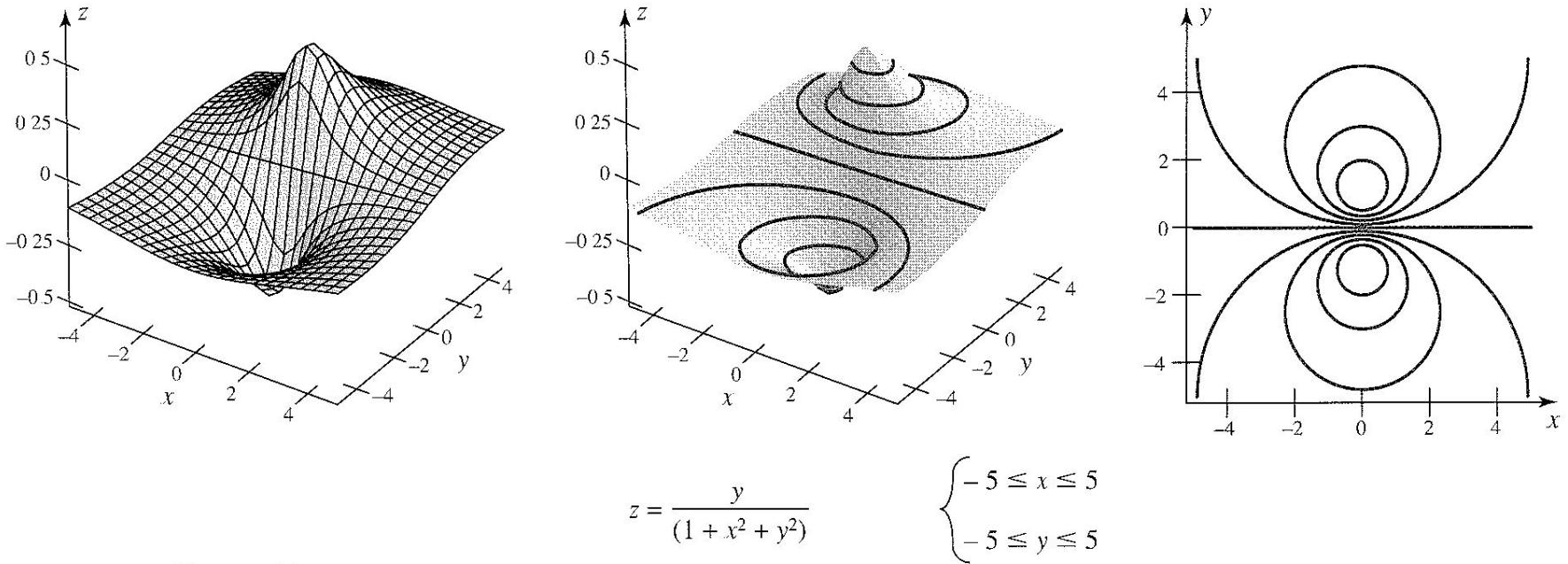


Figure 16

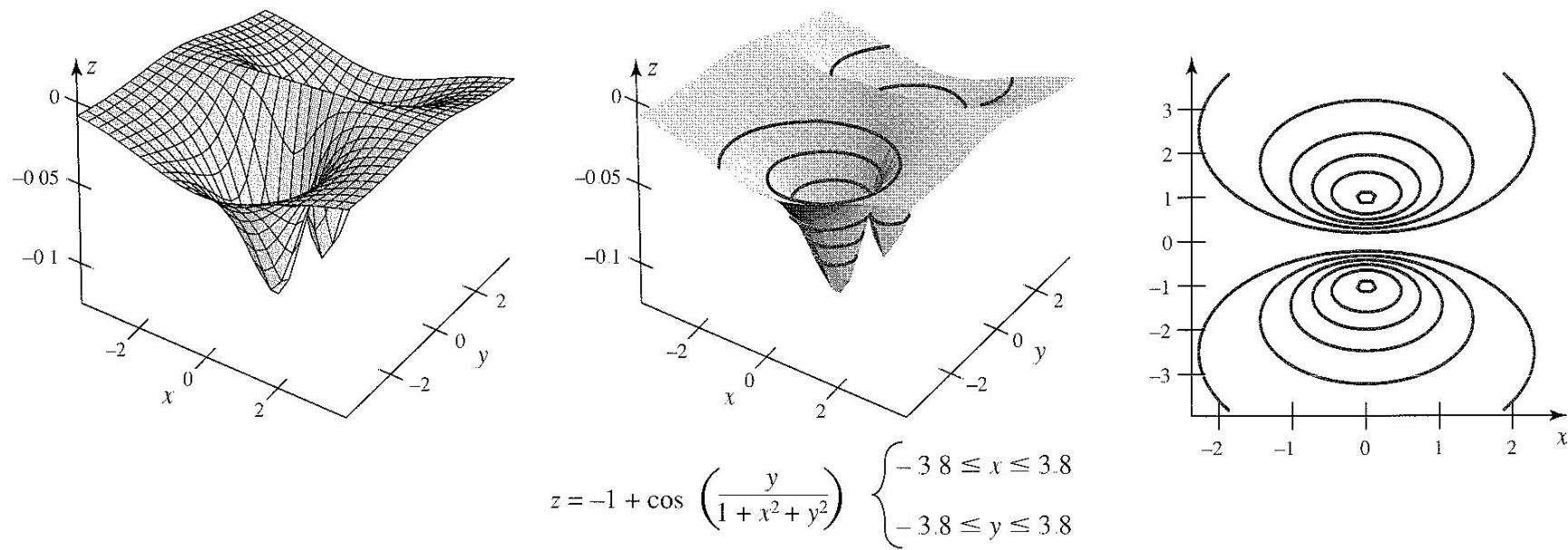


Figure 17

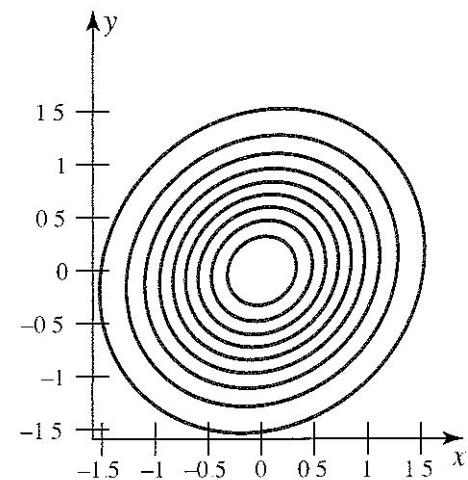
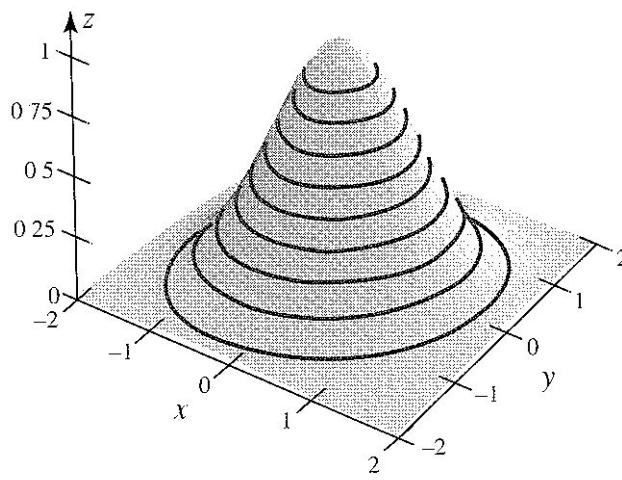
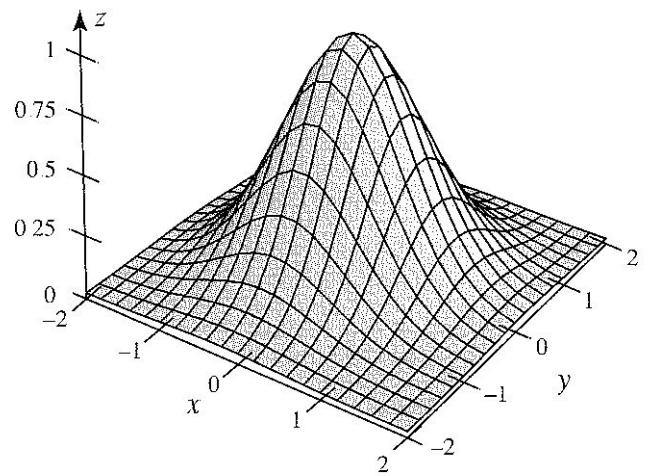
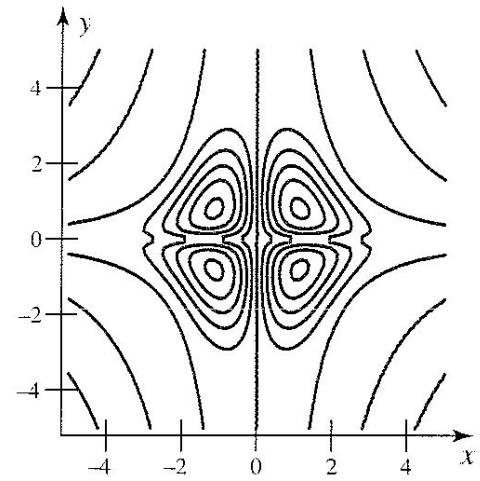
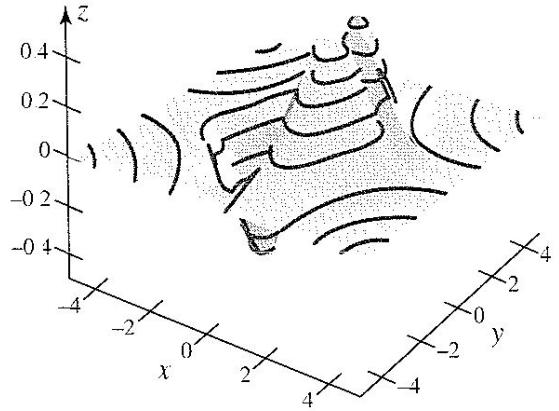
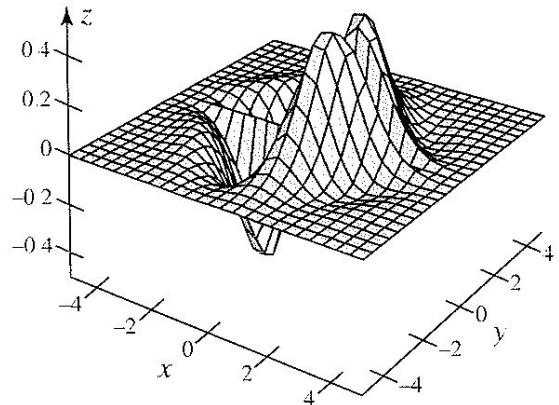


Figure 18

$$z = e^{-x^2 - y^2 + iy/4}$$

$$\begin{cases} -2 \leq x \leq 2 \\ -2 \leq y \leq 2 \end{cases}$$



$$z = e^{-(x^2 + y^2)/4} \sin(x\sqrt{|y|})$$

$$\begin{cases} -5 \leq x \leq 5 \\ -5 \leq y \leq 5 \end{cases}$$

Figure 19

Section 12.2

Partial Derivatives

Partial Derivatives

- Suppose that f is a function of two variables x and y . If y is held constant, say $y = y_0$, then $f(x, y_0)$ is a function of the single variable x . Its derivative at $x = x_0$ is called the **partial derivative of f with respect to x at (x_0, y_0)**

$$f_x(x_0, y_0) = \lim_{\Delta x \rightarrow 0} \frac{f(x_0 + \Delta x, y_0) - f(x_0, y_0)}{\Delta x}$$

Similarly, the partial derivative of f with respect to y at (x_0, y_0) is denoted by $f_y(x_0, y_0)$ and is given by

$$f_y(x_0, y_0) = \lim_{\Delta y \rightarrow 0} \frac{f(x_0, y_0 + \Delta y) - f(x_0, y_0)}{\Delta y}$$

 **EXAMPLE 1** Find $f_x(1, 2)$ and $f_y(1, 2)$ if $f(x, y) = x^2y + 3y^3$.

SOLUTION To find $f_x(x, y)$, we treat y as a constant and differentiate with respect to x , obtaining

$$f_x(x, y) = 2xy + 0$$

Thus,

$$f_x(1, 2) = 2 \cdot 1 \cdot 2 = 4$$

Similarly, we treat x as a constant and differentiate with respect to y , obtaining

$$f_y(x, y) = x^2 + 9y^2$$

and so

$$f_y(1, 2) = 1^2 + 9 \cdot 2^2 = 37$$



Partial Derivatives

The symbol ∂ is special to mathematics and is called the partial derivative sign. The symbols $\frac{\partial}{\partial x}$ and $\frac{\partial}{\partial y}$ represent linear operators, much like the linear operators D_x and $\frac{d}{dx}$ that we encountered in Chapter 2.

EXAMPLE 2 If $z = x^2 \sin(xy^2)$, find $\partial z / \partial x$ and $\partial z / \partial y$.

SOLUTION

$$\begin{aligned}\frac{\partial z}{\partial x} &= x^2 \frac{\partial}{\partial x} [\sin(xy^2)] + \sin(xy^2) \frac{\partial}{\partial x}(x^2) \\&= x^2 \cos(xy^2) \frac{\partial}{\partial x}(xy^2) + \sin(xy^2) \cdot 2x \\&= x^2 \cos(xy^2) \cdot y^2 + 2x \sin(xy^2) \\&= x^2 y^2 \cos(xy^2) + 2x \sin(xy^2)\end{aligned}$$

$$\frac{\partial z}{\partial y} = x^2 \cos(xy^2) \cdot 2xy = 2x^3y \cos(xy^2)$$

Geometric and Physical Interpretations

Geometric and Physical Interpretations Consider the surface whose equation is $z = f(x, y)$. The plane $y = y_0$ intersects this surface in the plane curve QPR (Figure 1), and the value of $f_x(x_0, y_0)$ is the slope of the tangent line to this curve at $P(x_0, y_0, f(x_0, y_0))$. Similarly, the plane $x = x_0$ intersects the surface in the plane curve LPM (Figure 2), and $f_y(x_0, y_0)$ is the slope of the tangent line to this curve at P .

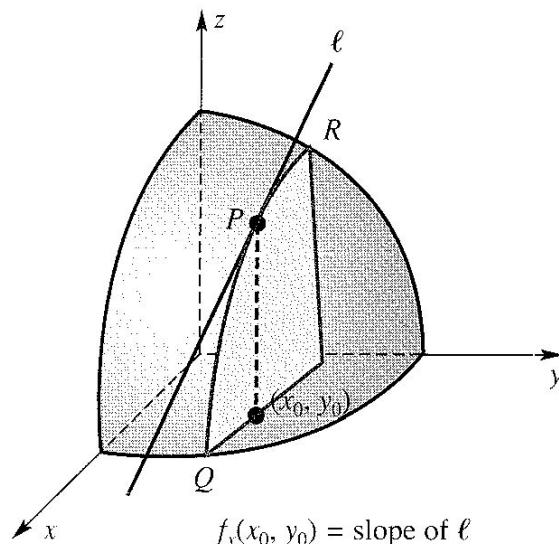


Figure 1

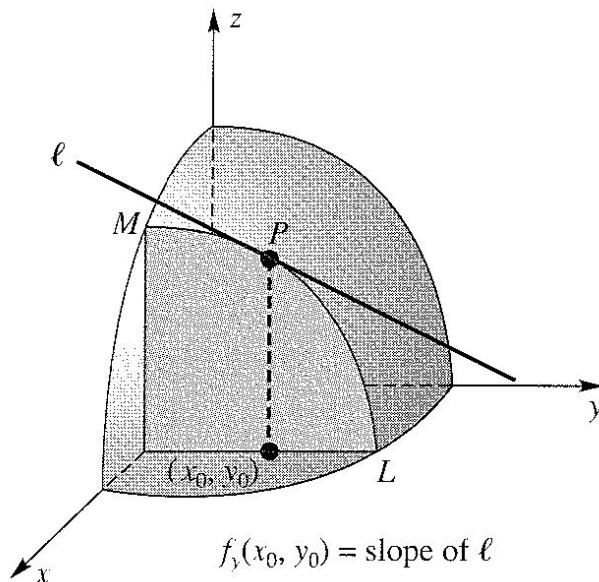


Figure 2

EXAMPLE 3 The surface $z = f(x, y) = \sqrt{9 - 2x^2 - y^2}$ and the plane $y = 1$ intersect in a curve as in Figure 1. Find parametric equations for the tangent line at $(\sqrt{2}, 1, 2)$.

SOLUTION

$$f_x(x, y) = \frac{1}{2}(9 - 2x^2 - y^2)^{-1/2}(-4x)$$

and so $f_x(\sqrt{2}, 1) = -\sqrt{2}$. This number is the slope of the tangent line to the curve at $(\sqrt{2}, 1, 2)$; that is, $-\sqrt{2}/1$ is the ratio of rise to run along the tangent line. It follows that this line has direction vector $\langle 1, 0, -\sqrt{2} \rangle$ and, since it goes through $(\sqrt{2}, 1, 2)$,

$$x = \sqrt{2} + t, \quad y = 1, \quad z = 2 - \sqrt{2}t$$

provide the required parametric equations.



Higher Partial Derivatives

Higher Partial Derivatives Since a partial derivative of a function of x and y is, in general, another function of these same two variables, it may be differentiated partially with respect to either x or y , resulting in four **second partial derivatives** of f .

$$f_{xx} = \frac{\partial}{\partial x} \left(\frac{\partial f}{\partial x} \right) = \frac{\partial^2 f}{\partial x^2}$$

$$f_{yy} = \frac{\partial}{\partial y} \left(\frac{\partial f}{\partial y} \right) = \frac{\partial^2 f}{\partial y^2}$$

$$f_{xy} = (f_x)_y = \frac{\partial}{\partial y} \left(\frac{\partial f}{\partial x} \right) = \frac{\partial^2 f}{\partial y \partial x}$$

$$f_{yx} = (f_y)_x = \frac{\partial}{\partial x} \left(\frac{\partial f}{\partial y} \right) = \frac{\partial^2 f}{\partial x \partial y}$$

EXAMPLE 5 Find the four second partial derivatives of

$$f(x, y) = xe^y - \sin(x/y) + x^3y^2$$

SOLUTION

$$f_x(x, y) = e^y - \frac{1}{y} \cos\left(\frac{x}{y}\right) + 3x^2y^2$$

$$f_y(x, y) = xe^y + \frac{x}{y^2} \cos\left(\frac{x}{y}\right) + 2x^3y$$

$$f_{xx}(x, y) = \frac{1}{y^2} \sin\left(\frac{x}{y}\right) + 6xy^2$$

$$f_{yy}(x, y) = xe^y + \frac{x^2}{y^4} \sin\left(\frac{x}{y}\right) - \frac{2x}{y^3} \cos\left(\frac{x}{y}\right) + 2x^3$$

$$f_{xy}(x, y) = e^y - \frac{x}{y^3} \sin\left(\frac{x}{y}\right) + \frac{1}{y^2} \cos\left(\frac{x}{y}\right) + 6x^2y$$

$$f_{yx}(x, y) = e^y - \frac{x}{y^3} \sin\left(\frac{x}{y}\right) + \frac{1}{y^2} \cos\left(\frac{x}{y}\right) + 6x^2y$$

Higher Partial Derivatives

- Partial derivatives of the third and higher orders are defined analogously, and the notation for them is similar.

$$\frac{\partial}{\partial y} \left[\frac{\partial}{\partial y} \left(\frac{\partial f}{\partial x} \right) \right] = \frac{\partial}{\partial y} \left(\frac{\partial^2 f}{\partial y \partial x} \right) = \frac{\partial^3 f}{\partial y^2 \partial x} = f_{xyy}$$

More Than Two Variables

More Than Two Variables Let f be a function of three variables, x , y , and z . The **partial derivative of f with respect to x** at (x, y, z) is denoted by $f_x(x, y, z)$ or $\partial f(x, y, z)/\partial x$ and is defined by

$$f_x(x, y, z) = \lim_{\Delta x \rightarrow 0} \frac{f(x + \Delta x, y, z) - f(x, y, z)}{\Delta x}$$

EXAMPLE 6 If $f(x, y, z) = xy + 2yz + 3zx$, find f_x , f_y , and f_z .

SOLUTION To get f_x , we think of y and z as constants and differentiate with respect to the variable x . Thus,

$$f_x(x, y, z) = y + 3z$$

To find f_y , we treat x and z as constants and differentiate with respect to y :

$$f_y(x, y, z) = x + 2z$$

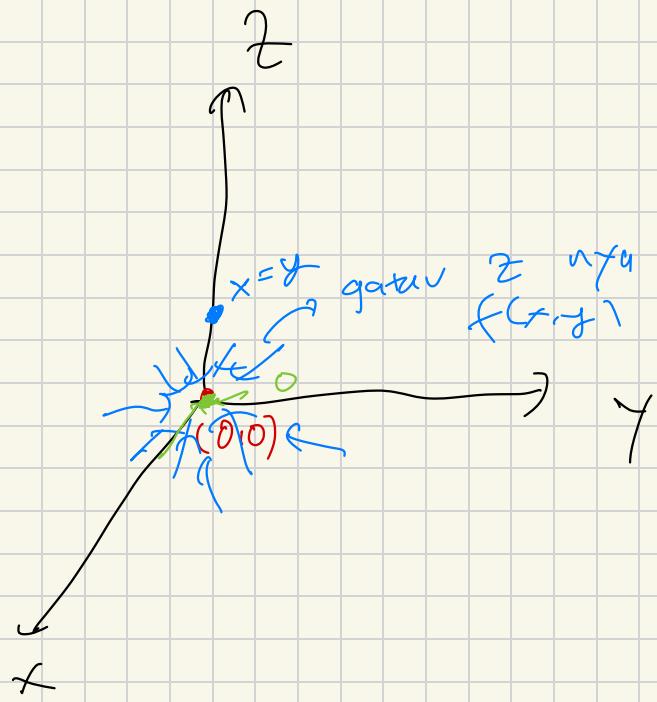
Similarly,

$$f_z(x, y, z) = 2y + 3x$$



Section 12.3

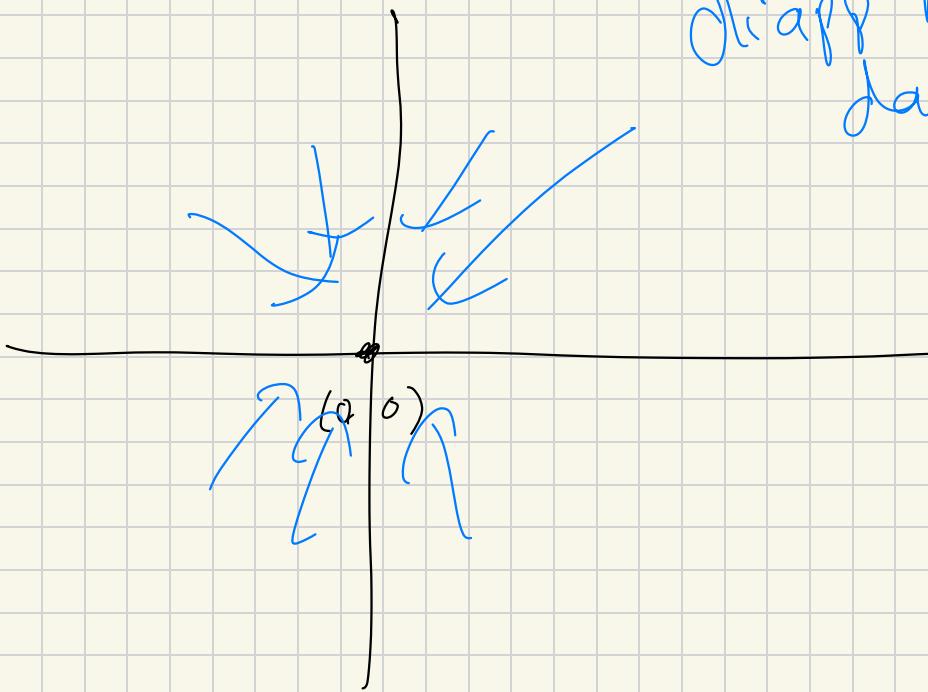
Limits and Continuity



$$\lim_{(x,y) \rightarrow (0,0)} f(x,y)$$

$$f(x,y) \rightarrow (0,0)$$

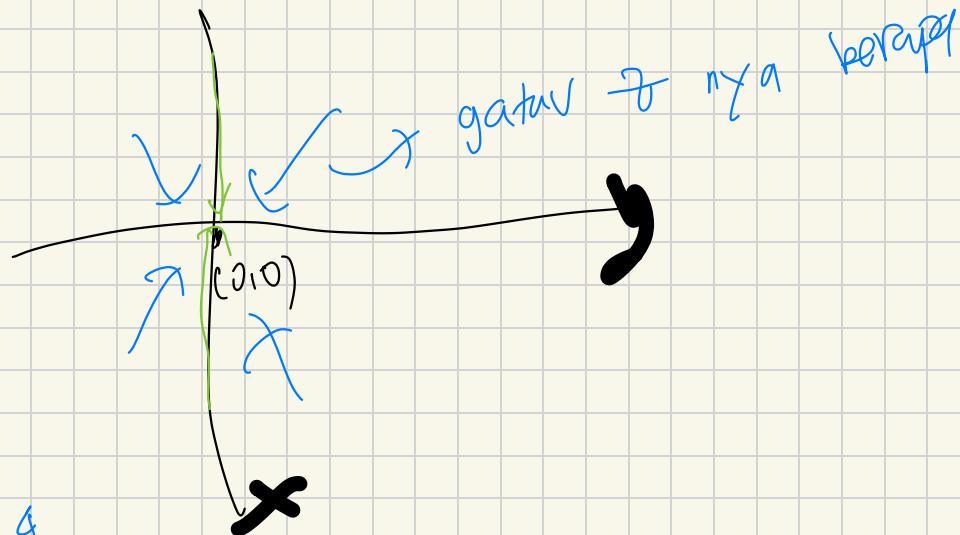
diapitbach
dari segala arah



(1) Cara awam / bntte force

$$\lim_{(x,y) \rightarrow (0,0)} \frac{x^2y^2}{(x^2+y^2)^2}$$

(2) Pdor



Cek ~~$x = y$~~

$$\lim_{y \rightarrow 0} \frac{(y^4)}{(2y^2)^2} = \lim_{y \rightarrow 0} \frac{y^4}{4y^4} = \frac{1}{4}$$

ga sand

$$\lim_{x \rightarrow 0} \frac{0}{(y^2)^2} = \frac{0}{y^4} = 0$$

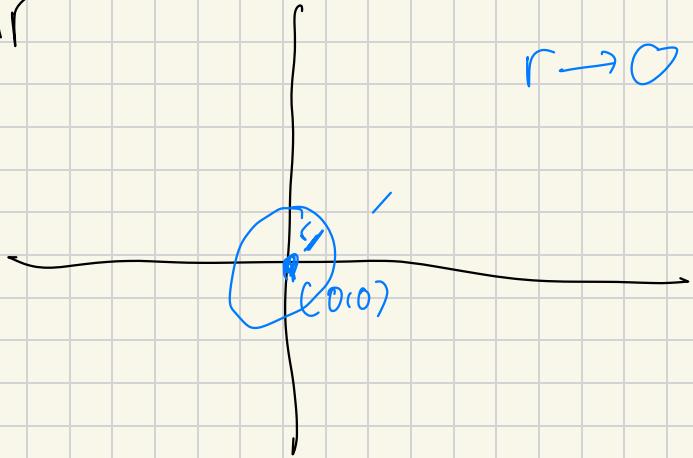
$$\lim_{y \rightarrow 0} \frac{0}{(y^2)^2}$$

Gak Kontinu

$(x, y \rightarrow 0, 0)$



2) Polar



$$r \rightarrow 0$$

$$x = r \cos \theta$$

$$\varphi = r \sin \theta$$

$$r^2 = x^2 + y^2$$

$$\lim_{r \rightarrow 0} \frac{r^2 \cos^2 \theta + r^2 \sin^2 \theta}{(r^2)^2} = \frac{\cos^2 \theta + \sin^2 \theta}{r^2}$$

~~$$\cos^2 \theta + \sin^2 \theta$$~~



menghasilkan
2 berbeda
di $\theta =$ berbeda.

$f(x,y)$

Gak - Kontinu.

converted

Jadi Segala θ berbeda $\lim_{r \rightarrow 0} f(x,y)$ gak

Kontinu

$$f(x,y) = \frac{1}{(1-x^2-y^2)^{1/2}}$$

=

$$\sqrt{1-x^2-y^2}$$

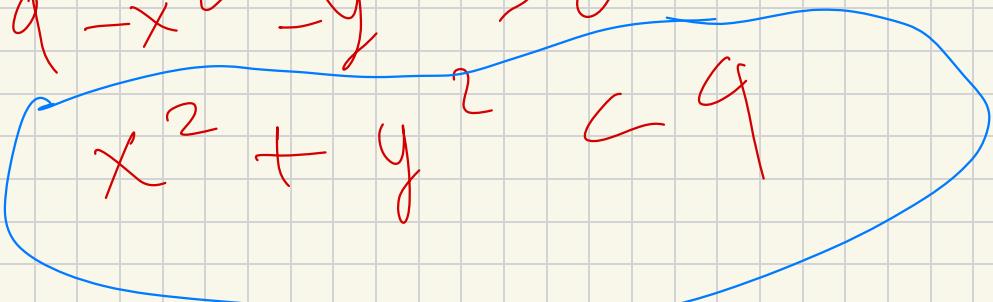
$$\sqrt{1-x^2-y^2} \leq 0$$

Bár kontinu

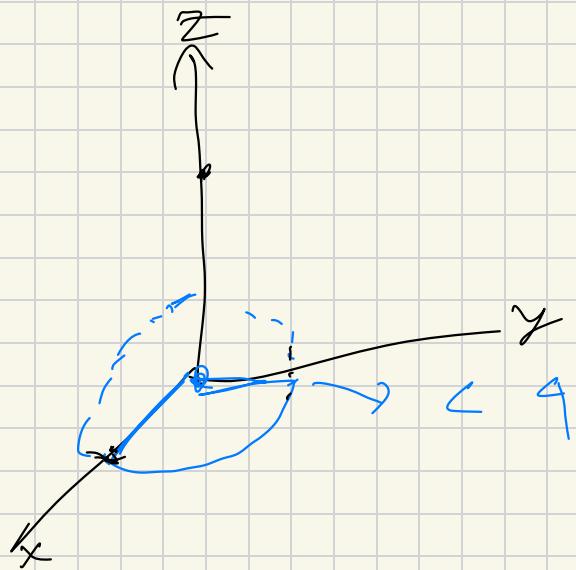
Set x,y value s hars kentky

$$1-x^2-y^2 > 0$$

$$x^2+y^2 < 1$$



Set x, y / Region $x^2 + y^2 \leq 9$
dit lingkaran dgn jari-jari ≤ 3
pusat $(0, 0)$



Limits

Definition Limit of a Function of Two Variables

To say that $\lim_{(x,y) \rightarrow (a,b)} f(x, y) = L$ means that for each $\varepsilon > 0$ (no matter how small) there is a corresponding $\delta > 0$ such that $|f(x, y) - L| < \varepsilon$, provided that $0 < \|(x, y) - (a, b)\| < \delta$.

Note several aspects of this definition.

1. The path of approach to (a, b) is irrelevant. This means that if different paths of approach lead to different L -values then the limit does not exist.
2. The behavior of $f(x, y)$ at (a, b) is irrelevant; the function does not even have to be defined at (a, b) . This follows from the restriction $0 < \|(x, y) - (a, b)\|$.

Limits

Theorem A

If $f(x, y)$ is a polynomial, then

$$\lim_{(x,y) \rightarrow (a,b)} f(x, y) = f(a, b)$$

and if $f(x, y) = p(x, y)/q(x, y)$, where p and q are polynomials, then

$$\lim_{(x,y) \rightarrow (a,b)} f(x, y) = \frac{p(a, b)}{q(a, b)}$$

provided $q(a, b) \neq 0$. Furthermore, if

$$\lim_{(x,y) \rightarrow (a,b)} p(x, y) = L \neq 0 \quad \text{and} \quad \lim_{(x,y) \rightarrow (a,b)} q(x, y) = 0$$

then

$$\lim_{(x,y) \rightarrow (a,b)} \frac{p(x, y)}{q(x, y)}$$

does not exist.

EXAMPLE 1 Evaluate the following limits if they exist:

$$(a) \lim_{(x,y) \rightarrow (1,2)} (x^2y + 3y) \quad \text{and} \quad (b) \lim_{(x,y) \rightarrow (0,0)} \frac{x^2 + y^2 + 1}{x^2 - y^2}$$

SOLUTION

(a) The function whose limit we seek is a polynomial, so by Theorem A

$$\lim_{(x,y) \rightarrow (1,2)} (x^2y + 3y) = 1^2 \cdot 2 + 3 \cdot 2 = 8$$

(b) The second function is a rational function, but the limit of the denominator is equal to 0, while the limit of the numerator is 1. Thus, by Theorem A, this limit does not exist. ■

EXAMPLE 2

Show that the function f defined by

$$f(x, y) = \frac{x^2 - y^2}{x^2 + y^2}$$

has no limit at the origin (Figure 3).

has no limit at the origin (Figure 3).

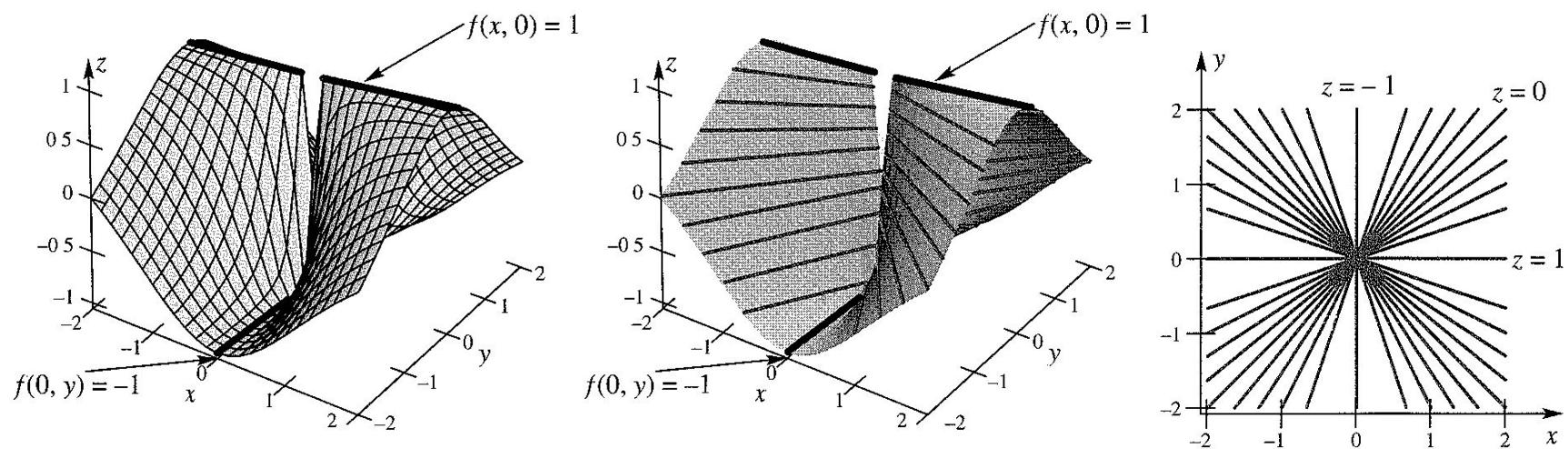


Figure 3

SOLUTION The function f is defined everywhere in the xy -plane except at the origin. At all points on the x -axis different from the origin, the value of f is

$$f(x, 0) = \frac{x^2 - 0}{x^2 + 0} = 1$$

Thus, the limit of $f(x, y)$ as (x, y) approaches $(0, 0)$ along the x -axis is

$$\lim_{(x,0) \rightarrow (0,0)} f(x, 0) = \lim_{(x,0) \rightarrow (0,0)} \frac{x^2 - 0}{x^2 + 0} = +1$$

Similarly, the limit of $f(x, y)$ as (x, y) approaches $(0, 0)$ along the y -axis is

$$\lim_{(0,y) \rightarrow (0,0)} f(0, y) = \lim_{(0,y) \rightarrow (0,0)} \frac{0 - y^2}{0 + y^2} = -1$$

Thus, we get different values depending on how $(x, y) \rightarrow (0, 0)$. In fact, there are points arbitrarily close to $(0, 0)$ at which the value of f is 1 and other points equally close at which the value of f is -1 . Therefore, the limit cannot exist at $(0, 0)$. ■■

Continuity at a Point

Continuity at a Point To say that $f(x, y)$ is **continuous** at the point (a, b) , we require the following: (1) f has a value at (a, b) , (2) f has a limit at (a, b) , and (3) the value of f at (a, b) is equal to the limit there. In summary, we require that

$$\lim_{(x,y) \rightarrow (a,b)} f(x, y) = f(a, b)$$

Theorem B Composition of Functions

If a function g of two variables is continuous at (a, b) and a function f of one variable is continuous at $g(a, b)$, then the composite function $f \circ g$, defined by $(f \circ g)(x, y) = f(g(x, y))$, is continuous at (a, b) .

Theorem C Equality of Mixed Partial Derivatives

If f_{xy} and f_{yx} are continuous on an open set S , then $f_{xy} = f_{yx}$ at each point of S .

Section 12.4

Differentiability

Differentiability

- A function f is **locally linear** at a if there is a constant m such that

$$f(a + h) = f(a) + hm + \overset{\circlearrowleft}{h\varepsilon(h)}$$

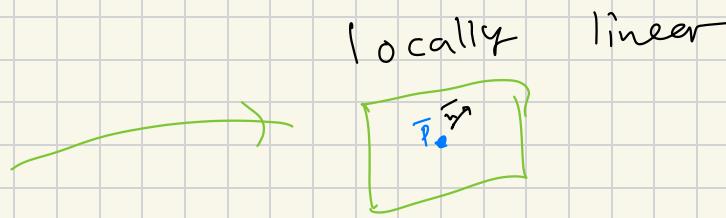
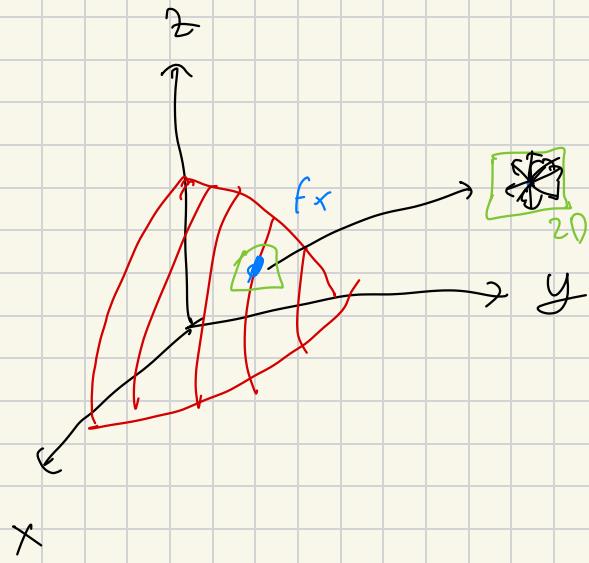
where $\varepsilon(h)$ is a function satisfying $\lim_{h \rightarrow 0} \varepsilon(h) = 0$

Definition Local Linearity for a Function of Two Variables

We say that f is **locally linear** at (a, b) if

$$\begin{aligned} f(a + h_1, b + h_2) \\ = f(a, b) + h_1 f_x(a, b) + h_2 f_y(a, b) + h_1 \varepsilon_1(h_1, h_2) + h_2 \varepsilon_2(h_1, h_2) \end{aligned}$$

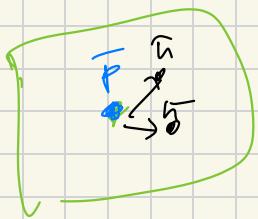
where $\varepsilon_1(h_1, h_2) \rightarrow 0$ as $(h_1, h_2) \rightarrow 0$ and $\varepsilon_2(h_1, h_2) \rightarrow 0$ as $(h_1, h_2) \rightarrow 0$.



$$f(\bar{p} + \bar{h}) = f(\bar{p}) + \nabla f \cdot \bar{h} +$$

\downarrow
 (x, y)

$$\nabla f = \begin{pmatrix} f_x \\ f_y \end{pmatrix} \quad \bar{h} = \begin{pmatrix} \Delta x \\ \Delta y \end{pmatrix}$$



$$f(\bar{p} + \bar{h}) = f(\bar{p}) + \cancel{f_x \cdot \Delta x} + \cancel{f_y \cdot \Delta y}$$

Persamaan Ridicency Singgung

$f(x, y)$

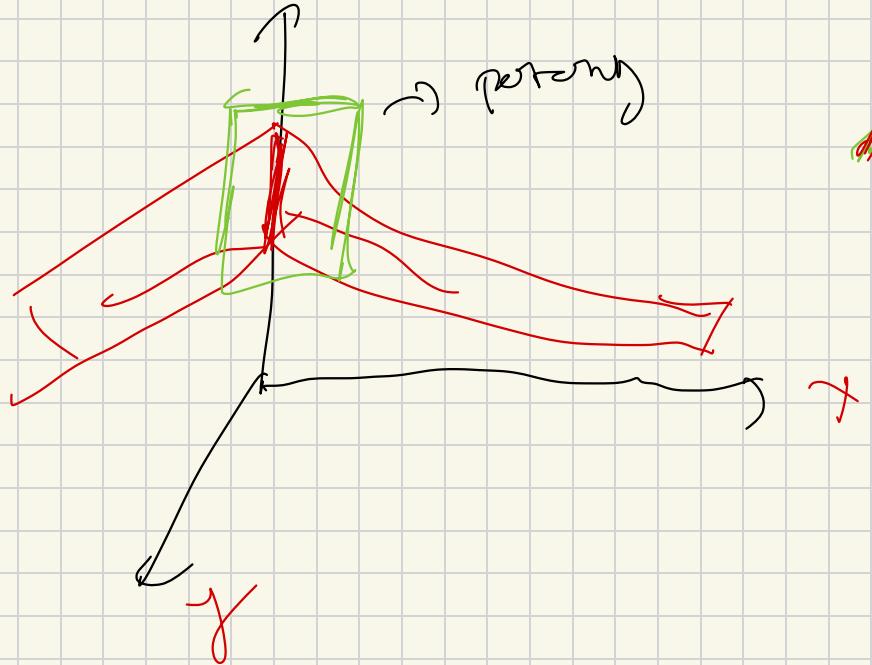
terdifferensialkan atau f'dcah

Jika $f(x, y)$

terdiferensialkan \rightarrow

f_x
 f_y

Kontinu

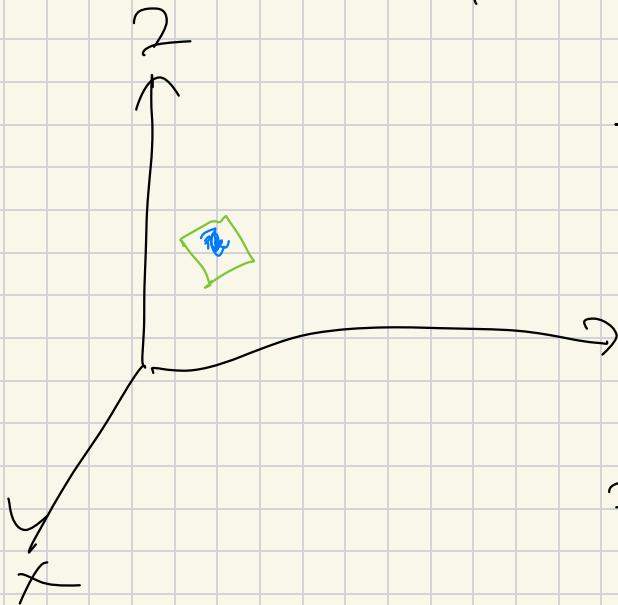


$$f(x,y) = \underline{x^2y} + \underline{y^2x} \rightarrow \overline{P} \left(\begin{smallmatrix} x \\ y \end{smallmatrix} \right)$$

$f(x,y) \rightarrow$ Polinomial \rightarrow Kontinu

maka terdiferensialkan,

$$\bar{h} \left(\begin{array}{c} \frac{\partial x}{\partial y} \end{array} \right)$$



$$f(\bar{p} + \bar{h}) = f(\bar{p}) + \nabla_f \cdot \bar{h}$$

$$z = 16 + \left(\begin{array}{c} 12 \\ 12 \end{array} \right) \cdot \left(\begin{array}{c} x-2 \\ y-2 \end{array} \right)$$

$$z = 16 + 12(x-2) + 12(y-2)$$

$$z = 16 + 12x - (16 + 12y - 24)$$

Bidang Singgung \Rightarrow

$$z = 12x + 12y - 32$$

$$f(x, y, z) = 3x^2 - 2y^2 + xz^2, P = (1, 2, -1)$$

$$\nabla f = \begin{pmatrix} 6x + z^2 \\ -4y \\ 2xz \end{pmatrix} = \begin{pmatrix} 7 \\ -8 \\ -2 \end{pmatrix}$$

tangent + gyrorplasm

$$f(\bar{P} + h) = w \rightarrow$$

$$w = (3(1)^2 - 2(2)^2 + (1)(-1)^2) + \begin{pmatrix} 7 \\ -8 \\ -2 \end{pmatrix} \begin{pmatrix} x-1 \\ y-2 \\ z+1 \end{pmatrix}$$

$$w = -9 + (7x - 7 - 8y + 16 - 2z - 2)$$

$$w = 7x - 8y - 2z + 3$$

// //

Differentiability

Definition Differentiability for a Function of Two or More Variables

The function f is **differentiable** at \mathbf{p} if it is locally linear at \mathbf{p} . The function f is differentiable on an open set R if it is differentiable at every point in R .

The vector $(f_x(\mathbf{p}), f_y(\mathbf{p})) = f_x(\mathbf{p})\mathbf{i} + f_y(\mathbf{p})\mathbf{j}$ is denoted $\nabla f(\mathbf{p})$ and is called the **gradient** of f . Thus, f is differentiable at \mathbf{p} if and only if

$$f(\mathbf{p} + \mathbf{h}) = f(\mathbf{p}) + \nabla f(\mathbf{p}) \cdot \mathbf{h} + \varepsilon(\mathbf{h}) \cdot \mathbf{h}$$

where $\varepsilon(\mathbf{h}) \rightarrow \mathbf{0}$ as $\mathbf{h} \rightarrow \mathbf{0}$. The operator ∇ is read “del” and is often called the **del operator**.

In the sense described above, *the gradient becomes the analog of the derivative*. We point out several aspects of our definitions.

1. The derivative $f'(x)$ is a number, whereas the gradient $\nabla f(\mathbf{p})$ is a vector.
2. The products $\nabla f(\mathbf{p}) \cdot \mathbf{h}$ and $\varepsilon(\mathbf{h}) \cdot \mathbf{h}$ are dot products.
3. The definitions of differentiability and gradient are easily extended to any number of dimensions.

Differentiability

Theorem A

If $f(x, y)$ has continuous partial derivatives $f_x(x, y)$ and $f_y(x, y)$ on a disk D whose interior contains (a, b) , then $f(x, y)$ is differentiable at (a, b) .

Differentiability

If the function f is differentiable at \mathbf{p}_0 , then, when \mathbf{h} has small magnitude

$$f(\mathbf{p}_0 + \mathbf{h}) \approx f(\mathbf{p}_0) + \nabla f(\mathbf{p}_0) \cdot \mathbf{h}$$

Letting $\mathbf{p} = \mathbf{p}_0 + \mathbf{h}$, we find that the function T defined by

$$T(\mathbf{p}) = f(\mathbf{p}_0) + \nabla f(\mathbf{p}_0) \cdot (\mathbf{p} - \mathbf{p}_0)$$

should be a good approximation to $f(\mathbf{p})$ if \mathbf{p} is close to \mathbf{p}_0 . The equation $z = T(\mathbf{p})$ defines a plane that approximates f near \mathbf{p}_0 . Naturally, this plane is called the **tangent plane**. See Figure 4.

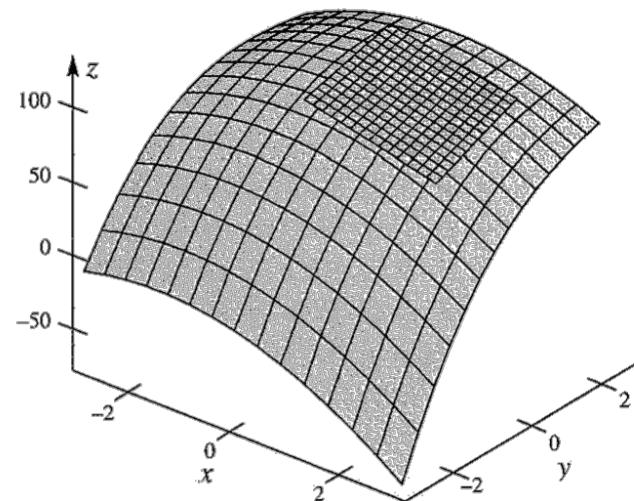


Figure 4
© 2006 Pearson Education

EXAMPLE 1 Show that $f(x, y) = xe^y + x^2y$ is differentiable everywhere and calculate its gradient. Then find the equation of the tangent plane at $(2, 0)$.

SOLUTION We note first that

$$\frac{\partial f}{\partial x} = e^y + 2xy \quad \text{and} \quad \frac{\partial f}{\partial y} = xe^y + x^2$$

Both of these functions are continuous everywhere and so, by Theorem A, f is differentiable everywhere. The gradient is

$$\nabla f(x, y) = (e^y + 2xy)\mathbf{i} + (xe^y + x^2)\mathbf{j} = \langle e^y + 2xy, xe^y + x^2 \rangle$$

Thus,

$$\nabla f(2, 0) = \mathbf{i} + 6\mathbf{j} = \langle 1, 6 \rangle$$

and the equation of the tangent plane is

$$\begin{aligned} z &= f(2, 0) + \nabla f(2, 0) \cdot \langle x - 2, y \rangle \\ &= 2 + \langle 1, 6 \rangle \cdot \langle x - 2, y \rangle \\ &= 2 + x - 2 + 6y = x + 6y \end{aligned}$$



Rules for Gradients

Theorem B Properties of ∇

The gradient operator ∇ satisfies

1. $\nabla[f(\mathbf{p}) + g(\mathbf{p})] = \nabla f(\mathbf{p}) + \nabla g(\mathbf{p})$
2. $\nabla[\alpha f(\mathbf{p})] = \alpha \nabla f(\mathbf{p})$
3. $\nabla[f(\mathbf{p})g(\mathbf{p})] = f(\mathbf{p}) \nabla g(\mathbf{p}) + g(\mathbf{p}) \nabla f(\mathbf{p})$

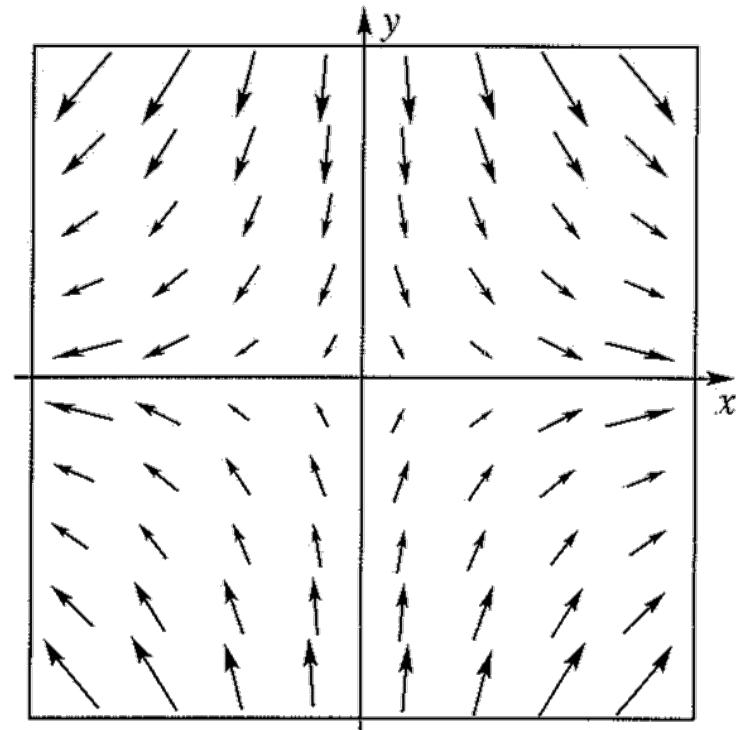
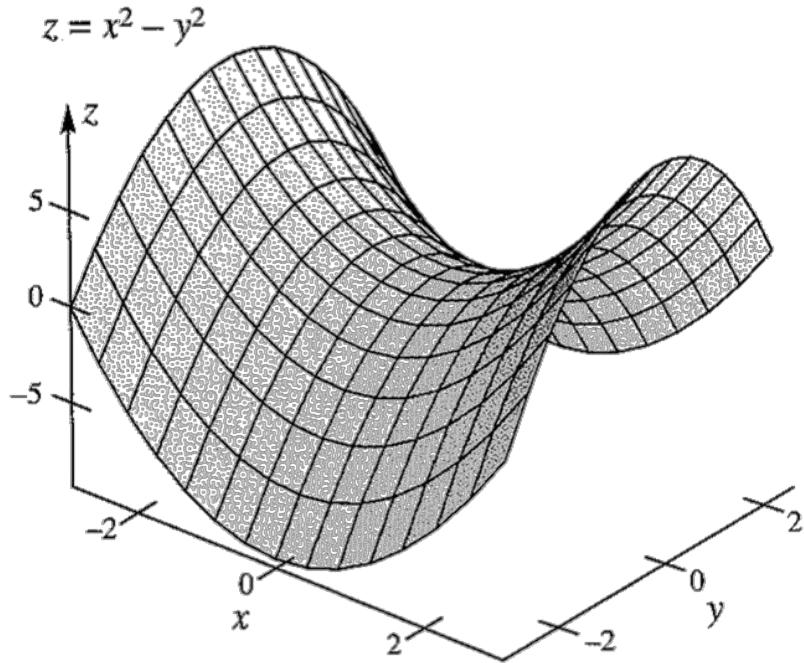
Continuity versus Differentiability

Theorem C

If f is differentiable at \mathbf{p} , then f is continuous at \mathbf{p} .

The Gradient Field

- The gradient ∇f associates with each point p in the domain of f a vector $\nabla f(p)$. The set of all these vectors is called the **gradient field** for f .



Section 12.5

Directional Derivatives and Gradients

Directional Derivative

Definition

For any unit vector \mathbf{u} , let

$$D_{\mathbf{u}}f(\mathbf{p}) = \lim_{h \rightarrow 0} \frac{f(\mathbf{p} + h\mathbf{u}) - f(\mathbf{p})}{h}$$

This limit, if it exists, is called the **directional derivative** of f at \mathbf{p} in the direction \mathbf{u} .

Thus, $D_{\mathbf{i}}f(\mathbf{p}) = f_x(\mathbf{p})$ and $D_{\mathbf{j}}f(\mathbf{p}) = f_y(\mathbf{p})$. Since $\mathbf{p} = (x, y)$, we also use the notation $D_{\mathbf{u}}f(x, y)$. Figure 1 gives the geometric interpretation of $D_{\mathbf{u}}f(x_0, y_0)$. The vector \mathbf{u} determines a line L in the xy -plane through (x_0, y_0) . The plane through L perpendicular to the xy -plane intersects the surface $z = f(x, y)$ in a curve C . Its tangent at the point $(x_0, y_0, f(x_0, y_0))$ has slope $D_{\mathbf{u}}f(x_0, y_0)$. Another useful interpretation is that $D_{\mathbf{u}}f(x_0, y_0)$ measures the rate of change of f with respect to distance in the direction

$$f_y(\mathbf{p}) = \lim_{h \rightarrow 0} \frac{f(\mathbf{p} + h\mathbf{j}) - f(\mathbf{p})}{h}$$

Connection with the Gradient

Theorem A

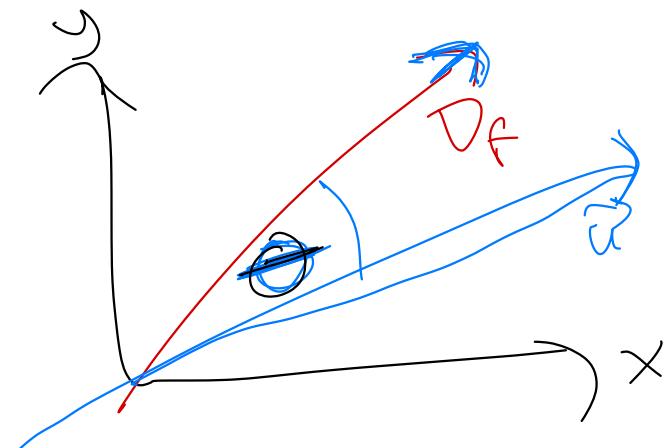
Let f be differentiable at \mathbf{p} . Then f has a directional derivative at \mathbf{p} in the direction of the unit vector $\mathbf{u} = u_1\mathbf{i} + u_2\mathbf{j}$ and

$$D_{\mathbf{u}}f(\mathbf{p}) = \underline{\mathbf{u}} \cdot \underline{\nabla f(\mathbf{p})} = \|\nabla f(\mathbf{p})\| \cdot \|\mathbf{u}\| - \cos \theta$$

That is,

$$D_{\mathbf{u}}f(x, y) = u_1 f_x(x, y) + u_2 f_y(x, y)$$

$$\hat{\mathbf{u}} = \frac{\langle \vec{\mathbf{u}} \rangle}{\|\vec{\mathbf{u}}\|}$$



$$f(x,y) = x^2y + y^2x$$

Caran' turunan berarah

d: $(2,2)$ dengan arah $\vec{a} \langle 3,4 \rangle$

$$\hat{u} = \frac{\langle u \rangle}{\|u\|} = \frac{\langle 3,4 \rangle}{\sqrt{25}} = \left(\begin{array}{c} \frac{3}{5} \\ \frac{4}{5} \end{array} \right)$$

D \hat{u} f(\vec{p}) = f($(2,2)$)

$$= \sqrt{12} \left(\begin{array}{c} \frac{3}{5} \\ \frac{4}{5} \end{array} \right)$$

$$= \frac{36}{5} + \frac{48}{5} = \frac{84}{5}$$

$$\theta = \frac{\pi}{6}$$

$$U = \begin{pmatrix} \cos \theta \\ \sin \theta \end{pmatrix}$$

Vektor Satran

(
))
Vektor arah
(. . .) → i + j

$$\sqrt{x^2 + y^2}$$

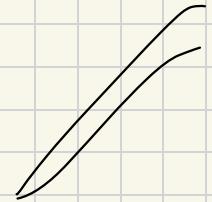
$$f(x, y) = x^3 - y^5$$

$$\nabla f = \begin{pmatrix} 3x^2 \\ -5y^4 \end{pmatrix} = \begin{pmatrix} 12 \\ -5 \end{pmatrix} \rightarrow \text{Direction}$$

rate of change, dapat dan panjang $|\nabla f|$

$$\nabla f = \underbrace{\langle 12, -5 \rangle}_{\sqrt{144 + 25}} = \underbrace{\langle 12, -5 \rangle}_{13} \rightarrow \begin{array}{l} \text{Unit vector} \\ \text{arah} \end{array}$$

$$\|\langle 12, -5 \rangle\| = \sqrt{13}$$



fungsi berakan
dan svd, hasilnya ^{sf} unit vektor

$$\begin{pmatrix} 1 & \cdot & \cdot & \cdot \\ - & 1 & \cdot & \cdot \end{pmatrix}$$

D_U f (

EXAMPLE 1 If $f(x, y) = 4x^2 - xy + 3y^2$, find the directional derivative of f at $(2, -1)$ in the direction of the vector $\mathbf{a} = 4\mathbf{i} + 3\mathbf{j}$.

SOLUTION The unit vector \mathbf{u} in the direction of \mathbf{a} is $\left(\frac{4}{5}\right)\mathbf{i} + \left(\frac{3}{5}\right)\mathbf{j}$. Also, $f_x(x, y) = 8x - y$ and $f_y(x, y) = -x + 6y$; thus, $f_x(2, -1) = 17$ and $f_y(2, -1) = -8$. Consequently, by Theorem A,

$$D_{\mathbf{u}}f(2, -1) = \left\langle \frac{4}{5}, \frac{3}{5} \right\rangle \cdot \langle 17, -8 \rangle = \frac{4}{5}(17) + \frac{3}{5}(-8) = \frac{44}{5}$$

EXAMPLE 2 Find the directional derivative of the function $f(x, y, z) = xy \sin z$ at the point $(1, 2, \pi/2)$ in the direction of the vector $\mathbf{a} = \mathbf{i} + 2\mathbf{j} + 2\mathbf{k}$.

SOLUTION The unit vector \mathbf{u} in the direction of \mathbf{a} is $\frac{1}{3}\mathbf{i} + \frac{2}{3}\mathbf{j} + \frac{2}{3}\mathbf{k}$. Also, $f_x(x, y, z) = y \sin z$, $f_y(x, y, z) = x \sin z$, and $f_z(x, y, z) = xy \cos z$, and so $f_x(1, 2, \pi/2) = 2$, $f_y(1, 2, \pi/2) = 1$, and $f_z(1, 2, \pi/2) = 0$. We conclude that

$$D_{\mathbf{u}}f\left(1, 2, \frac{\pi}{2}\right) = \frac{1}{3}(2) + \frac{2}{3}(1) + \frac{2}{3}(0) = \frac{4}{3}$$

Maximum Rate of Change

Maximum Rate of Change For a given function f at a given point \mathbf{p} , it is natural to ask in what direction the function is changing most rapidly, that is, in what direction is $D_{\mathbf{u}}f(\mathbf{p})$ the largest? From the geometric formula for the dot product (Section 11.3), we may write

$$D_{\mathbf{u}}f(\mathbf{p}) = \mathbf{u} \cdot \nabla f(\mathbf{p}) = \cancel{\|\mathbf{u}\|} \|\nabla f(\mathbf{p})\| \cos \theta = \cancel{\|\nabla f(\mathbf{p})\|} \cos \theta$$

where θ is the angle between \mathbf{u} and $\nabla f(\mathbf{p})$. Thus, $D_{\mathbf{u}}f(\mathbf{p})$ is maximized when $\theta = 0$ and minimized when $\theta = \pi$. We summarize as follows.



Theorem B

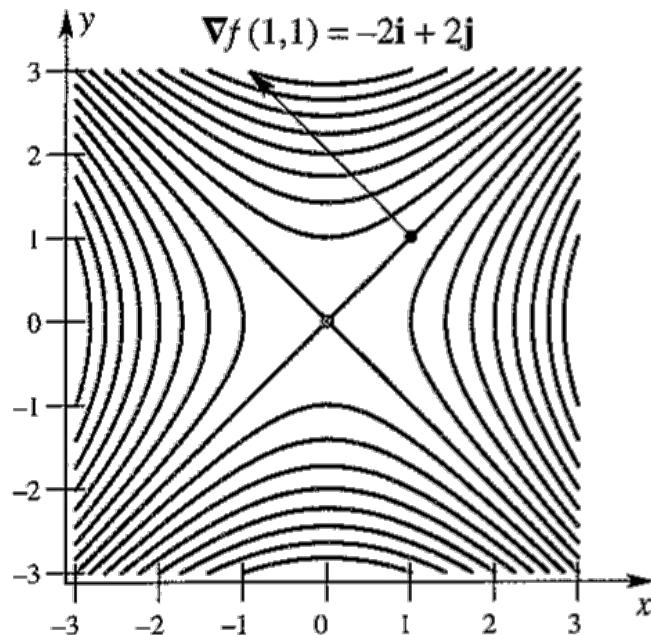
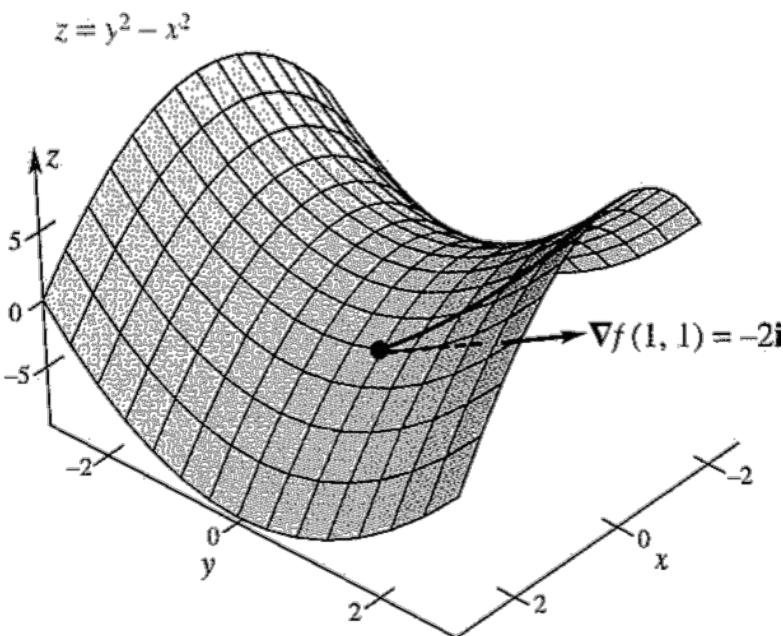
A function increases most rapidly at \mathbf{p} in the direction of the gradient (with rate $\|\nabla f(\mathbf{p})\|$) and decreases most rapidly in the opposite direction (with rate $-\|\nabla f(\mathbf{p})\|$).

EXAMPLE 3 Suppose that a bug is located on the hyperbolic paraboloid $z = y^2 - x^2$ at the point $(1, 1, 0)$, as in Figure 2. In what direction should it move for the steepest climb and what is the slope as it starts out?

SOLUTION Let $f(x, y) = y^2 - x^2$. Since $f_x(x, y) = -2x$ and $f_y(x, y) = 2y$,

$$\nabla f(1, 1) = f_x(1, 1)\mathbf{i} + f_y(1, 1)\mathbf{j} = -2\mathbf{i} + 2\mathbf{j}$$

Thus, the bug should move from $(1, 1, 0)$ in the direction $-2\mathbf{i} + 2\mathbf{j}$, where the slope will be $\| -2\mathbf{i} + 2\mathbf{j} \| = \sqrt{8} = 2\sqrt{2}$. ■



Level Curves and Gradients

Theorem C

The gradient of f at a point P is perpendicular to the level curve of f that goes through P .

- -

EXAMPLE 4 For the paraboloid $z = x^2/4 + y^2$, find the equation of its level curve that passes through the point $P(2, 1)$ and sketch it. Find the gradient vector of the paraboloid at P , and draw the gradient with its initial point at P .

SOLUTION The level curve of the paraboloid that corresponds to the plane $z = k$ has the equation $x^2/4 + y^2 = k$. To find the value of k belonging to the level curve through P , we substitute $(2, 1)$ for (x, y) and obtain $k = 2$. Thus, the equation of the level curve that goes through P is that of the ellipse

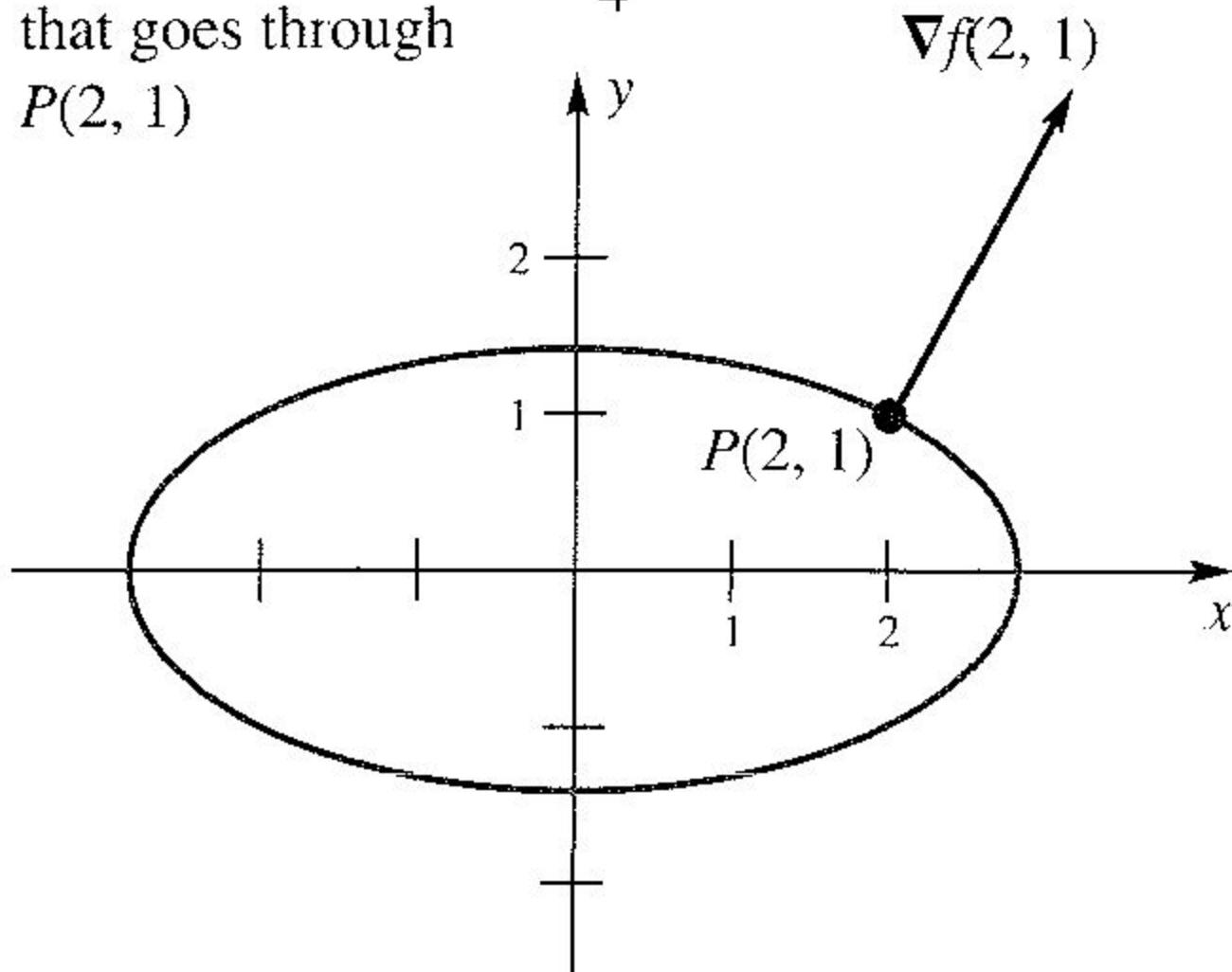
$$\frac{x^2}{8} + \frac{y^2}{2} = 1$$

Next let $f(x, y) = x^2/4 + y^2$. Since $f_x(x, y) = x/2$ and $f_y(x, y) = 2y$, the gradient of the paraboloid at $P(2, 1)$ is

$$\nabla f(2, 1) = f_x(2, 1)\mathbf{i} + f_y(2, 1)\mathbf{j} = \mathbf{i} + 2\mathbf{j}$$

The level curve and the gradient at P are shown in Figure 4.

The level curve of $z = \frac{x^2}{4} + y^2$
that goes through
 $P(2, 1)$



Section 12.6

The Chain Rule

$$\frac{dy}{dt} = \frac{dy}{dx} \cdot \frac{dx}{dt}$$

f_x

f_y

$$f(\bar{p} + \bar{\Delta}) = f(\bar{p}) + f_x \cdot \Delta x + f_y \cdot \Delta y$$

$$f(\bar{p} + \bar{\Delta}) - f(\bar{p}) = f_x \cdot \Delta x + f_y \cdot \Delta y$$

\dot{z}

$$\frac{\dot{z}}{\Delta t} = \frac{f_x \cdot \Delta x}{\Delta t} + \frac{f_y \cdot \Delta y}{\Delta t}$$

$$\frac{dz}{dt} = \left[\frac{\frac{dz}{dx} \cdot \frac{dx}{dt}}{dx} + \frac{\frac{dz}{dy} \cdot \frac{dy}{dt}}{dy} \right]$$

First Version

First Version If $z = f(x, y)$, where x and y are functions of t , then it makes sense to ask for dz/dt , and there ought to be a formula for it.

Theorem A Chain Rule

Let $x = x(t)$ and $y = y(t)$ be differentiable at t , and let $z = f(x, y)$ be differentiable at $(x(t), y(t))$. Then $z = f(x(t), y(t))$ is differentiable at t and

$$\frac{dz}{dt} = \frac{\partial z}{\partial x} \frac{dx}{dt} + \frac{\partial z}{\partial y} \frac{dy}{dt}$$

 **EXAMPLE 1** Suppose that $z = x^3y$, where $x = 2t$ and $y = t^2$. Find dz/dt .

SOLUTION

$$\begin{aligned}\frac{dz}{dt} &= \frac{\partial z}{\partial x} \frac{dx}{dt} + \frac{\partial z}{\partial y} \frac{dy}{dt} \\&= (3x^2y)(2) + (x^3)(2t) \\&= 6(2t)^2(t^2) + 2(2t)^3(t) \\&= 40t^4\end{aligned}$$



Second Version

Second Version Suppose next that $z = f(x, y)$, where $x = \underline{x(s, t)}$ and $y = \underline{y(s, t)}$. Then it makes sense to ask for $\partial z / \partial s$ and $\partial z / \partial t$.

Theorem B Chain Rule

Let $x = x(s, t)$ and $y = y(s, t)$ have first partial derivatives at (s, t) , and let $z = f(x, y)$ be differentiable at $(x(s, t), y(s, t))$. Then $z = f(x(s, t), y(s, t))$ has first partial derivatives given by

$$1. \quad \frac{\partial z}{\partial s} = \frac{\partial z}{\partial x} \frac{\partial x}{\partial s} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial s};$$

$$2. \quad \frac{\partial z}{\partial t} = \frac{\partial z}{\partial x} \frac{\partial x}{\partial t} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial t}.$$

EXAMPLE 4 If $z = 3x^2 - y^2$, where $x = 2s + 7t$ and $y = 5st$, find $\partial z/\partial t$ and express it in terms of s and t .

SOLUTION

$$\begin{aligned}\frac{\partial z}{\partial t} &= \frac{\partial z}{\partial x} \frac{\partial x}{\partial t} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial t} \\&= (6x)(7) + (-2y)(5s) \\&= 42(2s + 7t) - 10st(5s) \\&= 84s + 294t - 50s^2t\end{aligned}$$

Of course, if we substitute the expressions for x and y into the formula for z and then take the partial derivative with respect to t , we get the same answer:

$$\begin{aligned}\frac{\partial z}{\partial t} &= \frac{\partial}{\partial t}[3(2s + 7t)^2 - (5st)^2] \\&= \frac{\partial}{\partial t}[12s^2 + 84st + 147t^2 - 25s^2t^2] \\&= 84s + 294t - 50s^2t\end{aligned}$$

Implicit Function

Implicit Functions Suppose that $F(x, y) = 0$ defines y implicitly as a function of x , for example, $y = g(x)$, but that the function g is difficult or impossible to determine. We can still find dy/dx . One method for doing this, implicit differentiation, was discussed in Section 2.7. Here is another method.

Let's differentiate both sides of $F(x, y) = 0$ with respect to x using the Chain Rule. We obtain

$$\frac{\partial F}{\partial x} \frac{dx}{dx} + \frac{\partial F}{\partial y} \frac{dy}{dx} = 0$$

Solving for dy/dx yields the formula

$$\frac{dy}{dx} = -\frac{\partial F/\partial x}{\partial F/\partial y}$$

EXAMPLE 6

Find dy/dx if $x^3 + x^2y - 10y^4 = 0$ using

- (a) the Chain Rule, and (b) implicit differentiation.

SOLUTION

- (a) Let $F(x, y) = x^3 + x^2y - 10y^4$. Then

$$\frac{dy}{dx} = -\frac{\partial F/\partial x}{\partial F/\partial y} = -\frac{3x^2 + 2xy}{x^2 - 40y^3}$$

- (b) Differentiate both sides with respect to x to obtain

$$3x^2 + x^2 \frac{dy}{dx} + 2xy - 40y^3 \frac{dy}{dx} = 0$$

Solving for dy/dx gives the same result as we obtained with the Chain Rule. ■

If z is an implicit function of x and y defined by the equation $F(x, y, z) = 0$, then differentiation of both sides with respect to x , holding y fixed, yields

$$\frac{\partial F}{\partial x} \frac{\partial x}{\partial x} + \frac{\partial F}{\partial y} \frac{\partial y}{\partial x} + \frac{\partial F}{\partial z} \frac{\partial z}{\partial x} = 0$$

If we solve for $\partial z / \partial x$ and note that $\partial y / \partial x = 0$, we get the first of the formulas below. A similar calculation holding x fixed and differentiating with respect to y produces the second formula.

$$\frac{\partial z}{\partial x} = -\frac{\partial F / \partial x}{\partial F / \partial z}, \quad \frac{\partial z}{\partial y} = -\frac{\partial F / \partial y}{\partial F / \partial z}$$

EXAMPLE 7 If $F(x, y, z) = x^3 e^{y+z} - y \sin(x - z) = 0$ defines z implicitly as a function of x and y , find $\partial z / \partial x$.

SOLUTION

$$\frac{\partial z}{\partial x} = -\frac{\partial F / \partial x}{\partial F / \partial z} = -\frac{3x^2 e^{y+z} - y \cos(x - z)}{x^3 e^{y+z} + y \cos(x - z)}$$

Section 12.7

Tangent Planes and Approximations

Tangent Planes

$$z = f(x, y)$$
$$f(x, y) - z = 0$$
$$F(x, y, z) = 0$$

Definition

Let $F(x, y, z) = k$ determine a surface, and suppose that F is differentiable at a point $P(x_0, y_0, z_0)$ of this surface, with $\nabla F(x_0, y_0, z_0) \neq \mathbf{0}$. Then the plane through P perpendicular to $\nabla F(x_0, y_0, z_0)$ is called the **tangent plane** to the surface at P .

Theorem A | Tangent Planes

For the surface $F(x, y, z) = k$, the equation of the tangent plane at (x_0, y_0, z_0) is $\nabla F(x_0, y_0, z_0) \cdot \langle x - x_0, y - y_0, z - z_0 \rangle = 0$; that is,

$$F_x(x_0, y_0, z_0)(x - x_0) + F_y(x_0, y_0, z_0)(y - y_0) + F_z(x_0, y_0, z_0)(z - z_0) = 0$$

In particular, for the surface $z = f(x, y)$, the equation of the tangent plane at $(x_0, y_0, f(x_0, y_0))$ is

$$z - z_0 = f_x(x_0, y_0)(x - x_0) + f_y(x_0, y_0)(y - y_0)$$

$$z = f_x(x_0, y_0)(x - x_0) + f_y(x_0, y_0)(y - y_0)$$

$$\frac{\partial z}{\partial x} = z_0 + f_x(x - x_0) + f_y(y - y_0) + \frac{1}{2}(f_{xx}(x - x_0)^2 + f_{xy}(x - x_0)(y - y_0))$$

EXAMPLE 1 Find the equation of the tangent plane (Figure 3) to $z = x^2 + y^2$ at the point $(1, 1, 2)$.

SOLUTION Let $f(x, y) = x^2 + y^2$, and note that $\nabla f(x, y) = 2x\mathbf{i} + 2y\mathbf{j}$. Thus, $\nabla f(1, 1) = 2\mathbf{i} + 2\mathbf{j}$, and from Theorem A, the required equation is

$$z - 2 = 2(x - 1) + 2(y - 1)$$

or

$$2x + 2y - z = 2$$

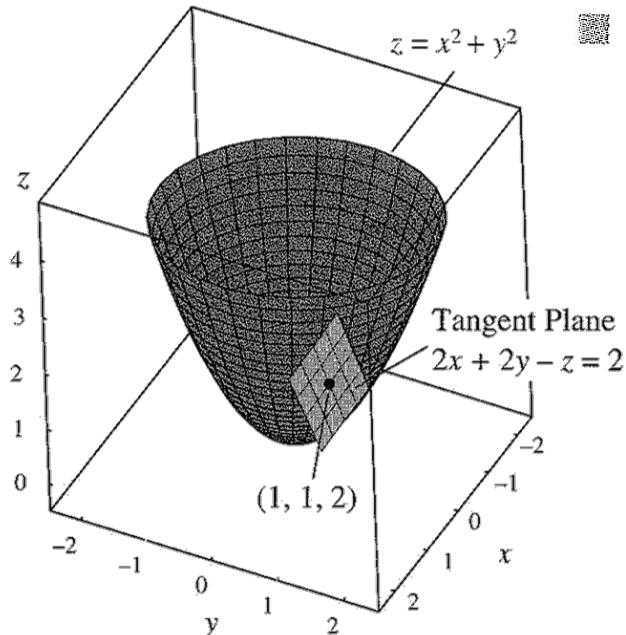


Figure 3

Differentials and Approximations

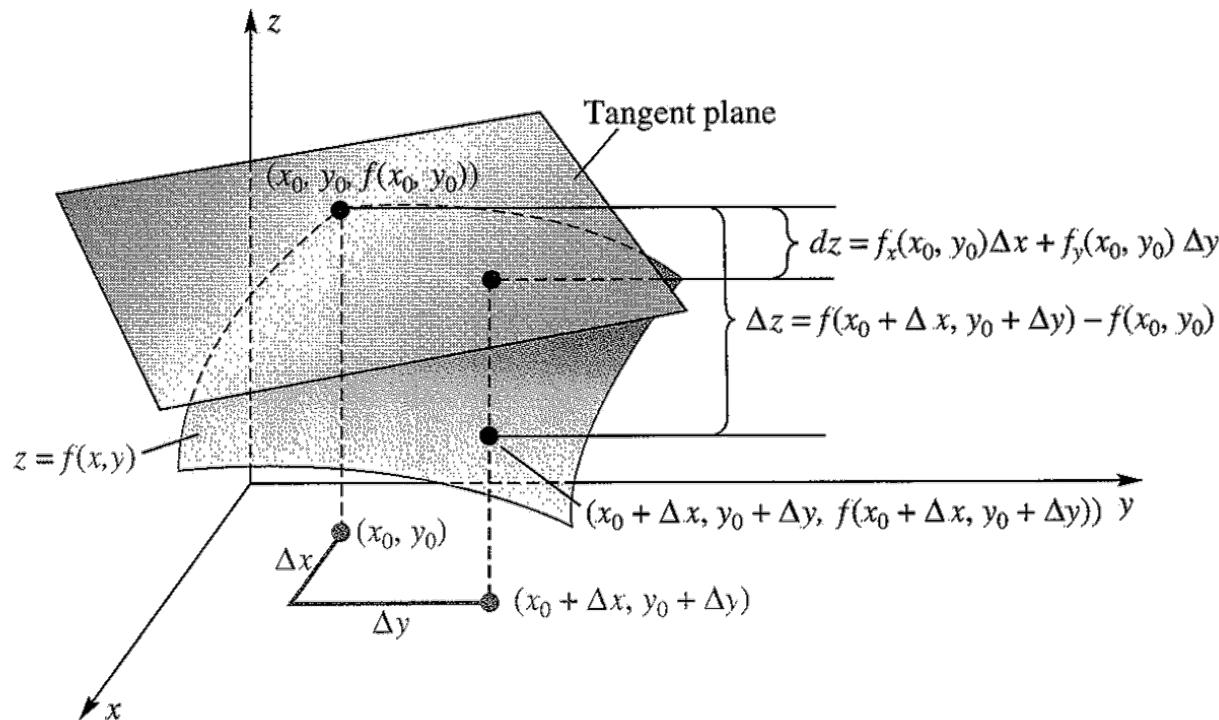
Definition

Let $z = f(x, y)$, where f is a differentiable function, and let dx and dy (called the differentials of x and y) be variables. The **differential of the dependent variable, dz** , also called the total **differential of f** and written $df(x, y)$, is defined by

$$dz = df(x, y) = f_x(x, y) dx + f_y(x, y) dy = \nabla f \cdot \langle dx, dy \rangle$$

Differentials and Approximations

The significance of dz arises from the fact that if $dx = \Delta x$ and $dy = \Delta y$ represent small changes in x and y , respectively, then dz will be a good approximation to Δz , the corresponding change in z . This is illustrated in Figure 5 and, while dz does not appear to be a very good approximation to Δz , you can see that it will get better and better as Δx and Δy get smaller.



EXAMPLE 3 Let $z = f(x, y) = 2x^3 + xy - y^3$. Compute Δz and dz as (x, y) changes from $(2, 1)$ to $(2.03, 0.98)$.

SOLUTION

$$\begin{aligned}\Delta z &= f(2.03, 0.98) - f(2, 1) \\&= 2(2.03)^3 + (2.03)(0.98) - (0.98)^3 - [2(2)^3 + 2(1) - 1^3] \\&= \underline{0.779062} \\dz &= f_x(x, y) \Delta x + f_y(x, y) \Delta y \\&= (6x^2 + y) \Delta x + (x - 3y^2) \Delta y\end{aligned}$$

At $(2, 1)$ with $\Delta x = 0.03$ and $\Delta y = -0.02$,

$$dz = (25)(0.03) + (-1)(-0.02) = 0.77$$

Section 12.8

Maxima and Minima

Maxima and Minima

Definition

Let f be a function with domain S , and let \mathbf{p}_0 be a point in S .

- (i) $f(\mathbf{p}_0)$ is a **global maximum value** of f on S if $f(\mathbf{p}_0) \geq f(\mathbf{p})$ for all \mathbf{p} in S .
- (ii) $f(\mathbf{p}_0)$ is a **global minimum value** of f on S if $f(\mathbf{p}_0) \leq f(\mathbf{p})$ for all \mathbf{p} in S .
- (iii) $f(\mathbf{p}_0)$ is a **global extreme value** of f on S if $f(\mathbf{p}_0)$ is either a global maximum value or a global minimum value.

We obtain definitions for **local maximum value** and **local minimum value** if in (i) and (ii) we require only that the inequalities hold on $N \cap S$, where N is some neighborhood of \mathbf{p}_0 . $f(\mathbf{p}_0)$ is a **local extreme value** of f on S if $f(\mathbf{p}_0)$ is either a local maximum value or a local minimum value.

Theorem A Max–Min Existence Theorem

If f is continuous on a closed bounded set S , then f attains both a (global) maximum value and a (global) minimum value there.

Where Do Extreme Values Occur?

Theorem B Critical Point Theorem

Let f be defined on a set S containing \mathbf{p}_0 . If $f(\mathbf{p}_0)$ is an extreme value, then \mathbf{p}_0 must be a critical point; that is, either \mathbf{p}_0 is

1. a boundary point of S ; or
2. a stationary point of f ; or
3. a singular point of f .

EXAMPLE 1 Find the local maximum or minimum values of $f(x, y) = x^2 - 2x + y^2/4$.

SOLUTION The given function is differentiable throughout its domain, the xy -plane. Thus, the only possible critical points are the stationary points obtained by setting $f_x(x, y)$ and $f_y(x, y)$ equal to zero. But $f_x(x, y) = 2x - 2$ and $f_y(x, y) = y/2$ are zero only when $x = 1$ and $y = 0$. It remains to decide whether $(1, 0)$ gives a maximum or a minimum or neither. We will develop a simple tool for this soon, but for now we must use a little ingenuity. Note that $f(1, 0) = -1$ and

$$\begin{aligned}f(x, y) &= x^2 - 2x + \frac{y^2}{4} = x^2 - 2x + 1 + \frac{y^2}{4} - 1 \\&= (x - 1)^2 + \frac{y^2}{4} - 1 \geq -1\end{aligned}$$

Thus, $f(1, 0)$ is actually a global minimum for f . There are no local maximum values.



Sufficient Conditions of Extrema

Theorem C Second Partial Test

Suppose that $f(x, y)$ has continuous second partial derivatives in a neighborhood of (x_0, y_0) and that $\nabla f(x_0, y_0) = \mathbf{0}$. Let

$$D = D(x_0, y_0) = f_{xx}(x_0, y_0)f_{yy}(x_0, y_0) - f_{xy}^2(x_0, y_0)$$

Then

1. if $D > 0$ and $f_{xx}(x_0, y_0) < 0$, then $f(x_0, y_0)$ is a local maximum value;
2. if $D > 0$ and $f_{xx}(x_0, y_0) > 0$, then $f(x_0, y_0)$ is a local minimum value;
3. if $D < 0$, then $f(x_0, y_0)$ is not an extreme value ((x_0, y_0) is a saddle point);
4. if $D = 0$, then the test is inconclusive.

EXAMPLE 3 Find the extrema, if any, of the function F defined by $F(x, y) = 3x^3 + y^2 - 9x + 4y$.

SOLUTION Since $F_x(x, y) = 9x^2 - 9$ and $F_y(x, y) = 2y + 4$, the critical points, obtained by solving the simultaneous equations $F_x(x, y) = F_y(x, y) = 0$, are $(1, -2)$ and $(-1, -2)$.

Now $F_{xx}(x, y) = 18x$, $F_{yy}(x, y) = 2$, and $F_{xy} = 0$. Thus, at the critical point $(1, -2)$,

$$D = F_{xx}(1, -2) \cdot F_{yy}(1, -2) - F_{xy}^2(1, -2) = 18(2) - 0 = 36 > 0$$

Furthermore, $F_{xx}(1, -2) = 18 > 0$ and so, by Theorem C(2), $F(1, -2) = -10$ is a local minimum value of F .

In testing the given function at the other critical point, $(-1, -2)$, we find that $F_{xx}(-1, -2) = -18$, $F_{yy}(-1, -2) = 2$, and $F_{xy}(-1, -2) = 0$, which makes $D = -36 < 0$. Thus, by Theorem C(3), $(-1, -2)$ is a saddle point and $F(-1, -2)$ is not an extremum.

EXAMPLE 4 Find the minimum distance between the origin and the surface $z^2 = x^2y + 4$.

SOLUTION Let $P(x, y, z)$ be any point on the surface. The square of the distance between the origin and P is $d^2 = x^2 + y^2 + z^2$. We seek the coordinates of P that make d^2 (and hence d) a minimum.

Since P is on the surface, its coordinates satisfy the equation of the surface. Substituting $z^2 = x^2y + 4$ in $d^2 = x^2 + y^2 + z^2$, we obtain d^2 as a function of two variables x and y .

$$d^2 = f(x, y) = x^2 + y^2 + x^2y + 4$$

To find the critical points, we set $f_x(x, y) = 0$ and $f_y(x, y) = 0$, obtaining

$$2x + 2xy = 0 \quad \text{and} \quad 2y + x^2 = 0$$

By eliminating y between these equations, we get

$$2x - x^3 = 0$$

Thus, $x = 0$ or $x = \pm\sqrt{2}$. Substituting these values in the second of the equations, we obtain $y = 0$ and $y = -1$. Therefore, the critical points are $(0, 0)$, $(\sqrt{2}, -1)$, and $(-\sqrt{2}, -1)$. (There are no boundary points.)

To test each of these, we need $f_{xx}(x, y) = 2 + 2y$, $f_{yy}(x, y) = 2$, $f_{xy}(x, y) = 2x$, and

$$D(x, y) = f_{xx}f_{yy} - f_{xy}^2 = 4 + 4y - 4x^2$$

Since $D(\pm\sqrt{2}, -1) = -8 < 0$, neither $(\sqrt{2}, -1)$ nor $(-\sqrt{2}, -1)$ yields an extremum. However, $D(0, 0) = 4 > 0$ and $f_{xx}(0, 0) = 2 > 0$; so $(0, 0)$ yields the minimum distance. Substituting $x = 0$ and $y = 0$ in the expression for d^2 , we find $d^2 = 4$.

The minimum distance between the origin and the given surface is 2.



Section 12.9

The Method of Lagrange Multipliers

Geometric Interpretation of the Method

Theorem A Lagrange's Method

To maximize or minimize $f(\mathbf{p})$ subject to the constraint $g(\mathbf{p}) = 0$, solve the system of equations

$$\nabla f(\mathbf{p}) = \lambda \nabla g(\mathbf{p}) \quad \text{and} \quad g(\mathbf{p}) = 0$$

for \mathbf{p} and λ . Each such point \mathbf{p} is a critical point for the constrained extremum problem, and the corresponding λ is called a Lagrange multiplier.

EXAMPLE 1 What is the greatest area that a rectangle can have if the length of its diagonal is 2?

SOLUTION Place the rectangle in the first quadrant with two of its sides along the coordinate axes; then the vertex opposite the origin has coordinates (x, y) , with x and y positive (Figure 3). The length of its diagonal is $\sqrt{x^2 + y^2} = 2$, and its area is xy .

Thus, we may formulate the problem to be that of maximizing $f(x, y) = xy$ subject to the constraint $g(x, y) = x^2 + y^2 - 4 = 0$. The corresponding gradients are

$$\nabla f(x, y) = f_x(x, y)\mathbf{i} + f_y(x, y)\mathbf{j} = y\mathbf{i} + x\mathbf{j}$$

$$\nabla g(x, y) = g_x(x, y)\mathbf{i} + g_y(x, y)\mathbf{j} = 2x\mathbf{i} + 2y\mathbf{j}$$

$$\nabla g(x, y) = g_x(x, y)\mathbf{i} + g_y(x, y)\mathbf{j} = 2x\mathbf{i} + 2y\mathbf{j}$$

Lagrange's equations thus become

$$(1) \quad y = \lambda(2x)$$

$$(2) \quad x = \lambda(2y)$$

$$(3) \quad x^2 + y^2 = 4$$

which we must solve simultaneously. If we multiply the first equation by y and the second by x , we get $y^2 = 2\lambda xy$ and $x^2 = 2\lambda xy$, from which

$$(4) \quad y^2 = x^2$$

From (3) and (4), we find that $x = \sqrt{2}$ and $y = \sqrt{2}$; and by substituting these values in (1), we obtain $\lambda = \frac{1}{2}$. Thus, the solution to equations (1) through (3), keeping x and y positive, is $x = \sqrt{2}$, $y = \sqrt{2}$, and $\lambda = \frac{1}{2}$.

We conclude that the rectangle of greatest area with diagonal 2 is the square having sides of length $\sqrt{2}$. Its area is 2. A geometric interpretation of this problem is shown in Figure 4.



EXAMPLE 3 Find the minimum of $f(x, y, z) = 3x + 2y + z + 5$ subject to the constraint $g(x, y, z) = 9x^2 + 4y^2 - z = 0$.

SOLUTION The gradients of f and g are $\nabla f(x, y, z) = 3\mathbf{i} + 2\mathbf{j} + \mathbf{k}$ and $\nabla g(x, y, z) = 18x\mathbf{i} + 8y\mathbf{j} - \mathbf{k}$. To find the critical points, we solve the equations

$$\nabla f(x, y, z) = \lambda \nabla g(x, y, z) \quad \text{and} \quad g(x, y, z) = 0$$

for (x, y, z, λ) , in which λ is a Lagrange multiplier. This is equivalent, in the present problem, to solving the following system of four simultaneous equations in the four variables x, y, z , and λ .

$$(1) \qquad \qquad \qquad 3 = 18x\lambda$$

$$(2) \qquad \qquad \qquad 2 = 8y\lambda$$

$$(3) \qquad \qquad \qquad 1 = -\lambda$$

$$(4) \qquad \qquad \qquad 9x^2 + 4y^2 - z = 0$$

From (3), $\lambda = -1$. Substituting this result in equations (1) and (2), we get $x = -\frac{1}{6}$ and $y = -\frac{1}{4}$. By putting these values for x and y in equation (4), we obtain $z = \frac{1}{2}$. Thus, the solution of the foregoing system of four simultaneous equations is $(-\frac{1}{6}, -\frac{1}{4}, \frac{1}{2}, -1)$, and the only critical point is $(-\frac{1}{6}, -\frac{1}{4}, \frac{1}{2})$. Therefore, the minimum of $f(x, y, z)$, subject to the constraint $g(x, y, z) = 0$, is $f(-\frac{1}{6}, -\frac{1}{4}, \frac{1}{2}) = \frac{9}{2}$. (How do we know that this value is a minimum rather than a maximum?) ■

End of Chapter 12

End of Chapter 12