

# Outlier Detection:

## *Density and Partition-Based*

### Mining Massive Datasets

Prof. Carlos Castillo — <https://chato.cl/teach>



Universitat  
Pompeu Fabra  
*Barcelona*

# Sources

Liu, F. T., Ting, K. M., & Zhou, Z. H. Isolation forest. ICDM 2008.

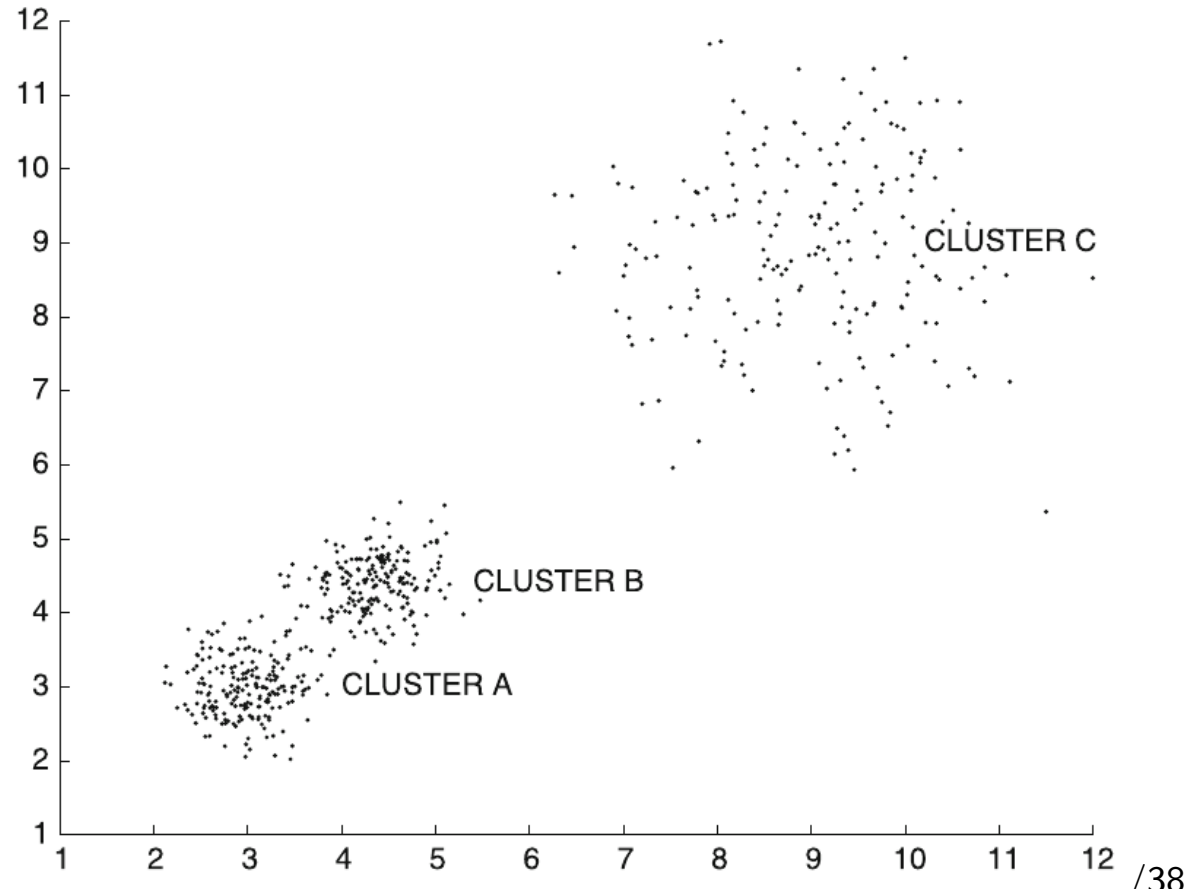
(1) Eryk Lewinson: Outlier detection with isolation forest (2018)

(2) Tobias Sterbak: Detecting network attacks with isolation forests (2018)

# Density-based methods

# Density-based methods

- Key idea:  
find sparse regions in  
the data
- Limitation:  
cannot handle  
variations of density

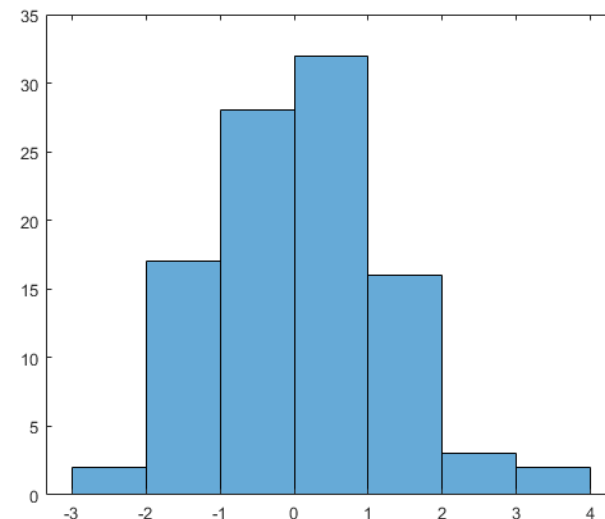


# Histogram- and grid-based methods

**Histogram-based** method:

1. Put data into **bins**
2. Outlier score:  $num - 1$ ,  
where  $num$  is the number of  
items in the same **bin**

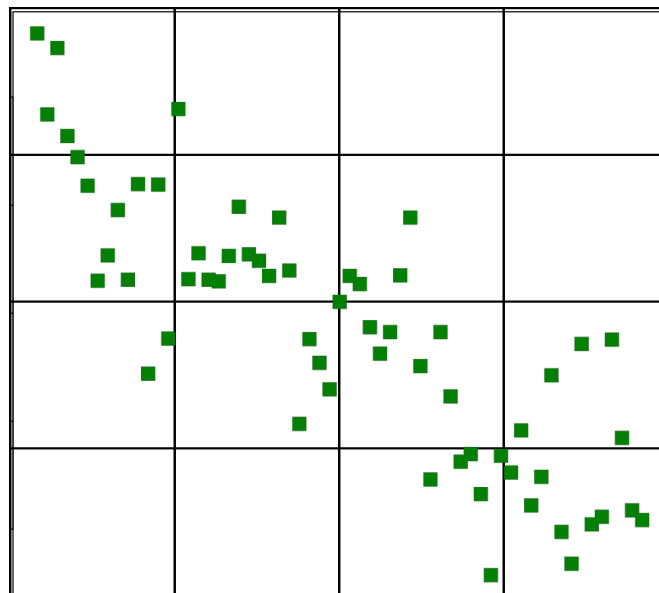
Clear outliers are alone or almost alone in a **bin**



# Histogram- and grid-based methods

## Grid-based method

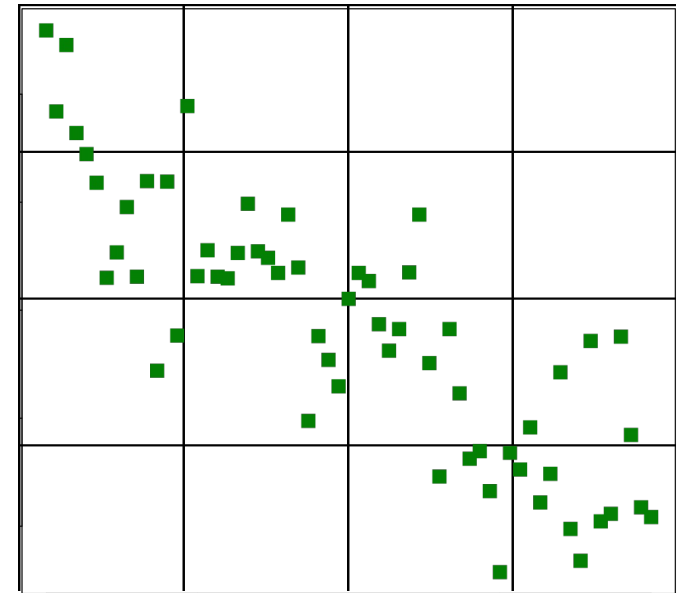
1. Put data into a **grid**
2. Outlier score:  $num - 1$ ,  
where  $num$  is the number of  
items in the same **cell**



Clear outliers are alone or almost alone in a **cell**

# Problems with grid-based methods

- How to choose the **grid size**?
- Grid size should be chosen considering data density, but **density might vary across regions**
- If **dimensionality is high**, then **most cells will be empty**



# Kernel-based methods

- Given  $n$  points  $\overline{X}_1, \overline{X}_2, \dots, \overline{X}_n$

$$f(\overline{X}) = \frac{1}{n} \sum_{i=1}^n K_h(\overline{X} - \overline{X}_i)$$

- $K_h$  is a function peaking at  $\overline{X}_i$  with *bandwidth*  $h$
- For instance, a Gaussian kernel:

$$K_h(\overline{X} - \overline{X}_i) = \left( \frac{1}{\sqrt{2\pi} \cdot h} \right)^d \cdot e^{-\|\overline{X} - \overline{X}_i\|^2 / (2h^2)}$$



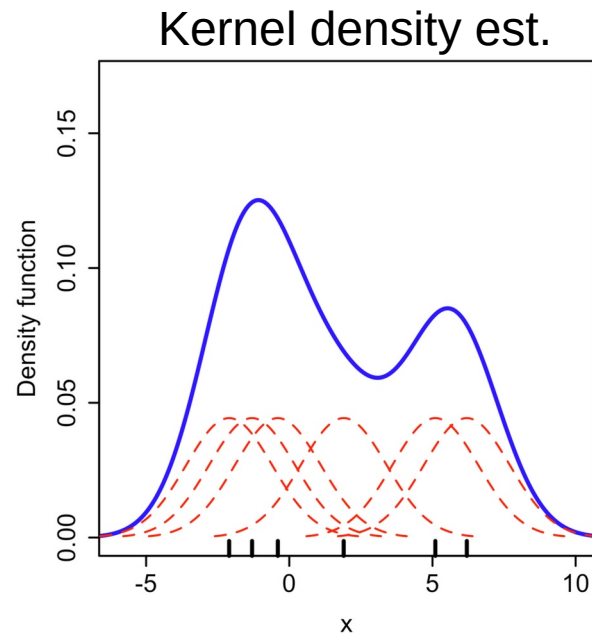
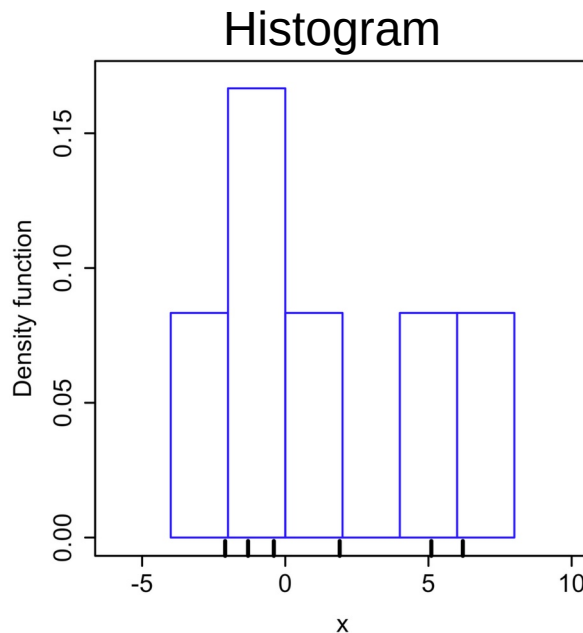
# Kernel-based methods (cont.)

- Example with a Gaussian kernel

$$\bar{X} = \langle -2.1, -1.3, -0.4, 1.9, 5.1, 6.2 \rangle$$

- Each  $K_h$  in red
- $f$  = sum of  $K_h$  in blue

$$f(\bar{X}) = \frac{1}{n} \sum_{i=1}^n K_h(\bar{X} - \bar{X}_i)$$



# Partitioning-based method: isolation forest

# Isolation forest method

- `tree_build(X)`
  - Pick a random dimension  $r$  of dataset  $X$
  - Pick a random point  $p$  in  $[\min_r(X), \max_r(X)]$
  - Divide the data into two pieces:  $x_r < p$  and  $x_r \geq p$
  - Recursively process each piece

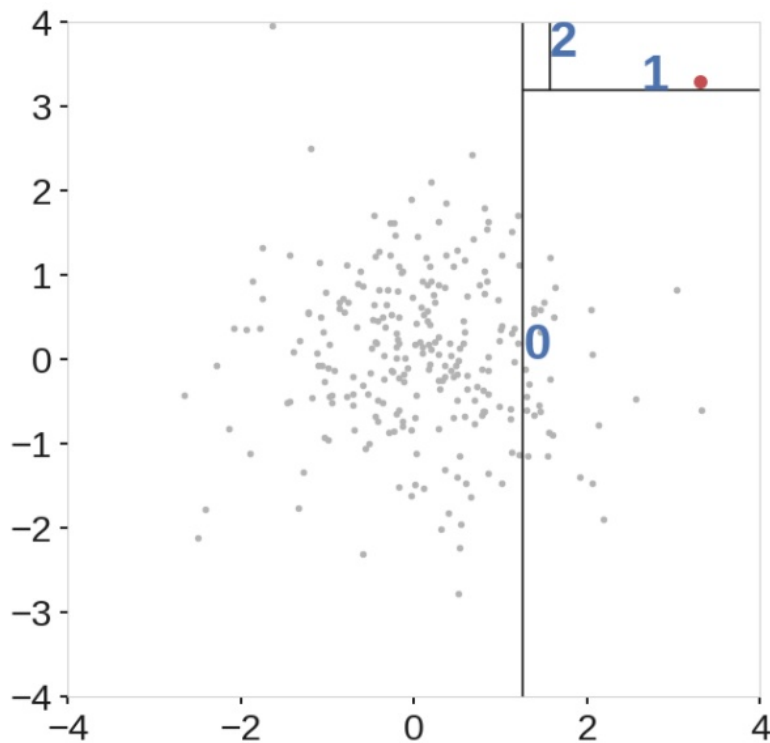
# Stopping criteria for recursion

- Stop when a **maximum depth** has been reached

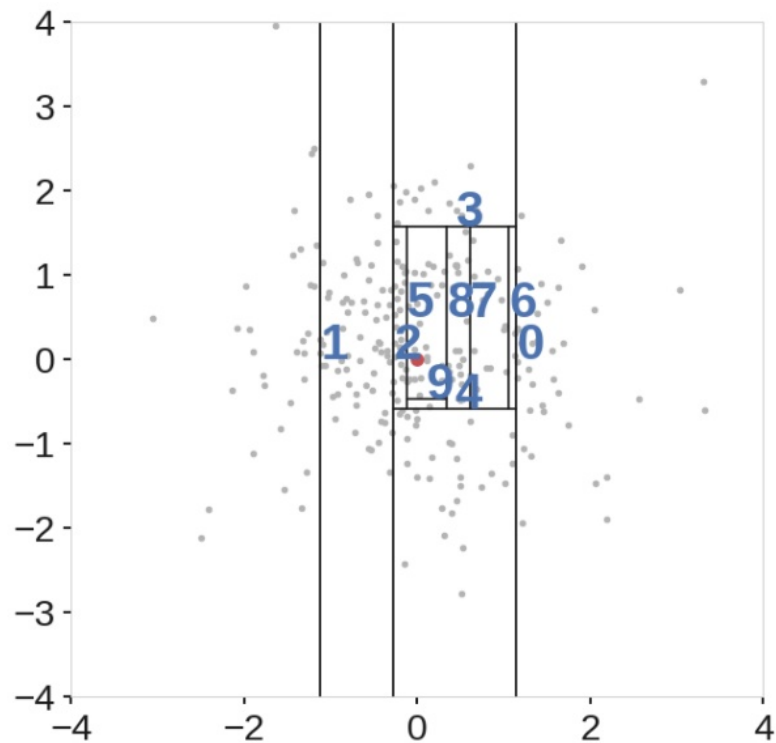
-or-

- Stop when each point is **alone** in one partition

# Key: outliers lie at **small depths**



(a) Anomaly point



(b) Nominal point

# Outlier score

- Let  $c(n)$  be the average path length of an unsuccessful search in a binary tree of  $n$  items

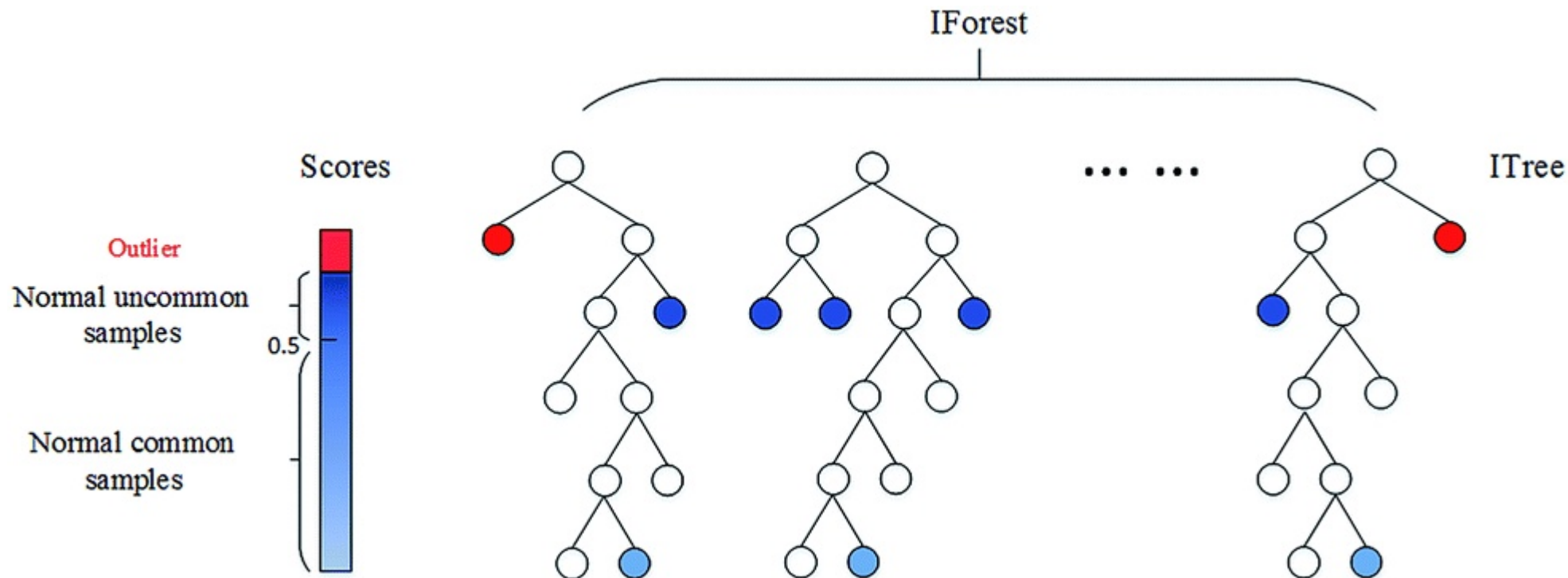
$$c(n) = 2H(n-1) - (2(n-1)/n)$$

$$H(n) = \sum_{k=1}^n \frac{1}{k}$$

- $h(x)$  is the depth at which  $x$  is found in tree
- Score:  $\text{outlier}(x, n) = 2^{-\frac{E(h(x))}{c(n)}}$

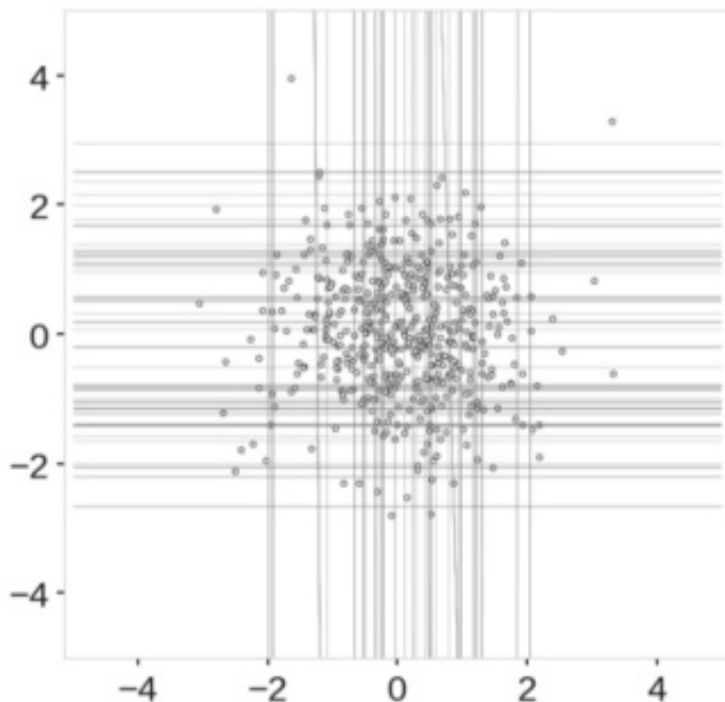
# Outlier scores in isolation forests

(each tree is built from a sub-sample of original data)

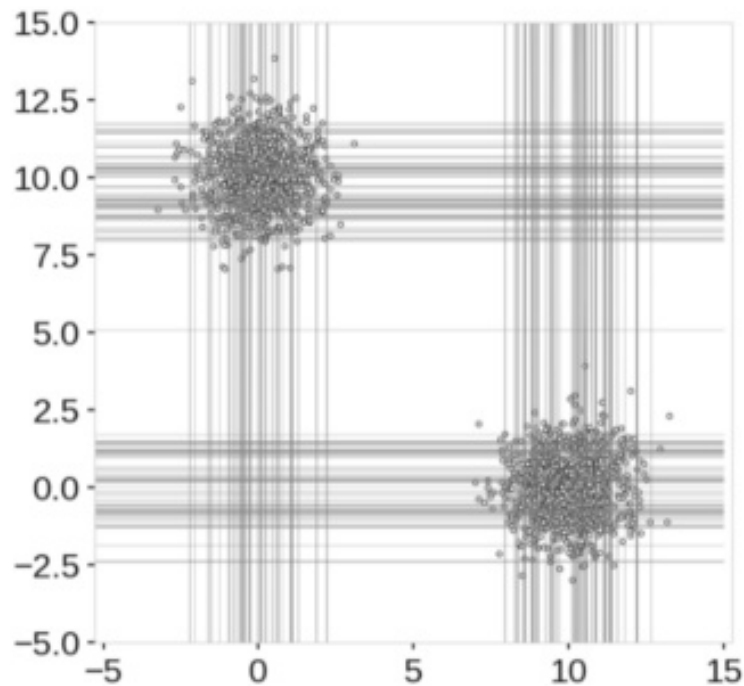


# Example

(Note: here lines cross each other: we do not cross lines)



(a) Single blob

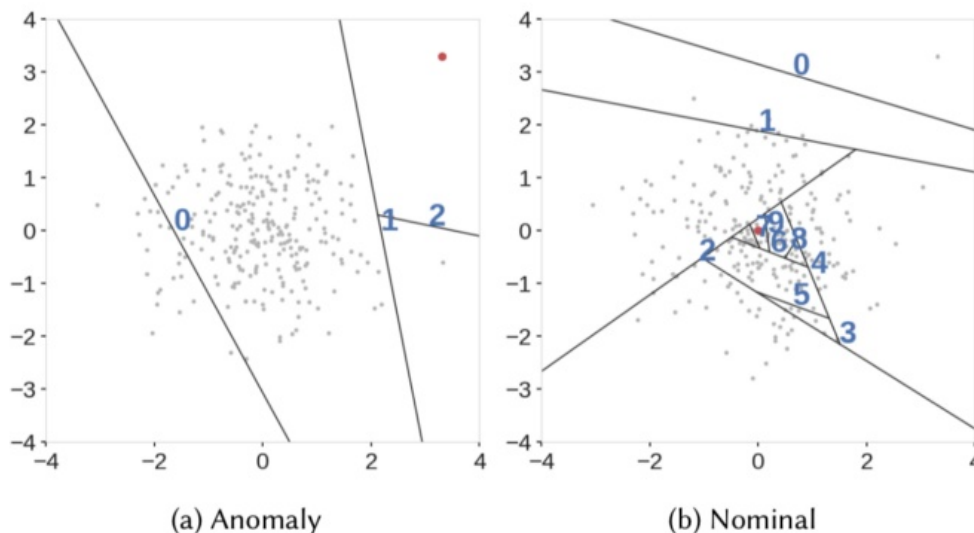


(b) Multiple Blobs



# Extended Isolation Forest

- More freedom to partitioning by choosing a random slope and a random intercept



# Exercise: isolation forest

- Create one tree of the isolation forest by repeating 4 times:

- Picking a sector containing  $>1$  element
- Picking a random dimension
- Picking a random cut-off between min and max value along that dimension
- Draw the line of your cut — do not cross lines, and label each line with a number 0, 1, 2, ...

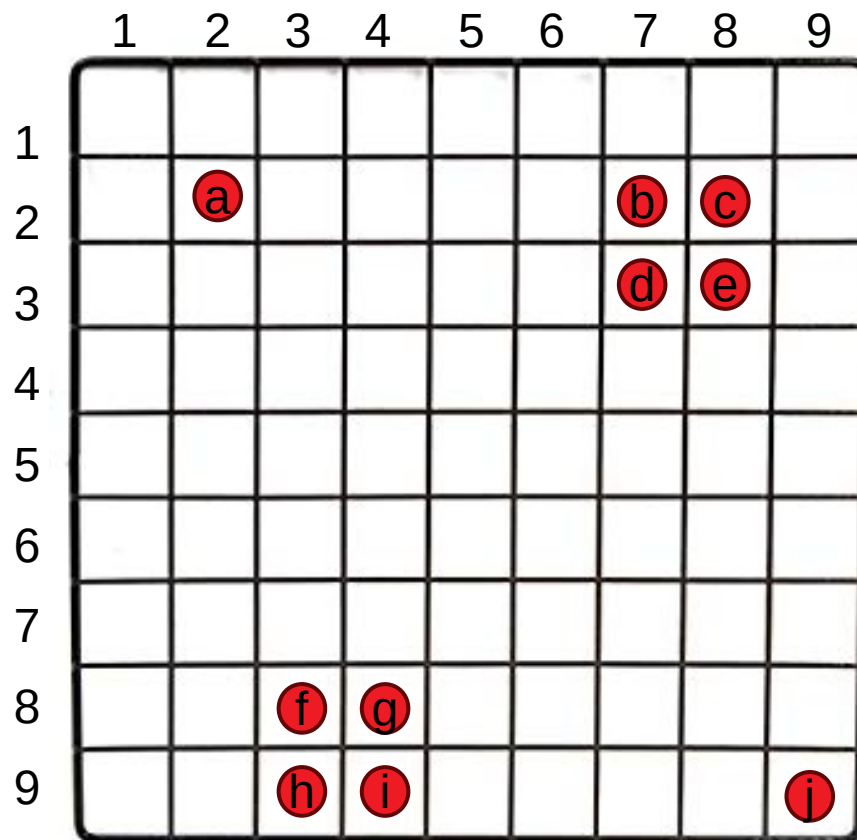
- Stop when each point is isolated

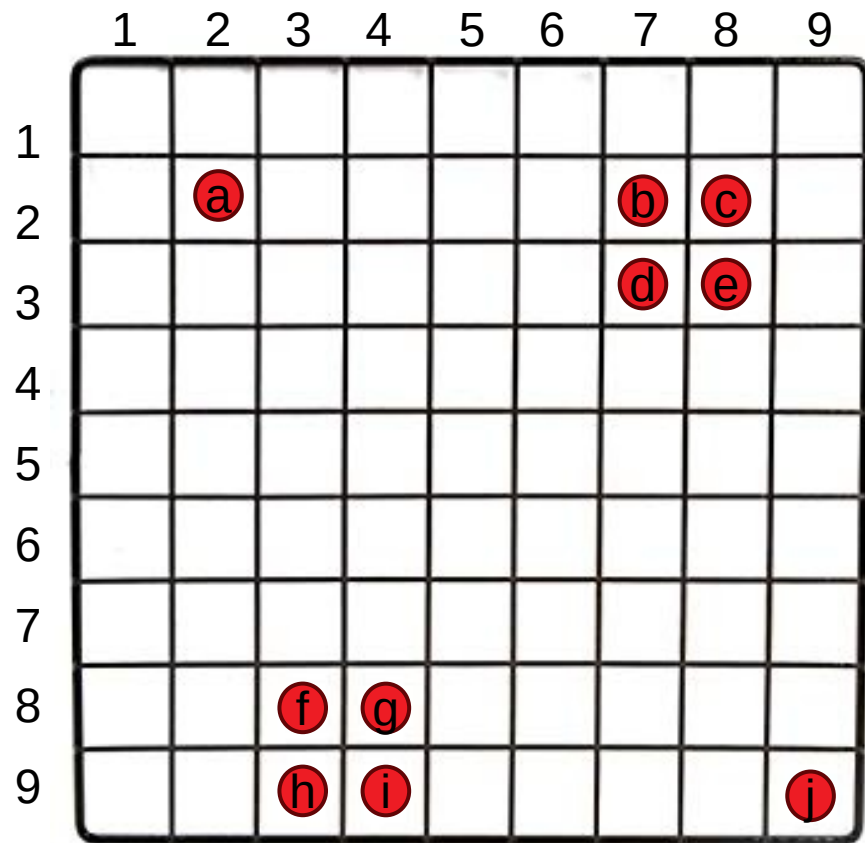
- Label each point with its depth  $h(x)$

This is normally repeated several times, in the end:

$$\text{outlier}(x, n) = 2^{-\frac{E(h(x))}{c(n)}}$$

In this case  $c(10) = 2 \times H(9) - (2 \times 9/10) \approx 3.857 \approx 4$





# Summary

# Things to remember

- Density-based methods
- Isolation forest

# Exercises for TT19-TT21

- Data Mining, The Textbook (2015) by Charu Aggarwal
  - Exercises 8.11  $\rightarrow$  all except 10, 15, 16, 17

**Additional contents**  
**(not included in exams)**

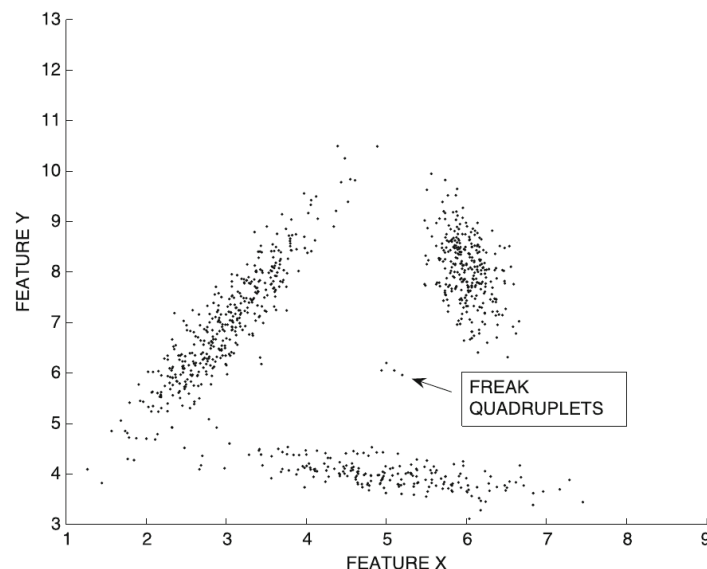
**EXTRA**

# Distance-based methods



# Instance-specific definition

- The distance-based outlier score of an object  $x$  is **its distance to its  $k^{\text{th}}$  nearest neighbor**
- In this example of a small group of 4 outliers, we can set  $k > 3$

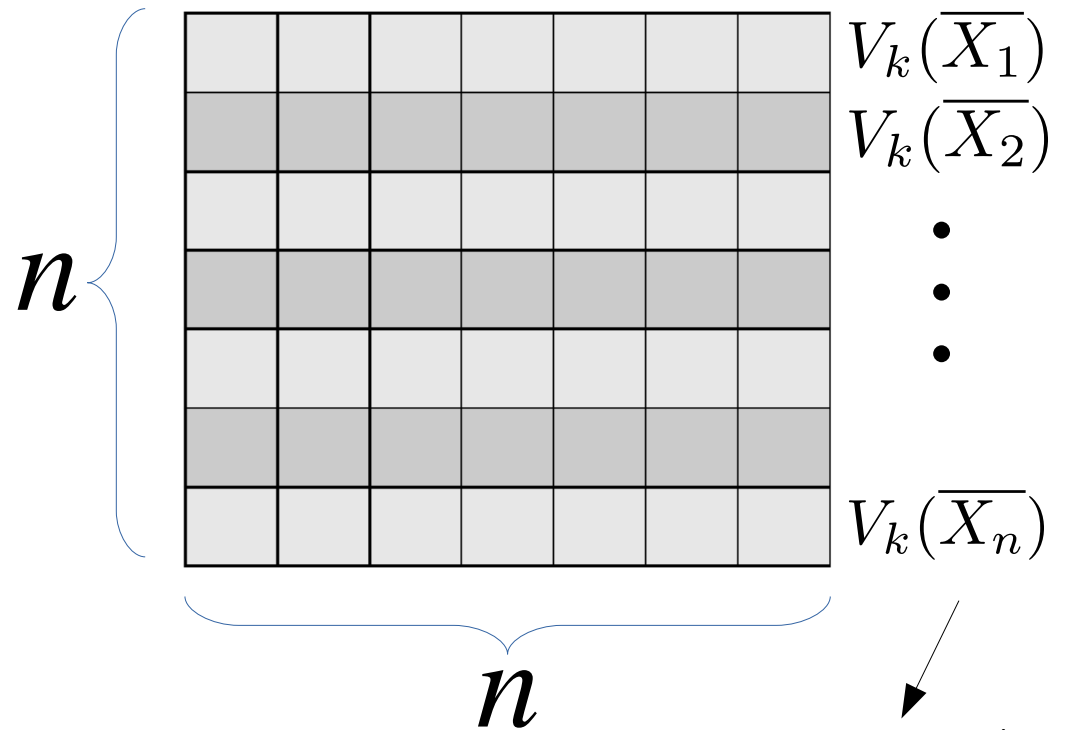


# Problem: computational cost

- The distance-based outlier score of an object  $x$  is its distance to its  $k^{\text{th}}$  nearest neighbor
- In principle this requires  $O(n^2)$  computations!
  - Index structure:  
useful only for cases of low data dimensionality
  - Pruning tricks:  
useful when only top- $r$  outliers are needed

# Problem: computational cost

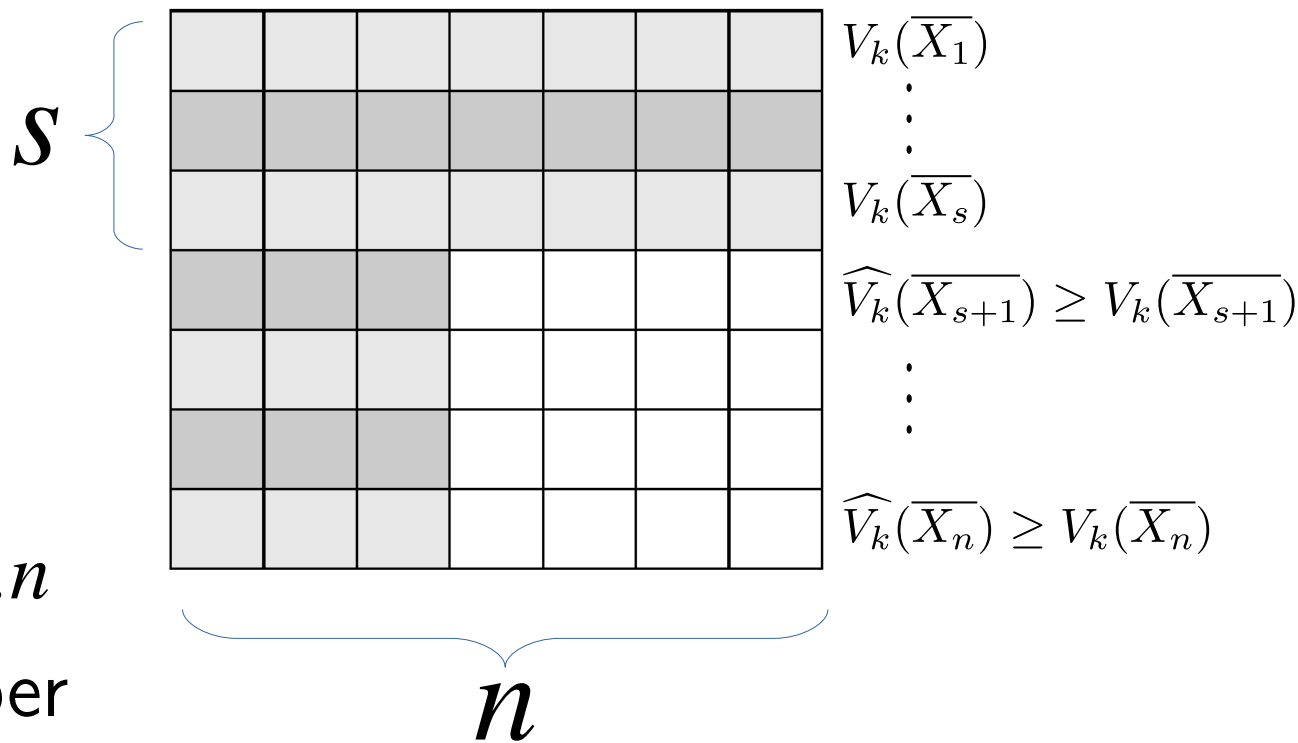
- The distance-based outlier score of an item  $x$  is its distance to its  $k^{\text{th}}$  nearest neighbor
- In principle this requires:
  - $O(n^2)$  computations for evaluating the  $n \times n$  distance matrix
  - $O(n^2)$  computations for finding the  $r$  smallest values on each row



Distance to  $k^{\text{th}}$   
nearest neighbor

# Pruning method: sampling

- Evaluate  $s \times n$  distances
- For points  $1 \dots s$  we are OK
- For points  $(s+1) \dots n$  we know only upper bounds



# Pruning method: sampling (cont.)

From points

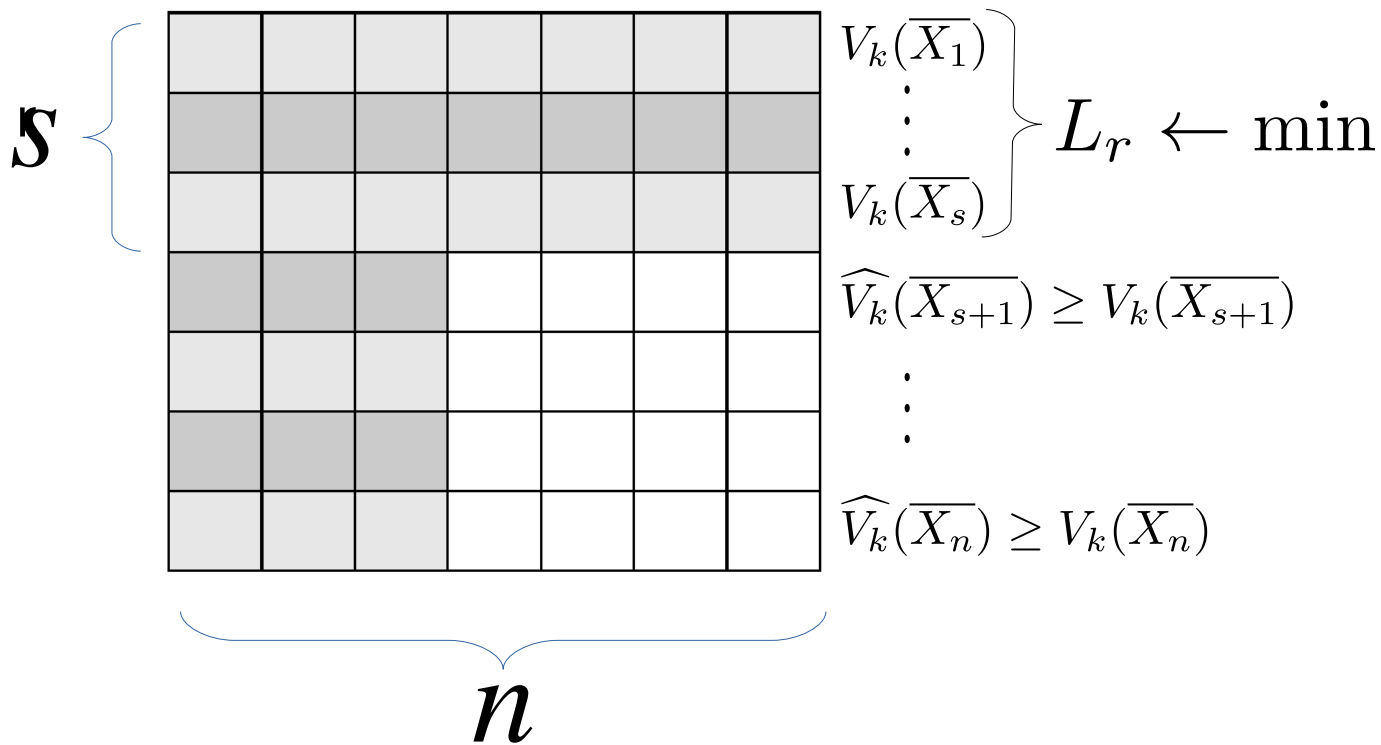
$1 \dots s$  we already know the “winners”

( $r \leq s$  nodes with the larger distance to their  $k^{\text{th}}$  nearest neighbor)

Any point having

$V_k < L_s$  cannot be among

the top  $r$  outliers



# Pruning method: sampling (cont.)

From points

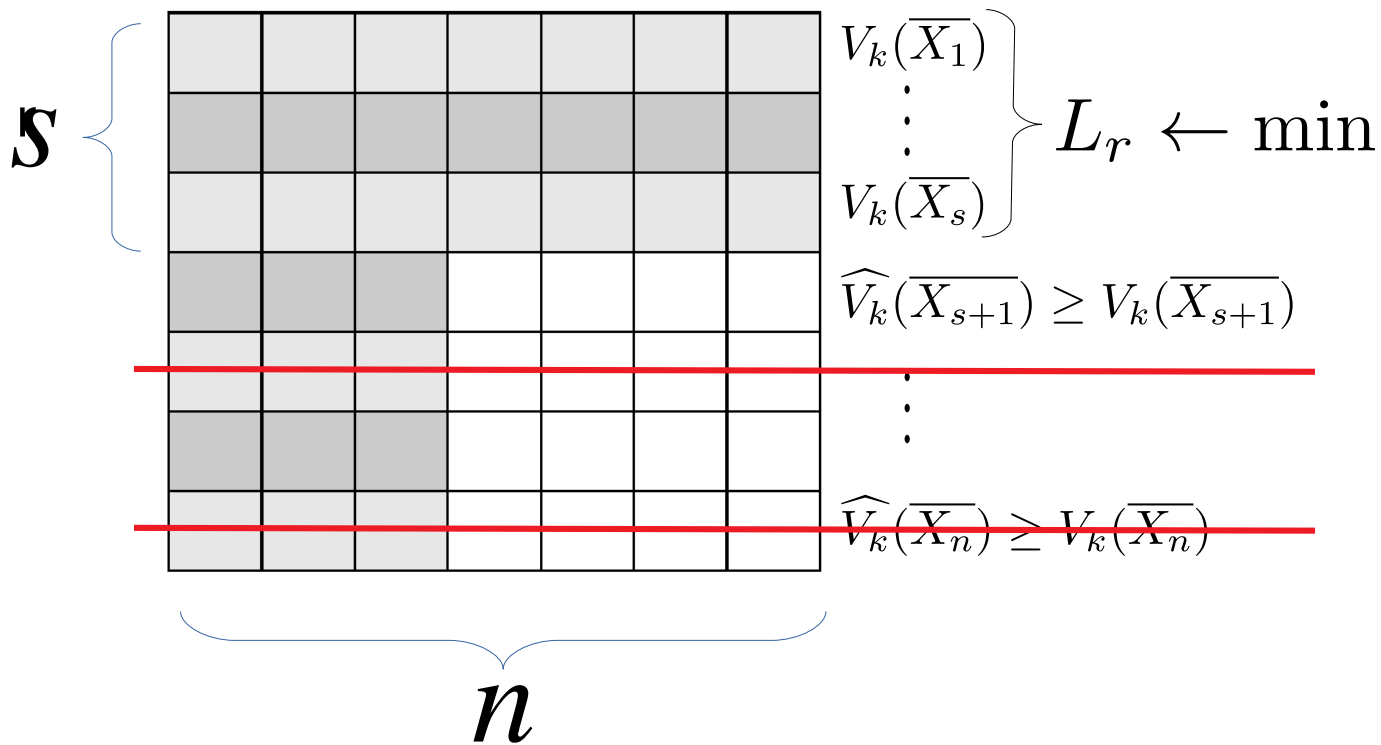
$1 \dots s$  we already know the “winners”

( $r \leq s$  nodes with the larger distance to their  $k^{\text{th}}$  nearest neighbor)

Any point having

$V_k < L_s$  cannot be among

the top  $r$  outliers



# Pruning method: sampling (cont.)

## Remove points

having  $\widehat{V}_k \leq L_r$

Update  $L_r$  keeping

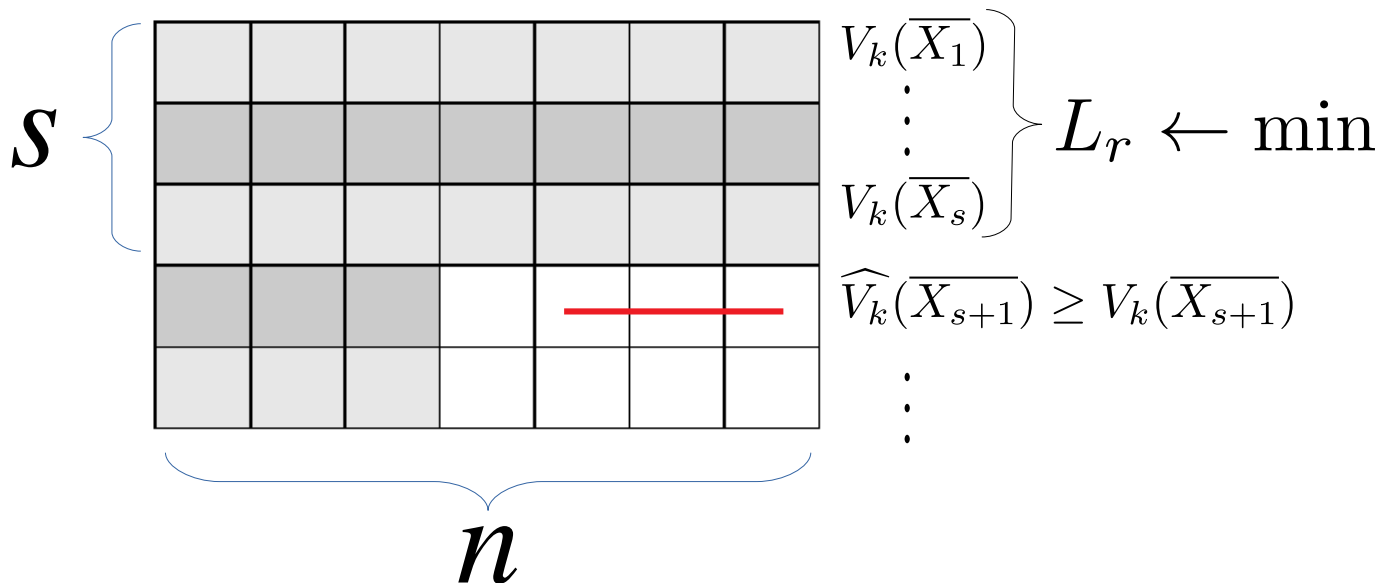
r largest values, and

stop computing for a

row if one already finds

k nearest neighbors in that row that

are all below distance  $L_r$



# Local outlier factor



# Local Outlier Factor (LOF)

- Let  $V_k(\bar{X})$  be the distance of  $\bar{X}$  to its  $k$ -nearest neighbor

- Reachability distance

$$R_k(\bar{X}, \bar{Y}) = \max\{\text{Dist}(\bar{X}, \bar{Y}), V_k(\bar{Y})\}$$

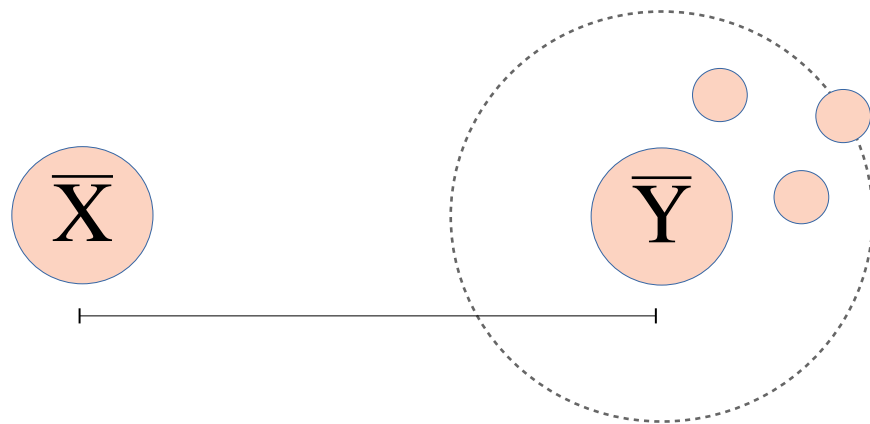
# Local Outlier Factor (LOF) (cont.)

- $V_k(\bar{X})$ : distance of  $\bar{X}$  to its k-nearest neighbor

- Reachability distance

$$R_k(\bar{X}, \bar{Y}) = \max\{\text{Dist}(\bar{X}, \bar{Y}), V_k(\bar{Y})\}$$

- Not symmetric
- Equal to simple distance for long distances
- Smoothed by  $V_k(\bar{X})$  for short distances



# Local Outlier Factor (LOF) (cont.)

- Reachability distance

$$R_k(\bar{X}, \bar{Y}) = \max\{\text{Dist}(\bar{X}, \bar{Y}), V_k(\bar{Y})\}$$

- Average reachability distance

$$AR_k(\bar{X}) = \frac{E}{\bar{Y} \in L_k(\bar{X})} [R_k(\bar{X}, \bar{Y})]$$

$L_k(\bar{X})$  is the set of points within distance  $V_k(\bar{X})$  of  $\bar{X}$   
(might be more than k due to ties)

# Local Outlier Factor (LOF) (cont.)

$$R_k(\bar{X}, \bar{Y}) = \max\{\text{Dist}(\bar{X}, \bar{Y}), V_k(\bar{Y})\}$$

$$AR_k(\bar{X}) = \underset{\bar{Y} \in L_k(\bar{X})}{E} [R_k(\bar{X}, \bar{Y})]$$

- Local outlier factor

$$\text{LOF}_k(\bar{X}) = \underset{\bar{Y} \in L_k(\bar{X})}{E} \frac{AR_k(\bar{X})}{AR_k(\bar{Y})}$$

Outlier score

$$\max_k \text{LOF}_k(\bar{X})$$

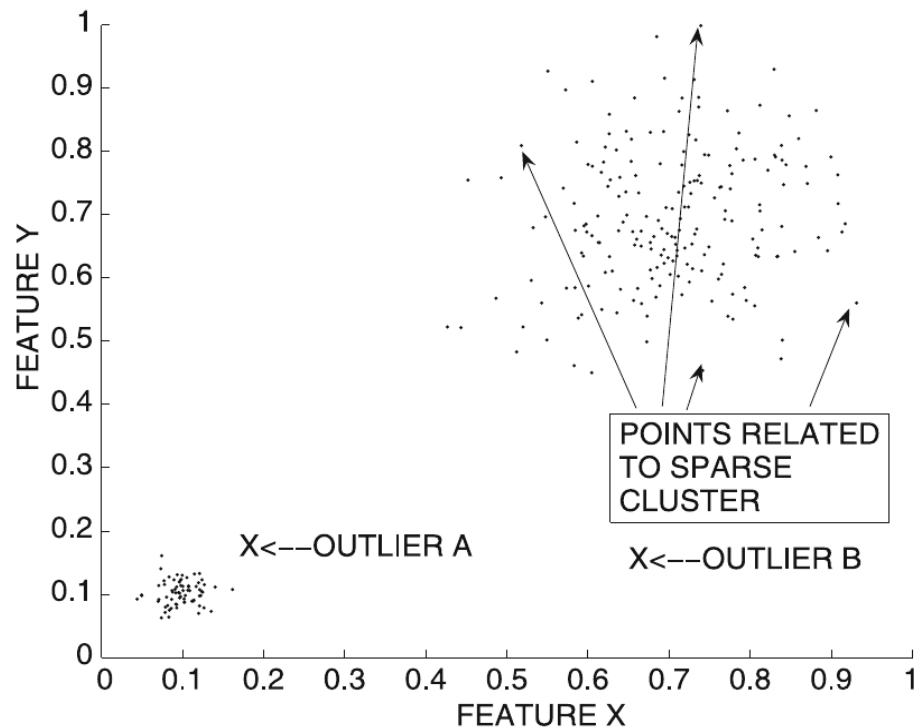
- Large for outliers, close to 1 for others

# Local Outlier Factor (LOF) (cont.)

- Local outlier factor

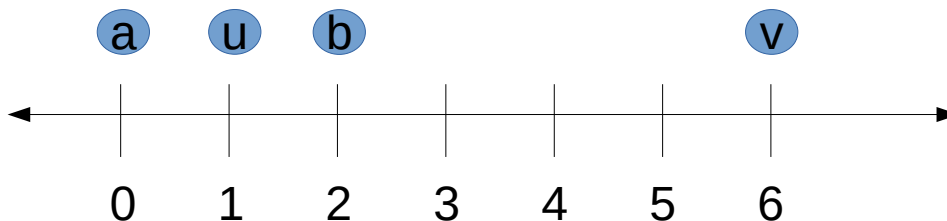
$$\text{LOF}_k(\bar{X}) = \frac{E_{\bar{Y} \in L_k(\bar{X})} AR_k(\bar{X})}{AR_k(\bar{Y})}$$

- LOF values for points inside a cluster are close to one if cluster is homogeneous
- LOF values much higher for outliers: they are computed in terms of average distances of near-by clusters



# Exercise

compare outlier score  $\text{LOF}(u)$ ,  $\text{LOF}(v)$



- Let  $k=2$
- $\text{LOF}_2(u) = E[ \{ \text{AR}_2(u) / \text{AR}_2(a), \text{AR}_2(u) / \text{AR}_2(b) \} ] = \underline{\hspace{2cm}}$
- $\text{LOF}_2(v) = E[ \{ \text{AR}_2(v) / \text{AR}_2(b), \text{AR}_2(v) / \text{AR}_2(u) \} ] = \underline{\hspace{2cm}}$

$$\text{LOF}_k(\bar{X}) = E_{\bar{Y} \in L_k(\bar{X})} \frac{\text{AR}_k(\bar{X})}{\text{AR}_k(\bar{Y})}$$

- $\text{AR}_2(u) = E[ \{ R_k(u,a), R_k(u,b) \} ] = \underline{\hspace{2cm}}$

- $\text{AR}_2(v) = E[ \{ R_k(v,b), R_k(v,u) \} ] = \underline{\hspace{2cm}}$

$$\text{AR}_k(\bar{X}) = E_{\bar{Y} \in L_k(\bar{X})} [R_k(\bar{X}, \bar{Y})]$$

- $\text{AR}_2(a) = E[ \{ R_k(a,u), R_k(a,b) \} ] = \underline{\hspace{2cm}}$

- $\text{AR}_2(b) = E[ \{ R_k(b,u), R_k(b,a) \} ] = \underline{\hspace{2cm}}$

- $R_k(a,u) = \underline{\hspace{1cm}}; R_k(a,b) = \underline{\hspace{1cm}}; R_k(b,u) = \underline{\hspace{1cm}}; R_k(b,a) = \underline{\hspace{1cm}}$

$$R_k(\bar{X}, \bar{Y}) = \max\{\text{Dist}(\bar{X}, \bar{Y}), V_k(\bar{Y})\}$$

- $R_k(u,a) = \underline{\hspace{1cm}}; R_k(u,b) = \underline{\hspace{1cm}}; R_k(v,b) = \underline{\hspace{1cm}}; R_k(v,u) = \underline{\hspace{1cm}}$

- $V_2 = \text{distance to } 2^{\text{nd}} \text{ nearest neighbor: } V_2(u) = \underline{\hspace{1cm}}; V_2(v) = \underline{\hspace{1cm}}; V_2(a) = \underline{\hspace{1cm}}; V_2(b) = \underline{\hspace{1cm}}$