

Computational Physics - Assignment I

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1>

$$\begin{bmatrix} 1 & 0.67 & 0.33 \\ 0.45 & 1 & 0.55 \\ 0.67 & 0.33 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2 \\ 2 \\ 2 \end{bmatrix}$$

$$C_2 \rightarrow C_2 - 0.45 \times C_1$$

$$0.45 \times 10^\circ - 0.45 \times 10^\circ = 0$$

$$0.1 \times 10^1 - (0.45)(0.67 \times 10^\circ)$$

$$= 0.1 \times 10^1 - 0.30 \times 10^\circ$$

$$= 0.1 \times 10^1 - 0.03 \times 10^1 = 0.7 \times 10^\circ$$

$$0.55 \times 10^\circ - (0.45)(0.33 \times 10^\circ)$$

$$= (0.55 - 0.15) \times 10^\circ = 0.40 \times 10^\circ$$

$$0.2 \times 10^1 - 0.09 \times 10^1 = 0.11 \times 10^1$$

$$\begin{bmatrix} 1 & 0.67 & 0.33 \\ 0 & 0.70 & 0.40 \\ 0.67 & 0.33 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2 \\ 1.1 \\ 2 \end{bmatrix}$$

$$C_3 \rightarrow C_3 - (0.67)C_1$$

$$0.1 \times 10^1 - 0.22 \times 10^\circ$$

$$= 0.8 \times 10^\circ = 0.80$$

$$\begin{bmatrix} 1 & 0.67 & 0.33 \\ 0 & 0.70 & 0.40 \\ 0 & -0.12 & 0.80 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2 \\ 1.1 \\ 0.7 \end{bmatrix}$$

$$C_2 \rightarrow C_2 / 0.70$$

$$\begin{bmatrix} 1 & 0.67 & 0.33 \\ 0 & 1 & 0.57 \\ 0 & -0.12 & 0.80 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2 \\ 1.6 \\ 0.7 \end{bmatrix}$$

$$C_3 \rightarrow C_3 + (0.12)C_2$$

$$\begin{bmatrix} 1 & 0.67 & 0.33 \\ 0 & 1 & 0.57 \\ 0 & 0 & 0.87 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2 \\ 1.6 \\ 0.89 \end{bmatrix}$$

$$C_3 \rightarrow C_3 / 0.87$$

$$\begin{bmatrix} 1 & 0.67 & 0.33 \\ 0 & 1 & 0.57 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2 \\ 1.6 \\ 1.0 \end{bmatrix}$$

$$\Rightarrow x_3 = 1.0 , \quad x_2 = 1.6 - 0.57 = (0.16 - 0.06) \times 10^1 \\ = 1.0$$

$$x_1 = 2 - 0.67 - 0.33 = (0.2 - 0.07 - 0.03) \times 10^1 = 1.0$$

$$x_1 = 1.0 , \quad x_2 = 1.0 , \quad x_3 = 1.0$$

2) np. lin alg. solve gives $x_1 = x_2 = x_3 = 1$. We seem to have gotten lucky!

$$A \begin{bmatrix} a_{11} \\ a_{21} \\ a_{31} \\ \vdots \\ a_{n1} \end{bmatrix}_{n \times n} x = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ \vdots \\ b_n \end{bmatrix}_{n \times 1}$$

Divide first row by $a_{11} \Rightarrow n+1$ divisions
 including b

Multiply first row by a_{i1} and subtract from i th row $\Rightarrow n+1$ multiplications, $n+1$ subtractions

Do this for all the $n-1$ rows

\Rightarrow No. of steps : $n+1 + (n+1+n+1)(n-1)$

Now repeat the above procedure for inner $(n-1)$ dimensional matrix,
 and so on

$n+1$ div., $(n+1$ mul., $n+1$ subtractions $) \times (n-1)$

n div., $(n$ mul., n sub) $\times (n-2)$

.

.

2 div

No. of steps to convert to upper-triangular form -

$$\sum_{j=1}^n \{ j+1 + 2(j+1)(j-1) \} = \sum_{j=1}^n (2j^2 + j - 1)$$

$$= \frac{n(n+1)}{2} - n + \frac{2}{6} n(n+1)(2n+1)$$

$\sum_{j=1}^n 2(j-1)$

↑
last row, j=n ⇒ first row
↓ 1 mul. + 1 sub.

No. of back substitution steps = $n(n+1) - 2n$

$$\Rightarrow \text{Total steps} = \frac{n^2+n}{2} + \frac{2n^3+3n^2+n}{3} - n + n^2 - n$$

$$= \frac{4n^3 + 15n^2 + 7n}{6} \sim \mathcal{O}(n^3)$$

5)

We can always express the complex matrix as $A + iB$,
where A, B are real matrices

Let $C + iD$ be the inverse, where C, D are real matrices

$$\Rightarrow (C + iD)(A + iB) = CA - DB + i(CB + DA) = I$$

$$\Rightarrow CB + DA = 0 \quad \Rightarrow \quad D = -CBA^{-1} \quad \left. \begin{array}{l} \text{equating imaginary} \\ \text{parts} \end{array} \right\}$$

Now equating the real part,

$$CA + CBA^{-1}B = I \Rightarrow$$

$$C^{-1} = A + BA^{-1}B$$

$$D = -CBA^{-1}$$

We can find C^{-1} and then invert it. Therefore we have reduced the problem of computing the inverse of a complex matrix to that of inverting real matrices

6)

$$\begin{bmatrix} 3 & -1 & 1 \\ 3 & 6 & 2 \\ 3 & 3 & 7 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 4 \end{bmatrix}$$

$$x_i = - \sum_{\substack{j=1 \\ j \neq i}}^n \frac{a_{ij}x_j}{a_{ii}} + \frac{b_i}{a_{ii}}$$

If we start with x as the zero vector,

$$x = \begin{bmatrix} 1/3 \\ 0 \\ 4/7 \end{bmatrix} \text{ after 1 iteration}$$

2nd iteration -

$$x_1 = - \left[\frac{(-1)(0)}{3} + \frac{(1)(4/7)}{3} \right] + \frac{1}{3} = \frac{1}{7}$$

$$x_2 = - \left[\frac{(3)(4/3)}{6} + \frac{(2)(4/7)}{6} \right] = - \frac{15}{6(7)} = - \frac{5}{14}$$

$$x_3 = - \left[\frac{(3)(4/3)}{7} + 0 \right] + \frac{4}{7} = \frac{3}{7}$$

$$\Rightarrow \begin{bmatrix} 3 & -1 & 1 \\ 3 & 6 & 2 \\ 3 & 3 & 7 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 4 \end{bmatrix}$$

$$x_i^{(k)} = \frac{1}{a_{ii}} \left[- \sum_{j=1}^{i-1} a_{ij} x_j^{(k)} - \sum_{j=i+1}^n a_{ij} x_j^{(k-1)} + b_i \right]$$

Again starting from zero vector,

$$x_1^{(1)} = \frac{1}{3} \quad x_2^{(1)} = \frac{1}{6} \left[-3 \left(\frac{1}{3} \right) + 0 \right] = -\frac{1}{6}$$

$$x_3^{(1)} = \frac{1}{7} \left[-3 \left(\frac{1}{3} \right) - 3 \left(-\frac{1}{6} \right) + 4 \right] = \frac{1}{2}$$

$$\frac{1}{2} - \frac{1}{6} = \frac{3-1}{6} = \frac{1}{3}$$

$$-\frac{1}{3} - 1 = -\frac{1}{3} - \frac{1}{3} = -\frac{2}{3}$$

$$-\frac{1}{3} + \frac{2}{3} = \frac{1}{3}$$

$$x_1^{(2)} = \frac{1}{3} \left[-(-1) \left(-\frac{1}{6} \right) - (1) \left(\frac{1}{2} \right) + 1 \right] = \frac{1}{9}$$

$$x_2^{(2)} = \frac{1}{6} \left[-3 \left(\frac{1}{9} \right) - 2 \left(\frac{1}{2} \right) \right] = -\frac{2}{9}$$

$$x_3^{(2)} = \frac{1}{7} \left[-3 \left(\frac{1}{9} \right) - 3 \left(-\frac{2}{9} \right) + 4 \right] = \frac{13}{21}$$

8)

$$\begin{array}{|c c c c c c|} \hline & 4 & -1 & 0 & -1 & 0 & 0 \\ \hline & -1 & 4 & -1 & 0 & -1 & 0 \\ \hline & 0 & -1 & 4 & 0 & 0 & -1 \\ \hline & -1 & 0 & 0 & 4 & -1 & 0 \\ \hline & 0 & -1 & 0 & -1 & 4 & -1 \\ \hline & 0 & 0 & -1 & 0 & -1 & 4 \\ \hline \end{array} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \end{bmatrix} = \begin{bmatrix} 0 \\ 5 \\ 0 \\ 6 \\ -2 \\ 6 \end{bmatrix}$$

$$\text{Jacobi-} \quad x_1^{(1)} = 0, \quad x_2^{(1)} = \frac{5}{4}, \quad x_3^{(1)} = 0, \quad x_4^{(1)} = \frac{3}{2}, \quad x_5^{(1)} = -\frac{1}{2}, \quad x_6^{(1)} = \frac{3}{2}$$

$$x_1^{(2)} = \frac{1}{4} \left[(+1) \left(\frac{5}{4} \right) + (1) \left(\frac{3}{2} \right) \right] = \frac{11}{16} \quad x_5^{(2)} = \frac{1}{4} \left[(1) \left(\frac{5}{4} \right) + (1) \left(\frac{3}{2} \right) + (1) \left(\frac{3}{2} \right) - 2 \right] \\ = \frac{9}{16}$$

$$x_2^{(2)} = \frac{1}{4} \left[(1) \left(-\frac{1}{2} \right) + 5 \right] = \frac{9}{8}$$

$$x_6^{(2)} = \frac{1}{4} \left[-\frac{1}{2} + 6 \right] = \frac{11}{8}$$

$$x_3^{(2)} = \frac{1}{4} \left[(1) \left(\frac{5}{4} \right) + (1) \left(\frac{3}{2} \right) \right] = \frac{11}{16}$$

$$x_4^{(2)} = \frac{1}{4} \left[(1) \left(-\frac{1}{2} \right) + 6 \right] = \frac{11}{8}$$

Gauss-Seidel

$$x_1^{(1)} = 0, \quad x_2^{(1)} = \frac{5}{4}, \quad x_3^{(1)} = \frac{5}{16}, \quad x_4^{(1)} = \frac{3}{2}$$

$$x_5^{(1)} = \frac{1}{4} \left[(1) \left(\frac{5}{4} \right) + (1) \frac{3}{2} - 2 \right] = \frac{3}{16}, \quad x_6^{(1)} = \frac{1}{4} \left[\frac{5}{16} + \frac{3}{16} + 6 \right] = \frac{13}{8}$$

$$x_1^{(2)} = \frac{1}{4} \left[\frac{5}{4} + \frac{3}{2} \right] = \frac{11}{16}, \quad x_2^{(2)} = \frac{1}{4} \left[\frac{11}{16} + \frac{5}{16} + \frac{3}{16} + 5 \right] = \frac{99}{64}$$

$$x_3^{(2)} = \frac{1}{4} \left[\frac{99}{64} + \frac{13}{8} \right] = \frac{203}{256}, \quad x_4^{(2)} = \frac{1}{4} \left[\frac{11}{16} + \frac{3}{16} + 6 \right] = \frac{55}{32}$$

$$x_5^{(2)} = \frac{1}{4} \left[\frac{99}{64} + \frac{55}{32} + \frac{13}{8} - 2 \right] = \frac{185}{256}, \quad x_6^{(2)} = \frac{1}{4} \left[\frac{203 + 185}{256} + 6 \right] = \frac{1995}{1024}$$

10)

Eigenvalues using np.linalg.qz (12 iterations): 8.99999993
4.00000007

Using eigh - 9., 4.

12) The time taken by the codes to run varies with each execution.

Manual - 0.002996s

Numpy - 0.001999s

q) No. of iterations needed -

Jacobi - 36

Gauss-Seidel - 17

Relaxation - 6

Conjugate Gradient - 5

13)

i) sgelsv	gsl_linalg_LU_solve	numpy.linalg.solve
ii)		
iii)		
iv)		
v)		
vi) sgetrf	gsl_linalg_LU_decomp	scipy.linalg.lu
vii) sgeqrf	gsl_linalg_QR_decomp	numpy.linalg.qr
viii) sgesvd	gsl_linalg_SV_decomp	numpy.linalg.svd
ix) sy/heev	gsl_eigen_symm	numpy.linalg.eigh
x) sy/heev	gsl_eigen_herm	numpy.linalg.eigh
xi) sgbeev	gsl_eigen_nonsym	numpy.linalg.eig