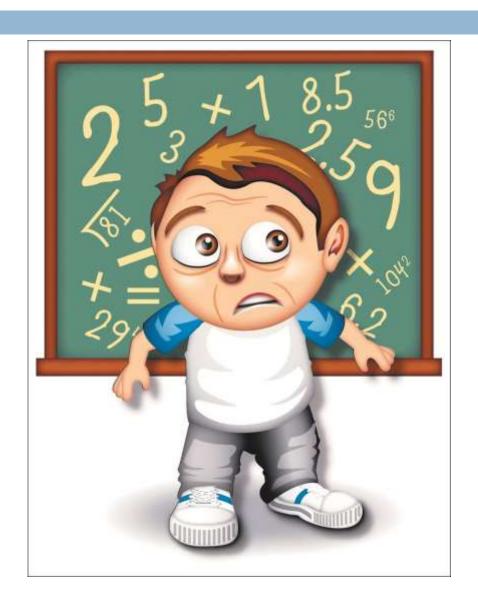
REGULARIZATION

David Kauchak CS 451 – Fall 2013

Admin

Assignment 5

Math so far...



Model-based machine learning

pick a model

$$0 = b + \mathop{\mathring{\mathbf{a}}}_{j=1}^{m} w_j f_j$$

pick a criteria to optimize (aka objective function)

$$\mathring{\mathbf{a}}_{i=1}^{n} 1 [y_i(w \times x_i + b) \pm 0]$$

develop a learning algorithm

$$\underset{i=1}{\operatorname{argmin}} \sum_{w,b}^{n} 1 [y_i(w \times x_i + b) \pm 0]$$

Find w and b that minimize the 0/1 loss

Model-based machine learning

pick a model

$$0 = b + \mathop{\mathring{\mathbf{a}}}_{j=1}^{m} w_j f_j$$

pick a criteria to optimize (aka objective function)

$$\overset{n}{\underset{i=1}{\circ}} \exp(-y_i(w \times x_i + b))$$

use a convex surrogate loss function

develop a learning algorithm

$$\underset{i=1}{\operatorname{argmin}} \overset{n}{\underset{i=1}{\circ}} \exp(-y_i(w \times x_i + b))$$

Find w and b that minimize the surrogate loss

Finding the minimum





You're blindfolded, but you can see out of the bottom of the blindfold to the ground right by your feet. I drop you off somewhere and tell you that you're in a convex shaped valley and escape is at the bottom/minimum. How do you get out?

Gradient descent

- pick a starting point (w)
- repeat until loss doesn't decrease in all dimensions:
 - pick a dimension
 - move a small amount in that dimension towards decreasing loss (using the derivative)

$$w_j = w_j - h \frac{d}{dw_j} loss(w)$$

Some maths

$$\frac{d}{dw_{j}}loss = \frac{d}{dw_{j}} \mathop{\overset{n}{\overset{n}{\rightleftharpoons}}} \exp(-y_{i}(w \times x_{i} + b))$$

$$= \mathop{\overset{n}{\overset{n}{\rightleftharpoons}}} \exp(-y_{i}(w \times x_{i} + b)) \frac{d}{dw_{j}} - y_{i}(w \times x_{i} + b)$$

$$= \mathop{\overset{n}{\overset{n}{\rightleftharpoons}}} -y_{i}x_{ij} \exp(-y_{i}(w \times x_{i} + b))$$

Gradient descent

- pick a starting point (w)
- repeat until loss doesn't decrease in all dimensions:
 - pick a dimension
 - move a small amount in that dimension towards decreasing loss (using the derivative)

$$w_j = w_j + h \mathop{\triangle}_{i=1}^n y_i x_{ij} \exp(-y_i (w \times x_i + b))$$

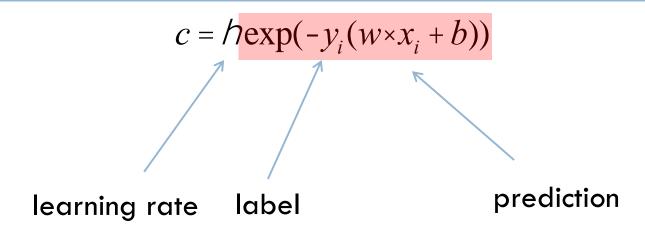
What is this doing?

Perceptron learning algorithm!

```
repeat until convergence (or for some # of iterations): for each training example (f_1, f_2, ..., f_m, label): prediction = b + \mathring{\triangle}_{j=1}^m w_j f_j if prediction * label \le 0: // they don't agree for each w_i: w_i = w_i + f_i^* label b = b + label
```

$$w_{j} = w_{j} + hy_{i}x_{ij} \exp(-y_{i}(w \times x_{i} + b))$$
or
$$w_{j} = w_{j} + x_{ij}y_{i}c \quad \text{where} \quad c = h\exp(-y_{i}(w \times x_{i} + b))$$

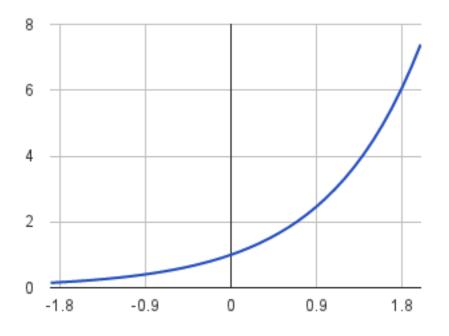
The constant



When is this large/small?

The constant

$$c = h \exp(-y_i(w \times x_i + b))$$
label prediction



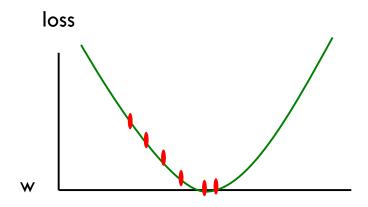
If they're the same sign, as the predicted gets larger there update gets smaller

If they're different, the more different they are, the bigger the update

One concern

$$\underset{i=1}{\operatorname{argmin}} \overset{n}{\underset{i=1}{\circ}} \exp(-y_i(w \times x_i + b))$$

What is this calculated on? Is this what we want to optimize?



Perceptron learning algorithm!

```
repeat until convergence (or for some # of iterations): for each training example (f_1, f_2, ..., f_m, label): prediction = b + \mathring{\triangle}_{j=1}^m w_j f_j - if prediction * label \leq 0: // they don't agree for each w_i: Note: for gradient descent, we always update w_i = w_i + f_i^* label b = b + label
```

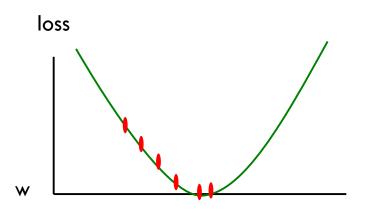
$$w_{j} = w_{j} + hy_{i}x_{ij} \exp(-y_{i}(w \times x_{i} + b))$$
or
$$w_{j} = w_{j} + x_{ij}y_{i}c \quad \text{where} \quad c = h\exp(-y_{i}(w \times x_{i} + b))$$

One concern

$$\underset{i=1}{\operatorname{argmin}} \overset{n}{\underset{i=1}{\circ}} \exp(-y_i(w \times x_i + b))$$

We're calculating this on the training set

We still need to be careful about overfitting!



The min w,b on the training set is generally NOT the min for the test set

How did we deal with this for the perceptron algorithm?

Overfitting revisited: regularization

A regularizer is an additional criteria to the loss function to make sure that we don't overfit

It's called a regularizer since it tries to keep the parameters more normal/regular

It is a bias on the model forces the learning to prefer certain types of weights over others

$$\underset{i=1}{\operatorname{argmin}} \overset{n}{\underset{i=1}{\circ}} loss(yy') + / regularizer(w,b)$$

Regularizers

$$0 = b + \mathop{\mathring{a}}\nolimits_{j=1}^n w_j f_j$$

Should we allow all possible weights?

Any preferences?

What makes for a "simpler" model for a linear model?

Regularizers

$$0 = b + \mathop{\mathring{a}}\nolimits_{j=1}^n w_j f_j$$

Generally, we don't want huge weights

If weights are large, a small change in a feature can result in a large change in the prediction

Also gives too much weight to any one feature

Might also prefer weights of 0 for features that aren't useful

How do we encourage small weights? or penalize large weights?

Regularizers

$$0 = b + \mathop{\mathring{a}}\nolimits_{j=1}^n w_j f_j$$

How do we encourage small weights? or penalize large weights?

$$\underset{i=1}{\operatorname{argmin}} \overset{n}{\underset{i=1}{\circ}} loss(yy') + / regularizer(w,b)$$

Common regularizers

sum of the weights

sum of the squared weights

$$r(w,b) = \mathop{\mathsf{a}}_{w_j} |w_j|$$

$$r(w,b) = \sqrt{\mathop{\mathsf{a}}_{w_i} |w_j|^2}$$

What's the difference between these?

Common regularizers

sum of the weights

 $r(w,b) = \mathop{\mathsf{a}}_{w_j} |w_j|$

sum of the squared weights

$$r(w,b) = \sqrt{\frac{\mathbf{a} \left| w_j \right|^2}{w_j}}$$

Squared weights penalizes large values more Sum of weights will penalize small values more

p-norm

sum of the weights (1-norm)

$$r(w,b) = \mathop{\mathsf{a}}_{w_i} |w_j|$$

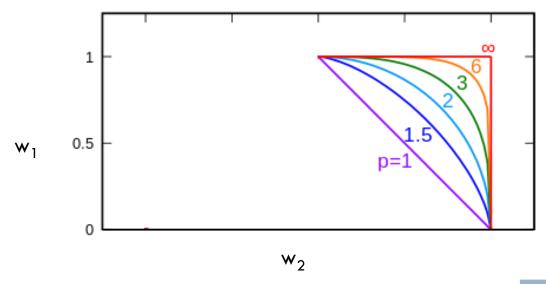
sum of the squared weights (2-norm)

$$r(w,b) = \sqrt{\frac{|w_j|^2}{|w_j|^2}}$$

p-norm
$$r(w,b) = \sqrt{\frac{|a|}{|w_j|^p}} = ||w||^p$$

Smaller values of p (p < 2) encourage sparser vectors Larger values of p discourage large weights more

p-norms visualized

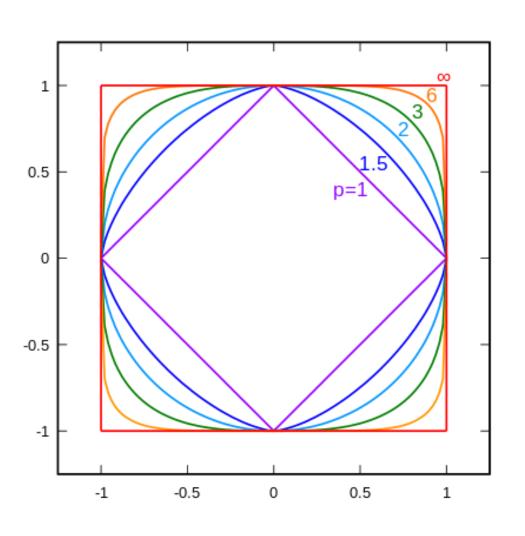


lines indicate penalty = 1

For example, if $w_1 = 0.5$

р	w ₂
1	0.5
1.5	0.75
2	0.87
3	0.95
∞	1

p-norms visualized



all p-norms penalize larger weights

p < 2 tends to create sparse(i.e. lots of 0 weights)

p > 2 tends to like similar weights

Model-based machine learning

pick a model



$$0 = b + \mathop{\mathring{a}}\nolimits_{j=1}^n w_j f_j$$

pick a criteria to optimize (aka objective function)

$$\overset{n}{\underset{i=1}{\circ}} loss(yy') + / regularizer(w)$$

develop a learning algorithm

$$\underset{i=1}{\operatorname{argmin}} \overset{n}{\underset{i=1}{\circ}} loss(yy') + / regularizer(w)$$
 Find w and b that minimize

Minimizing with a regularizer

We know how to solve convex minimization problems using gradient descent:

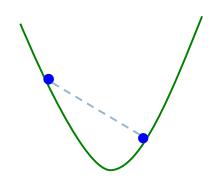
$$\underset{i=1}{\operatorname{argmin}}_{w,b} \overset{n}{\underset{i=1}{\circ}} loss(yy')$$

If we can ensure that the loss + regularizer is convex then we could still use gradient descent:

$$\underset{i=1}{\operatorname{argmin}_{w,b}} \overset{n}{\underset{i=1}{\circ}} loss(yy') + / regularizer(w)$$

$$\text{make convex}$$

Convexity revisited



One definition: The line segment between any two points on the function is above the function

Mathematically, f is convex if for all x_1, x_2 :

$$f(tx_1 + (1-t)x_2) \in tf(x_1) + (1-t)f(x_2)$$
 " $0 < t < 1$

the value of the function at some point between x_1 and x_2

the value at some point on the **line segment** between x_1 and x_2

Adding convex functions

Claim: If f and g are convex functions then so is the function z=f+g

Prove:

$$z(tx_1 + (1-t)x_2) \to tz(x_1) + (1-t)z(x_2)$$
 " $0 < t < 1$

Mathematically, f is convex if for all x_1 , x_2 :

$$f(tx_1 + (1-t)x_2) \in tf(x_1) + (1-t)f(x_2)$$
 " $0 < t < 1$

Adding convex functions

By definition of the sum of two functions:

$$z(tx_1 + (1-t)x_2) = f(tx_1 + (1-t)x_2) + g(tx_1 + (1-t)x_2)$$

$$tz(x_1) + (1-t)z(x_2) = tf(x_1) + tg(x_1) + (1-t)f(x_2) + (1-t)g(x_2)$$

$$= tf(x_1) + (1-t)f(x_2) + tg(x_1) + (1-t)g(x_2)$$

Then, given that:

$$f(tx_1 + (1-t)x_2) \stackrel{\cdot}{\vdash} tf(x_1) + (1-t)f(x_2)$$
$$g(tx_1 + (1-t)x_2) \stackrel{\cdot}{\vdash} tg(x_1) + (1-t)g(x_2)$$

We know:

$$f(tx_1 + (1-t)x_2) + g(tx_1 + (1-t)x_2) \stackrel{\cdot}{\in} tf(x_1) + (1-t)f(x_2) + tg(x_1) + (1-t)g(x_2)$$
So: $z(tx_1 + (1-t)x_2) \stackrel{\cdot}{\in} tz(x_1) + (1-t)z(x_2)$

Minimizing with a regularizer

We know how to solve convex minimization problems using gradient descent:

$$\underset{i=1}{\operatorname{argmin}}_{w,b} \overset{n}{\underset{i=1}{\circ}} loss(yy')$$

If we can ensure that the loss + regularizer is convex then we could still use gradient descent:

$$\underset{i=1}{\operatorname{argmin}_{w,b}} \bigotimes_{i=1}^{n} loss(yy') + / regularizer(w)$$

convex as long as both loss and regularizer are convex

p-norms are convex

$$r(w,b) = \sqrt{\frac{\mathop{a}\limits_{w_j} \left| w_j \right|^p}{\left| w_j \right|^p}} = \left\| w \right\|^p$$

p-norms are convex for $p \ge 1$

Model-based machine learning

pick a model

$$0 = b + \mathop{\mathring{\mathbf{a}}}_{j=1}^{n} w_j f_j$$

2. pick a criteria to optimize (aka objective function)

$$\overset{n}{\underset{i=1}{\circ}} \exp(-y_i(w \times x_i + b)) + \frac{1}{2} ||w||^2$$

develop a learning algorithm

$$\underset{i=1}{\operatorname{argmin}} \overset{n}{\underset{i=1}{\circ}} \exp(-y_i(w \times x_i + b)) + \frac{1}{2} \|w\|^2$$
 Find w and b that minimize

Our optimization criterion

$$\underset{i=1}{\operatorname{argmin}}_{w,b} \overset{n}{\underset{i=1}{\circ}} \exp(-y_i(w \times x_i + b)) + \frac{1}{2} \|w\|^2$$

Loss function: penalizes examples where the prediction is different than the label

Regularizer: penalizes large weights

Key: this function is convex allowing us to use gradient descent

Gradient descent

- pick a starting point (w)
- repeat until loss doesn't decrease in all dimensions:
 - pick a dimension
 - move a small amount in that dimension towards decreasing loss (using the derivative)

$$w_i = w_i - h \frac{d}{dw_i} (loss(w) + regularizer(w, b))$$

$$\underset{i=1}{\operatorname{argmin}} \overset{n}{\underset{i=1}{\circ}} \exp(-y_i(w \times x_i + b)) + \frac{1}{2} ||w||^2$$

Some more maths

$$\frac{d}{dw_i}objective = \frac{d}{dw_i} \mathop{\circ}\limits_{i=1}^n \exp(-y_i(w \times x_i + b)) + \frac{1}{2} ||w||^2$$

(some math happens)

$$= - \mathop{\triangle}\limits_{i=1}^{n} y_i x_{ij} \exp(-y_i (w \times x_i + b)) + /w_j$$

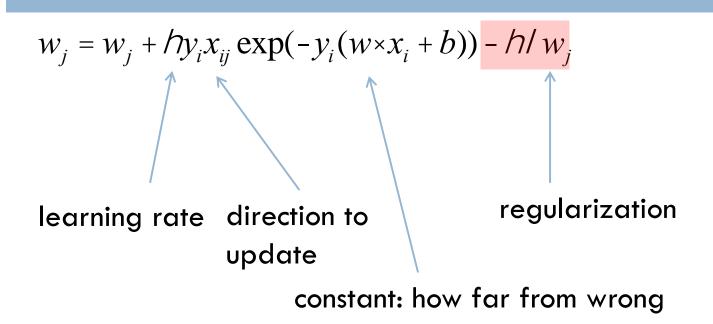
Gradient descent

- pick a starting point (w)
- repeat until loss doesn't decrease in all dimensions:
 - pick a dimension
 - move a small amount in that dimension towards decreasing loss (using the derivative)

$$w_i = w_i - h \frac{d}{dw_i} (loss(w) + regularizer(w, b))$$

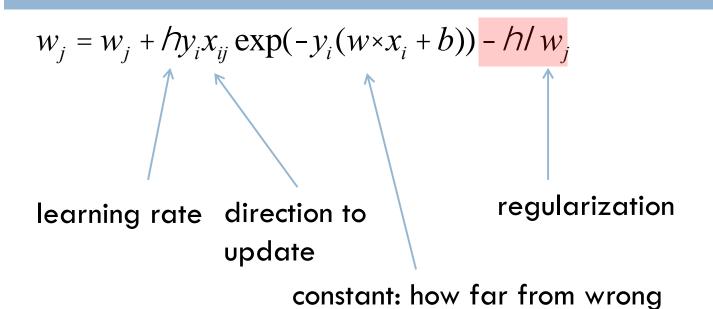
$$w_{j} = w_{j} + h \mathop{a}_{i=1}^{n} y_{i} x_{ij} \exp(-y_{i}(w \times x_{i} + b)) - h/w_{j}$$

The update



What effect does the regularizer have?

The update



If
$$w_i$$
 is positive, reduces w_i moves w_i towards 0 If w_i is negative, increases w_i

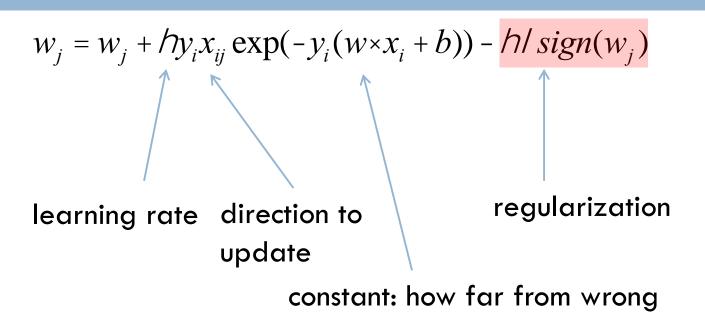
L1 regularization

$$\underset{i=1}{\operatorname{argmin}}_{w,b} \overset{n}{\underset{i=1}{\circ}} \exp(-y_i(w \times x_i + b)) + ||w||$$

$$\frac{d}{dw_{j}}objective = \frac{d}{dw_{j}} \mathop{a}_{i=1}^{n} \exp(-y_{i}(w \times x_{i} + b)) + / \|w\|$$

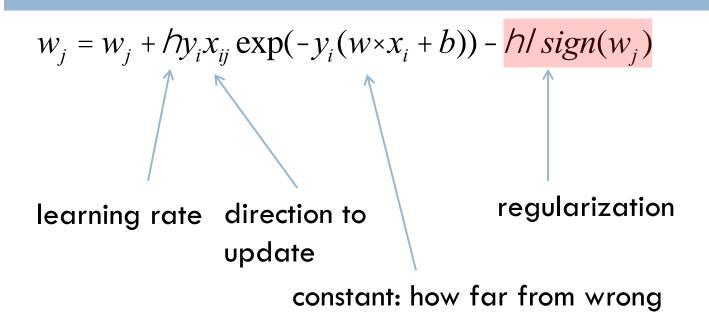
$$= - \mathop{\aa}_{i=1}^{n} y_i x_{ij} \exp(-y_i(w \times x_i + b)) + / sign(w_j)$$

L1 regularization



What effect does the regularizer have?

L1 regularization



If w_i is positive, reduces by a constant If w_i is negative, increases by a constant

moves w_i towards 0 regardless of magnitude

Regularization with p-norms

L1:

$$w_i = w_i + h(loss_correction - lsign(w_i))$$

L2:

$$w_j = w_j + h(loss_correction - / w_j)$$

Lp:

$$w_j = w_j + h(loss_correction - / cw_j^{p-1})$$

How do higher order norms affect the weights?

Regularizers summarized

L1 is popular because it tends to result in sparse solutions (i.e. lots of zero weights)

However, it is not differentiable, so it only works for gradient descent solvers

L2 is also popular because for some loss functions, it can be solved directly (no gradient descent required, though often iterative solvers still)

Lp is less popular since they don't tend to shrink the weights enough

The other loss functions

Without regularization, the generic update is:

$$w_j = w_j + \hbar y_i x_{ij} c$$

where

$$c = \exp(-y_i(w \times x_i + b))$$

exponential

$$c = 1[yy' < 1]$$

hinge loss

$$w_j = w_j + h(y_i - (w \times x_i + b)x_{ij})$$
 squared error

Many tools support these different combinations

Look at scikit learning package:

http://scikit-learn.org/stable/modules/sgd.html

Common names

(Ordinary) Least squares: squared loss

Ridge regression: squared loss with L2 regularization

Lasso regression: squared loss with L1 regularization

Elastic regression: squared loss with L1 AND L2 regularization

Logistic regression: logistic loss

Real results