

Graph Traversal Algorithms I

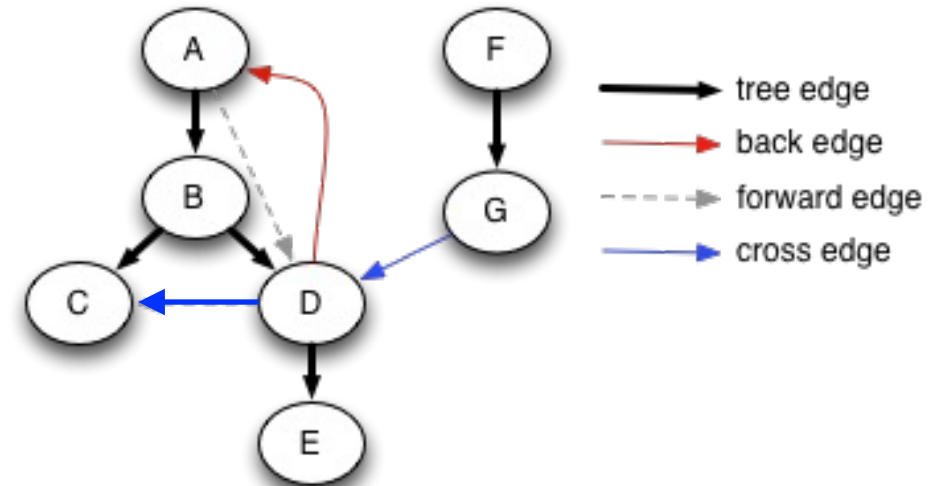
Instructor: Meng-Fen Chiang

COMPSCI: WEEK 9.3



OUTLINE

- Graph Traversal Algorithm
- Facts about Traversal Trees
- Complexity Analysis
- Illustrative Example

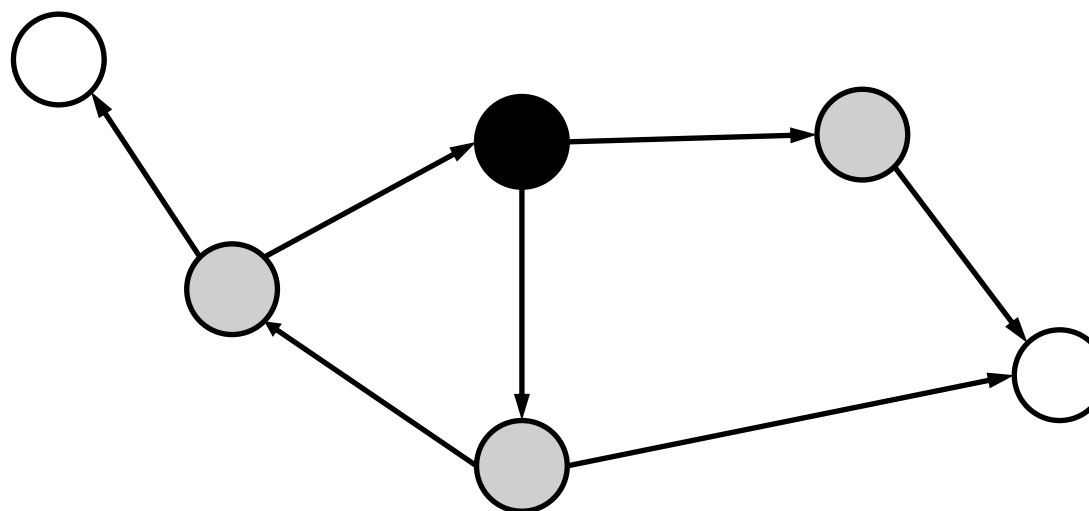


Motivation: Graph Traversals

- Want to visit each node of a digraph in a systematic and efficient way (e.g., to search a graph).
- We can walk only on arcs following their direction

General Graph Traversal: Colour Scheme

- All graph traversal algorithms follow the same structure which is called the **The general graph traversal algorithm**. This algorithm uses three types of nodes:
 - **White nodes**: have not yet been visited.
 - **Grey (frontier) nodes**: have been visited but may have adjacent nodes that are white.
 - **Black nodes**: have been visited and all their (out-)neighbors have been visited as well.



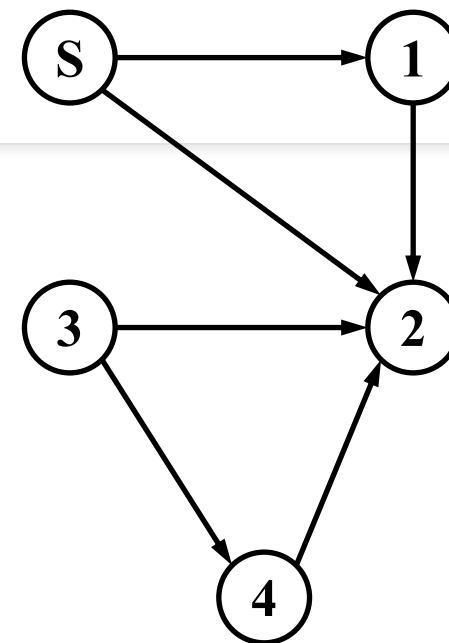
Graph Traversal Algorithm

- All nodes are **white** to begin with.
- A starting white node is chosen and turned grey.
- A **grey** node is chosen and its out-neighbours explored.
- If any out-neighbour is white, it is visited and turned **grey**. If no out-neighbours are white, the grey node is turned **black**.
- The process of choosing grey nodes and exploring neighbours is continued until all nodes reachable from the initial node are black.
- If any white nodes remain in the digraph, a new starting node is chosen and the process continues until all nodes are **black**.

General Graph Traversal: Visit(s)

1. s is coloured grey and $pred[s]=null$.
2. choose a grey node u .
3. if u has a white (out)-neighbour v then colour v grey and $pred[v]=u$ else colour u black.
4. if we have grey nodes go to step (2).

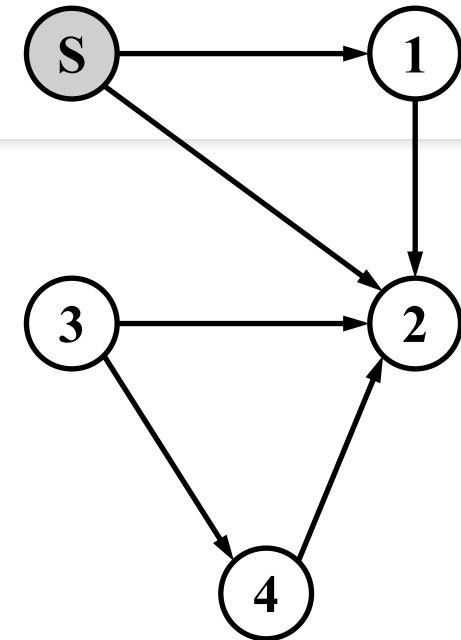
* $pred$ - predecessor



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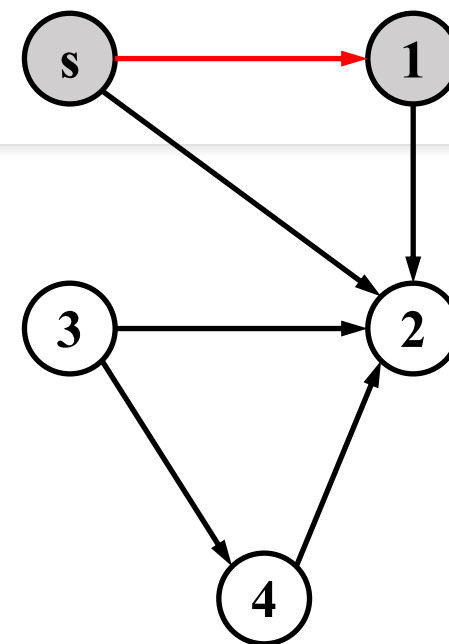


$Pred[s] = null$

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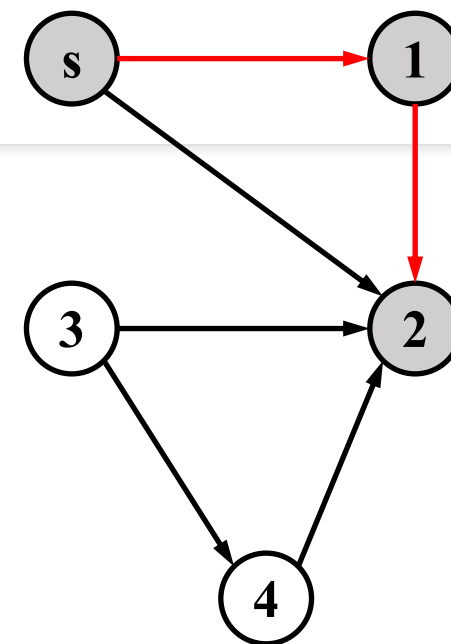


$Pred[1] = s$

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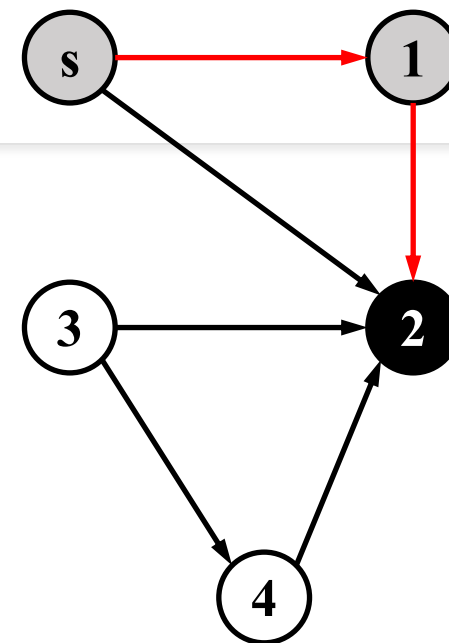


$Pred[2] = 1$

General Graph Traversal: Visit(s)

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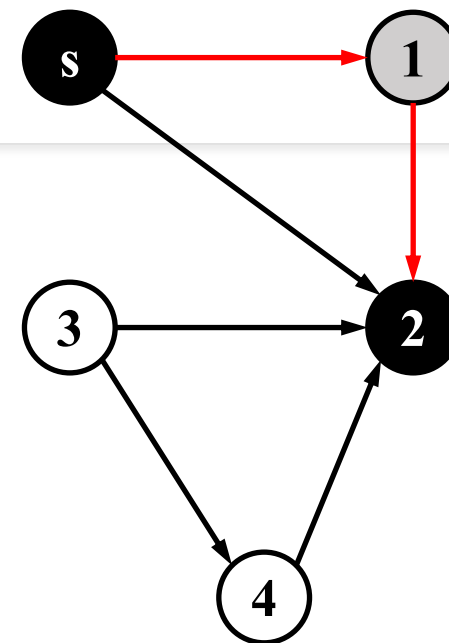
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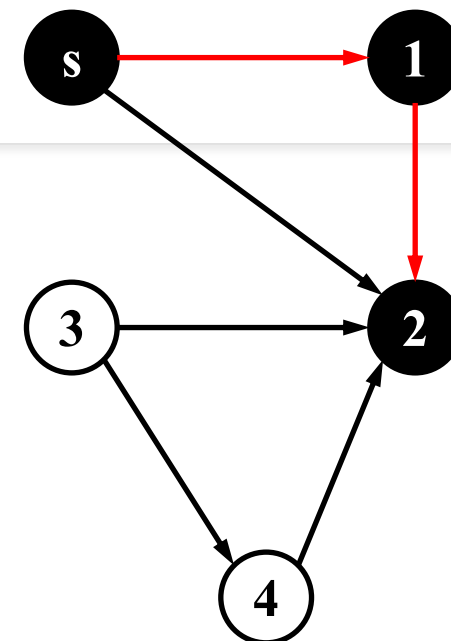


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* $pred$ – predecessor

- $Visit(s)$ visits all nodes reachable from s .
- After the run of $visit(s)$ all reachable nodes are coloured black.



General Graph Traversal: Visit(s)

Algorithm 1 Visit.

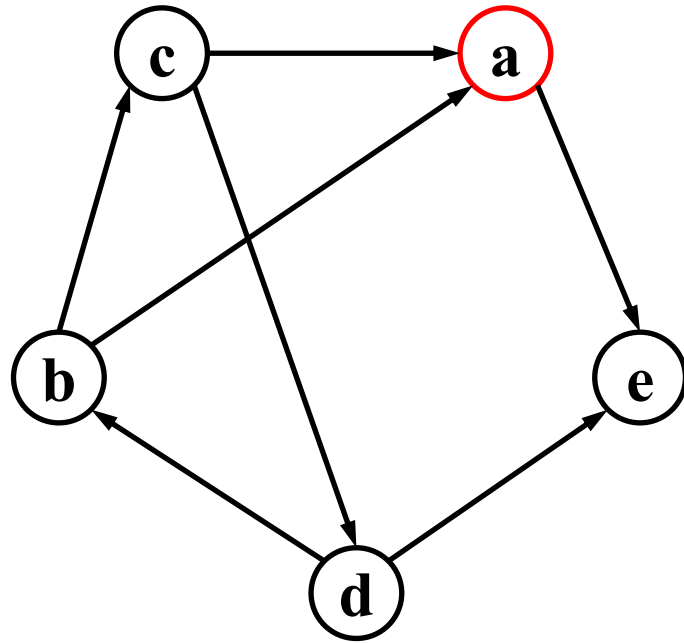
```
1: function VISIT(node  $s$  of digraph  $G$ )
2:    $color[s] \leftarrow \text{Grey}$ 
3:    $pred[s] \leftarrow \text{Null}$ 
4:   while there is a Grey node do
5:     choose a Grey node  $u$ 
6:     if  $u$  has a WHITE (out-)neighbour then
7:       choose such a white (out-)neighbour  $v$ 
8:        $color[v] \leftarrow \text{Grey}$ 
9:        $pred[v] \leftarrow u$ 
10:    else
11:       $color[u] \leftarrow \text{Black}$ 
```

General Graph Traversal Algorithm: Main

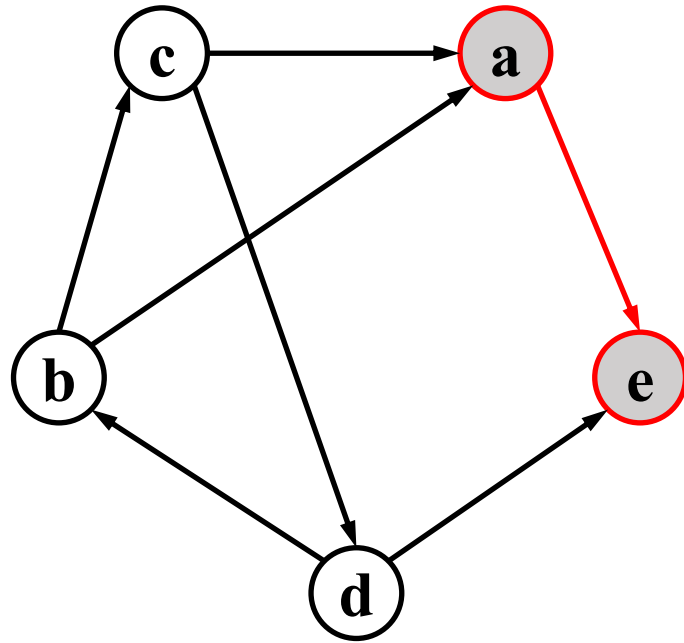
Algorithm 2 Traverse.

```
1: function TRAVERSE(digraph  $G$ )
2:   array  $color[0..n-1]$ 
3:   array  $pred[0..n-1]$ 
4:   for  $u \in V(G)$  do
5:      $color[u] \leftarrow \text{WHITE}$ 
6:   end for
7:   for  $s \in V(G)$  do
8:     if  $color[s] = \text{WHITE}$  then
9:       VISIT( $s$ )
10:  return  $pred$ 
```

Illustrating the general traversal algorithm

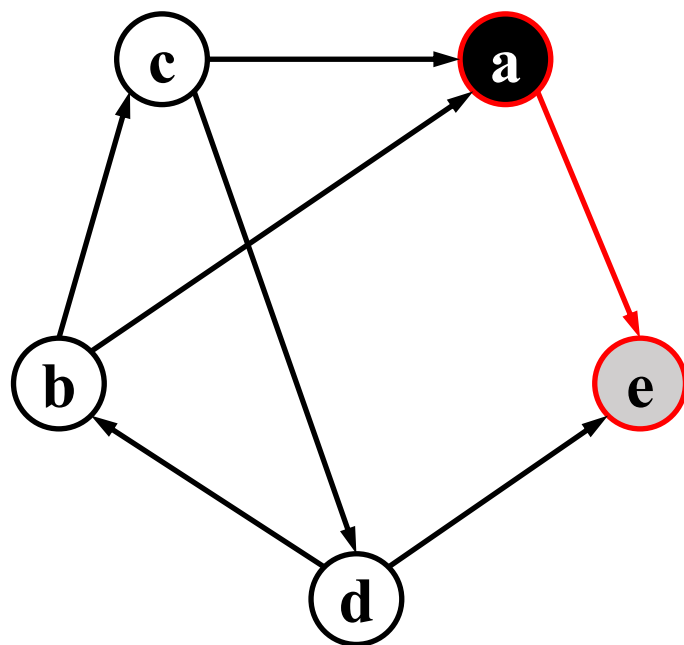


Illustrating the general traversal algorithm



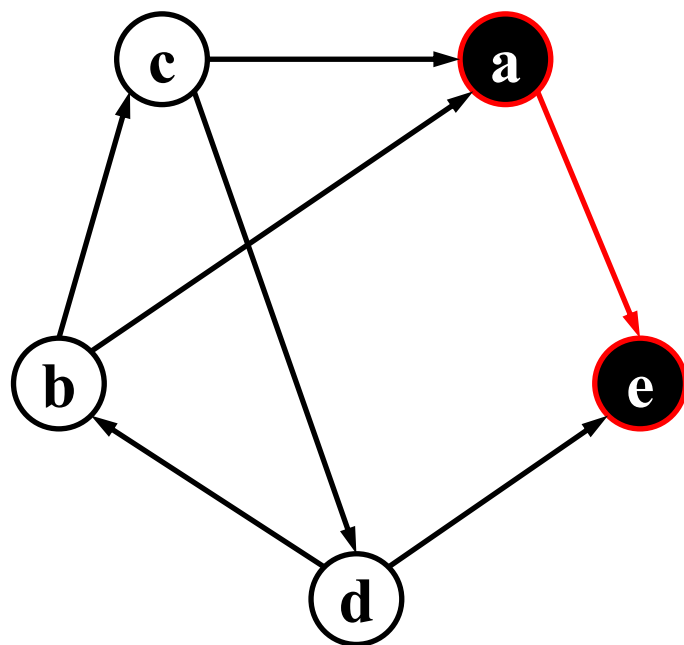
- VISIT(a)
e is the white neighbour of a

Illustrating the general traversal algorithm



- VISIT(a)
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choose grey a; no white neighbour; colour black

Illustrating the general traversal algorithm



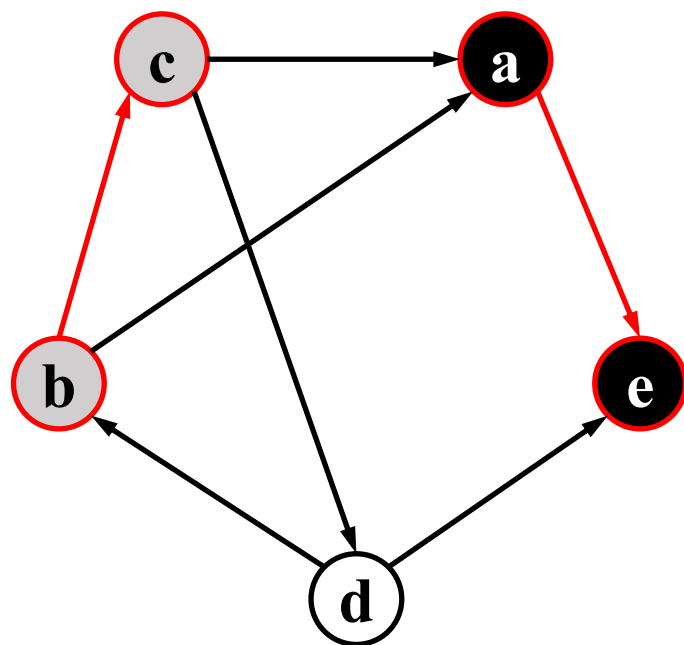
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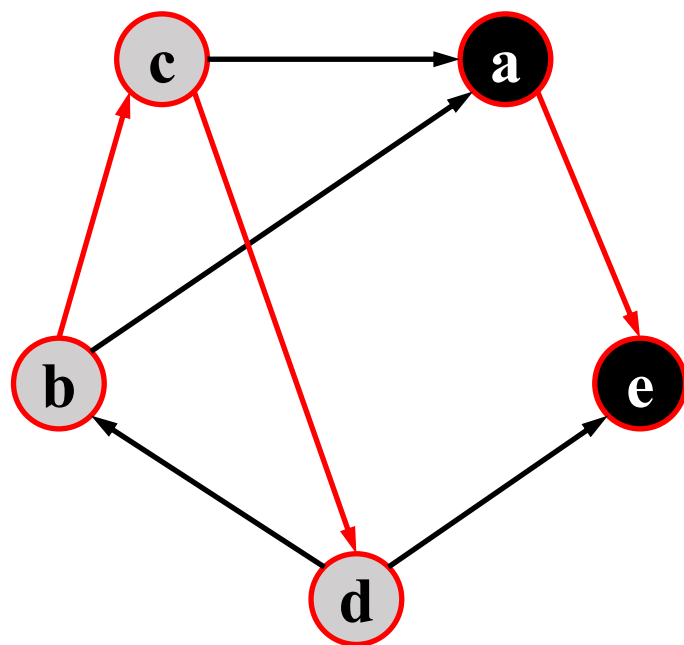
choose grey e; no white neighbour; colour black

Illustrating the general traversal algorithm



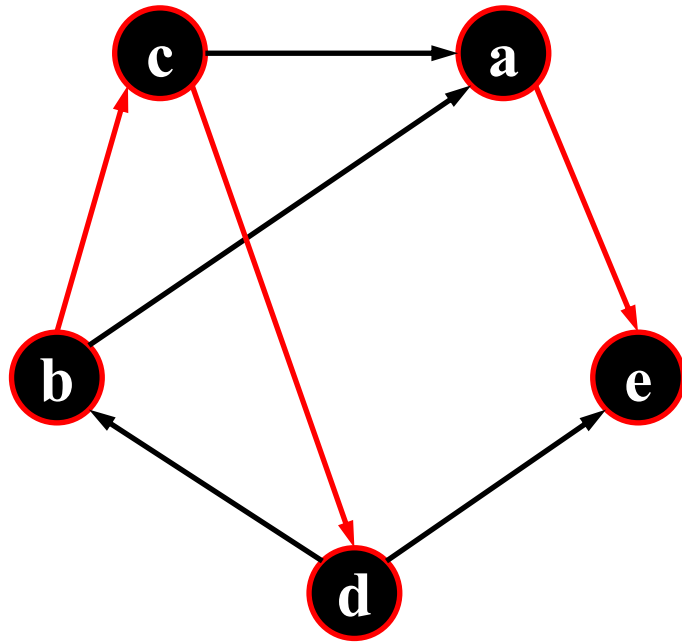
- VISIT(a)
 - e is the white neighbour of a
 - choose grey a; no white neighbour; colour black
 - choose grey e; no white neighbour; colour black
- VISIT(b)
 - c is the white neighbour of b

Illustrating the general traversal algorithm



- VISIT(a)
e is the white neighbour of a
choose grey a; no white neighbour; colour black
choose grey e; no white neighbour; colour black
- VISIT(b)
c is the white neighbour of b
choose grey c; d is white neighbour

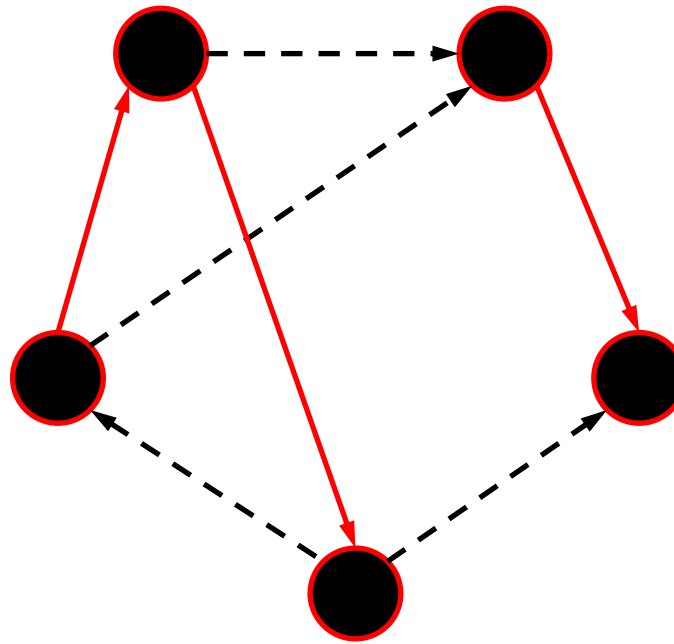
Illustrating the general traversal algorithm



- VISIT(a)
e is the white neighbour of a
choose grey a; no white neighbour; colour black
choose grey e; no white neighbour; colour black
- VISIT(b)
c is the white neighbour of b
choose grey c; d is white neighbour
no more white nodes; all nodes turn black

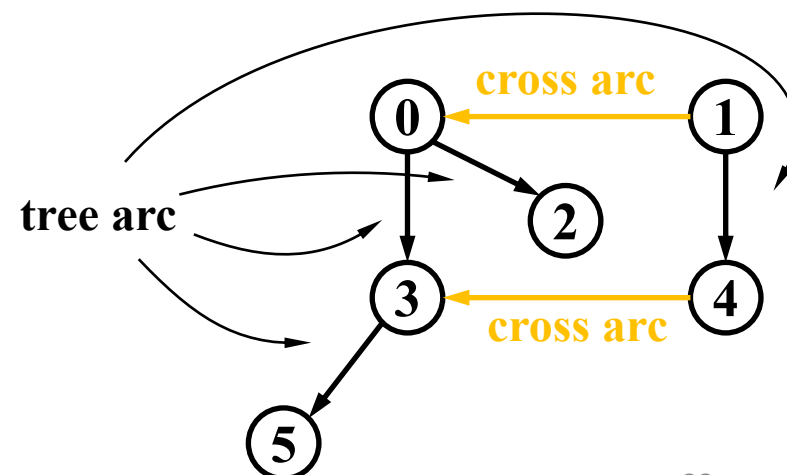
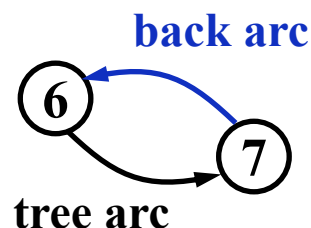
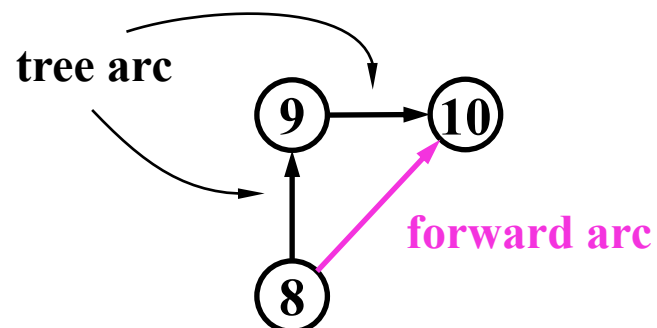
A search forest

A search forest is a collection of node-disjoint trees that span the digraph and contain, for each node u with $\text{pred}[u] \neq \text{NULL}$, the arc $(\text{pred}[u], u)$.



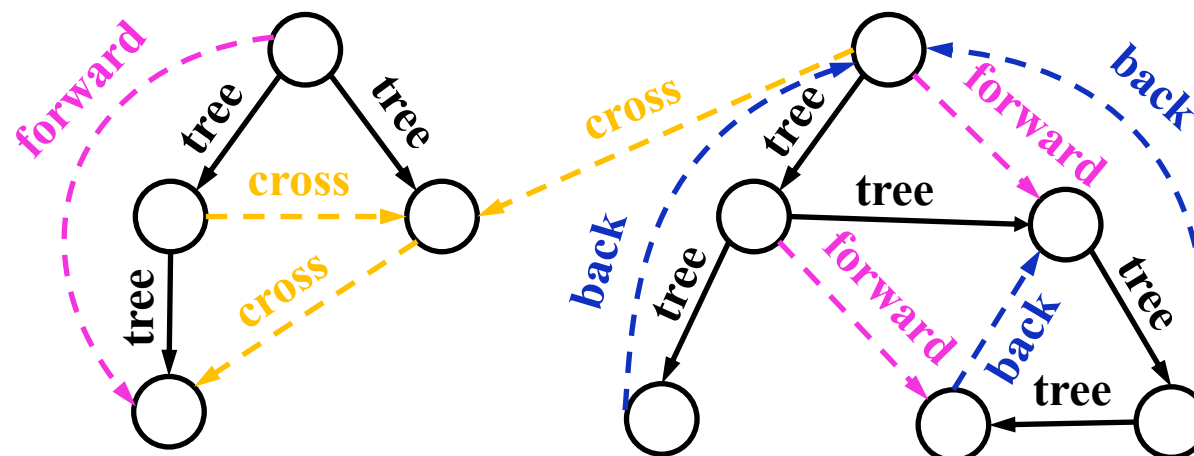
Traversal Arc Classifications

- Suppose we have performed a traversal of a digraph G , resulting in a search forest F . Let $(u, v) \in E(G)$ be an arc.
- The arc is called a **tree arc** if it belongs to one of the trees of F . If the arc is not a tree arc, there are three possibilities:
 - a **forward arc** if u is an ancestor of v in F ,
 - a **back arc** if u is a descendant of v in F , and
 - a **cross arc** if neither u nor v is an ancestor of the other in F .



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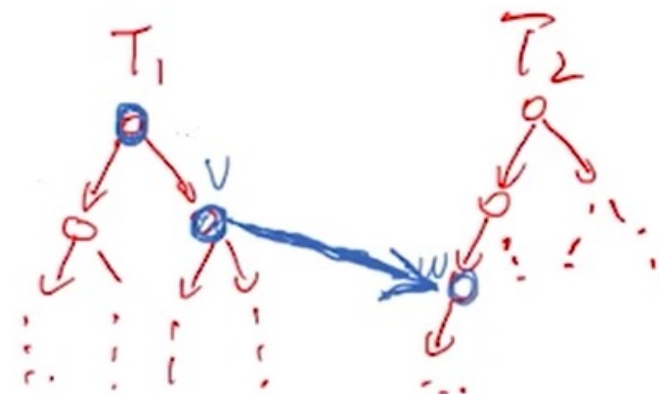
Facts about Traversal Trees

- **Theorem:** Suppose we run algorithm `traverse` on G , resulting in a search forest F . Let $v, w \in V(G)$.

Let T_1 and T_2 be different trees in F and suppose that T_1 was explored before T_2 . Then there are no arcs from T_1 to T_2 .

- **Proof:**

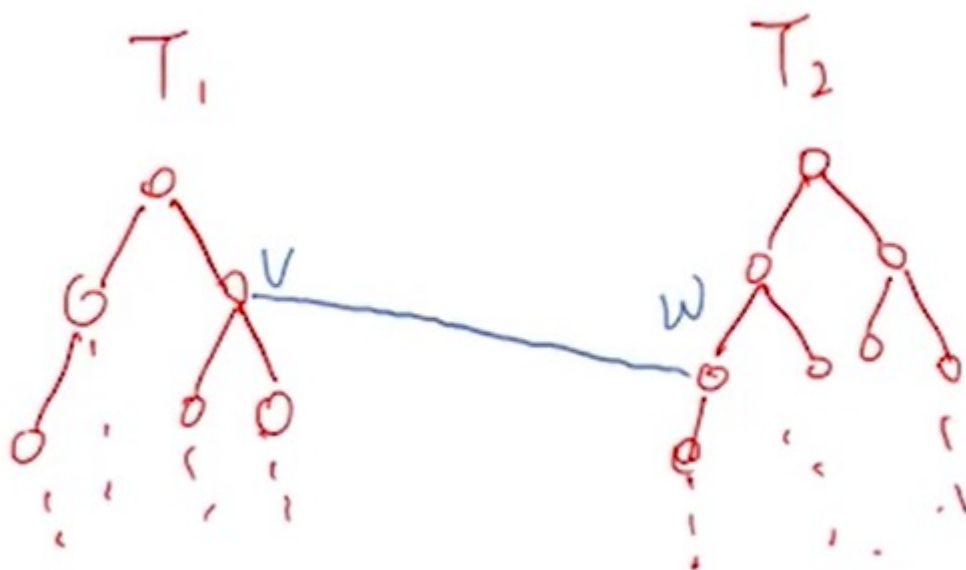
1. Assume $(v, w) \in E(G)$, $v \in T_1, w \in T_2$
2. $\text{VISIT}(s) \left\{ \begin{array}{l} \bullet \text{ A single run of VISIT generates a tree} \\ \bullet \text{ All nodes reachable from } s \text{ will be visited} \end{array} \right.$
3. With 1 and 2, we have $w \in T_1 \Rightarrow \text{contradiction}$



Facts about Traversal Trees (Contd.)

- **Theorem:** Suppose we run algorithm `traverse` on G , resulting in a search forest F . Let $v, w \in V(G)$.

Then there can be no edges joining different trees of F .



Facts about Traversal Trees (Contd.)

- **Theorem:** Suppose we run algorithm `traverse` on G , resulting in a search forest F . Let $v, w \in V(G)$.

Suppose that (1) v is visited before w and (2) w is reachable from v in G . Then v and w belong to the same tree of F .

- **Proof.**

- Let $v \in T$ and s be the root of T .
- Because w is reachable from v , v is reachable from s , then w is reachable from s
- Then, w should be in the same tree as v .



Facts about Traversal Trees (Contd.)

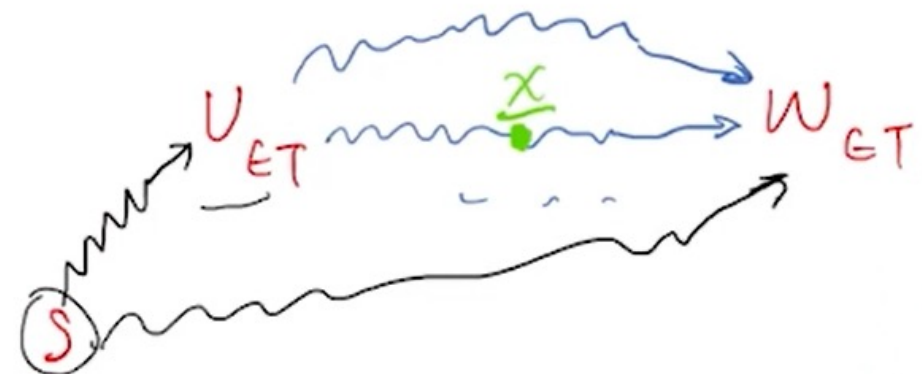
- **Theorem:** Suppose we run algorithm traverse on G , resulting in a search forest F . Let $v, w \in V(G)$.

Suppose that v and w belong to the same tree T in F . Then the nodes of any path from v to w in G must belong to T .

- **Proof.**

For any node x in any path from v to w

1. $v, w \in T$
2. v is reachable from s the root of T , then x is reachable from s
3. By 2, $x \in T$



Complexity Analysis: General Graph Traversal

Algorithm 2 Traverse.

```
1: function TRAVERSE(digraph  $G$ )
2:   array  $color[0..n - 1]$ 
3:   array  $pred[0..n - 1]$ 
4:   for  $u \in V(G)$  do
5:      $color[u] \leftarrow \text{WHITE}$ 
6:   end for
7:   for  $s \in V(G)$  do
8:     if  $color[s] = \text{WHITE}$  then
9:       VISIT( $s$ )
10:  return  $pred$ 
```

Complexity Analysis: Visit(s)

Algorithm 1 Visit.

```
1: function VISIT(node  $s$  of digraph  $G$ )
2:    $color[s] \leftarrow \text{Grey}$ 
3:    $pred[s] \leftarrow \text{Null}$ 
4:   while there is a Grey node do
5:     choose a Grey node  $u$  //  $\Theta(1)$ 
6:     if  $u$  has a WHITE (out-)neighbour then //  $\Theta(n)$  or  $\Theta(|L_u|)$ 
7:       choose such a white (out-)neighbour  $v$ 
8:        $color[v] \leftarrow \text{Grey}$ 
9:        $pred[v] \leftarrow u$ 
10:    else
11:       $color[u] \leftarrow \text{Black}$ 
```

Runtime Analysis of Traverse

- The initialization of the array *colour* takes time $\Theta(n)$ so *traverse* is in $\Theta(n + t)$, where t is the total time taken by all the calls to *visit*.
- We execute the while-loop of *visit* in total $\Theta(n)$ times since every node must eventually move from white through grey to black. In each loop:
 - The time taken in choosing grey nodes is $\Theta(1)$ each time.
 - The time taken to find a white neighbour involves examining each neighbour of u and checking whether it is white, then applying a selection rule.
 - If **adjacency matrix** is used, we need to scan the whole row, which takes $\Theta(n)$
 - If **adjacency lists** are used, we only need $\Theta(|L_i|)$ for finding white nodes in the adjacency list of node i .
- So the running time of *traverse* is
 - $\Theta(n + (n + \sum_i |L_i|)) = \Theta(n + e)$ if adjacency lists are used
 - $\Theta(n + n^2) = \Theta(n^2)$ if the adjacency matrix format is used

Runtime Analysis of Traverse (Contd.)

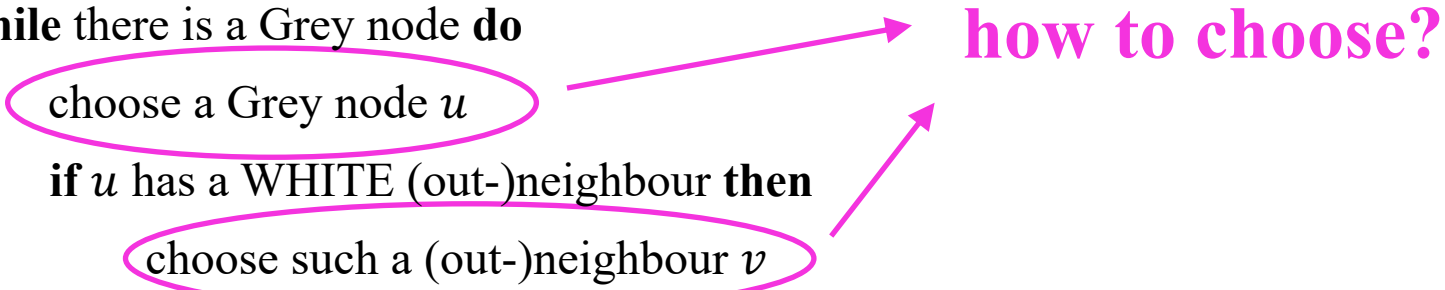
- Given **simple selection rules** and assuming a **sparse** input digraph, the adjacency list format seems preferable.
- If more **complex selection rules** are used, for example, rules that choose a single grey node $\Theta(n)$ time by scanning the whole list of grey nodes, then the running time is asymptotically $\Theta(n^2)$ regardless of the data structure.

Graph Traversal

Algorithm 1 Visit.

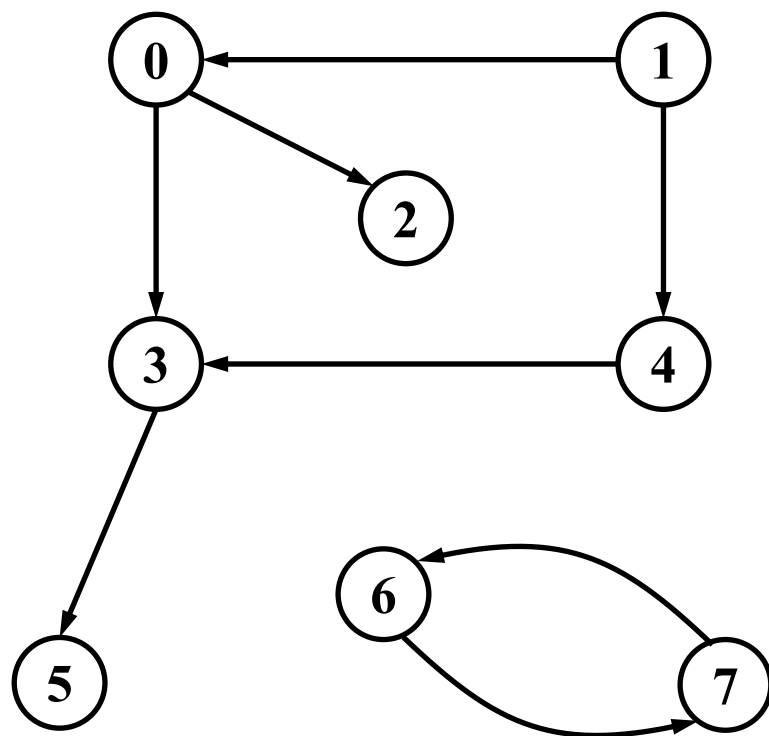
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```

how to choose?



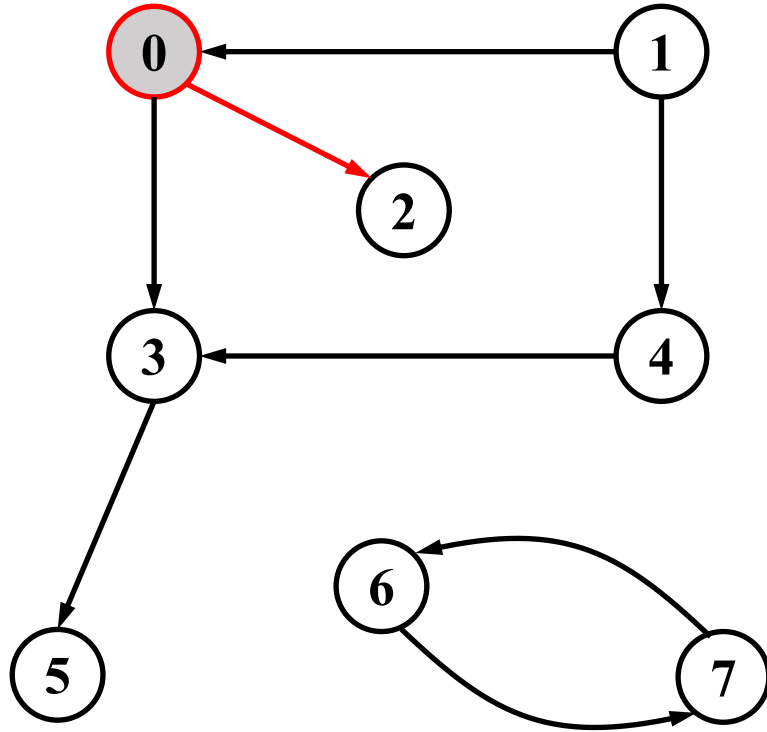
General graph traversal: example

- Emmmm.....



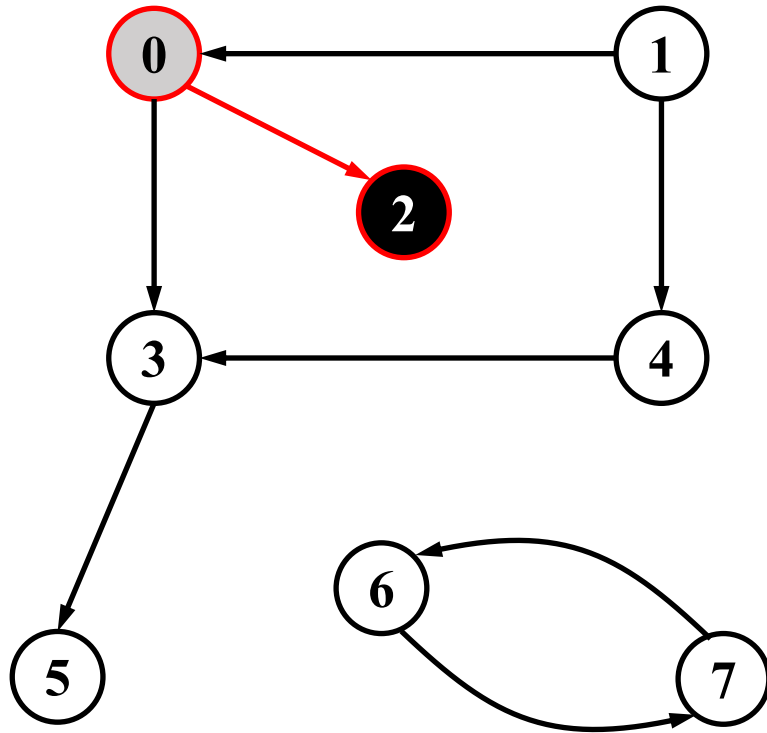
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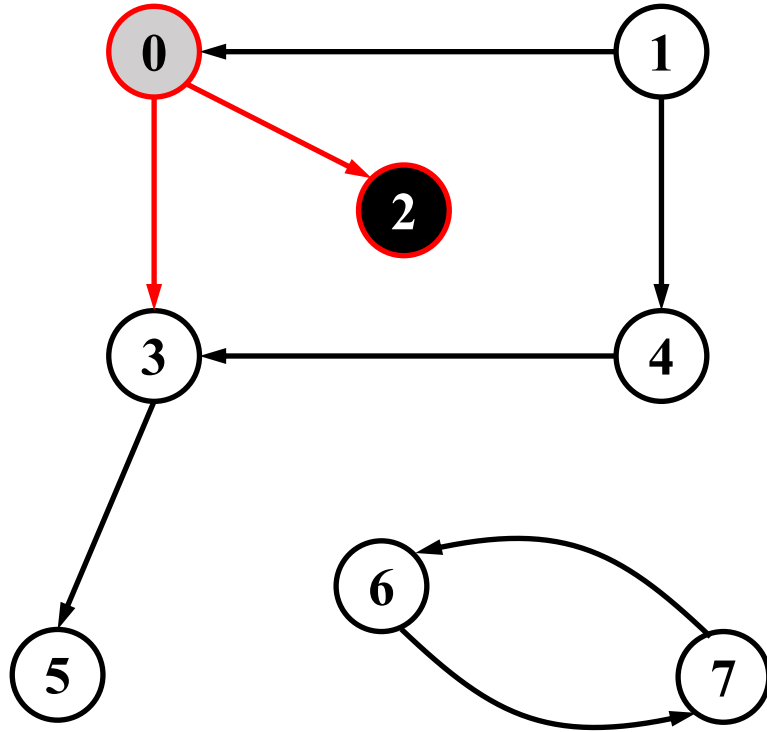
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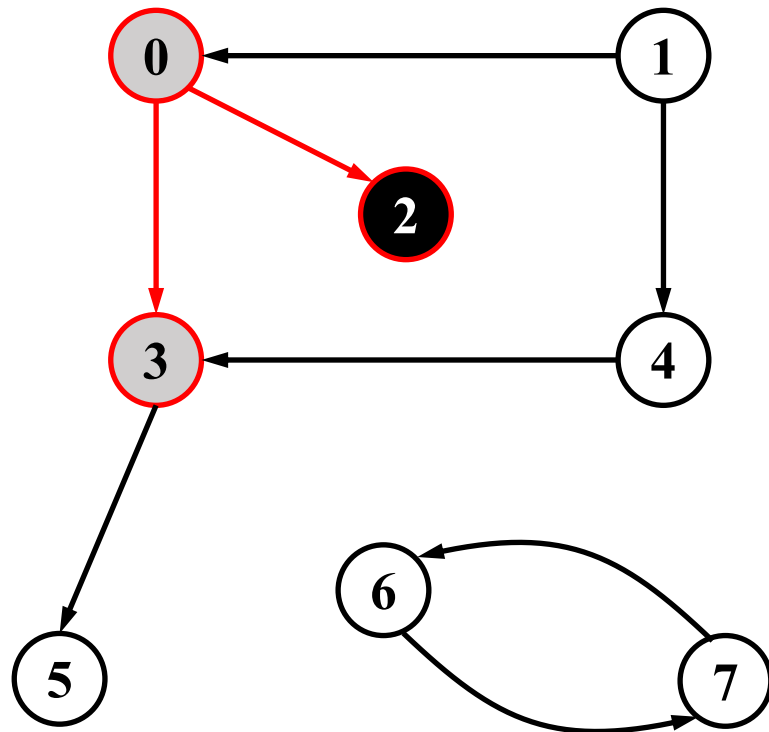
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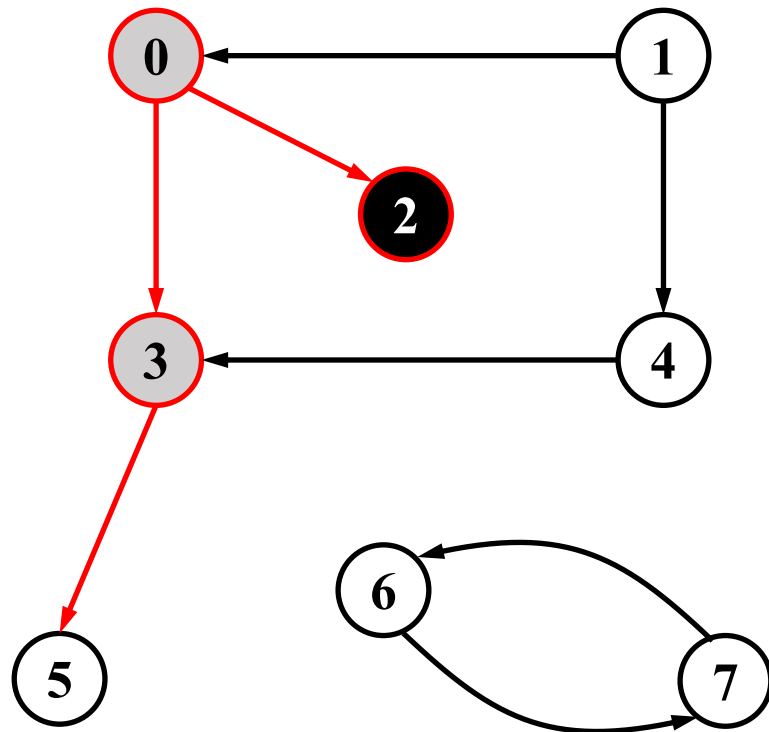
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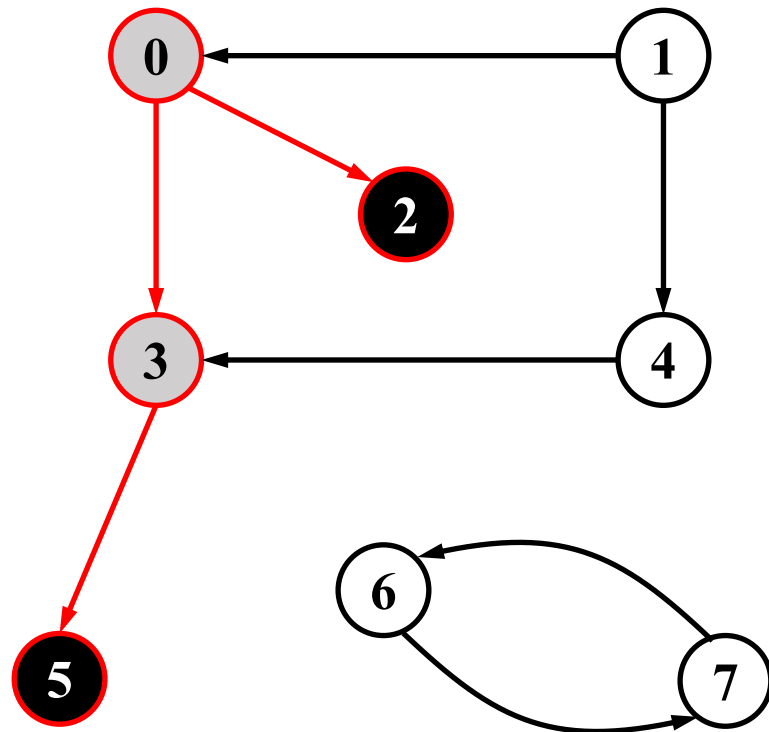
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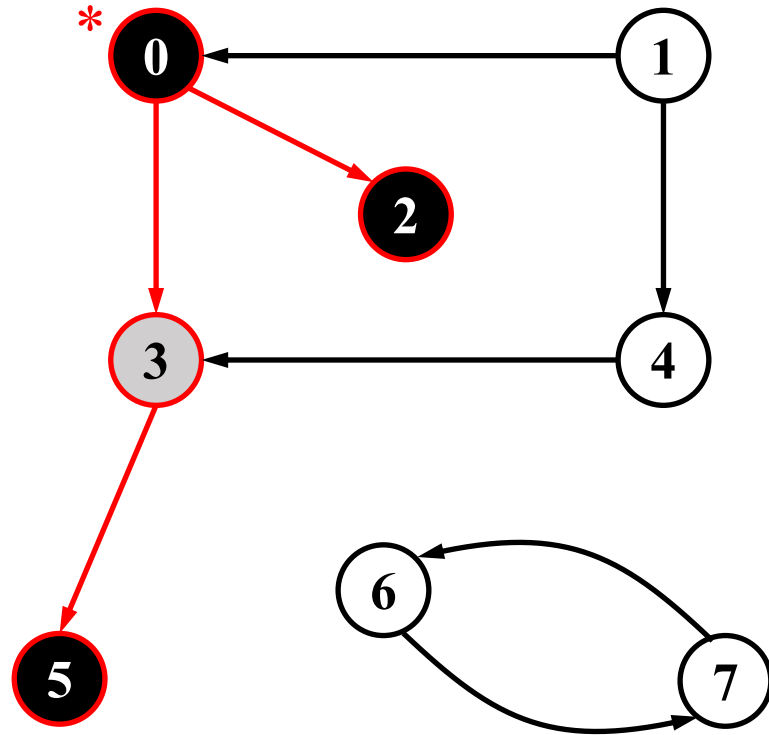


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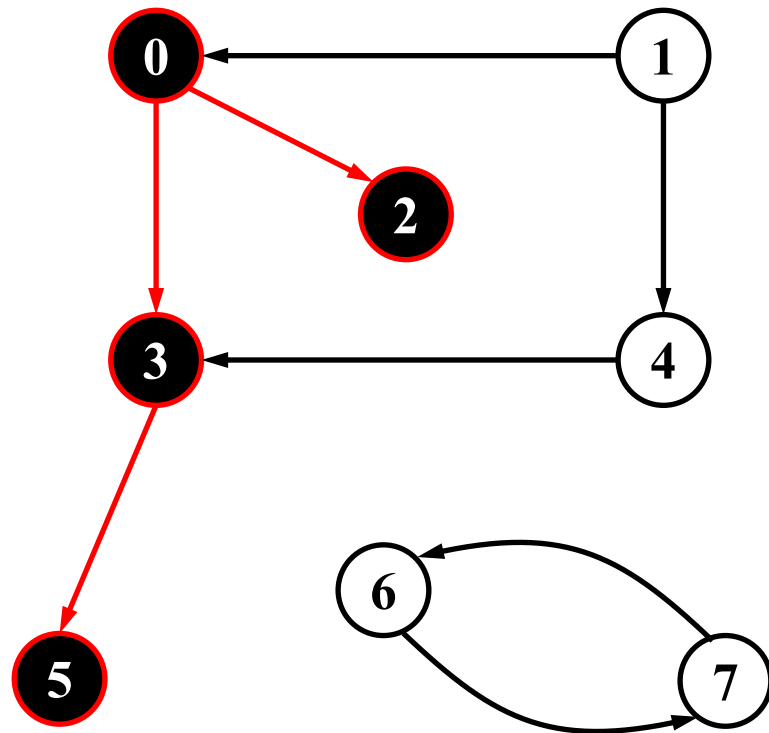
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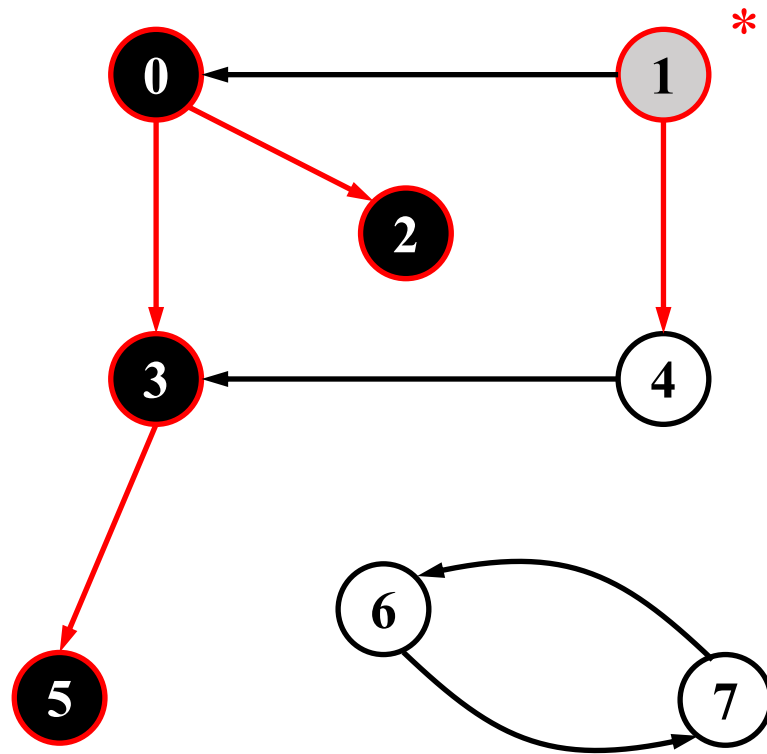
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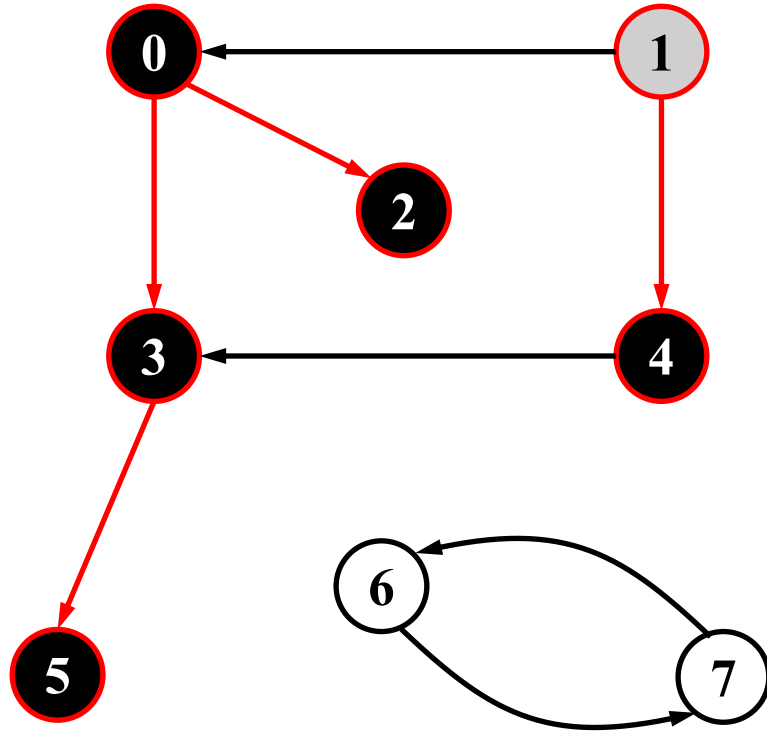
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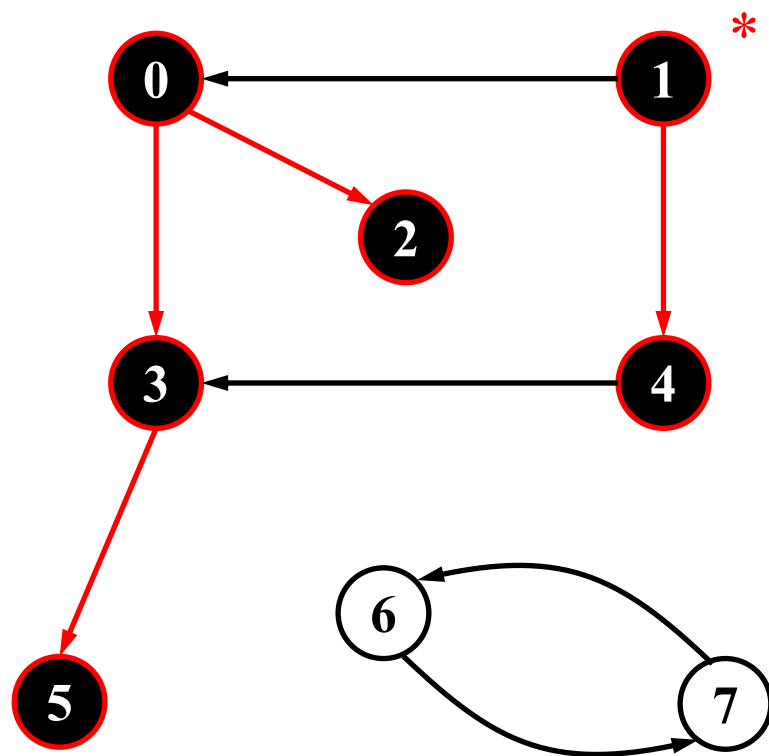
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General graph traversal: example

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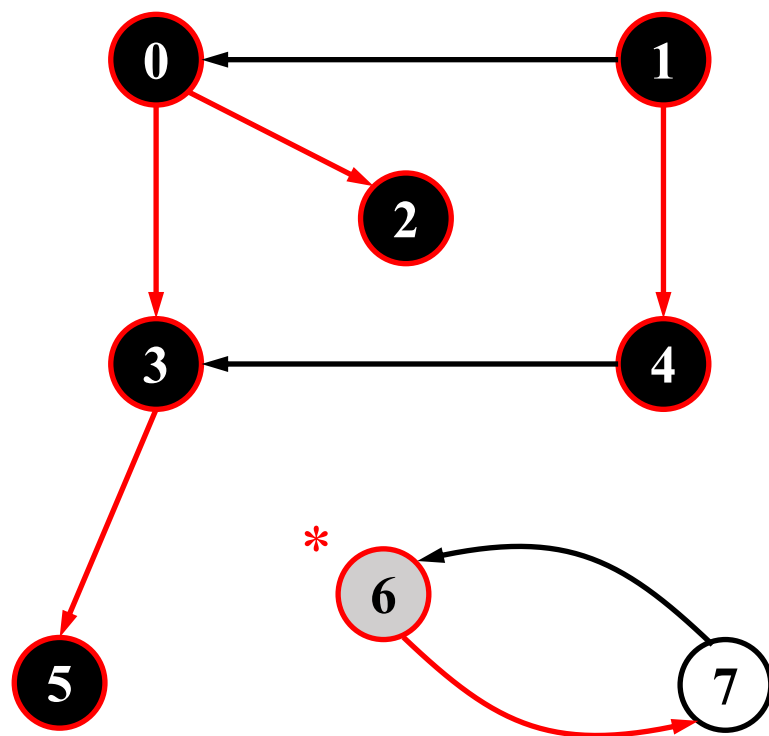
General graph traversal: example



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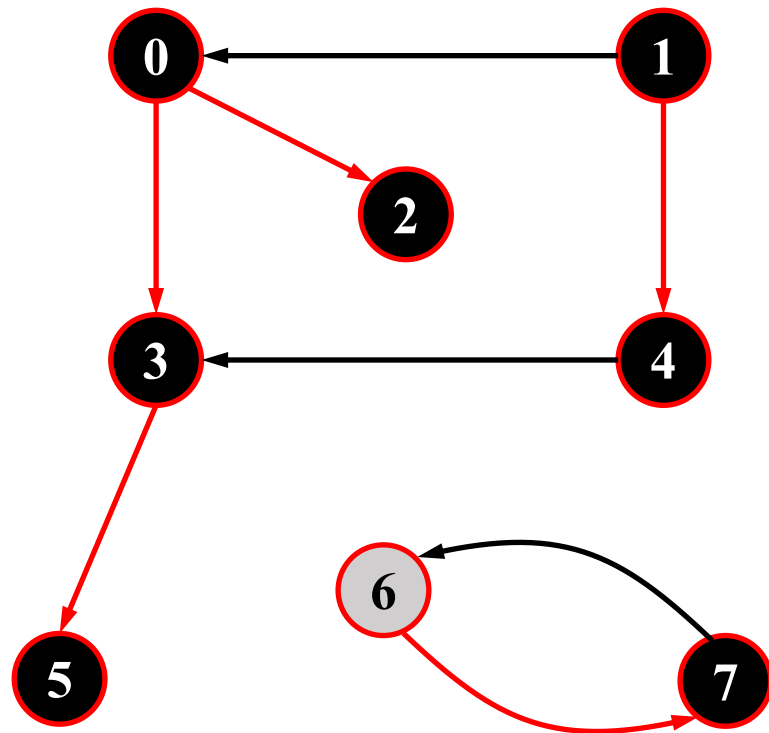
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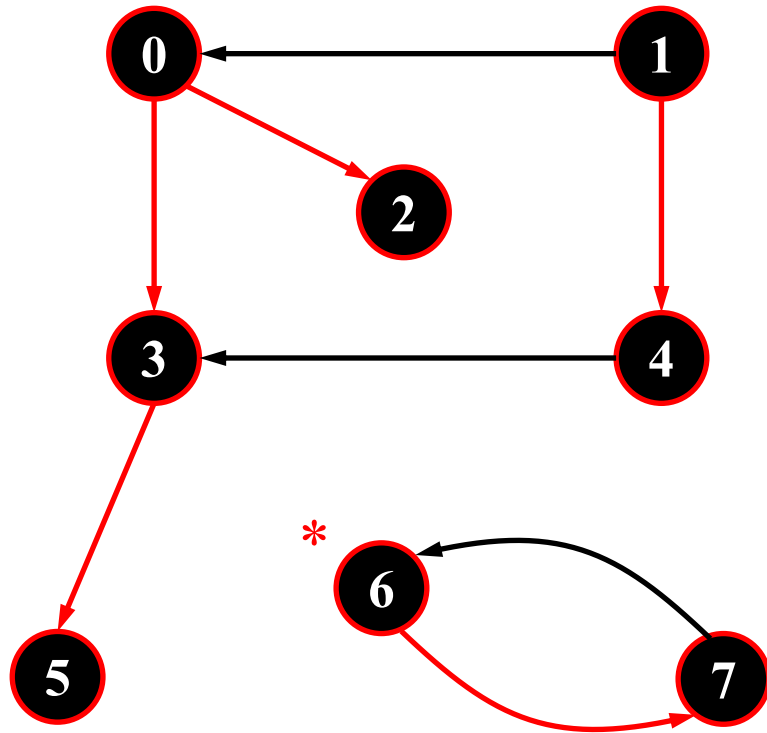
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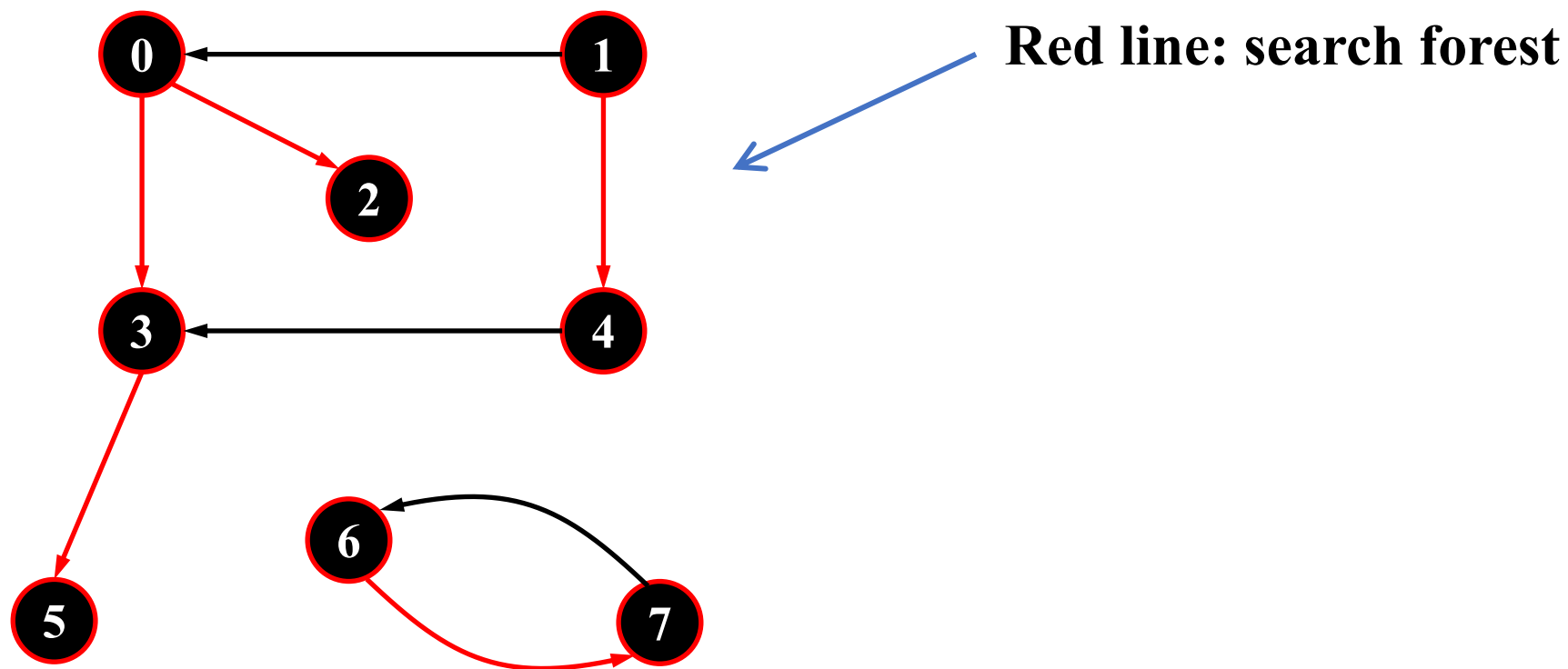


General graph traversal: example

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General graph traversal: example



SUMMARY

- Graph Traversal Algorithm
- Facts about Traversal Trees
- Complexity Analysis
- Illustrative Example

