

# Priority Queues

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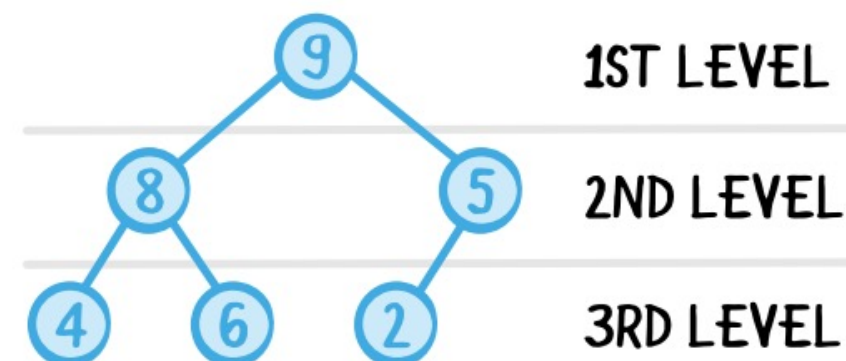
COMPCSI220: WEEK 9



Slides adapted from Mark Wilson, Georgy Gimel'farb, Simone Linz and Tanya Gvozdeva

# OUTLINE

- Priority Queue
- Heaps
  - Illustrating examples
  - Basic Operations
  - Implementation
  - Complexity Analysis



# Definition of Priority Queue

- A priority queue is a container Abstract Data Type (ADT), where each element has a **key** (from a totally ordered set, as with sorting) called its priority.
  - E.g., Queuing in a bank, VIPs have higher priority
  - E.g., A TODO list highlighting the importance of the items
- Applications: Sorting, Graph algorithms
- Three key operations: insert an element, and to find and delete the element of highest priority
- Implementations: unsorted array, sorted array and binary heap.

# Sorted and Unsorted Arrays

- The three key operations: **Insert**, **FindMax** and **DeleteMax**



|                | FindMax     | DeleteMax   | Insert      |
|----------------|-------------|-------------|-------------|
| Unsorted Array | $\Theta(n)$ | $\Theta(n)$ | $\Theta(1)$ |
|                |             |             |             |
|                |             |             |             |

Unsorted array:

- Find maximum element:** needs  $\Theta(n)$  to scan the array
- Delete maximum element:** needs  $\Theta(n)$  to find the max element, and  $\Theta(n)$  to move all elements on its right hand side.
- Insert an element:** Insert at the end in  $\Theta(1)$

# Sorted and Unsorted Arrays (Contd.)

- The three key operations: **Insert**, **FindMax** and **DeleteMax**



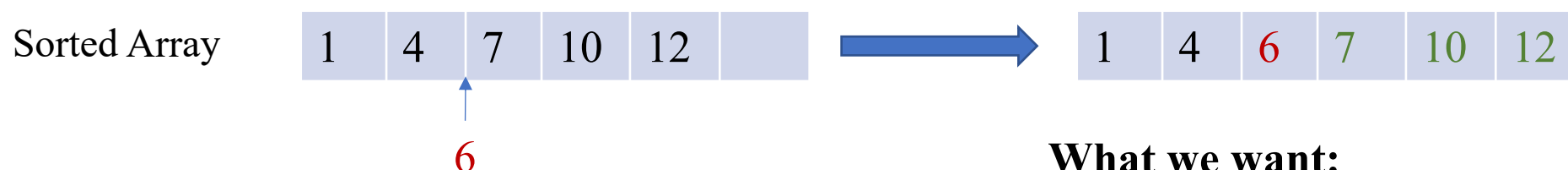
|                | FindMax     | DeleteMax   | Insert      |
|----------------|-------------|-------------|-------------|
| Unsorted Array | $\Theta(n)$ | $\Theta(n)$ | $\Theta(1)$ |
| Sorted Array   | $\Theta(1)$ | $\Theta(1)$ | $\Theta(n)$ |
|                |             |             |             |

Sorted array:

- Find maximum element:** needs  $\Theta(1)$  to retrieve the last element
- Delete maximum element:** needs  $\Theta(1)$  to remove the last element
- Insert an element:** Find the location to insert in  $\Theta(n)$ , move at most  $n$  elements in  $\Theta(n)$

# Sorted and Unsorted Arrays (Contd.)

- The three key operations: **Insert**, **FindMax** and **DeleteMax**



**What we want:**

A data structure that can support dynamically organizing the items efficiently:

1. **Inserting** new items
2. **Finding** the most important one
3. **Deleting** the most important one and reorganizing the structure

|                      | <b>FindMax</b> | <b>DeleteMax</b> | <b>Insert</b>    |
|----------------------|----------------|------------------|------------------|
| Unsorted Array       | $\Theta(n)$    | $\Theta(n)$      | $\Theta(1)$      |
| Sorted Array         | $\Theta(1)$    | $\Theta(1)$      | $\Theta(n)$      |
| <b>Heap (Binary)</b> | $\Theta(1)$    | $\Theta(\log n)$ | $\Theta(\log n)$ |

# Property of Heaps

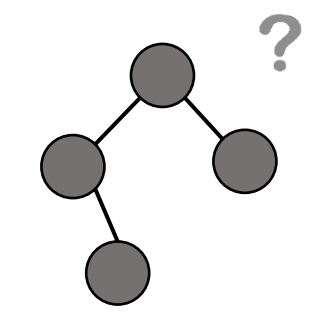
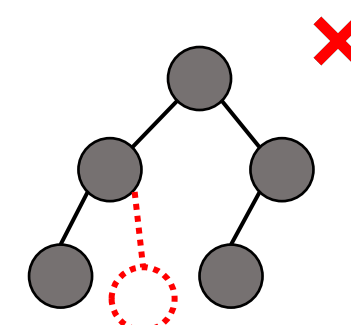
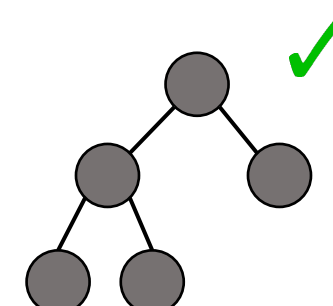
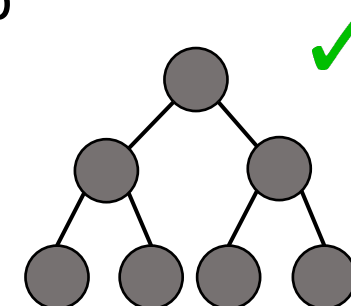
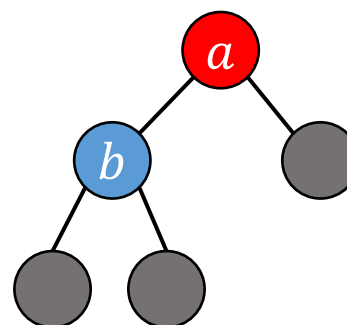
- A binary heap: A complete binary tree that satisfies heap ordering property.

- Complete Binary Tree

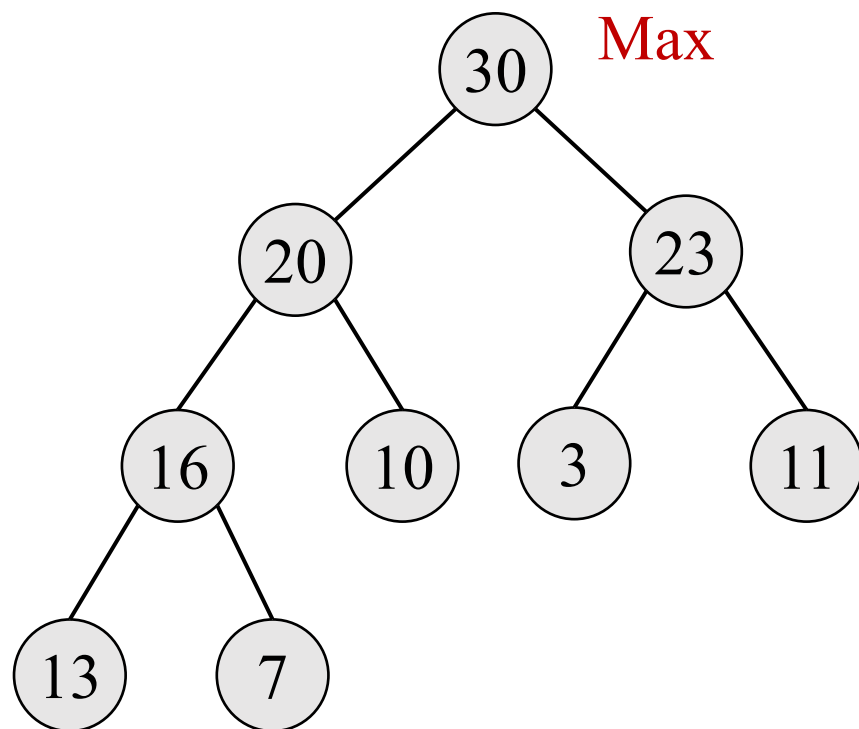
- All levels except the last level are full
- Nodes in last level are placed left to right

- Heap ordering property: Suppose a node  $a$  has child node  $b$

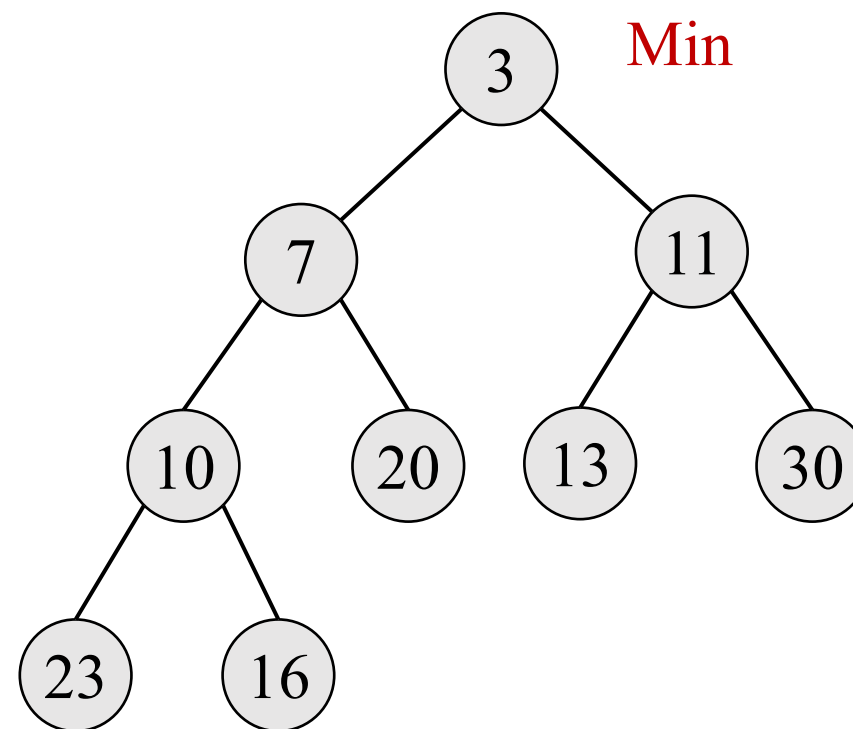
- max-heap property:  $val(a) \geq val(b)$
- min-heap property:  $val(a) \leq val(b)$



Example: [23, 13, 11, 20, 10, 3, 30, 16, 7] → Heaps



Max Heap



Min Heap



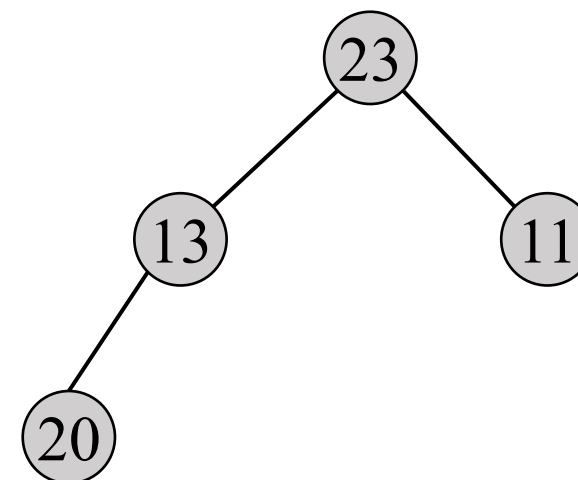
# Heap Operations

- FindMax() / FindMin()
- Insert()
- DeleteMax() / DeleteMin()

# Insertion

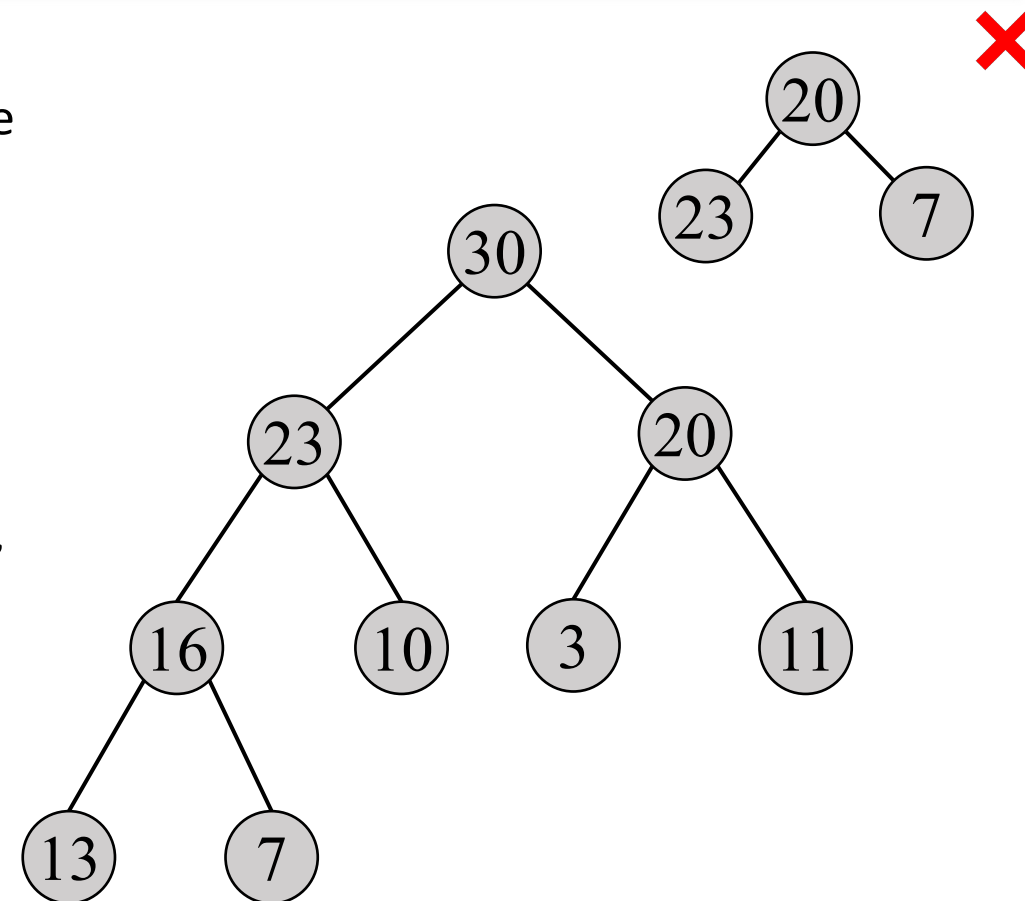
- Step 1 – Insert a new node  $N$  at the end of the tree.
- Step 2 – Compare the value of the node  $n$  with its parent.
- Step 3 – If the parent is smaller than node  $N$ , swap them.
- Step 4 – Repeat step 2 & 3 until heap ordering property holds.

Input → 23, 13, 11, 20, 10, 3, 30, 16, 7



# Deletion

- Step 1 – Delete the root node and move the last node  $N$  to the root.
- Step 2 – Compare the value of node  $N$  with its children.
- Step 3 – If node  $N$  has smaller value than its children, swap  $N$  with the larger child.
- Step 4 – Repeat step 2 & 3 until heap ordering property holds.

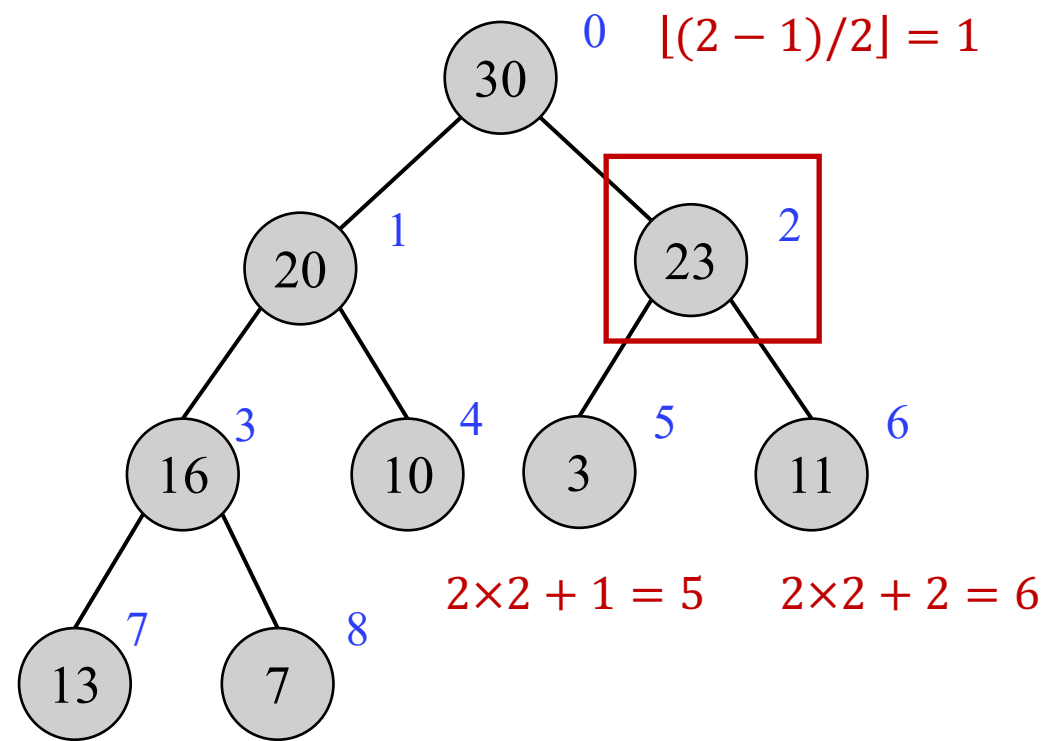


# Array Implementation

- Array Implementation for heap
  - Compact representation
  - Easy to swap
- Find parent and children quickly?

|    |    |    |    |    |   |    |    |   |
|----|----|----|----|----|---|----|----|---|
| 0  | 1  | 2  | 3  | 4  | 5 | 6  | 7  | 8 |
| 30 | 20 | 23 | 16 | 10 | 3 | 11 | 13 | 7 |

- For the  $k$ -th element in the array
  - Left child  $\rightarrow 2k+1$
  - Right child  $\rightarrow 2k+2$
  - Parent  $\rightarrow \lfloor (k-1)/2 \rfloor$



# Implementation - Insertion

- Heap operation on arrays?

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**Algorithm 1** Insert an element to a heap

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1: **function** Insert(array  $a[0..n-1]$ , key  $x$ )

2:      $a \leftarrow \text{append}(a[0..n-1], x)$

3:      $k \leftarrow n$

4:     **while**  $k > 0$  **do**

5:         **if**  $a[k] > a[\lfloor k/2 \rfloor]$  **then**

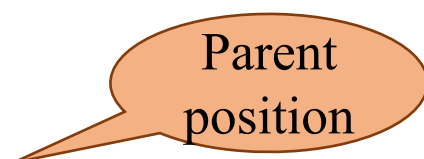
6:              $\text{swap}(a, k, \lfloor k/2 \rfloor)$

7:              $k \leftarrow \lfloor k/2 \rfloor$

7:         **else**

8:             **return**

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Parent  
position

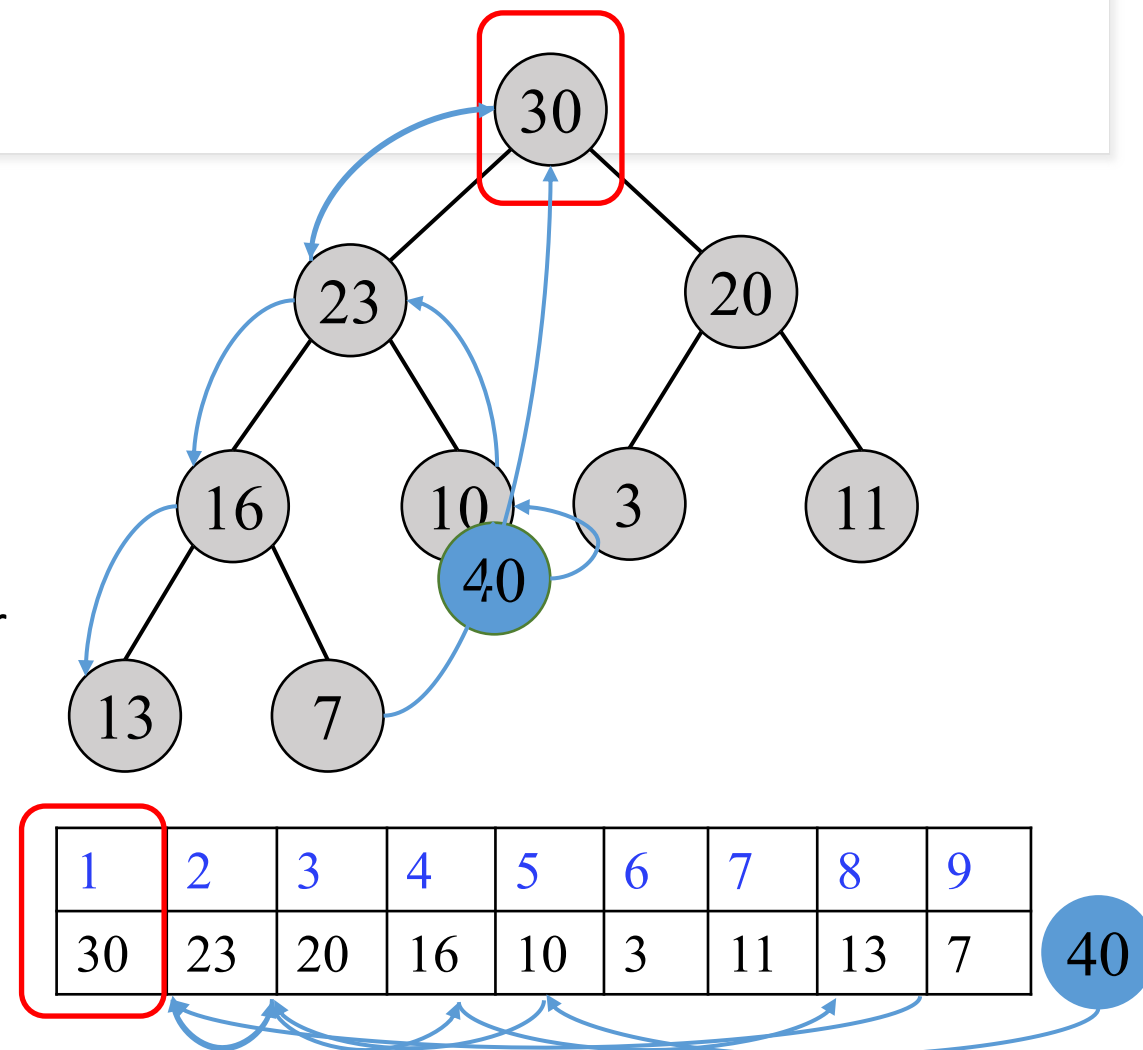
For the  $k$ -th element in the array

- Left child  $\rightarrow 2k$
- Right child  $\rightarrow 2k + 1$
- Parent  $\rightarrow \lfloor k/2 \rfloor$

# Complexity Analysis

- Worst-case analysis
  - FindMax() / FindMin()  $\Theta(1)$
  - Insert()  $\Theta(h)$
  - DeleteMax() / DeleteMin()  $\Theta(h)$
- Let  $h$  be the height of the tree. The number of nodes at level  $l < h$  is  $2^l$ , then the total number of nodes up to level  $l$  is
 
$$2^0 + 2^1 + \dots + 2^l = 2^{l+1} - 1$$
- The number of nodes up to level  $h-1$  is then  $2^h - 1$ , therefore, the number of nodes in a heap of height  $h$  always satisfies
 
$$2^h - 1 + 1 \leq n \leq 2^{h+1} - 1$$

$$h = \lfloor \log_2 n \rfloor$$



# SUMMARY

- Priority Queue
- Heaps
  - Illustrating examples
  - Basic Operations
  - Implementation
  - Complexity Analysis

