Priority Queues

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COMPCSI220: WEEK 9

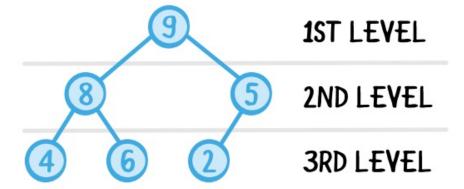




OUTLINE

Priority Queue

- Heaps
 - Illustrating examples
 - Basic Operations
 - Implementation
 - Complexity Analysis





Definition of Priority Queue

- A priority queue is a container Abstract Data Type (ADT), where each element has a key (from a totally ordered set, as with sorting) called its priority.
 - E.g., Queuing in a bank, VIPs have higher priority
 - E.g., A TODO list highlighting the importance of the items
- Applications: Sorting, Graph algorithms
- Three key operations: insert an element, and to find and delete the element of highest priority
- Implementations: unsorted array, sorted array and binary heap.



Sorted and Unsorted Arrays

• The three key operations: Insert, FindMax and DeleteMax

Unsorted Array 10 7 12 1 4 10 7 1 4

	FindMax	DeleteMax	Insert
Unsorted Array	Θ(n)	$\Theta(n)$	Θ(1)

Unsorted array:

- Find maximum element: needs $\Theta(n)$ to scan the array
- **Delete maximum element**: needs $\Theta(n)$ to find the max element, and $\Theta(n)$ to move all elements on its right hand side.
- Insert an element: Insert at the end in $\Theta(1)$



Sorted and Unsorted Arrays (Contd.)

The three key operations: Insert, FindMax and DeleteMax



	FindMax	DeleteMax	Insert
Unsorted Array	Θ(n)	$\Theta(n)$	Θ(1)
Sorted Array	Θ(1)	Θ(1)	$\Theta(n)$

Sorted array:

- Find maximum element: needs $\Theta(1)$ to retrieve the last element
- **Delete maximum element**: needs $\Theta(1)$ to remove the last element
- **Insert an element**: Find the location to insert in $\Theta(n)$, move at most n elements in $\Theta(n)$



Sorted and Unsorted Arrays (Contd.)

The three key operations: Insert, FindMax and DeleteMax



	FindMax	DeleteMax	Insert	
Unsorted Array	Θ(n)	$\Theta(n)$	Θ(1)	
Sorted Array	Θ(1)	Θ(1)	$\Theta(n)$	
Heap (Binary)	Θ(1)	Θ(logn)	Θ(logn)	

What we want:

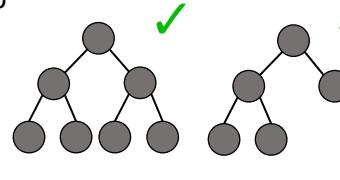
A data structure that can support dynamically organizing the items efficiently:

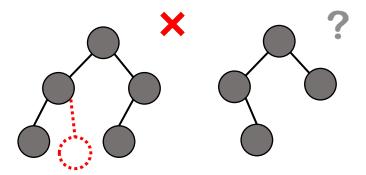
- 1. Inserting new items
- 2. Finding the most important one
- 3. Deleting the most important one and reorganizing the structure



Property of Heaps

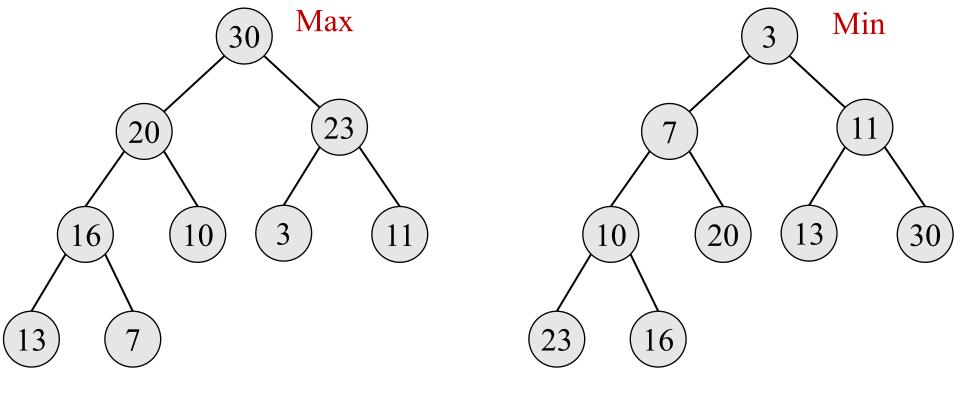
- A binary heap: A complete binary tree that satisfies heap ordering property.
 - Complete Binary Tree
 - All levels except the last level are full
 - Nodes in last level are placed left to right
 - Heap ordering property: Suppose a node α has child node b
 - max-heap property: $val(a) \ge val(b)$
 - min-heap property: $val(a) \le val(b)$







Example: [23, 13, 11, 20, 10, 3, 30, 16, 7] -> Heaps



Max Heap

Min Heap



Heap Operations

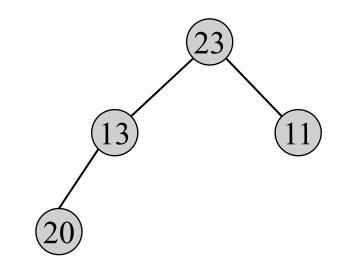
- FindMax() / FindMin()
- Insert()
- DeleteMax() / DeleteMin()



Insertion

- Step 1 Insert a new node *N* at the end of the tree.
- Step 2 Compare the value of the node n with its parent.
- Step 3 If the parent is smaller than node N, swap them.
- Step 4 Repeat step 2 & 3 until heap ordering property holds.

Input \rightarrow 23, 13, 11, 20, 10, 3, 30, 16, 7





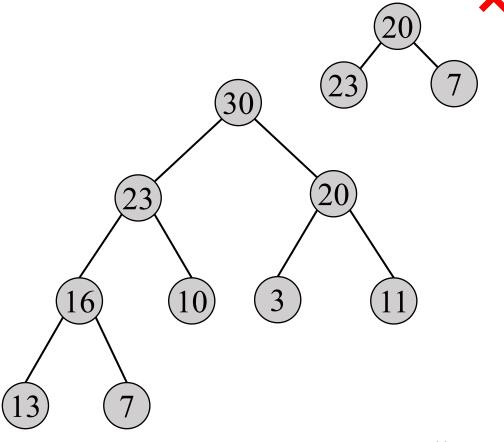
Deletion

• Step 1 – Delete the root node and move the last node *N* to the root.

• Step 2 – Compare the value of node *N* with its children.

• Step 3 – If node *N* has smaller value than its children, swap *N* with the larger child.

• Step 4 – Repeat step 2 & 3 until heap ordering property holds.



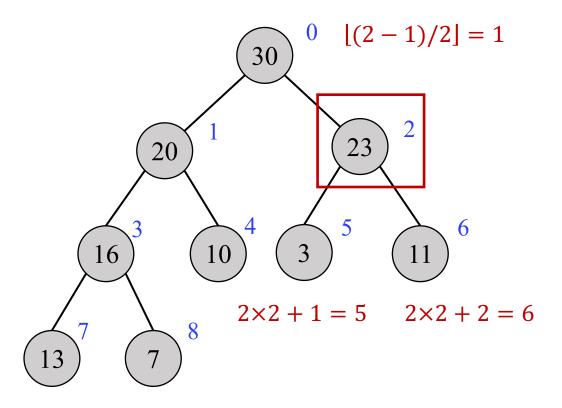


Array Implementation

- Array Implementation for heap
 - Compact representation
 - Easy to swap
- Find parent and children quickly?

0	1	2	3	4	5	6	7	8
30	20	23	16	10	2	11	13	7

- For the *k*-th element in the array
 - Left child $\rightarrow 2k+1$
 - Right child $\rightarrow 2k+2$
 - Parent $\rightarrow \lfloor (k-1)/2 \rfloor$





Implementation - Insertion

Heap operation on arrays?

Algorithm 1 Insert an element to a heap

```
1: function Insert(array a[0..n-1], key x)
        a \leftarrow append(a[0, ... n-1], x)
3:
           k \leftarrow n
                                               Parent
                                                                        For the k-th element in the array
           while k > 0 do
                                              position
4:
                                                                         • Left child \rightarrow 2k
                 if a[k] > a[[k/2]] then
5:
                                                                         • Right child \rightarrow 2k + 1
6:
                      swap(a, k, |k/2|)
                                                                         • Parent \rightarrow |k/2|
                   k \leftarrow \lfloor k/2 \rfloor
7:
              else
8:
                    return
```



Complexity Analysis

- Worst-case analysis
 - FindMax() / FindMin() $\Theta(1)$
 - Insert()

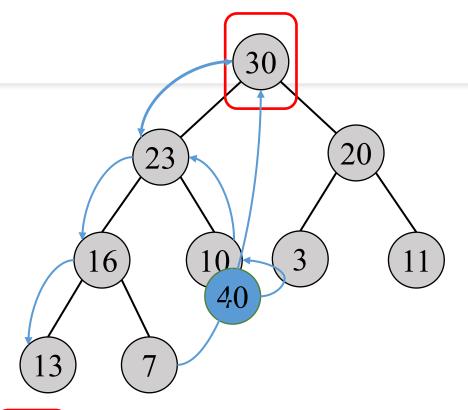
- h
- DeleteMax() / DeleteMin()
 2h
- Let h be the height of the tree. The number of nodes at level l < h is 2^l , then the total number of nodes up to level l is

$$2^{0} + 2^{1} + \cdots + 2^{l} = 2^{l+1} - 1$$

• The number of nodes up to level h-1 is then 2^h-1 , therefore, the number of nodes in a heap of height h always satisfies

$$2^h - 1 + 1 \le n \le 2^{h+1} - 1$$

$$h = \lfloor \log_2 n \rfloor$$



1	2	3	4	5	6	7	8	9
30	23	20	16	10	2	11	13	7



SUMMARY

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- Heaps
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 - Basic Operations
 - Implementation
 - Complexity Analysis

