

Information Theory

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1 Entropy

Definition 1.1. The *uncertainty or entropy* of a discrete random variable U that takes values in the set \mathcal{U} (also called alphabet \mathcal{U}) is defined as

$$H(U) = - \sum_{u \in \mathcal{U}} P_U(u) \log_b P_U(u),$$

where $P_U(\cdot)$ denotes the probability mass function of the random variable U .

Remark 1.2. It should be noted that when $P_U(u) = 0$, the corresponding term does not contribute to entropy because $\lim_{t \downarrow 0} t \log_b t = 0$. In view of this result, one can equivalently define entropy on the support of P_U which is defined as

$$\text{supp}(P_U) = \{u : P_U(u) > 0\} \subseteq \mathcal{U}.$$

Remark 1.3. Entropy does not depend on different possible values that U can take on, but only on the probabilities of these values.

Definition 1.4. If U is binary with two possible values u_1 and u_2 , such that $\mathbb{P}[U = u_1] = p$ and $\mathbb{P}[U = u_2] = 1 - p$, then

$$H(U) = H_b(p) = -p \log_2 p - (1 - p) \log_2 (1 - p), p \in [0, 1],$$

where $H_b(\cdot)$ is called the *binary entropy function*.

Definition 1.5. Let f be a function from a convex set C to \mathbb{R} . Then f is said to be convex on C if for every $x, y \in C$ and $0 \leq \lambda \leq 1$,

$$f((1 - \lambda)x + \lambda y) \leq (1 - \lambda)f(x) + \lambda f(y).$$

A function is said to be strictly convex if equality holds only if $\lambda = 0$ or $\lambda = 1$. A function f is concave if $-f$ is convex.

Lemma 1.6. Let $f : \mathbb{R} \rightarrow \mathbb{R}$ be a twice continuously differentiable function on an open set E . Then f is convex on E iff its second derivative f'' is nonnegative throughout E . If f'' is positive on E , then f is strictly convex.

Remark 1.7. Notice that $-\log x$ and $x \log x$ are strictly convex on $(0, \infty)$.

Lemma 1.8 (Jensen's Inequality). Let $f : \mathbb{R} \rightarrow \mathbb{R}$ be a convex function. Then

$$f\left(\sum_{i=1}^n \lambda_i x_i\right) \leq \sum_{i=1}^n \lambda_i f(x_i),$$

where $\lambda_i \geq 0 \forall i$, $\sum_{i=1}^n \lambda_i = 1$ and equality holds iff $x_1 = \dots = x_n$ or f is linear.

Remark 1.9. If f is strictly convex which rules out the linearity, the equality of Jensen inequality holds iff $x_1 = \dots = x_n$.

Remark 1.10. Suppose X is a discrete random variable over an alphabet $\mathcal{X} = \{x_1, \dots, x_n\}$ and f is a strictly convex function on \mathbb{R} . Then by setting $\lambda_i = P_X(x_i)$, we have

$$f(\mathbb{E}[X]) \leq \mathbb{E}[f(X)],$$

where equality holds iff $x_1 = \dots = x_n$, i.e., X is a constant.

Theorem 1.11. If U has r possible values, then

$$0 \leq H(U) \leq \log r,$$

where

$$\begin{aligned} H(U) = 0 &\iff \exists u \in \mathcal{U}, P_U(u) = 1, \\ H(U) = \log r &\iff \forall u \in \mathcal{U}, P_U(u) = \frac{1}{r}. \end{aligned}$$

Proof. Since $0 \leq P_U(u) \leq 1$, we have

$$-P_U(u) \log_2 P_U(u) \begin{cases} = 0 & \text{if } P_U(u) = 1, \\ > 0 & \text{if } 0 < P_U(u) < 1. \end{cases}$$

Hence, $H(U) \geq 0$. Equality can only be achieved if $-P_U(u) \log_2 P_U(u) = 0$ for all $u \in \text{supp}(P_U)$, i.e., $P_U(u) = 1$ for all $u \in \text{supp}(P_U)$.

To derive the upper bound we use a trick that is quite common in information theory: We take the difference and try to show that it must be nonpositive:

$$\begin{aligned} H(U) - \log r &= -\sum_{u \in \mathcal{U}} P_U(u) \log P_U(u) - \log r \\ &= \sum_{u \in \mathcal{U}} P_U(u) \log \frac{1}{P_U(u)r} \\ &\leq \log \left(\sum_{u \in \mathcal{U}} P_U(u) \frac{1}{P_U(u)r} \right) = 0, \end{aligned}$$

where we have used the strict concavity of $\log x$ and Jensen inequality. Equality holds iff $\frac{1}{P_U(u)r} = 1$ for all $u \in \mathcal{U}$, i.e., $P_U(u) = \frac{1}{r}$ for all $u \in \mathcal{U}$. \square

Definition 1.12. The **conditional entropy** of the random variable X given the event $Y = y$ is defined as

$$H(X|Y = y) = - \sum_{x \in \mathcal{X}} P_{X|Y}(x|y) \log P_{X|Y}(x|y) = -\mathbb{E} \left[\log P_{X|Y}(X|Y) \middle| Y = y \right],$$

where the conditional probability distribution is given by

$$P_{X|Y}(x|y) = \frac{P_{X,Y}(x, y)}{P_Y(y)}.$$

Corollary 1.13. If X has r possible values, then

$$0 \leq H(X|Y = y) \leq \log r,$$

where

$$\begin{aligned} H(X|Y = y) = 0 &\iff \exists x \in \mathcal{X}, P_{X|Y}(x|y) = 1, \\ H(X|Y = y) = \log r &\iff \forall x \in \mathcal{X}, P_{X|Y}(x|y) = \frac{1}{r}. \end{aligned}$$

Definition 1.14. The **conditional entropy** of the random variable X given the random variable Y is defined as

$$\begin{aligned} H(X|Y) &= \sum_{y \in \mathcal{Y}} P_Y(y) H(X|Y = y) \\ &= \mathbb{E}_Y [H(X|Y = y)] \\ &= - \sum_{x \in \mathcal{X}, y \in \mathcal{Y}} P_{X,Y}(x, y) \log P_{X|Y}(x|y) \\ &= -\mathbb{E} \left[\log P_{X|Y}(X|Y) \right]. \end{aligned}$$

Corollary 1.15. If X has r possible values, then

$$0 \leq H(X|Y) \leq \log r,$$

where

$$\begin{aligned} H(X|Y) = 0 &\iff \exists x \in \mathcal{X}, \forall y \in \mathcal{Y}, P_{X|Y}(x|y) = 1, \\ H(X|Y) = \log r &\iff \forall x \in \mathcal{X}, \forall y \in \mathcal{Y}, P_{X|Y}(x|y) = \frac{1}{r}. \end{aligned}$$

Remark 1.16. Generally, $H(X|Y) \neq H(Y|X)$.

Theorem 1.17 (Conditioning Reduced Uncertainty). For any two discrete random variables X and Y ,

$$H(X|Y) \leq H(X),$$

where equality holds iff X and Y are independent, i.e., $X \perp Y$.

Proof. Consider the following:

$$\begin{aligned}
H(X|Y) - H(X) &= - \sum_{x \in \mathcal{X}, y \in \mathcal{Y}} P_{X,Y}(x, y) \log P_{X|Y}(x|y) + \sum_{x \in \mathcal{X}, y \in \mathcal{Y}} P_{X,Y}(x, y) \log P_X(x) \\
&= \sum_{x \in \mathcal{X}, y \in \mathcal{Y}} P_{X,Y}(x, y) \log \frac{P_X(x)}{P_{X|Y}(x|y)} \\
&= \sum_{x \in \mathcal{X}, y \in \mathcal{Y}} P_{X,Y}(x, y) \log \frac{P_X(x)P_Y(y)}{P_{X,Y}(x, y)} \\
&\leq \log \left(\sum_{x \in \mathcal{X}, y \in \mathcal{Y}} P_{X,Y}(x, y) \frac{P_X(x)P_Y(y)}{P_{X,Y}(x, y)} \right) \\
&= \log \left(\left(\sum_{x \in \mathcal{X}} P_X(x) \right) \left(\sum_{y \in \mathcal{Y}} P_Y(y) \right) \right) = 0,
\end{aligned}$$

where we have used the strict concavity of $\log x$ and Jensen inequality. Equality holds iff $\frac{P_X(x)P_Y(y)}{P_{X,Y}(x, y)} = 1$ for all $x \in \mathcal{X}$ and $y \in \mathcal{Y}$, i.e., $X \perp Y$. \square

Remark 1.18. The conditioning reduces entropy-rule only applies to random variables, but not to events. In particular,

$$H(X|Y = y) \leq H(X).$$

To understand why this is the case, consider the following example. Suppose X, Y are random variables such that $P_X(x_1) = 0.4, P_X(x_2) = 0.6, P_{X|Y}(x_1|y_1) = 1$ and $P_{X|Y}(x_i|y_2) = 1/2, i = 1, 2$. Then we see that

$$\begin{aligned}
H(X) &= H_b(0.4) \approx 0.97 \text{ bits}, \\
H(X|Y = y_1) &= H_b(1) = 0 \text{ bits}, \\
H(X|Y = y_2) &= H_b(0.5) = 1 \text{ bit}.
\end{aligned}$$

However from Theorem 1.17 we know that on average the knowledge of Y will reduce the uncertainty about X : $H(X|Y) \leq H(X)$.

Theorem 1.19 (Chain Rule). *Let X_1, \dots, X_n be n discrete random variables. Then*

$$H(X_1, \dots, X_n) = H(X_1) + H(X_2|X_1) + \dots + H(X_n|X_1, \dots, X_{n-1}) = \sum_{k=1}^n H(X_k|X^{(k-1)}),$$

where $X^{(k-1)} = X_{1:k-1}$.

Proof. This follows directly from the chain rule for probability mass functions:

$$P_{X^{(n)}} = \prod_{k=1}^n P_{X_k|X^{(k-1)}}.$$

\square

Definition 1.20. The **mutual information** between the random variables X and Y is

$$I(X; Y) = H(X) - H(X|Y).$$

Remark 1.21. Notice that mutual information is symmetric in its arguments:

$$\begin{aligned}
H(X, Y) &= H(X) + H(Y|X) = H(Y) + H(X|Y) \\
\Rightarrow H(X) - H(X|Y) &= H(Y) - H(Y|X) \\
\Rightarrow I(X; Y) &= I(Y; X).
\end{aligned}$$

Remark 1.22. When $X \perp\!\!\!\perp Y$, we have $I(X; Y) = 0$. Additionally, $I(X; X) = H(X)$.

Remark 1.23. From the chain rule it follows that

$$H(X|Y) = H(X, Y) - H(Y),$$

and thus we obtain

$$I(X; Y) = H(X) + H(Y) - H(X, Y).$$

Remark 1.24. The mutual information can be expressed as follows.

$$\begin{aligned} I(X; Y) &= H(X) - H(X|Y) \\ &= \mathbb{E}[-\log P_X(X)] - \mathbb{E}[P_{X|Y}(X|Y)] \\ &= \mathbb{E}\left[\log \frac{P_{X|Y}(X|Y)}{P_X(X)}\right] \\ &= \mathbb{E}\left[\log \frac{P_{X,Y}(X, Y)}{P_X(X)P_Y(Y)}\right] \\ &= \sum_{x \in \mathcal{X}, y \in \mathcal{Y}} P_{X,Y}(x, y) \log \frac{P_{X,Y}(x, y)}{P_X(x)P_Y(y)}. \end{aligned}$$

Theorem 1.25. Let X and Y be two random variables. Then

$$0 \leq I(X; Y) \leq \min\{H(X), H(Y)\}.$$

where equality holds on the left-hand side iff $P_{X,Y} = P_X P_Y$, i.e., iff $X \perp\!\!\!\perp Y$, and equality holds on the right-hand side iff X determines Y or vice versa.

Proof. It follows directly from the definition of mutual information and nonnegativity of conditional entropy. \square

Theorem 1.26 (Chain Rule). Let X, Y_1, \dots, Y_n be $n + 1$ discrete random variables. Then

$$I(X; Y_1, \dots, Y_n) = I(X; Y_1) + I(X; Y_2|Y_1) + \dots + I(X; Y_n|Y_1, \dots, Y_{n-1}) = \sum_{k=1}^n I(X; Y_k|Y^{(k-1)}).$$

Proof. From the chain rule of entropy we have

$$\begin{aligned} I(X; Y^{(n)}) &= H(Y^{(n)}) - H(Y^{(n)}|X) \\ &= \sum_{k=1}^n H(Y_k|Y^{(k-1)}) - H(Y_k|Y^{(k-1)}, X) \\ &= \sum_{k=1}^n I(X; Y_k|Y^{(k-1)}). \end{aligned}$$

\square

Theorem 1.27 (Data Processing Inequality (DPI)). Let X, Y, Z be random variables that form a Markov chain, denoted by $X - Y - Z$, i.e., $X \perp\!\!\!\perp Z | Y$. Then

$$I(X; Z) \leq I(X; Y).$$

Proof 1. We start by considering

$$\begin{aligned}
I(X; Z) &= H(X) - H(X|Z) \\
&\leq H(X) - H(X|Z, Y) \quad (\text{conditioning reduces entropy}), \\
&= H(X) - H(X|Y) \quad (\text{since } X \perp\!\!\!\perp Z | Y), \\
&= I(X; Y).
\end{aligned}$$

□

Proof 2. Another way of proving the inequality is to start by considering the following mutual information

$$\begin{aligned}
I(X; Y, Z) &= I(X; Y) + \underbrace{I(X; Z|Y)}_{=0} \\
&= I(X; Z) + \underbrace{I(X; Y|Z)}_{\geq 0} \\
\implies I(X; Z) &\leq I(X; Y).
\end{aligned}$$

□

Remark 1.28. Sometimes it is convenient to use another notation for entropy and mutual information, which is explicit in the probability mass functions these quantities depend on. Sometimes, we shall write $H(X)$ as $H(P_X)$ and $I(X; Y)$ as $I(P_X, P_{Y|X})$.

Theorem 1.29 (Uniqueness of the Definition of Entropy).

2 Relative Entropy and Variational Distance

Definition 2.1. Let P and Q be two probability mass functions over the same finite (or countably infinite) alphabet \mathcal{X} . The relative entropy or Kullback-Leibler divergence between P and Q is defined as

$$\mathcal{D}(P\|Q) = \sum_{x \in \mathcal{X}} P(x) \log \frac{P(x)}{Q(x)} = \mathbb{E}_P \left[\log \frac{P(x)}{Q(x)} \right].$$

Remark 2.2. Note that $\mathcal{D}(P\|Q) = \infty$ if there exists an $x \in \text{supp}(P)$ such that $Q(x) = 0$. So, strictly speaking, we should defined relative entropy as follows:

$$\mathcal{D}(P\|Q) = \begin{cases} \sum_{x \in \text{supp}(P)} P(x) \log \frac{P(x)}{Q(x)} & \text{if } \text{supp}(P) \subseteq \text{supp}(Q), \\ \infty & \text{otherwise.} \end{cases}$$

Theorem 2.3 (Gibbs' Inequality).

$$\mathcal{D}(P\|Q) \geq 0,$$

where equality holds iff $P(x) = Q(x) \forall x \in \mathcal{X}$.

Proof. In the case when $\text{supp}(P) \not\subseteq \text{supp}(Q)$, we have $\mathcal{D}(P\|Q) = \infty > 0$ trivially. So, we assume that $\text{supp}(P) \subseteq \text{supp}(Q)$. Then,

$$\begin{aligned}
-\mathcal{D}(P\|Q) &= \sum_{x \in \text{supp}(P)} P(x) \log \frac{Q(x)}{P(x)} \\
&\leq \log \left(\sum_{x \in \text{supp}(P)} P(x) \frac{Q(x)}{P(x)} \right) \leq 0.
\end{aligned}$$

Equality holds in both the inequalities iff $\frac{Q(x)}{P(x)} = 1$ and $\text{supp}(P) = \text{supp}(Q)$, i.e., $P(x) = Q(x)$ for all $x \in \mathcal{X}$. \square

Remark 2.4. Relative Entropy is not a norm as it is not symmetric and does not satisfy triangle inequality.

Remark 2.5. From Remark 1.24, it can be seen that mutual information is the relative entropy between the joint $P_{X,Y}$ and the product of its marginals:

$$I(X; Y) = \mathcal{D}(P_{X,Y} \| P_X P_Y).$$

Definition 2.6. The conditional divergence between two discrete probability distributions $P_{Y|X}$ and $Q_{Y|X}$ is defined as

$$\mathcal{D}(P_{Y|X} \| Q_{Y|X} | P_X) = \sum_{x \in \mathcal{X}} P_X(x) \mathcal{D}(P_{Y|X=x} \| Q_{Y|X=x}).$$

Remark 2.7. The conditional divergence can be represented in terms of divergence as follows:

$$\begin{aligned} \mathcal{D}(P_{Y|X} \| Q_{Y|X} | P_X) &= \sum_x P_X(x) \mathcal{D}(P_{Y|X=x} \| Q_{Y|X=x}) \\ &= \sum_x P_X(x) \sum_y P_{Y|X=x}(y) \log \frac{P_{Y|X=x}(y)}{Q_{Y|X=x}(y)} \\ &= \sum_{x,y} P_X(x) P_{Y|X=x}(y) \log \frac{P_{Y|X=x}(y) P_X(x)}{Q_{Y|X=x}(y) P_X(x)} \\ &= \mathcal{D}(P_{Y|X} P_X \| Q_{Y|X} P_X). \end{aligned}$$

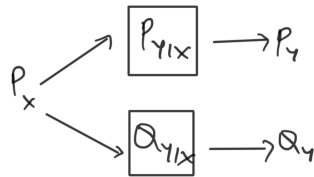
Theorem 2.8 (Chain Rule). $\mathcal{D}(P_{X,Y} \| Q_{X,Y}) = \mathcal{D}(P_{Y|X} \| Q_{Y|X} | P_X) + \mathcal{D}(P_X \| Q_X)$.

Proof.

$$\begin{aligned} \mathcal{D}(P_{X,Y} \| Q_{X,Y}) &= \sum_{X,Y} P_{Y|X}(y) P_X(x) \log \frac{P_{Y|X=x}(y) P_X(x)}{Q_{Y|X}(y) Q_X(x)} \frac{P_X(x)}{P_X(x)} \\ &= \sum_{X,Y} P_{Y|X}(y) P_X(x) \log \frac{P_{Y|X=x}(y)}{Q_{Y|X=x}(y)} + \sum_{X,Y} P_{Y|X=x}(y) P_X(x) \log \frac{P_X(x)}{Q_X(x)} \\ &= \mathcal{D}(P_{Y|X} \| Q_{Y|X} | P_X) + \mathcal{D}(P_X \| Q_X). \end{aligned}$$

\square

Theorem 2.9 (Conditioning Increases Divergence). Given $P_{Y|X}, Q_{Y|X}$ and P_X , let $P_Y = P_{Y|X} P_X$ and $Q_Y = Q_{Y|X} P_X$, as represented by the diagram.



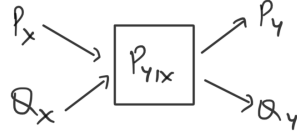
Then $\mathcal{D}(P_Y \| Q_Y) \leq \mathcal{D}(P_{Y|X} \| Q_{Y|X} | P_X)$, with equality iff $\mathcal{D}(P_{X|Y} \| Q_{X|Y} | P_Y) = 0$.

Proof.

$$\begin{aligned}
\mathcal{D}(P_{X,Y} \| Q_{X,Y}) &= \mathcal{D}(P_{Y|X} \| Q_{Y|X} | P_X) + \underbrace{\mathcal{D}(P_X \| P_X)}_{=0} \\
&= \underbrace{\mathcal{D}(P_{X|Y} \| Q_{X|Y} | P_Y)}_{\geq 0} + \mathcal{D}(P_Y \| Q_Y) \\
\implies \mathcal{D}(P_Y \| Q_Y) &\leq \mathcal{D}(P_{Y|X} \| Q_{Y|X} | P_X).
\end{aligned}$$

□

Theorem 2.10 (DPI for Divergence). *Given $P_{Y|X}, P_X$ and Q_X , let $P_Y = P_{Y|X}P_X$ and $Q_Y = P_{Y|X}Q_X$, as represented by the diagram.*



Then $\mathcal{D}(P_Y \| Q_Y) \leq \mathcal{D}(P_X \| Q_X)$, with equality iff $\mathcal{D}(P_{X|Y} \| Q_{X|Y} | P_Y) = 0$.

Proof.

$$\begin{aligned}
\mathcal{D}(P_{X,Y} \| Q_{X,Y}) &= \underbrace{\mathcal{D}(P_{Y|X} \| Q_{Y|X} | P_X)}_{=0} + \mathcal{D}(P_X \| Q_X) \\
&= \underbrace{\mathcal{D}(P_{X|Y} \| Q_{X|Y} | P_Y)}_{\geq 0} + \mathcal{D}(P_Y \| Q_Y) \\
\implies \mathcal{D}(P_Y \| Q_Y) &\leq \mathcal{D}(P_X \| Q_X).
\end{aligned}$$

□

Theorem 2.11. *DPI for Divergence implies DPI for Mutual Information.*

Proof. Now suppose we consider a Markov chain $X - Y - Z$ over discrete random variables. Then notice that

$$P_{Z|X} = P_{Z|X,Y}P_{Y|X} = \textcolor{red}{P}_{Z|Y}P_{Y|X}, \quad P_Z = \textcolor{red}{P}_{Z|Y}P_Y.$$

We apply DPI for divergence on $P_{Z|Y}, P_{Y|X=x}$ and P_Y to get

$$\begin{aligned}
\mathcal{D}(P_{Y|X=x} \| P_Y) &\geq \mathcal{D}(P_{Z|X=x} \| P_Z) \implies \mathbb{E}_X[\mathcal{D}(P_{Y|X=x} \| P_Y)] \geq \mathbb{E}_X[\mathcal{D}(P_{Z|X=x} \| P_Z)] \\
&\implies \mathcal{D}(P_{Y|X} \| P_Y | P_X) \geq \mathcal{D}(P_{Z|X} \| P_Z | P_X). \tag{1}
\end{aligned}$$

Now consider the mutual information

$$\begin{aligned}
I(X; Z) &= \mathcal{D}(P_{X,Z} \| P_X P_Z) \\
&= \mathcal{D}(P_{Z|X} \| P_Z | P_X) \\
&\leq \mathcal{D}(P_{Y|X} \| P_Y | P_X), \quad (\text{using (1)}) \\
&= \mathcal{D}(P_{X,Y} \| P_X P_Y) \\
&= I(X; Y).
\end{aligned}$$

□

Theorem 2.12 (Golden Formula).

$$I(X; Y) = \min_{Q_Y} \mathcal{D}(P_{Y|X} \| Q_Y | P_X).$$

Proof.

$$\begin{aligned} \mathcal{D}(P_{Y|X} \| Q_Y | P_X) &= \mathcal{D}(P_{Y|X} P_X \| Q_Y P_X) \\ &= \sum_{x,y} P_{X,Y} \log \frac{P_{X,Y}}{Q_Y P_X} \frac{P_Y}{P_Y} \\ &= \sum_{x,y} P_{X,Y} \log \frac{P_{X,Y}}{P_X P_Y} + \sum_{x,y} P_{X,Y} \log \frac{P_Y}{Q_Y} \\ &= \mathcal{D}(P_{X,Y} \| P_X P_Y) + \mathcal{D}(P_Y \| Q_Y) \\ &= I(X; Y) + \mathcal{D}(P_Y \| Q_Y). \end{aligned}$$

We get the result by noting that $\mathcal{D}(P_Y \| Q_Y) \geq 0$ where equality holds iff $Q_Y = P_Y$. □

Definition 2.13. Variational Distance.

Remark 2.14. Trivial bounds on variational distance.

Remark 2.15. Variational Distance is a Norm.

Theorem 2.16. Upper bound of relative entropy in terms of variational distance and entropy.

Theorem 2.17 (Pinsker Inequality).

Definition 2.18. Total Variation Distance.

3 Differential Entropy

4 Typicality

Definition 4.1. We say that a sequence of random variables $\{X_n\}$ **converges in probability** to a random variable X if for all $\varepsilon > 0$, we have

$$\lim_{n \rightarrow \infty} \mathbb{P}[|X_n - X| > \varepsilon] = 0.$$

Lemma 4.2 (Markov Inequality). *Let X be a nonnegative random variable of finite mean $\mathbb{E}[X] < \infty$. Then for all $a > 0$, we have*

$$\mathbb{P}[X \geq a] \leq \frac{\mathbb{E}[X]}{a}.$$

Lemma 4.3 (Chebyshev Inequality). *Let X be a random variable with finite mean μ and finite variance σ^2 . Then for all $\varepsilon > 0$, we have*

$$\mathbb{P}[|X - \mu| \geq \varepsilon] \leq \frac{\sigma^2}{\varepsilon^2}.$$

Lemma 4.4 (Weak Law of Large Numbers). *Let $\{Z_n\}$ be a sequence of independent and identically distributed (i.i.d.) random variables with mean μ and variance σ^2 . Let*

$$S_n = \frac{1}{n} \sum_{k=1}^n Z_k$$

be the sample mean. Then $\{S_n\}$ converges in probability to μ . In particular,

$$\mathbb{P}[|S_n - \mu| \geq \varepsilon] \leq \frac{\sigma^2}{n\varepsilon^2}.$$

Definition 4.5 (Type). Let $x^{(n)}$ be a sequence of n elements drawn from a finite-cardinality alphabet \mathcal{X} . The **empirical probability mass function** of $x^{(n)}$, also referred to as its **type**, is defined for $x \in \mathcal{X}$ as

$$\pi(x|x^{(n)}) = \frac{|\{i \in [n] : x_i = x\}|}{n},$$

where $[n] = \{1, \dots, n\}$.

Theorem 4.6. Let $\{X_n\}$ be an i.i.d. sequence of random variables with $X_i \sim P_X(x_i)$. Then $\forall x \in \mathcal{X}$ and for all $\varepsilon > 0$, we have

$$\lim_{n \rightarrow \infty} \mathbb{P}[|\pi(x|X^{(n)}) - P_X(x)| > \varepsilon] = 0,$$

or in other words, $\{\pi(x|X^{(n)})\}$ converges in probability to $P_X(x)$ for all $x \in \mathcal{X}$.

Definition 4.7 (Typical Set). The **set of ε -typical n -sequences** for a random variable $X \sim P_X$ and $\varepsilon \in (0, 1)$ (simply typical set) is defined as

$$\mathcal{T}_\varepsilon^{(n)}(X) = \{x^{(n)} : |\pi(x|x^{(n)}) - P_X(x)| \leq \varepsilon P_X(x), \forall x \in \mathcal{X}\}.$$

Remark 4.8. For an element $x \in \mathcal{X}$ which has $P_X(x)$ cannot be a part of typical sequence. Suppose such an x belonged to a sequence $x^{(n)}$, then $\pi(x|x^{(n)}) > 0$. Consequently, we have $|\pi(x|x^{(n)}) - P_X(x)| = \pi(x|x^{(n)}) > 0 = \varepsilon P_X(x)$ for all $\varepsilon > 0$, which shows that $x^{(n)}$ is not a typical sequence.

Lemma 4.9 (Typical Average Lemma). Consider a typical sequence $x^{(n)} \in \mathcal{T}_\varepsilon^{(n)}(X)$. Then for any **nonnegative** function $g(\cdot)$ on \mathcal{X} , we have

$$(1 - \varepsilon)\mathbb{E}[g(X)] \leq \frac{1}{n} \sum_{k=1}^n g(x_k) \leq (1 + \varepsilon)\mathbb{E}[g(X)].$$

5 Source Coding

6 Joint Typical

Definition 6.1 (Joint Type). Let $(x^{(n)}, y^{(n)})$ be a sequence of a pair of n length sequences from a finite-cardinality alphabet $(\mathcal{X}, \mathcal{Y})$. The **joint empirical probability mass function** of $(x^{(n)}, y^{(n)})$, also referred to as its **joint type**, is defined for $x \in \mathcal{X}$ as

$$\pi(x, y|x^{(n)}, y^{(n)}) = \frac{|\{i \in [n] : (x_i, y_i) = (x, y)\}|}{n}.$$

Remark 6.2. The X -marginal of X, Y -joint empirical probability mass function is the X -empirical probability mass function.

Definition 6.3 (Jointly Typical Set). The **set of ε -jointly typical n -sequences** for a random variable $(X, Y) \sim (P_X, P_Y)$ and $\varepsilon \in (0, 1)$ (simply jointly typical set) is defined as

$$\mathcal{T}_\varepsilon^{(n)}(X, Y) = \{(x^{(n)}, y^{(n)}) : |\pi(x, y|x^{(n)}, y^{(n)}) - P_{X,Y}(x, y)| \leq \varepsilon P_{X,Y}(x, y), \forall x \in \mathcal{X}, y \in \mathcal{Y}\}.$$

Remark 6.4. If $(x^{(n)}, y^{(n)}) \in \mathcal{T}_\varepsilon^{(n)}(X, Y)$, then $x^{(n)} \in \mathcal{T}_\varepsilon^{(n)}(X)$ and $y^{(n)} \in \mathcal{T}_\varepsilon^{(n)}(Y)$.

7 Channel Coding

References

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