

# Theory of Optimization

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# 1 Unconstrained Minimization

Let  $\mathbb{R}^n$  denote the  $n$ -dimensional Euclidean real vector space with the inner product defined for any  $x, y \in \mathbb{R}^n$  as  $\langle x, y \rangle = x^T y = \sum_{i=1}^n x_i y_i$ , where  $x = [x_1, \dots, x_n]^T$  and  $y = [y_1, \dots, y_n]^T$  are the coordinates of  $x$  and  $y$  respectively. Let the norm and the metric on  $\mathbb{R}^n$  be defined as  $\|x\| = \sqrt{\langle x, x \rangle}$  and  $d(x, y) = \|x - y\|$ , respectively.

Suppose  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  is a real-valued function on  $\mathbb{R}^n$ . We consider the following optimization problem

$$\min_{x \in \mathbb{R}^n} f(x). \quad (1)$$

The problem (1) is called as the unconstrained minimization problem as there are no constraints on  $x$ .

**Definition 1.1.** A **local minimum** of  $f$  in the problem (1) is a vector  $x^* \in \mathbb{R}^n$  for which there exists  $\varepsilon > 0$  such that for all  $x \in \mathbb{R}^n$  we have

$$f(x^*) \leq f(x), \quad (2)$$

when  $\|x - x^*\| \leq \varepsilon$ . A **global minimum** of  $f$  in the problem (1) is a vector  $x^* \in \mathbb{R}^n$  such that for all  $x \in \mathbb{R}^n$  we have

$$f(x^*) \leq f(x). \quad (3)$$

The global or local minimum  $x^*$  is said to be **strict** if the corresponding inequality given above is strict for  $x \neq x^*$ . The vector  $x^*$  with  $\nabla f(x^*) = 0$  is referred to as a **stationary point**.

**Proposition 1.2** (Necessary Optimality Conditions). *Let  $x^*$  be an unconstrained local minimum of  $f : \mathbb{R}^n \rightarrow \mathbb{R}$ , and assume that  $f$  is continuously differentiable in an open set  $U$  containing  $x^*$ . Then*

$$\nabla f(x^*) = 0. \quad (\text{First Order Necessary Condition})$$

*If in addition  $f$  is twice continuously differentiable within  $U$ , then*

$$\nabla^2 f(x^*) \succeq 0. \quad (\text{Second Order Necessary Condition})$$

*Proof.* Fix some  $d \in \mathbb{R}^n$ . Then, using chain rule to differentiate the function  $g(\alpha) = f(x^* + \alpha d)$ , we have

$$0 \leq \lim_{\alpha \downarrow 0} \frac{f(x^* + \alpha d) - f(x^*)}{\alpha} = \frac{dg(0)}{d\alpha} = \nabla f(x^*)^T d,$$

where the inequality follows from the assumption that  $x^*$  is a local minimum and  $\alpha \downarrow 0$  indicates the right-hand limit, i.e.,  $\alpha > 0$  and  $\alpha \rightarrow 0$ . Since  $d$  is arbitrary, the same inequality holds with  $d$  replaced by  $-d$ . Therefore,  $\nabla f(x^*)^T d = 0$  for all  $d \in \mathbb{R}^n$ , which shows that  $\nabla f(x^*) = 0$ .

Assume that  $f$  is twice continuously differentiable, and let  $d$  be any vector in  $\mathbb{R}^n$ . For all  $\alpha \in \mathbb{R}$ , the second order Taylor expansion yields

$$f(x^* + \alpha d) - f(x^*) = \alpha \nabla f(x^*)^T d + \frac{\alpha^2}{2} d^T \nabla^2 f(x^*) d + o(\alpha^2).$$

Using the condition  $\nabla f(x^*) = 0$  and the local optimality of  $x^*$ , we see that there is a sufficiently small  $\varepsilon > 0$  such that for all  $\alpha \in (0, \varepsilon)$ ,

$$0 \leq \frac{f(x^* + \alpha d) - f(x^*)}{\alpha^2} = \frac{1}{2} d^T \nabla^2 f(x^*) d + \frac{o(\alpha^2)}{\alpha^2}.$$

Taking the limit  $\alpha \rightarrow 0$  and using the fact that  $\lim_{\alpha \rightarrow 0} o(\alpha^2)/\alpha^2 = 0$ , we obtain  $d^T \nabla^2 f(x^*) d \geq 0$ , showing that  $\nabla^2 f(x^*)$  is positive semidefinite.  $\square$

**Remark 1.3.** Suppose for a function  $f : \mathbb{R}^n \rightarrow \mathbb{R}$ , the point  $x^*$  is a local minimum of  $f$  along every line that passes through  $x^*$ , i.e., the function

$$g(\alpha) = f(x^* + \alpha d)$$

is minimized at  $\alpha = 0$  for all  $d \in \mathbb{R}^n$ . Then

$$0 = \left. \frac{dg}{d\alpha} \right|_{\alpha=0} = \nabla f(x^*)^T d = 0, \quad \forall d \in \mathbb{R}^n.$$

This shows that  $\nabla f(x^*) = 0$ , i.e., first order necessary condition is satisfied at  $x^*$ . This only shows that  $x^*$  is a stationary point and it need not be a local minimum of  $f$ . For example, consider  $f(y, z) = (z - py^2)(z - qy^2)$ , where  $0 < p < q$ . Here  $(0, 0)$  is one such stationary point that minimizes  $f$  along every line passing through it but  $(0, 0)$  is not a local minimum of  $f$ .

**Proposition 1.4** (Second Order Sufficient Optimality Conditions). *Let  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  be twice continuously differentiable over an open set  $U$ . Suppose that a vector  $x^* \in U$  satisfies the conditions*

$$\nabla f(x^*) = 0, \quad \nabla^2 f(x^*) \succeq 0.$$

*Then,  $x^*$  is a strict unconstrained local minimum of  $f$ . In particular, there exists a scalar  $\gamma > 0$  and  $\varepsilon > 0$  such that for all  $x \in \mathbb{R}^n$  with  $\|x - x^*\| < \varepsilon$ , we have*

$$f(x) \geq f(x^*) + \frac{\gamma}{2} \|x^* - x\|^2.$$

*Proof.* Denote by  $\lambda > 0$  the smallest eigenvalue of  $\nabla^2 f(x^*)$ . Then we have

$$d^T \nabla^2 f(x^*) d \geq \lambda \|d\|^2, \quad \forall d \in \mathbb{R}^n.$$

Using this relation, the hypothesis  $\nabla f(x^*) = 0$ , and the second order Taylor expansion, we have for all  $d$

$$\begin{aligned} f(x^* + d) - f(x^*) &= \nabla f(x^*)^T d + \frac{1}{2} d^T \nabla^2 f(x^*) d + o(\|d\|^2) \\ &\geq \frac{\lambda}{2} \|d\|^2 + o(\|d\|^2) \\ &= \left( \frac{\lambda}{2} + \frac{o(\|d\|^2)}{\|d\|^2} \right) \|d\|^2. \end{aligned}$$

Choose any  $\varepsilon > 0$  and  $\gamma > 0$  such that for all  $d \in \mathbb{R}^n$  with  $\|d\| < \varepsilon$ ,

$$\frac{\lambda}{2} + \frac{o(\|d\|^2)}{\|d\|^2} \geq \frac{\gamma}{2}.$$

□