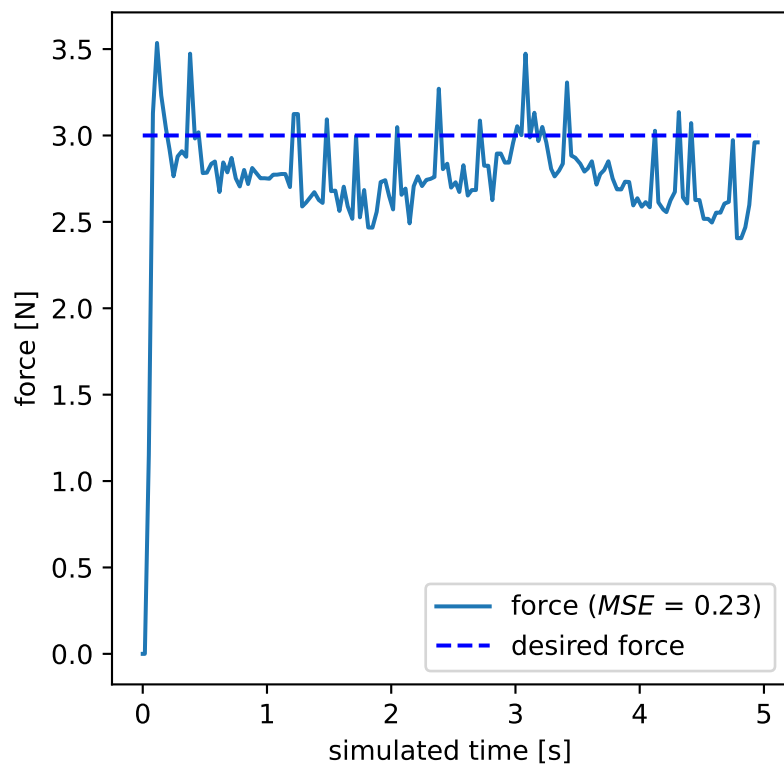
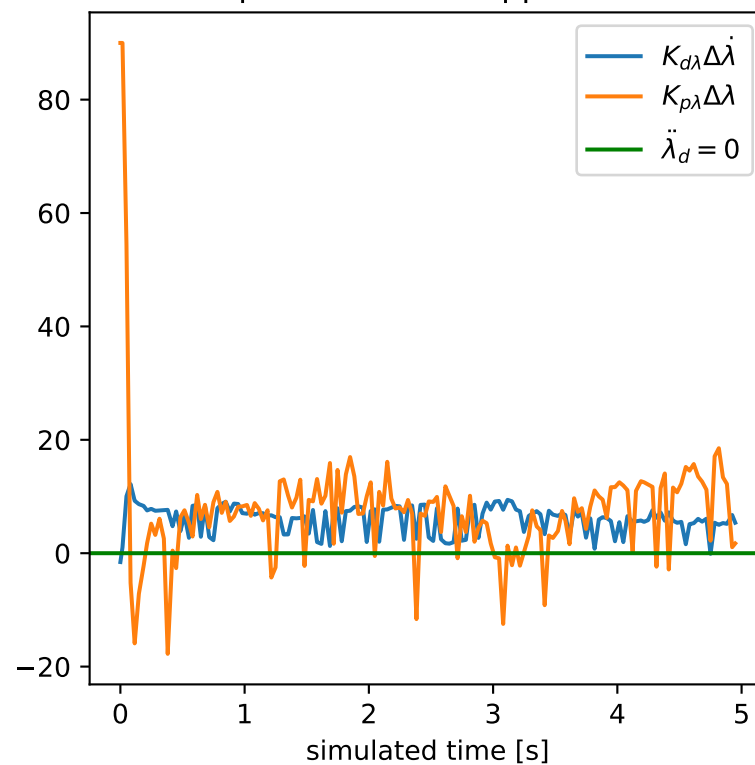


# Performance of HFMC (sim)

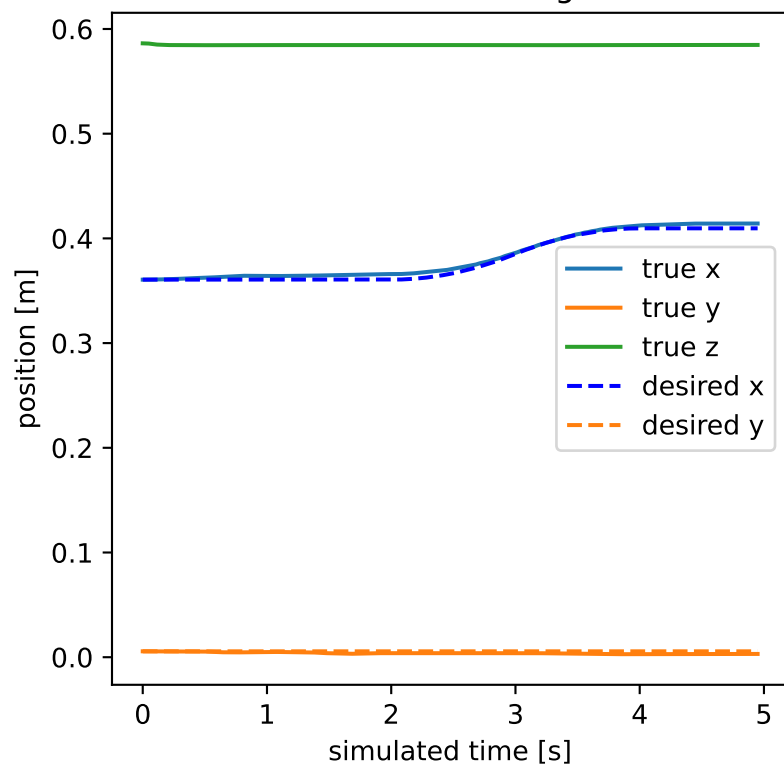
## Contact force



## Components of the applied force



## Motion tracking



## Deviation from desired orientation

