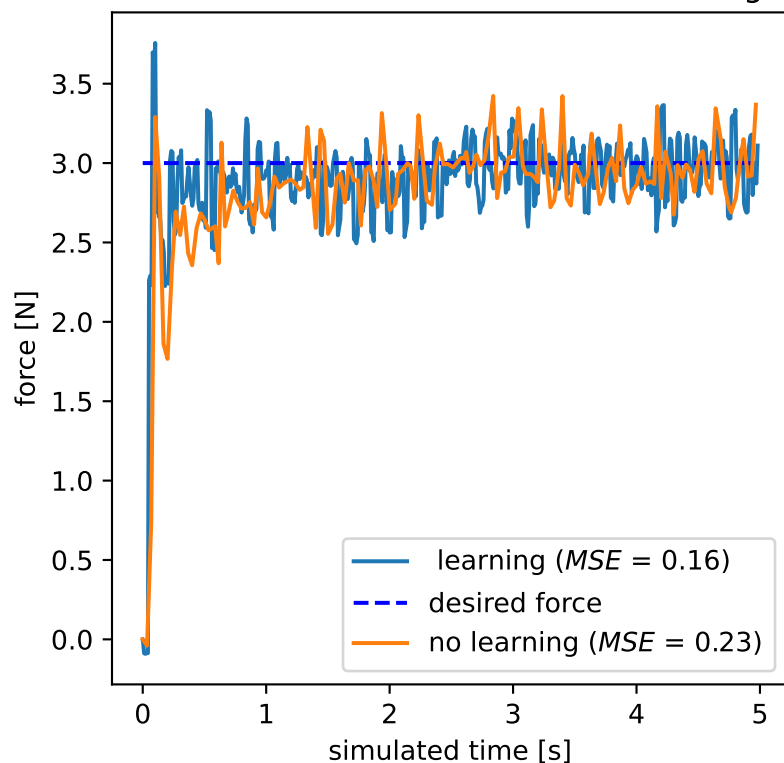
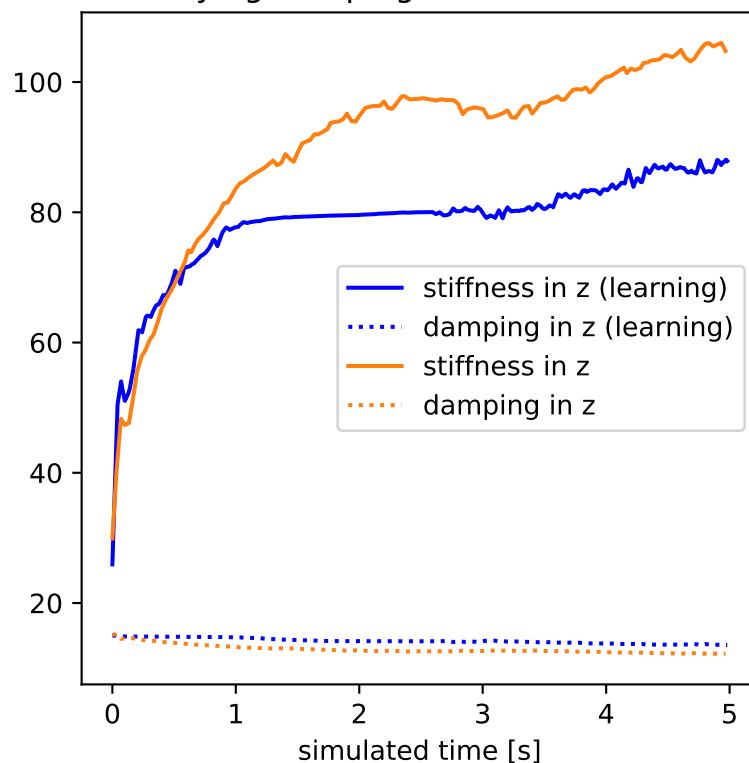


Force-based VIC with learning (sim)

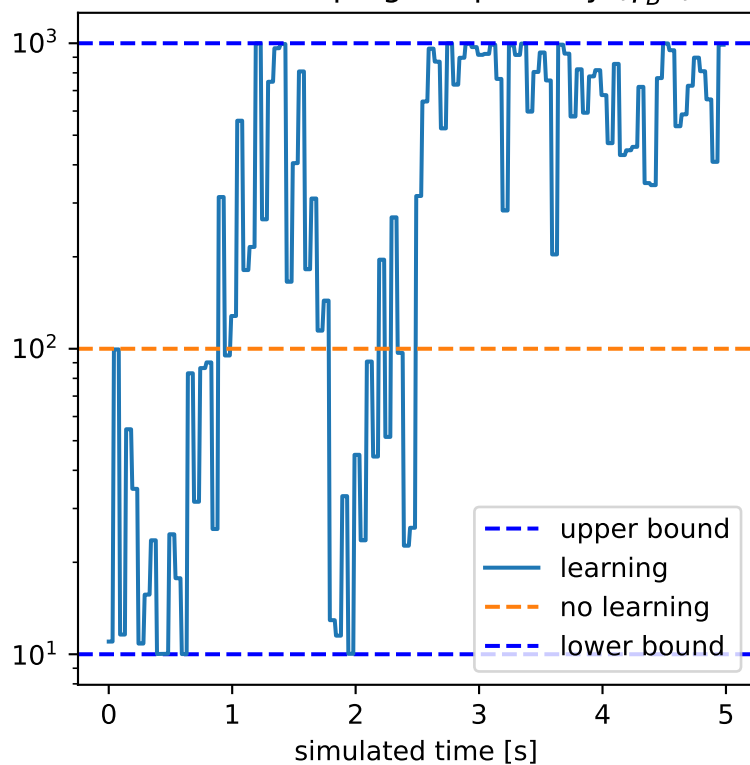
Contact force with- and without learning



Varying damping and stiffness in z



Rate of damping-adaptability (γ_B^{-1})



Rate of stiffness-adaptability (γ_K^{-1})

