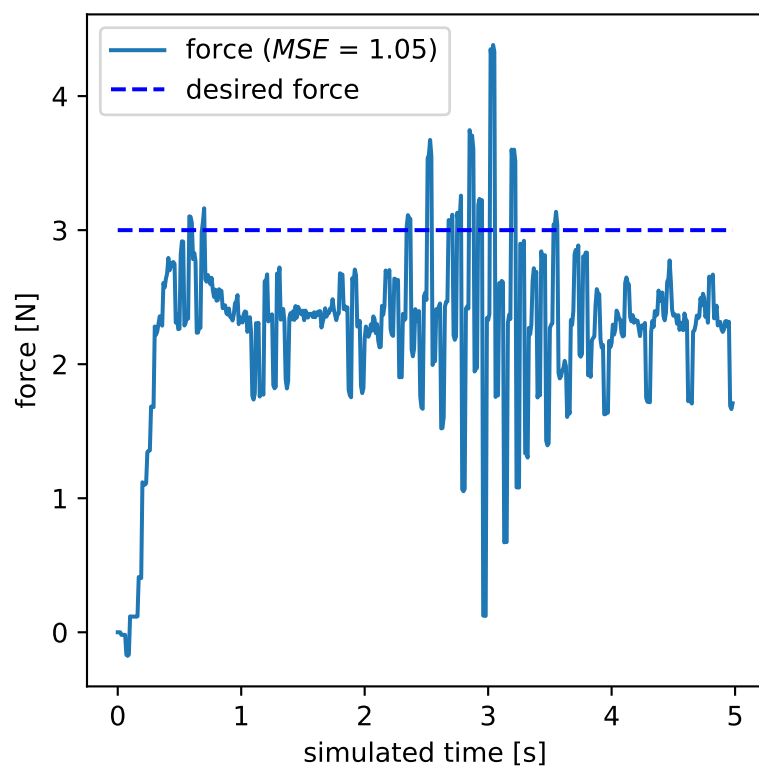
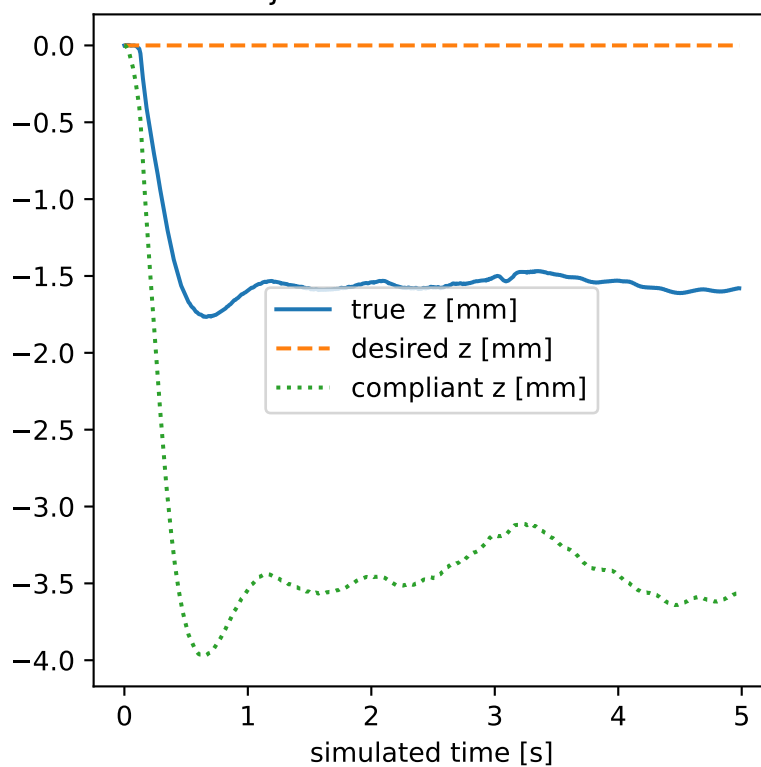


# Performance of Admittance Control (sim)

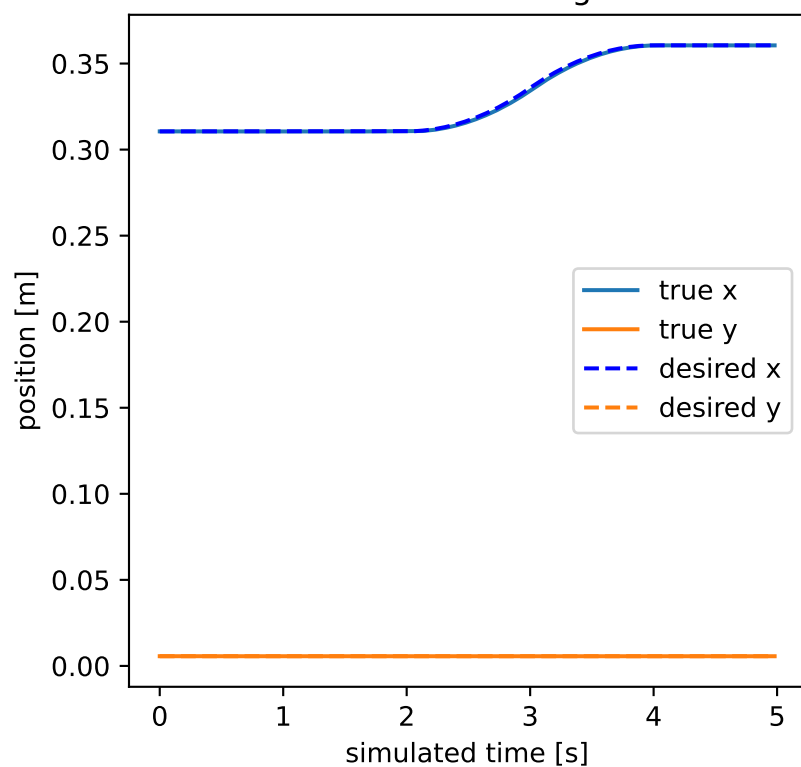
## Contact force



## Positional adjustments in z relative to surface



## Motion tracking



## Deviation from desired orientation

