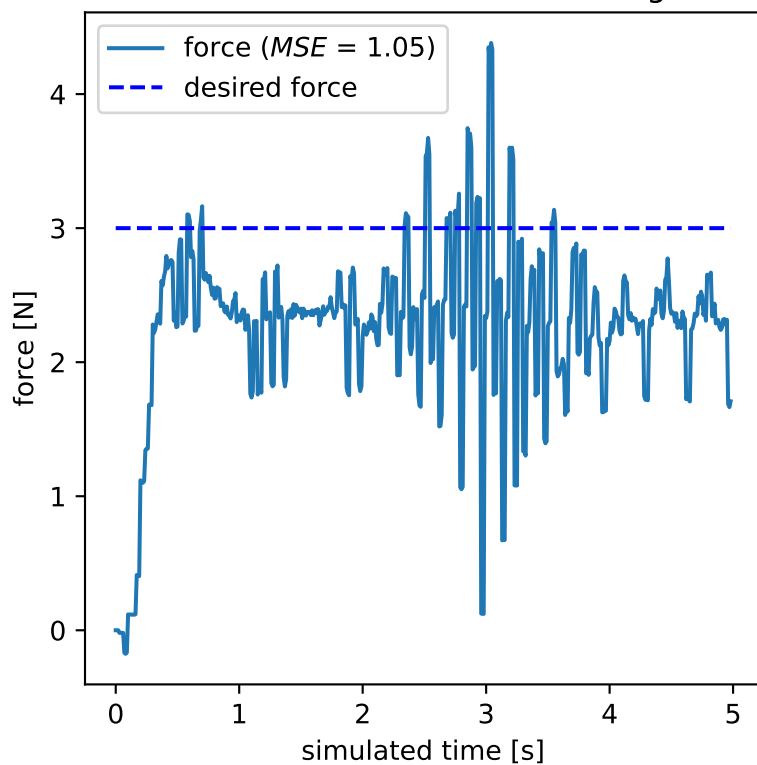
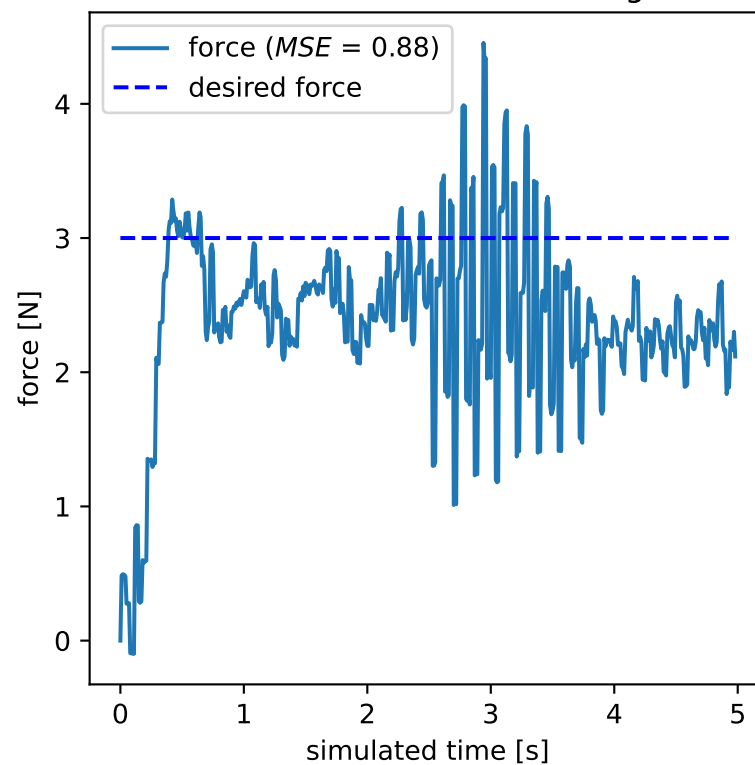


Performance of Learning-based Admittance Control (sim)

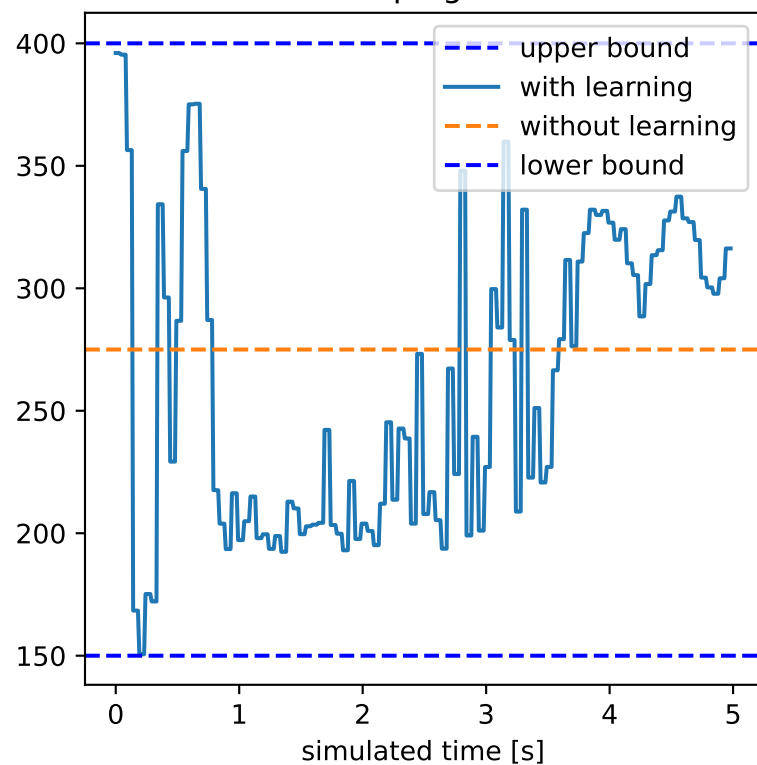
Contact force without learning



Contact force with learning



Damping in z



Stiffness in z

