
Instrument Timbre Transformation using Gaussian Mixture Models and Centroid and Matrix Transformation

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1 Introduction

Timbre is the characteristic of instruments. People use timbre to identify different musical instruments. Sometimes, people may want to hear a piece with different instrumentation. Timbre transformation would expand the scope of sounds of any existing music, for instance, we could transform a piece of classical guitar performance into one performed with electric guitar without having the musician playing it all over. Together with the technique of instrumentation separation, we could apply timbre transformation on each individual instrument and yield a high-quality remix of any existing piece of music.

2 Related Work

In the previous work of [1], Settel, et al.(1994) use FFT/IFFT in real time to conduct digital signal processing in Max programming environment, which requires no compilation for digital signal processing(DSP). They use what's called overlap-add technique, including the following steps: (1) windowing input signal (2) transformation of the input signals into the spectral domain using FFT (3) operate on signal's spectra (4) resynthesis of modified spectra using IFFT (5) windowing the output signal. Their operation in the spectral domain includes convolution, addition, square root. We want to apply similar procedures for our timbre transformation project on data from Megenta's NSynth.

3 Dataset

After loading NSynth Dataset of guitar family[4], we obtain train, test and validation sub directories. Within each sub directory, audio files is formatted as: guitar_source_identifier_pitch_velocity.wav, (e.g.,guitar_acoustic_000-021-025.wav)

In each sub directory, we have 3 sources: acoustic, electronic and synthetic; number of identifiers varies between sources, pitch ranges from 21 to 108 and 5 velocity options: 25, 50, 75, 100, 127.

4 Method

Our goal is to transform audio of original source S (acoustic) to target source T (electronic). To simplify the problem for now, we take S and T to be of the same family, which is the guitar and keyboard family in our experiment.

27 4.1 Approach 1: Gaussian Mixture Models

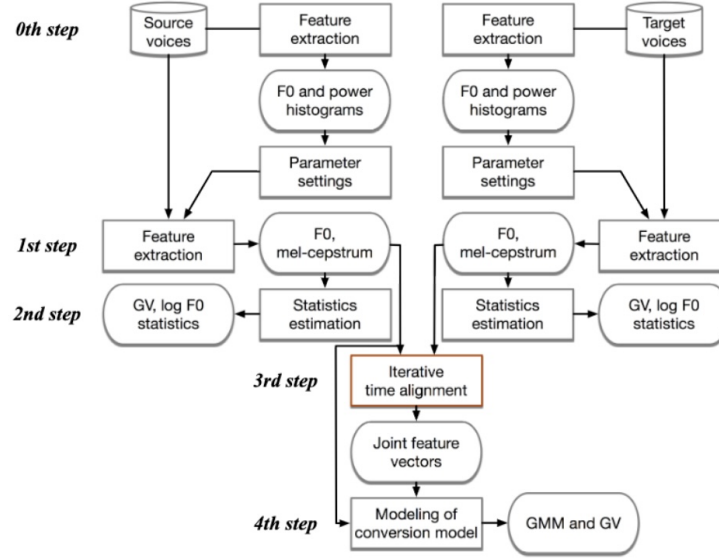


Figure 1: Gaussian Mixture Models

28 We apply a Voice Conversion toolkit “sprocket”[5] to our dataset. Sprocket first extracts acoustic
 29 features like F0 and the global variance(GV), then it estimates statistics of the extracted acoustic
 30 features, such as the mean and standard deviation.

31 To model a joint probability density function based on the GMM, frame-aligned joint feature vectors
 32 are extracted with an iterative Dynamic Time Wrapping(DTW) in sprocket. The joint probability
 33 density function based on the GMM is trained as the conversion model for the conversion process
 34 using the refined joint feature vectors.

35 Sprocket transforms acoustic features with GMM from the original sound. Then it converts the
 36 original sound into the converted sound by utilizing excitation generation and the mel log spectral
 37 approximation (MLSA) filter (i.e., a vocoder) based on transformed acoustic features.

38 4.2 Approach 2. Centroid and Matrix Transformation

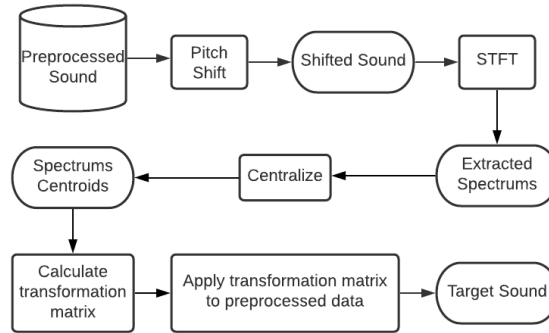


Figure 2: Centroid and Matrix Transformation

39 We model our goal as we would like to obtain a transformation matrix W that would transform the
 40 original source S to an approximated spectrum of target source as T' which would be close to T .

41 To obtain such transformation matrix, our idea is to find spectrum centroid of S and T , s and t . Then
 42 use s and t to compute the transform matrix W between the two spectrum centroids. Our method to
 43 compute such transformation W is taking the pseudo inverse of one:

$$W = P_{inv}(s) \times t. \quad (1)$$

44 Since we want our centroids to focus on timbre information and not be diverged by varying pitches in
 45 our training data set. We make an assumption: performing pitch-shift on our data would not cause
 46 too much loss on its timbre information. Based on this assumption, we pitch-shifted our training set
 47 to pitch center, and used a range of pitch-shifted data with the original pitch centered around the pitch
 48 center for computing centroids.

49 In our experiment, we tried different pitch centers and different range of pitch range around the pitch
 50 center to obtain better centroid representation. The centroid representation would give us a better
 51 transformation matrix. To choose the best parameter for pitch center and range, we were making our
 52 judgments based on the subjective listening experience of the timbre transformed version and the
 53 target timbre audio samples.

54 Our method for computing centroids is quite naive and this is definitely the part we want to improve
 55 on. For now, the centroid of each source is computed by adding all spectrum in the pitch-shifted
 56 training data set then take its mean. The resulting centered audio suffered recognizable loss phase
 57 cancellation.

58 5 Evaluation metrics

59 We use Mel cepstral distortion (MCD) [6] as evaluation metric because it's a popular objective
 60 measure for evaluating the timbre similarity [7]. MCD represents the distance between the MFCC
 61 feature of spectrum of the transformed electric guitar sound set and the standard electric guitar sound
 62 set, and the formula is as follows:

$$MCD(y - \hat{y}) = \frac{10\sqrt{2}}{\ln 10} \|y - \hat{y}\|_2 \quad (2)$$

63 Where y is the standard sound, \hat{y} is the transformed sound and the coefficient in front of the norm is
 64 to convert the unit to decibels.

65 6 Results

66 6.1 Result of Gaussian Mixture Models

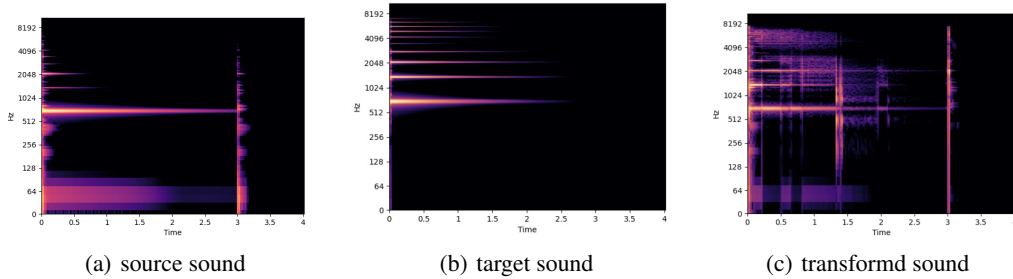


Figure 3: guitar family

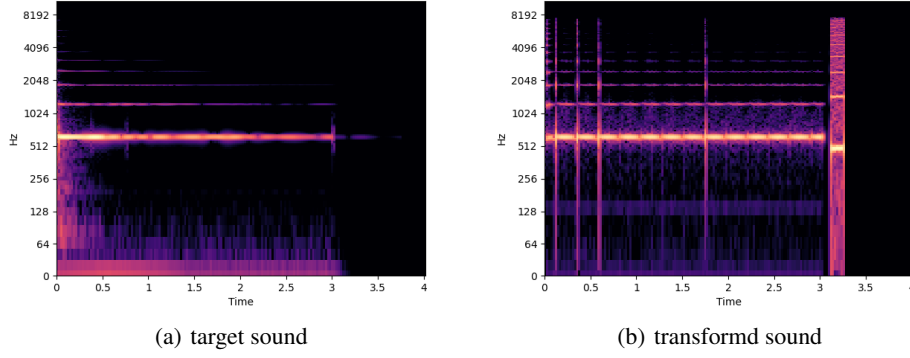


Figure 4: keyboard family

67 We trained the sprocket on the parallel dataset to learn the model. The result generated from the
 68 sprocket has successfully erased the lower frequency of the source sound (Figure 3 (a)).

69 We then calculated the average norm distance between MFCC feature of the source sound S and the
 70 target sound of same pitch, T . The average MCD distance between S and T is 2450.

71 Since the source sound has a spike near its end, sprocket moved as much lower frequencies to the
 72 higher frequencies as possible (Figure 3 (c)).

73 However, almost all of our acoustic guitar source sounds contains a clap-ish sound at their own
 74 timing; sprocket would falsely learn to generate an arbitrary spike in the middle of the spectrogram
 75 for all transformed sounds.

76 We also did the transformation on the keyboard sounds (See figure4 (a) and (b)).

6.2 Result of Centroid and Matrix Transformation

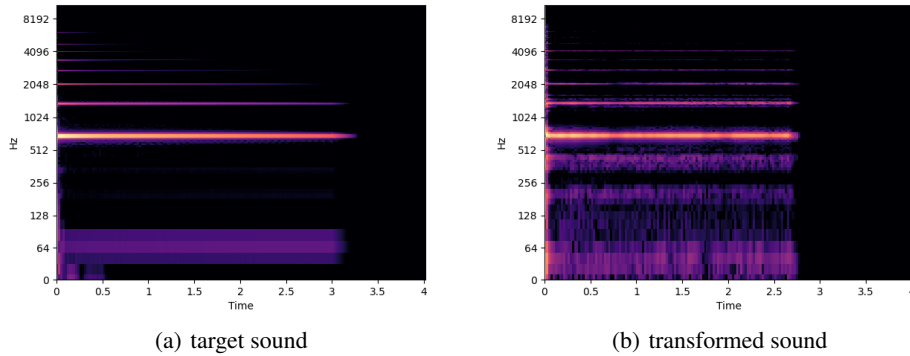


Figure 5: guitar family

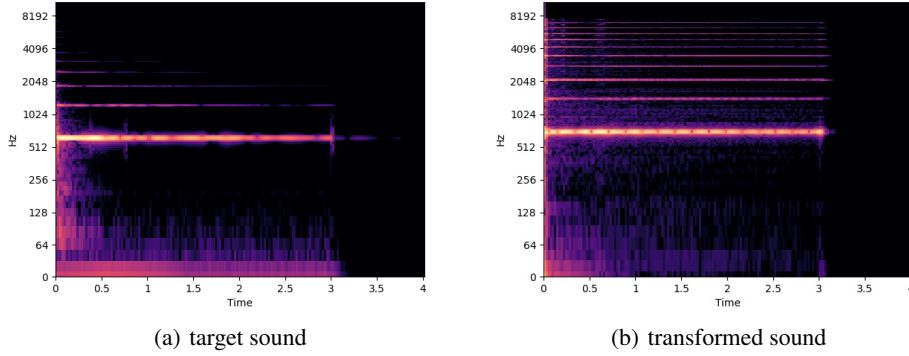


Figure 6: keyboard family

78 In our experiment, we take the original source S as acoustic guitar and keyboard samples and target
 79 source T as electronic guitar and keyboard samples.

80 After getting the transformation matrix W between spectrum centroids of s and t , we would apply
 81 W to transform acoustic source to electronic source in the testing data set.

82 We tested our transform on the testing set by randomly selecting acoustic audio file S and electronic
 83 audio file T of the same pitch. Then conduct the transform on the S and collect the transformed audio
 84 T' . We then calculated the average norm distance between MFCC feature of T' and the electronic
 85 source audio of same pitch, T . The average MCD distance between T and T' of guitar is 849. The
 86 average MCD distance of keyboard family is 1708.

87 Figure 5(a) and 6(a) are the spectrum of one of the electronic guitar and keyboard source audio from
 88 testing data set, figure 5(b) and 6(b) is the spectrum of the transformed electronic guitar and keyboard
 89 from one of the acoustic source audio of the same pitch from testing data set.

90 7 Discussion and analysis

Table 1: Compare 2 approach in different instrument family

MCD Distance	Keyboard	Guitar
GMM (sprocket)	3574	1708
Centroid and Matrix Transformation	2450	849

91 In this timbre transformation task, the difficulty lies not only in how to extract the feature that are
 92 sufficient to represent timbre for transformation, but also in the need to use these feature to synthesize
 93 the transformed audio. In table 1, we can see that our Centroid and Matrix Transformation (see
 94 section 4.2) has better performance than GMM(sprocket) (see section 4.1) in keyboard and guitar
 95 family(both transform from acoustics source to electronics source).

96 One reason is that our Centroid and Matrix Transformation uses all the frequency spectrum as
 97 the feature, and there is almost no loss of information during the transform process. Therefore,
 98 except that the synthesized transformed audio sounds dull because of pitch distortion due to some
 99 aliasing(because of pitch shifting), most of the timbre-related information is reserved to make the
 100 audio sound more fidelity.

101 On the other hand, we find it to be difficult to train a GMM to model all different guitars because
 102 even in the same instrument family, different guitars have different timbre.

103 For the next improvement, using other ways of centralize, such as K-means on dimension reduction
104 data samples to obtain multiple centroids, which could enhance the generalizing ability of Centriod
105 and Matrix Transformation method.

106 **References**

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