

Sx no: 12

Decision tree Classification

Aim:- To implement the decision tree classification

from google.colab import drive

drive.mount("/content/gdrive")

import pandas as pd

import numpy as np

import matplotlib.pyplot as plt

import seaborn as sns

% matplotlib inline

x, y = make_regression(n_samples=1000,
noise=0.05, n_features=100)

x.shape, y.shape = (1000, 100); (1000, 1)

x_train, x_test, y_train, y_test = train_test.
split(x, y, test_size=0.2, shuffle=True, random-
state=42)

id = MLPRegressor(max_iter=1000)

id.fit(x_train, y_train)

i, stop = x_set[:, 0].max() + 1, step=0.01)

np.arange(start = x_set[:, 1].min(),

i, stop = x_set[:, 1].max() + 1, step=0.01)

```

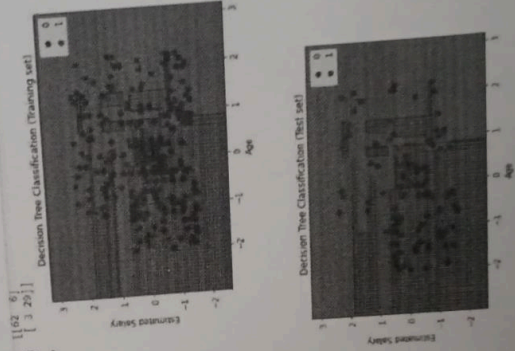
plt.constant(x1, x2, classifier.predict
(x1.shape[0], x2.shape[0]))
plt.array(x1.shape, alpha=0.75)
cmap = ListedColormap(['red', 'green'])
plt.xlim(x1.min(), x1.max())
plt.ylim(x2.min(), x2.max())
for i, j in enumerate(np.unique(y_set)):
    plt.scatter(x_set[y_set == j, 0],
                y_set[y_set == j, 1], c = ListedColormap(['red', 'green'])
plt.show()

```

O/P

Images of That

OUTPUT:



Result

Thus the program was successfully executed and O/P is verified