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**Vellore Institute of Technology**  
(Deemed to be University under section 3 of UGC Act, 1956)

**School of Electronics Engineering (SENSE)**

**B. Tech – Electronics & Communication Engineering**

**BECE403E – EMBEDDED SYSTEM DESIGN**

**LAB RECORD**

**(lab slot L49+L50)**

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**Submitted To**

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**DATE: 27/03/2025**

**Slot:** L49+L50

**Date:** 27/03/2025

## **LAB – 11: SPI**

### **AIM:**

To understand the working of Nucleo64-STM32L152RE Board and to perform the following tasks:

**Lab Task-1:** Read input from master and display on slave.

**Lab Task-2:** Exchange of Button press state between master and slave.

**Lab Task-3:** Half Adder.

### **SOFTWARE REQUIRED:**

ARM Keil Studio (MBED Online compiler)

### **Hardware Required:**

Micro USB cable, 2 Nos. NUCLEO64-STM32L152 Board, LEDs, Jumper Wires (M-F and M- M), Breadboards.

### **Procedure:**

1. Log in to ARM Keil Studio.
2. Go to File → New → Mbed Project.
3. Select mbed2-example-blinky from the Example project drop-down.
4. Name your project and click Add project.
5. Open main.cpp from the project folder and edit the code as needed.
6. Check the Problems tab for errors.
7. If error-free, connect the Nucleo Board via Micro USB.
8. Click the Play icon to upload and run the code on the board.

## **PROGRAM:**

**Lab Task 1:** Read input form master and display on slave.

## **CODE:**

MASTER:

```
#include "mbed.h"
```

```
SPI spi(PB_15, PB_14, PB_13);
```

```
DigitalOut cs(PB_12);
```

```
Serial pc(USBTX, USBRX);
```

```
int main() {
```

```
char send_val;
```

```
pc.printf("Press any key to start...\n");
```

```
while (1) {
```

```
send_val = pc.getc();
```

```
pc.printf("%c", send_val);
```

```
cs = 0;
```

```
spi.write(send_val);
```

```
cs = 1;
```

```
wait(0.01);
```

```
}
```

```
}
```

SLAVE:

```
#include "mbed.h"
```

```
SPISlave spi(PB_15, PB_14, PB_13, PB_12);
```

```
Serial pc(USBTX, USBRX);
```

```
int main() {
```

```
char recd_val; pc.printf("Received word is...\n");
```

```
while (1) {
```

```
if (spi.receive()) { recd_val = spi.read();
```

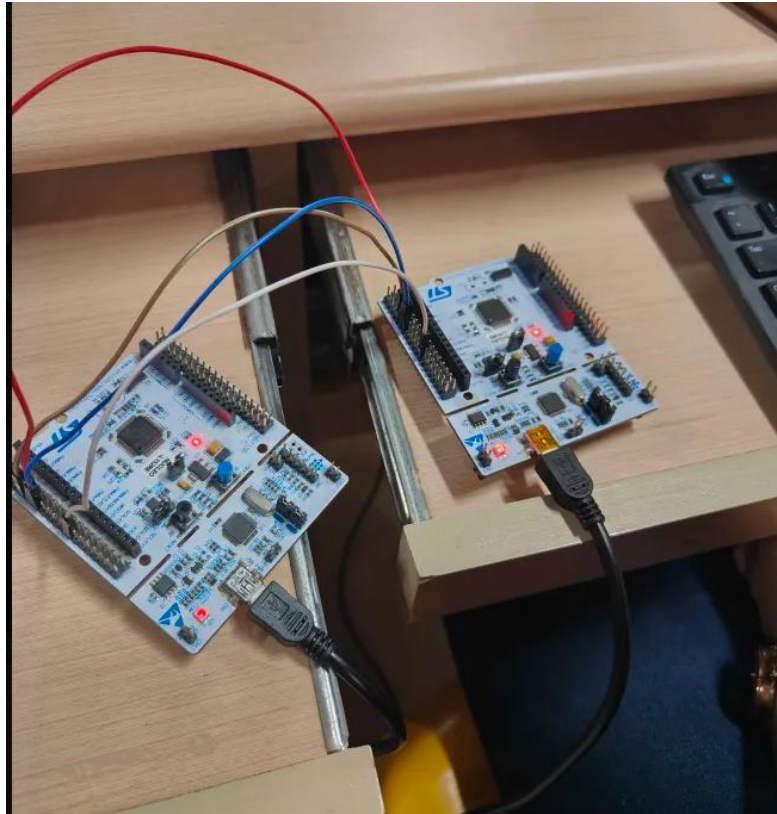
```
pc.printf("%c", recd_val);
```

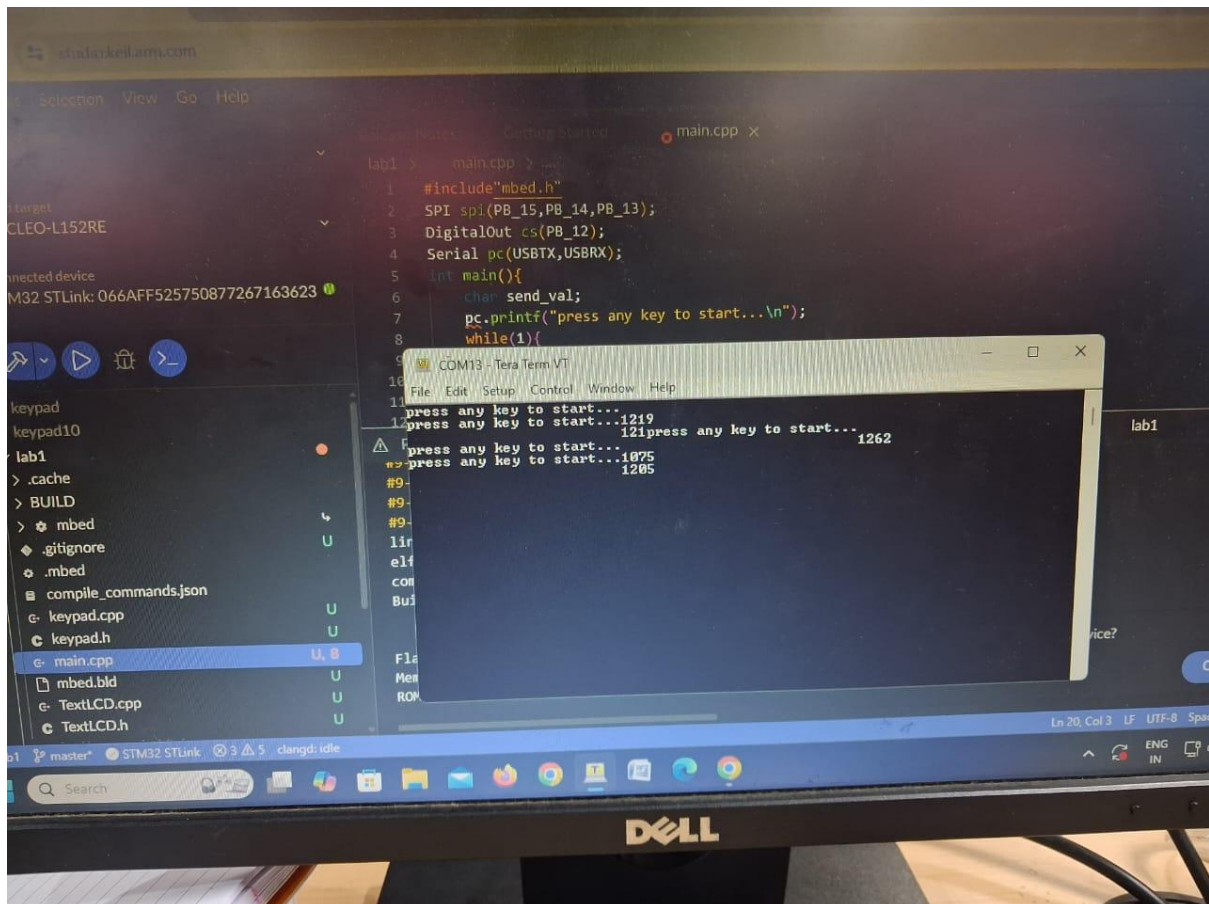
```
}
```

```
}
```

```
}
```

## **OUTPUT:**





**Fig.1: Reading input form master and display on slave.**

**Lab Task-2: Exchange of Button press state between master and slave.**

### CODE:

MASTER:

```
#include "mbed.h"
SPI ser_port(PB_15, PB_14, PB_13);
DigitalOut cs(PB_12);
Serial pc(USBTX, USBRX);
```

```
DigitalOut led(PC_8);
DigitalIn switch_ip(PC_4);
```

```
int switch_word_tx;
char tx_val;
```

```
int main() {
```

```

while (1) {
    switch_word_tx = 0x00;
    if (switch_ip == 1)
        switch_word_tx = switch_word_tx | 0x01;
    cs = 0;
    tx_val = ser_port.write(switch_word_tx);
    cs = 1;
    wait(1);
    led = 0;
    tx_val = tx_val & 0x01;

    if (tx_val == 1) led = 1;
}
}

```

SLAVE:

```
#include "mbed.h"
```

```

SPISlave ser_port(PB_15, PB_14, PB_13, PB_12);
Serial pc(USBTX, USBRX);
DigitalOut led(PC_8);
DigitalIn switch_ip(PC_4);

```

```

int switch_word_rx;
char rx_val;

```

```

int main() {
    while (1) {
        switch_word_rx = 0x00;

        if (switch_ip == 1) {
            switch_word_rx = switch_word_rx | 0x01;
        }

        if (ser_port.receive()) {
            rx_val = ser_port.read();

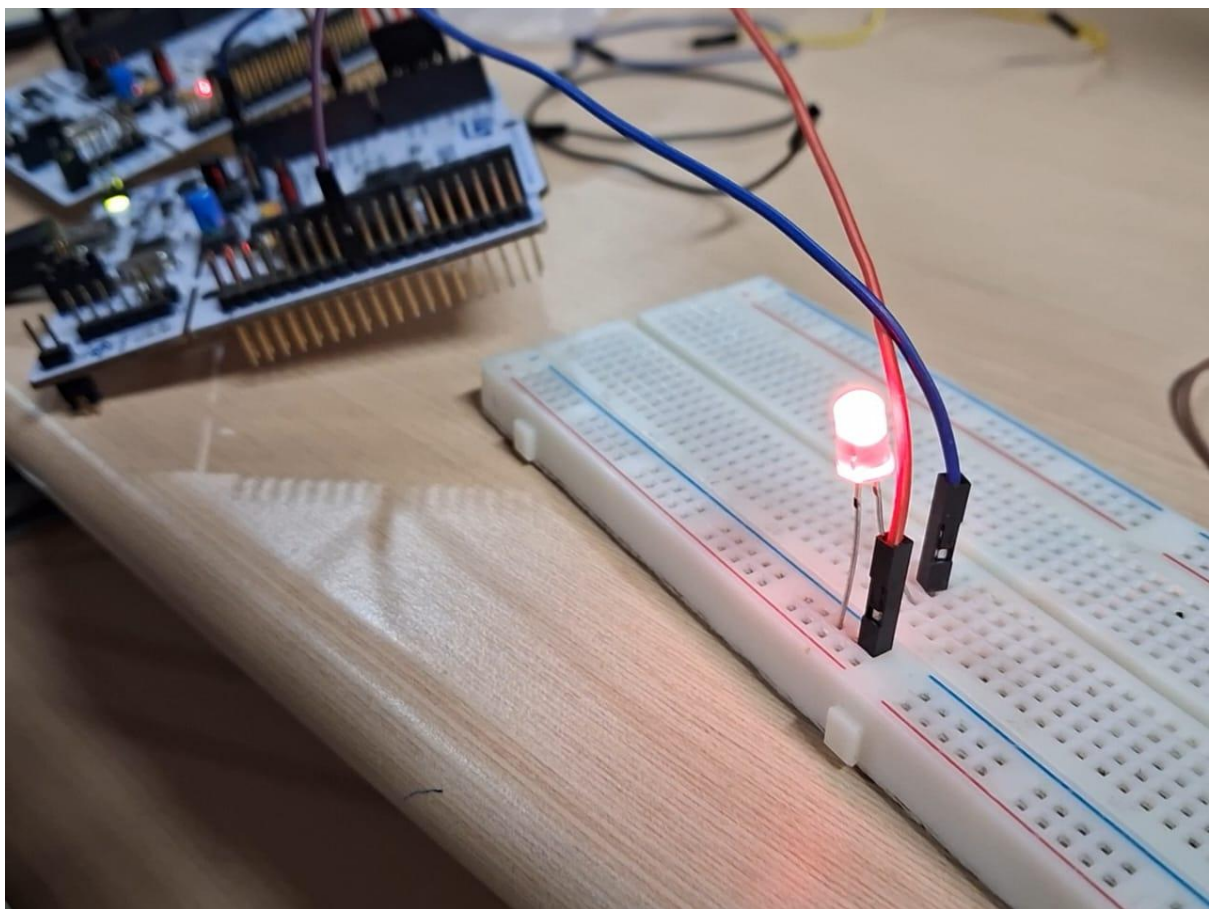
            ser_port.reply(switch_word_rx);
        }

        led = 0;
        rx_val = rx_val & 0x01;

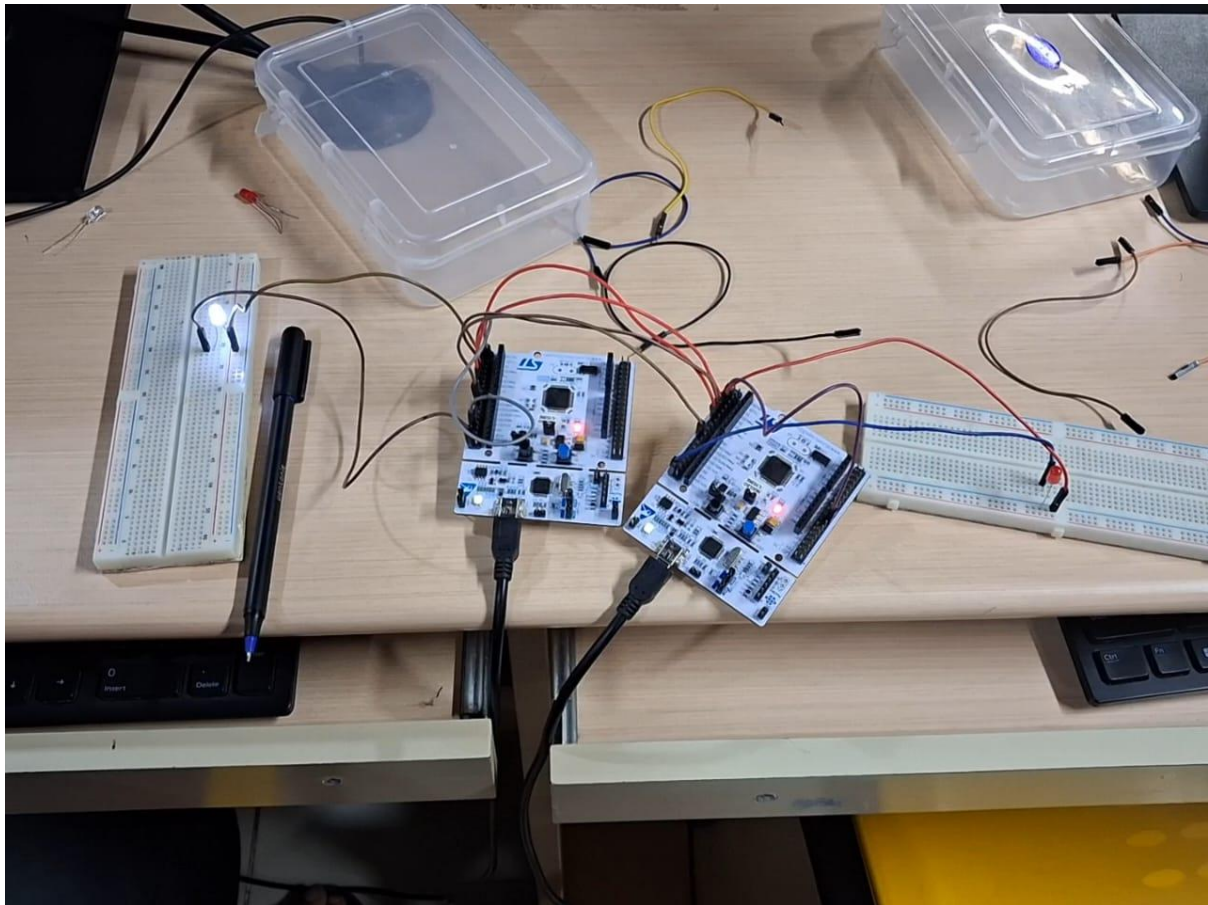
        if (rx_val == 1) { led = 1;
        }
        }
    }
}

```

**OUTPUT:**







**Fig.2: Button Press state between master and slave**

### **Lab Task-3: Half Adder.**

#### **CODE:**

MASTER:

```
#include "mbed.h"
```

```
SPI ser_port(PB_15, PB_14, PB_13);
```

```
DigitalOut cs(PB_12);
```

```
Serial pc(USBTX, USBRX);
```

```
DigitalOut sum_led(PC_8);
```

```
DigitalIn switch_A(PC_4);
```

```
char received_sum;
```



```

int A;
int main() {
ser_port.format(8, 0);
ser_port.frequency(1000000);
cs = 1;
while (1) {
A = switch_A.read();
pc.printf("Master: A = %d\r\n", A);
cs = 0;
wait_us(10);
received_sum = ser_port.write(A);
wait_us(10);
cs = 1;
pc.printf("Master Received Sum: %x\r\n", received_sum);
sum_led = received_sum;
wait(0.5);
}
}

```

SLAVE:  
#include "mbed.h"

```

SPISlave ser_port(PB_15, PB_14, PB_13, PB_12);

```

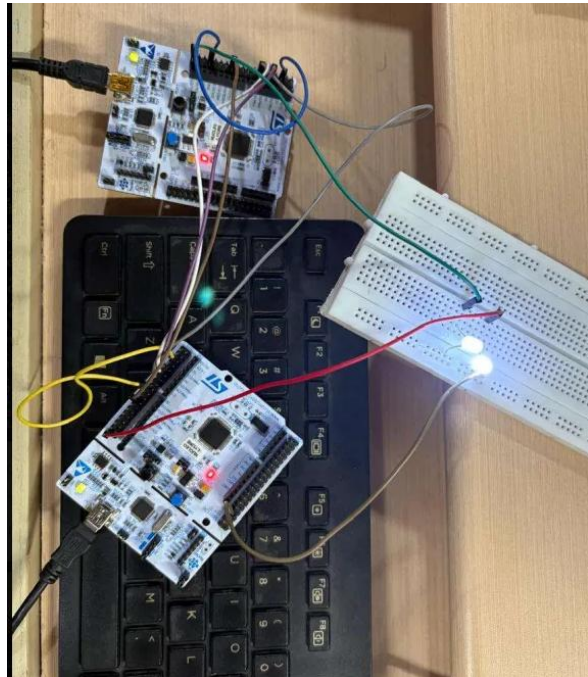
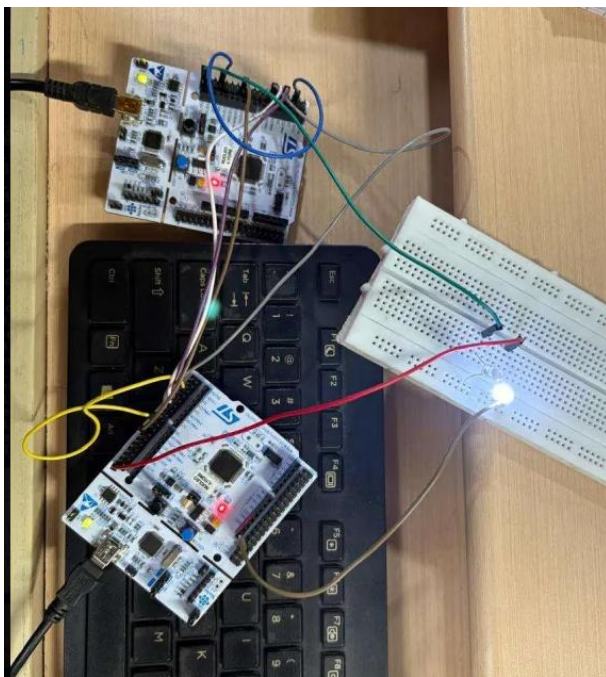
```

Serial pc(USBTX, USBRX);
DigitalOut carry_led(PC_8);
DigitalIn switch_B(PC_4);
char A, B, sum, carry;
int main() {
while (1) {
if (ser_port.receive()) {
A = ser_port.read();
B = switch_B.read();
pc.printf("Slave: Received A = %d, B = %d\r\n", A, B);
sum = A ^ B;
carry = A & B;
ser_port.reply(sum);
carry_led = carry;
pc.printf("Slave: Sum = %d, Carry = %d\r\n", sum, carry);
}
}
}

```

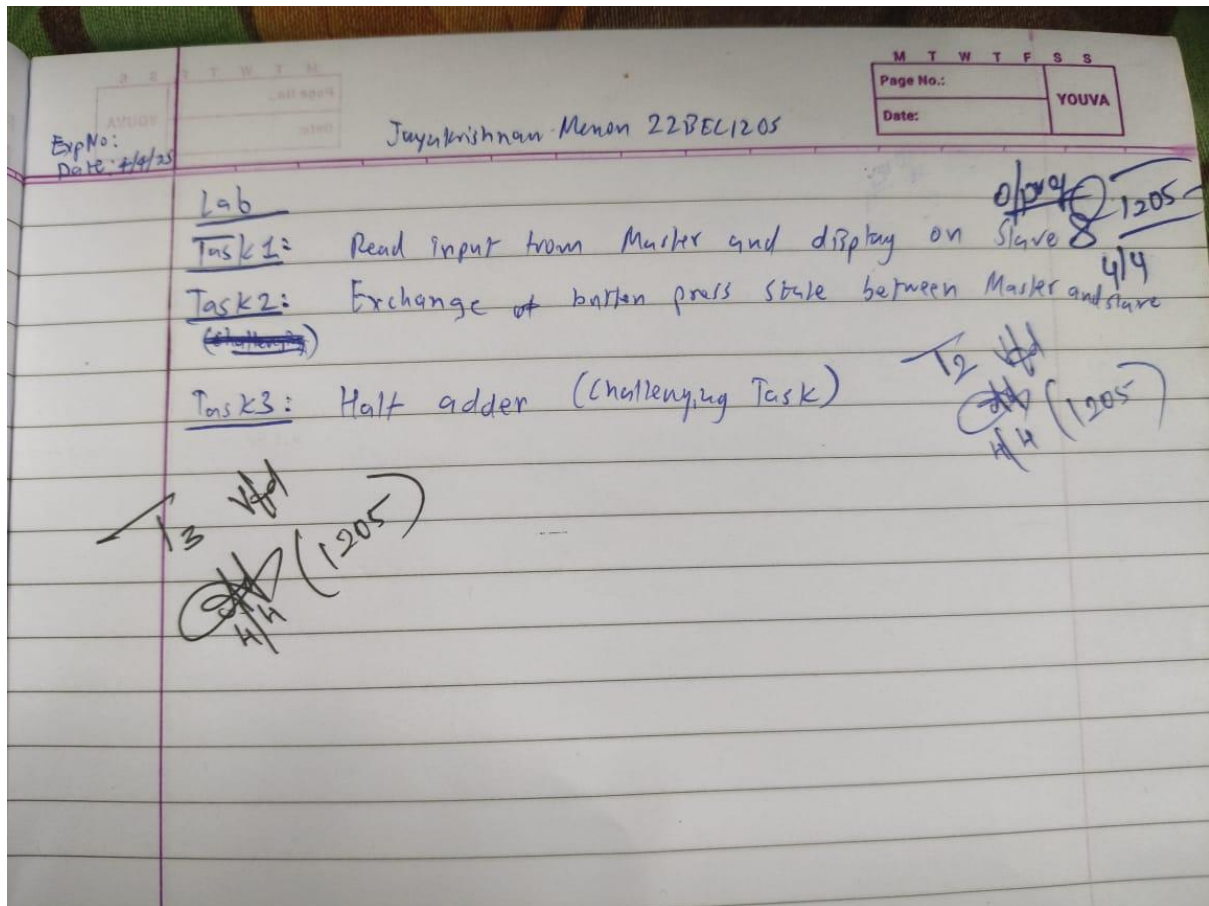
## **OUTPUT:**

```
COM4 - Tera Term VT
File Edit Setup Control Window Help
Slave: Sum = 1, Carry = 0
Slave: Received A = 1, B = 0
Slave: Sum = 1, Carry = 0
Slave: Received A = 1, B = 0
Slave: Sum = 1, Carry = 0
Slave: Received A = 1, B = 1
Slave: Sum = 0, Carry = 1
Slave: Received A = 1, B = 1
Slave: Sum = 0, Carry = 1
Slave: Received A = 1, B = 1
Slave: Sum = 0, Carry = 1
Slave: Received A = 1, B = 1
Slave: Sum = 0, Carry = 1
Slave: Received A = 1, B = 0
Slave: Sum = 1, Carry = 0
Slave: Received A = 1, B = 0
Slave: Sum = 1, Carry = 0
Slave: Received A = 1, B = 0
Slave: Sum = 1, Carry = 0
Slave: Received A = 1, B = 0
Slave: Sum = 1, Carry = 0
```



**Fig.3: Half Adder Logic**

## OUTPUT VERIFICATION:



## RESULT:

Thus, we have successfully implemented and executed using Nucleo64- STM32L152RE Board and terra term application to perform the following tasks.

- Read the input from Master and display on Slave.
- Exchange of button press state between Master and slave.
- Half Adder Implementation using SPI Protocol.