

Computer-aided Interpretable Features for Leaf Image Classification

Abstract

Plant species identification is time consuming, costly, and requires lots of efforts, and expertise knowledge. The studies on medicinal plant identification are often performed based on medicinal plant leaf images. This is because plant leaves contain a large number of diverse set of features such as shape, veins, edge features, apices etc. that are useful in identifying different medicinal plants. In recent, many researchers use deep learning methods to classify plants directly using plant images. While deep learning models have achieved a great success, the lack of interpretability limit their widespread application. To overcome this, we explore the use of interpretable, measurable and computer-aided features extracted from plant leaf images. Image processing is one of the most challenging, and crucial steps in feature-extraction. The purpose of image processing is to improve the leaf image by removing undesired distortion. The main image processing steps of our algorithm involves: i) Convert original image to RGB (Red-Green-Blue) image, ii) Gray scaling, iii) Gaussian smoothing, iv) Binary thresholding, v) Remove stalk, vi) Closing holes, and vii) Resize image. The next step after image processing is to extract features from plant leaf images. We introduced 52 computationally efficient features to classify plant species. These features are mainly classified into four groups as: i) shape-based features, ii) color-based features, iii) texture-based features, and iv) image-space statistics-based features. Length, width, area, texture correlation, monotonicity and scagnostics are to name few of them. We explore the ability of features to discriminate the classes of interest under supervised learning and unsupervised learning settings. For that, supervised dimensionality reduction technique Linear Discriminant Analysis (LDA), and unsupervised dimensionality reduction technique as Principal Component Analysis (PCA) are used to convert and visualize the images from digital-image space to feature space. All the applications are performed on Flavia and Swedish open source benchmark leaf datasets. The results show that the features are sufficient to discriminate the classes of interest under both supervised and unsupervised learning settings. The results of this study are beneficial for the researchers working in the field of developing automated plant identification and classification systems.

1 Introduction

Leaf identification is becoming very popular in classifying plant species. Plant leaf contains significant number of features that can help people to identify and classify the plant species. In medical perspective, medicinal plants are usually identified by practitioners based on years of experience through sensory or olfactory senses. The other method of recognizing these plants involves laboratory-based testing, which requires trained skills, data interpretation which is costly and time-intensive. Automatic ways to identify medicinal plants are useful especially those that are lacking experience in medicinal plant recognition. Statistical machine learning techniques play a crucial role in the development of automatic system to identify medicinal plants. In developing such system image processing and feature extraction play crucial roles.

The main aim of image processing is to extract important features by removing undesired noise and distortion (Waldchen and Mader 2018). Image processing steps include image segmentation (Anantrasirichai, Hannuna, and Canagarajah 2017), image orientation, cropping, grey scaling, binary thresholding, noise removal, contrast stretching, threshold inversion, image normalization, and edge recognition are some of image processing techniques applied in recent research. These steps can be applied parallelly or individually, on several times until the quality of leaf image reaches a specific threshold.

The second step is feature extraction, which identifies and encodes relevant features from leaf images (Waldchen and Mader 2018). This is a challenging task due to the structural diversity of the leaf images.

Therefore, in recent years, many researchers use deep learning methods to classify plants directly using plant images (Wu et al. 2007; Azlah et al. 2019; Herdiyeni and Wahyuni 2012). While deep learning models have achieved a great success, the most models remain complex black boxes. The lack of interpretability limit their widespread application.

A digital image is a combination of pixels from three different color planes red, green and blue. Images are stored in computers as three separate matrices corresponding to the red, green and blue color channels of the image. The three separate matrices corresponding to intensities of colors at different positions of the image (Gonzalez and Woods 2006).

The main aim of feature extraction is to reduce dimensionality of this information by obtaining measurable patterns of leaf images. For example, shape, color, and texture are some of the patterns that may be observed. In this paper we introduce a collection of interpretable, measurable and computer-aided features that are useful in image leaf classification. This feature collection includes several pre-established features identified through a thorough review of literature. Other than existing features, we introduce a number of features computed based on the cartesian coordinate of the images. Furthermore, we explore the ability of features to discriminate the class of interest under supervised learning setting and unsupervised learning setting.

The paper is organized as follows. In the first section, describes about the steps of image processing. Preprocessing is necessary before extracting features from the images. In section 2, discusses about feature extraction in in-detail because features are highly influenced by the plant species to be classified. Under this section, we discuss about mainly four types of features as shape, color, texture, and diagnostics and how to extract them. The next section 3, discuss about applications of leaf features. This section consists of details about the datasets that are used to explain the applications, and visualization of leaf images in the feature space using supervised, and unsupervised dimensionality reduction techniques. In section 4, consist of summary of the software and packages that use to extract the features. Some discussion about the outputs and concluding remarks are given in last section.

2 Image Processing

Image processing is an essential step to reduce noise, background subtraction and content enhancement in the identification process (Goyal, Kapil, and Kumar 2018). The workflow we use to process images in this paper is shown in Figure 1. This includes seven main steps. They are converting BGR (Blue-Green-Red) image to RGB, gray scaling, Gaussian filtering, binary thresholding, remove stalk, close holes, and image resizing. Some of these steps can be applied for the necessary cases like applying remove stalk to the leaf images which only have a stalk.

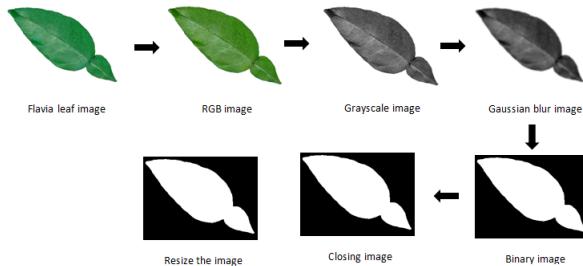


Figure 1: Image processing

In classifying plant species the focus was on the leaf which has a simple arrangement as shown in Figure 2. A single leaf that is never divided into smaller leaflet units is known as a leaf with simple arrangement. That leaf is always attached to a twigs by its stem or the petiole. The margins, or edges, of the leaf can be smooth, lobed, or toothed.

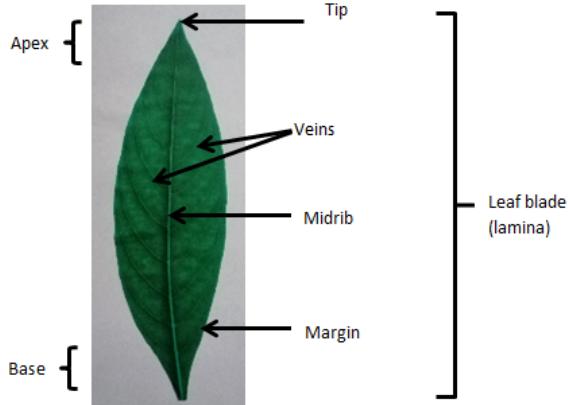


Figure 2: Leaf with simple arrangement

2.1 Step 1: Converting BGR Image to RGB

BGR and RGB are conventions for the order of the different colour channels. They are not colour spaces. When converting BGR image to RGB, there is no any computations, just switches around the order. Several image processing libraries have different pixel ordering. Therefore to compatible with other libraries we convert the BGR image in to RGB format.

As an example when read an image using OpenCV by default it interprets BGR format, but when plot the image it takes the RGB format in matplotlib.

2.2 Step 2: Grayscaleing

Grayscaleing is the process of converting an image to shades of gray from other colour spaces like RGB. Gray conversion of the image is implemented to optimize the contrast and intensity of images (Goyal, Kapil, and Kumar 2018).

Grayscale image requires only one single byte for each pixel where as colored (RGB) image requires 3 bytes for each pixel. Therefore reduces the dimension in using grayscaled image. In extracting Haralick (Haralick, Shanmugam, and Dinstein 1973) texture features, grayscale images are used. Another advantage of using grayscaled image is to reduce model complexity. Consider an example of training neural article on RGB images of 20x20x3 pixel. The input layer will have 1200 input nodes. Whereas for gray scaled images the same neural network will need only 400 input node.

2.3 Step 3: Gaussian Filtering (Gaussian Blurring/Gaussian Smoothing)

Gaussian smoothing is an image smoothing technique. Image smoothing techniques use to remove the noise that can be occurred because of the source (camera sensor). Image smoothing techniques help in smoothing images and to remove low intensity edges.

Gaussian function is used to blur the image. It is a linear filter which is done by using the functions in OpenCV. By specifying the width and height of the Gaussian kernel that must be positive and odd, and specifying the kernel standard deviation along x and y-axis, Gaussian smoothing is established in OpenCV. When the kernel standard deviation along x-axis is specified, kernel standard deviation along y-axis is taken as equal to the the kernel standard deviation along x-axis. But if both kernel standard deviation are given

as zeros, they are calculated by using the kernel size. In our research the width and height of the kernel is defined as 55 and the kernel standard deviation along x-axis is assigned as zero.

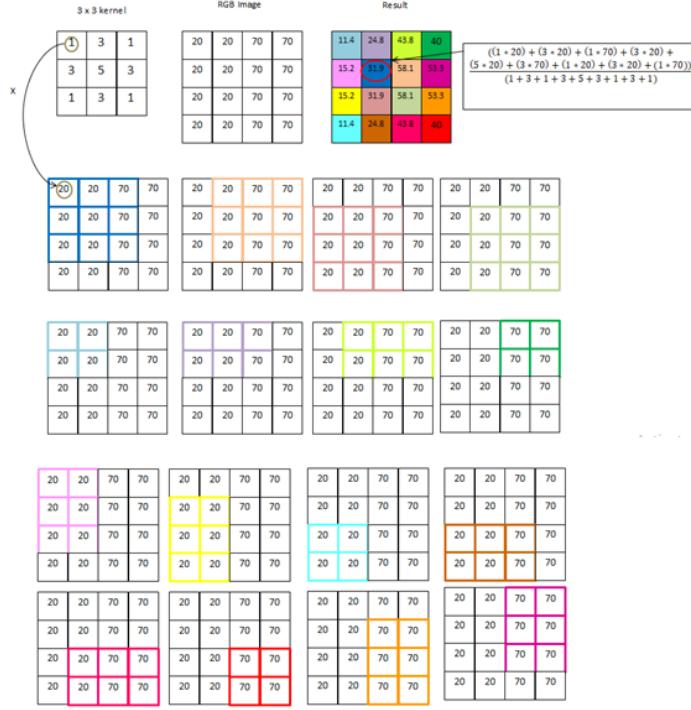


Figure 3: Example of gaussian smoothing

2.4 Step 4: Binary Thresholding

Thresholding is a segmentation technique that is used to separate foreground from its background. In thresholding technique, the pixel values are assigned by using the threshold value. By comparing each pixel value with the threshold value, the thresholding technique is worked. If the pixel value is smaller than the threshold value, the pixel value is set as 0, and if not the pixel value is set to a maximum value which is generally 255. Thersholding technique is done on grayscale images in computer vision.

We used Otsu's binarization which is an adaptive thresholding after Gaussian filtering to convert color images to the binary images. In Otsu's method, the threshold value is determined automatically. The algorithm of Otsu's method finds the optimal threshold value which is chosen arbitrary.

Otsu's Thresholding

Nobuyuki Otsu was introduced Otsu's method which is defined for a gray scale histogram $ghist_I$ of an input image Im . To segment an image Im into two subsets of pixels Otsu's method calculates an optimal threshold τ . The number of pixel locations of the gray scale image is defined as $|\Omega|$.

The algorithm maximizes the variance σ^2 between the two subsets (Within-class-variance) to find the threshold τ .

$$\sigma^2 = P_1(\mu_1 - \mu)^2 + P_2(\mu_2 - \mu)^2 = P_1P_2(\mu_1 - \mu_2)^2$$

where μ is the mean of the histogram, μ_1 and μ_2 are the mean values of first and second subset respectively, P_1 and P_2 are the corresponding probabilities of the two clusters, defined by

$$P_1 = \frac{\sum_{i=0}^u ghist_I(i)}{|\Omega|}$$

$$P_2 = \frac{\sum_{i=u+1}^{255} ghist_I(i)}{|\Omega|}$$

Where u is the candidate threshold and the maximum gray level (G_{max}) is assumed as 255. To find optimal threshold τ for segmenting image Im , all candidate thresholds are evaluated this way.

The algorithm of Otsu's method is defined as follows,

```

Create a histogram for the grayscale image
Set the histogram variance  $S_{max} = 0$ 
while  $u < G_{max}$  do
    Compute  $\sigma^2 = P_1 * P_2(\mu_1 - \mu_2)^2$ 
    if  $\sigma^2 > S_{max}$  then
         $S_{max} = \sigma^2$ 
         $\tau = u$ 
    end if
    Set  $u = u + 1$ 
end while

```

Table 1: Otsu's method

As an example, assume that candidate threshold value u is 2. Therefore the image is separated into two classes, which are class 1 (pixel value ≤ 2) and class 2 (pixel value > 2). Class 1 represents the background and class 2 represents the foreground of the grayscale image. According to figure 4, there are 9 pixel locations.

$$P_1 = \frac{5}{9}$$

$$P_2 = \frac{4}{9}$$

$$\mu_1 = \frac{(0 * 2) + (1 * 1) + (2 * 2)}{(2 + 1 + 2)} = 1$$

$$\mu_2 = \frac{(3 * 3) + (4 * 1)}{(3 + 1)} = \frac{13}{4}$$

$$\sigma^2 = \frac{5}{9} * \frac{4}{9} * \left(1 - \frac{13}{4}\right)^2 = 1.25$$

2.5 Step 5: Image Resizing

There are two different leaf image datasets (Flavia, Swedish) which have different sizes. To compare the results on different datasets, to improve the memory storage capacity and to reduce computational complexity the leaf images are resized to a fixed resolution. In our study, the leaf images have been resized to [1600 x 1200px] which is the size of Flavia leaf images.

Other than the main image processing techniques, the following two techniques are applied in some or all cases as an image processing techniques after image thresholding.

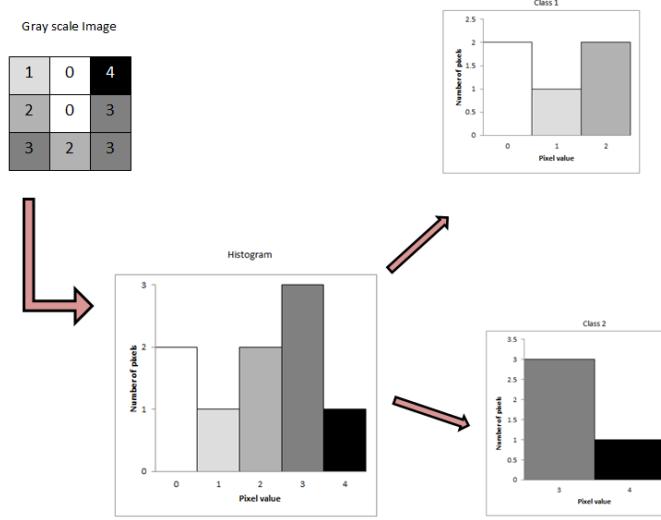


Figure 4: Example of Otsu's binary thresholding

Remove Stalk

Remove the petiole (stalk) of leaf image is another version of thresholding process. Thresholding is applied after finding the sure foreground area. To find the sure foreground area, distance transform technique is used. Binary image is used as the input of distance transform technique. In distance transform technique, image is created by assigning a number for each object pixel that corresponds to the distance to the nearest background pixel. The distance is calculated using the euclidean distance (1). After finding the sure foreground area, Otsu's binarization is applied again as the thresholding technique.

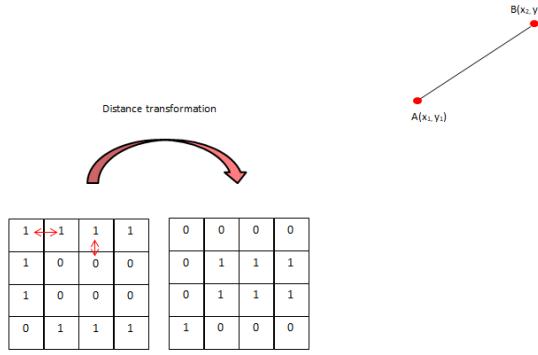


Figure 5: Example of distance transformation

$$\text{Euclidean distance} = \sqrt{(x_1 - x_2)^2 + (y_1 - y_2)^2} \quad (1)$$

Closing Holes

Closing holes is followed by noise removal technique which demonstrates the closing effect. Closing effect is used to remove small holes inside the foreground objects. Closing holes is a result of morphological transformation. Morphological transformations are the operations based on image shape. Binary image is used as one input in morphological transformation. Kernel or structuring element which decides the nature of the operation is used as the second input. There are two morphological operators as Erosion and Dilation. Closing is a variant form of morphological operators which is used in closing holes process. Closing is also known as Dilation followed by Erosion.

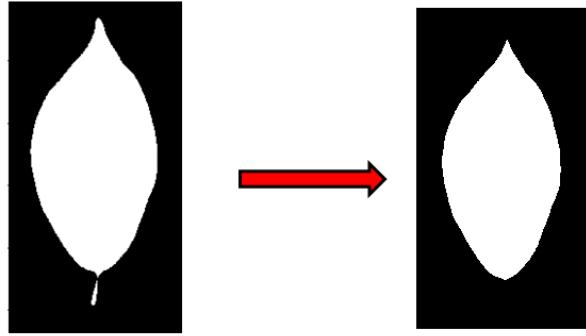


Figure 6: Remove stalk

Erosion

The basic idea of Erosion is that erodes away the boundaries of foreground object. Since the input is binary image, a pixels in the original image is either 1 or 0. If all the pixels under the kernel is 1, a pixel of original image is considered as 1, otherwise made to zero (eroded). Which means that depending upon the size of the kernel all pixels near boundary will be discarded. Therefore the thickness or size of the foreground object decreases (White region of the image decreases).

Dilation

Opposite of erosion is defined as Dilation. If at least one pixel under the kernel is 1, the pixel element is 1 in Dilation. It tends to increase the foreground of the image or the white region of the object.

Noise removal is that a technique of erosion is followed by Dilation. In erosion white noise is removed and shrinks the object (dilate) which doesn't come back. But in closing holes approach the white area is increased.

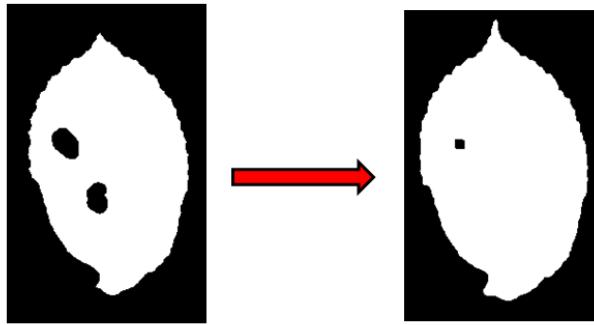


Figure 7: Closing holes

3 Leaf Features

In identification of plant species by using leaf images, features of the leaves play a main role, because each leaf posses unique feature that it make different from other. In previous research (Azlah et al. 2019; Jeon and Rhee 2017), let the algorithm like CNN to extract features by itself and do the classification. Therefore it is so hard to interpret and generalize the features. We introduced pre-calculate features which can be easy to interpret and generalize. They are also computational efficient. Mainly we focused on four types of features

of leaf images as Shape features, Texture features, Color features and Scagnostics features. We identified altogether 52 features.

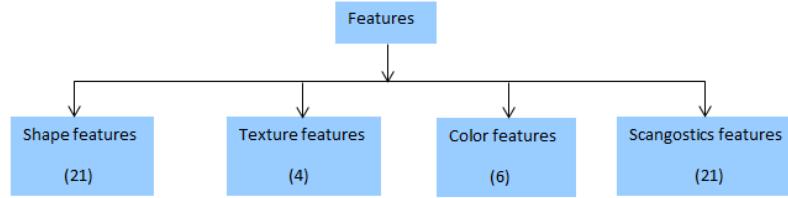


Figure 8: Example of geometric transformation

3.1 Shape Features

When identifying real-world objects, the shape is known as an essential sign for humans. A shape measure is a quantity, which relates to a particular shape characteristic of an object in general (Waldchen and Mader 2018).

The main geometric transformation are rotation reflection, scaling and translation (see figure 9). In our research, the defined shape features are invariant to the rotation and reflection. But some limitations are applied in translation and scaling.

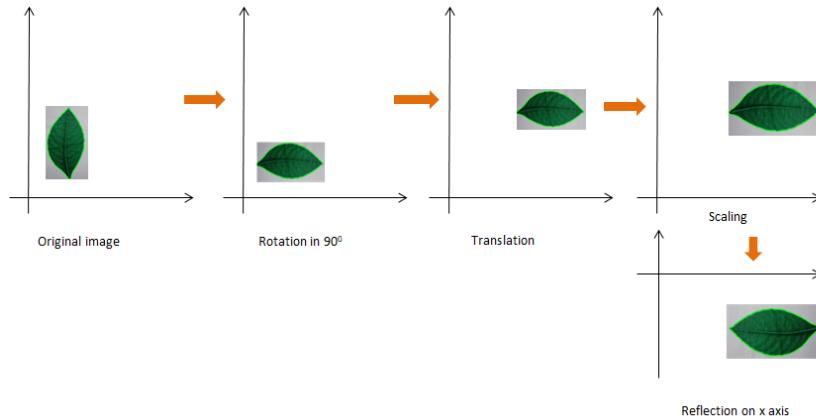
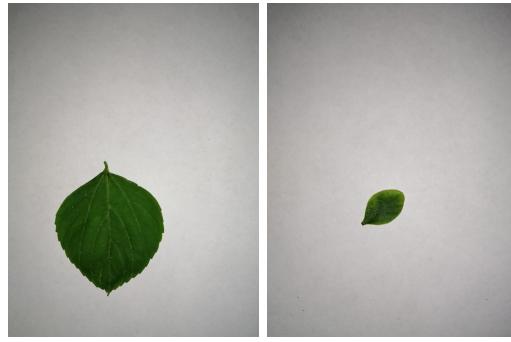


Figure 9: Example of geometric transformation

The finding contour function doesn't work well when the center of the leaf image is not in the contour. Therefore if the translation is applied away from the contour ??, then function can't identify the contour. Inappropriate scaling (see figure ??) also arises problems in the calculation. If the leaf image is really small, the function also hard to recognize the contour. Therefore taking the closest photo of the leaf images by keeping them in the center of the white paper is more suitable.

All the shape features are extracted from the binary images.



(a) Inappropriate translation
(b) Inappropriate scaling

3.2 Contours

Simply contour (see figure 10) is a curve joining all the continuous points (along the boundary), having the same color or intensity.

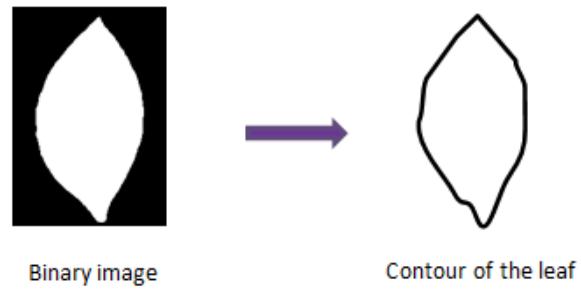


Figure 10: Extract contour of the leaf image

Shape features can be classified into two main categories as contour-based and region-based features. Contour-based (Waldchen and Mader 2018) shape features are extracted solely from the contour of a shape. Whereas, region-based (Waldchen and Mader 2018) shape features are obtained from the whole region of a shape. In addition, there also exist some methods, which cannot be classified as either contour-based or region-based (see figure 11).

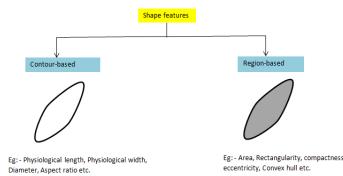


Figure 11: Categorization of shape features

Through this research, we use 6 initial shape features that are used to extract 12 shape features. Also as new shape features, we introduce number of convex points, x and y coordinates of center, number of maximum and minimum points, correlation of cartesian contour. The 6 initial features are diameter, physiological length, physiological width, area, perimeter, and eccentricity.

3.3 Diameter (F_1)

Diameter is defined as the longest distance between any two points on the margin of the leaf (Waldchen and Mader 2018).

To calculate the diameter of the leaf image, firstly we have to find the contour of the leaf image. Then we have to select all pair of contour points and measure the Euclidean distance (equation 2) between the two points separately. Finally have to find the maximum distance among the calculated distances. (see figure 12)

$$d(A, B) = \sqrt{\sum_{i=1}^2 (q_i - p_i)^2} \quad (2)$$

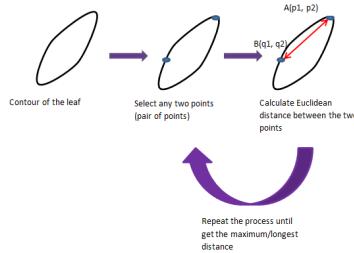


Figure 12: Logic behind calculation of diameter

$$F_1 = \max(\sqrt{(x_i - x_j)^2 + (y_i - y_j)^2}); \forall i, j, i \neq j \quad (3)$$

3.4 Physiological length (F_2) and Physiological width (F_3)

According to the authors in Azlah et al. (2019), the physiological length is measured based on the main vein of leaf, as it stretches from the main vein to the end tip. The physiological width is the span of leaf viewed from one side to the other, from the leftmost point to the rightmost point of leaf (Azlah et al. 2019).

There are horizontal, vertical and angled leaf images in the datasets (Flavia, Swedish). The straight bounding rectangle is enough to extract physiological length and physiological width of horizontal, and vertical leaf images.

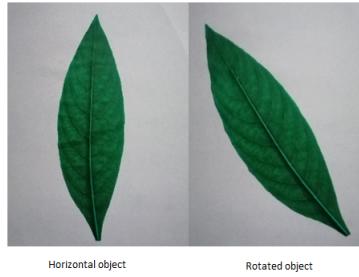
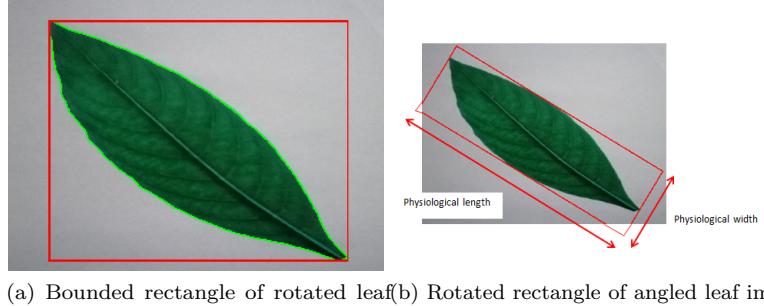


Figure 13: Straight(Horizontal or vertical) and rotated leaf image in Actual leaf image dataset

But straight bounding rectangle of angled image doesn't give the correct values for physiological length and physiological width of leaf images.

To solve this problem, we considered rotated rectangle rather than bounded rectangle in computing shape features of angled images. The physiological length of the leaf image is the length of the rectangle. The physiological width of the leaf image is the width of the rectangle.



(a) Bounded rectangle of rotated leaf
 (b) Rotated rectangle of angled leaf
 image in Actual leaf image dataset image in Actual leaf image dataset

There are two types of bounding rectangles.

- Straight Bounding Rectangle

This is a straight rectangle which doesn't consider the rotation of the object. Therefore area of the bounding rectangle doesn't minimize.

- Rotated Rectangle

This bounding rectangle is drawn with minimum area. Therefore the rotation of the object is also considered.

$$F_2 = \text{Length of the rectangle} \quad (4)$$

$$F_3 = \text{Width of the rectangle} \quad (5)$$

3.5 Area (F_4)

Area is defined as the result of thresholding process. Pixel (Azlah et al. 2019) which is represented by the number 0 defines the leaf area.

$$F_4 = \text{Number of zero pixels covered by the contour} \quad (6)$$

Firstly, we have to extract the best contour and based on that contour area is measured. Number of 0 pixels covered by the contour is the measure of area of leaf image.

1	1	1	1	1	1	1
1	1	1	1	1	1	1
1	1	1	0	0	0	1
0	0	0	0	0	0	0
1	0	0	0	0	0	1
1	1	1	1	1	1	1

Figure 14: Measure the area

Figure 15 shows that the changes of the shape when the area is increasing.

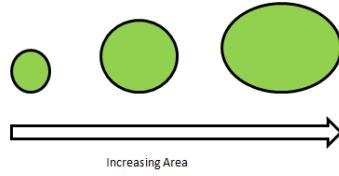


Figure 15: Area

3.6 Perimeter (F_5)

Perimeter is defined as the summation of euclidean distance of all continuous points in the contour (see figure 16).

$$F_5 = \sum_{i=0}^n d_i \quad (7)$$

where n is the number of distances around the contour

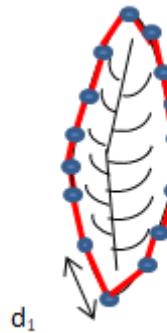


Figure 16: Calculation of perimeter

3.7 Eccentricity ((F_6))

Eccentricity is definitive characteristic of any conic section of a leaf (Azlah et al. 2019). Eccentricity is defined that how much the ellipse actually varying being circular. Eccentricity is calculated using equation 8.

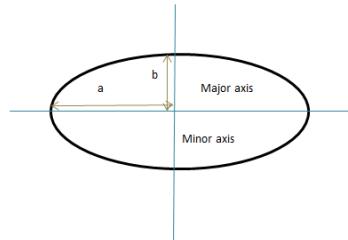


Figure 17: Ellipse

$$F_6 = \sqrt{1 - \frac{b^2}{a^2}} \quad (8)$$

where a is semi major axis and b is semi minor axis

Eccentricity of an ellipse is varied between 0 and 1. If eccentricity is 0, then we obtain a circle whereas eccentricity is 1, then we obtain an ellipse.

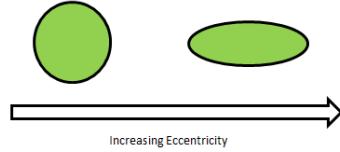


Figure 18: Eccentricity

3.8 Number of Convex Points (F_{21})

If a hull (Wilkinson, Anand, and Grossman 2005) contains all the straight line segments connecting any pair of points in its interior, is known as a convex hull. The convex hull bounds a single polygon.

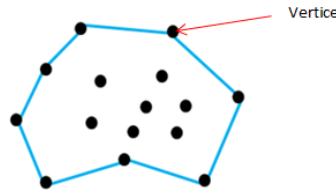


Figure 19: Convex hull

Number of convex points is a new feature which calculate using the convex hull.

$$F_7 = \text{Number of vertices of the convexHull} \quad (9)$$

3.9 Roundness/ Circularity

Roundness is named as aka form factor, circularity, or isoperimetric factor. Roundness illustrates the difference between the leaf and a circle. Equation 10 is used to calculate roundness.

$$R = \frac{4\pi F_4}{F_5^2} \quad (10)$$

Figure 20 shows what happen to the shape when the roundness measure is changed.

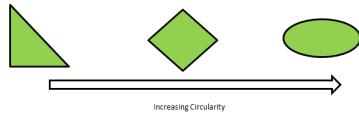


Figure 20: Circularity

3.10 Compactness

Compactness is closely related to roundness. Compactness measures that how compatible the leaf fits to a circle area (see figure 21).

$$C = \frac{F_5^2}{F_4} \quad (11)$$

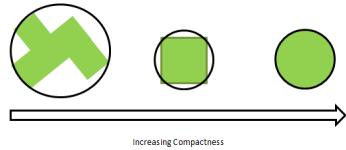


Figure 21: Compactness

3.11 Convexity

Convexity measures the curvature of the convex hull.

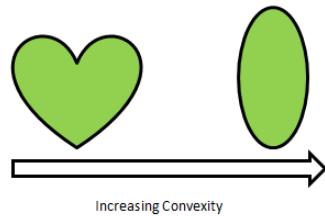


Figure 22: Convexity

The definition of all shape features as follows (see figure 2);

Shape feature	Feature name	Figure	Formula	Range	Software package
F_1	Diameter		eq:3	$[0, \infty]$	combinations, numpy
F_2	Physiological length		eq:4	$[0, \infty)$	OpenCV

Table 2 continued from previous page

Shape feature	Feature name	Figure	Formula	Range	Software package
F_3	Physiological width		eq:5	$[0, \infty)$	OpenCV
F_4	Area		eq:6		OpenCV
F_5 F_6	Perimeter Eccentricity		eq:7 eq:8	$[0, \infty)$ $[0, 1]$	OpenCV OpenCV
F_7, F_8	x and y coordinate of center				scipy.ndimage
F_9	Aspect ratio		$F_9 = \frac{F_2}{F_3}$	$[0, \infty)$	-
F_{10}	Roundness/ Circularity		eq:10	$[0, \infty)$	numpy
F_{11} F_{12}	Compactness Rectangularity		eq:11 $F_{12} = \frac{F_5^2}{F_4}$	$(0, \infty)$ $(0, \infty)$	-
F_{13}	Narrow factor		$F_{13} = \frac{F_1}{F_2}$	$[0, \infty)$	-
F_{14}	Perimeter ratio of diameter		$F_{14} = \frac{F_5}{F_1}$	$[0, \infty)$	-
F_{15}	Perimeter ratio of physiological length		$F_{15} = \frac{F_5}{F_2}$	$[0, \infty)$	-
F_{16}	Perimeter ratio of physiological length and width		$F_{16} = \frac{F_5}{F_2 * F_3}$	$[0, \infty)$	-
F_{17}	Perimeter convexity		$F_{17} = \frac{\text{Perimeter of convex hull}}{F_5}$	$[0, \infty)$	OpenCV

Table 2 continued from previous page

Shape feature	Feature name	Figure	Formula	Range	Software package
F_{18}	Area convexity		$F_{18} = \frac{(\text{Area of convex hull} - F_4)}{F_4}$	$[0, \infty)$	OpenCV
F_{19}	Area ratio of convexity		$F_{19} = \frac{F_4}{\text{Area of convex hull}}$	$[0, \infty)$	OpenCV
F_{20}	Equivalent diameter		$F_{20} = \sqrt{\frac{4*F_4}{\pi}}$	$[0, \infty)$	numpy
F_{21}	Number of convex points		eq:9	$[0, \infty)$	OpenCV

Table 2: Definitions of shape features

3.12 Texture Features

Texture features are used to describe the surface or the appearance of the leaf image. Texture can only be assessed for a group of pixels whereas color is usually a property of a pixel.

Generally, texture is associated with the feel of various materials to human touch and texture image analysis is based on visual interpretation of this feeling. Leaf surface is a natural texture which has random persistent patterns and do not show detectable quasi-periodic structure (Waldchen and Mader 2018). Therefore to describe the natural texture patterns of the leaf fractal theory (Waldchen and Mader 2018) is the best approach.

The Haralick texture features (Boland 2000) are functions of the normalized GLCM (Gray Level co-occurrence Matrix) which is a common method to represent image texture.

$$GLCM = \begin{bmatrix} h(1, 1) & h(1, 2) & \dots & \dots & h(1, n) \\ h(2, 1) & h(2, 2) & \dots & \dots & h(2, n) \\ \vdots & \vdots & \ddots & & \vdots \\ \vdots & \vdots & & \ddots & \vdots \\ h(n, 1) & h(n, 2) & \dots & \dots & h(n, n) \end{bmatrix}$$

The GLCM is square with dimension n , where n is the number of gray levels in the image.

$$h(a, b) = \frac{\text{Number of times a pixel with value } a \text{ is adjacent to a pixel with value } b}{\text{Total number of such comparisons made}}$$

where $h(a, b)$ is the probability that a pixel with value a will be found adjacent to a pixel of value b

Four such matrices can be calculated, because adjacency can be defined to occur in each of four directions in a 2D (see figure 25), square pixel image (horizontal, vertical, left and right diagonals - see equation 23).

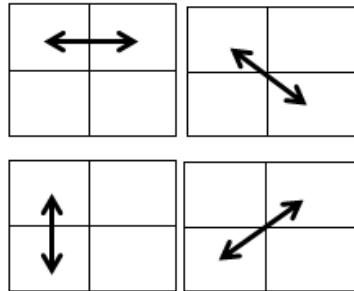


Figure 23: Four directions of adjacency as defined for calculation of the Haralick texture features

The Haralick statistics (Boland 2000) are calculated for co-occurrence matrices generated using each of these directions (see figure 24) of adjacency. Haralick then described 14 statistics that can be calculated from the co-occurrence matrix with the intent of describing the texture of the image. Through the research, we only used the following 4 statistics among 14 of them, because most of the researchers used these 4 statistics as texture features (see figure 3) of leaf images. All the texture features are extracted from the gray scale image. Texture features are calculated from the mahotas package in Python. The following table 3 shows the definitions of texture features.

where $h(a, b)$ = Probability density function of gray - level pairs (a, b) and dimension of GLCM is $n * n$ (Number of columns * Number of rows)

Texture feature	Feature name	Detailed description	Formula	Value range
F_{22}	Contrast	Measures the relation or difference between the highest and lowest gray levels of the GLCM	$\frac{\sum_{a=1}^{columns} \sum_{b=1}^{rows} (a-b)^2 h(a,b)}{\text{Number of gray levels}-1}$	$[0, \infty]$
F_{23}	Entropy	Measures the randomness which means that how uniform the image is	$-\sum_{a=1}^{columns} \sum_{b=1}^{rows} h(a,b) \log_2(h(a,b))$	$[-\infty, 0]$
F_{24}	Correlation	Measurement of dependence of gray levels of the GLCM. It measures that how a particular pixel is correlated to its neighbor pixel over the whole image	$\frac{\sum_{a=1}^{columns} \sum_{b=1}^{rows} (ab)h(a,b) - \mu_x \mu_y}{\sigma_x \sigma_y}$	$[-1, 1]$
F_{25}	Inverse difference moments	It's a measure of homogeneity. Inverse level of contrast that measures how close the values of GLCM to diagonal values in GLCM	$\sum_{a=1}^{columns} \sum_{b=1}^{rows} \frac{h(a,b)}{(a-b)^2}$	$[0, \infty]$

Table 3: Definitions of texture features

$$\begin{aligned}\mu_x &= \sum_{a=1}^{columns} a \sum_{b=1}^{rows} h(a,b) \\ \mu_y &= \sum_{b=1}^{rows} b \sum_{a=1}^{columns} h(a,b) \\ \sigma_x &= \sum_{a=1}^{columns} (a - \mu_x)^2 \sum_{b=1}^{rows} h(a,b) \\ \sigma_y &= \sum_{b=1}^{rows} (b - \mu_y)^2 \sum_{a=1}^{columns} h(a,b)\end{aligned}$$

3.13 Color Features

Color is an important feature of images (Waldchen and Mader 2018; Caglayan, Guclu, and Can 2013). Color properties are defined within a particular color space like red-green-blue (RGB) (Kodituwakku and S.Selvarajah 2010; Waldchen and Mader 2018). Color properties can be extracted from images after a colour space is specified. In the field of image recognition, a number of general color descriptors have been introduced. Color moments (Kodituwakku and S.Selvarajah 2010; Waldchen and Mader 2018) are the simple descriptor among them. Mean, standard deviation skewness and kurtosis are the common moments. Color moments are used for characterizing planar color patterns, irrespective of viewpoint or illumination conditions and without the need for object contour detection (Waldchen and Mader 2018). Color moments are convenient for real-time applications because of its low dimension and low computational complexity.

Some of leaf images have very similar shape like Hathawariya (figure 26) and Iramusu (figure 26). Even though shapes are similar in some leaves, there are some differences in colors of leaf images. Therefore in addition to the shape features, we extract color based features of leaf images as well.

We used mean(M) and standard deviation(SD) of intensity values of red, green and blue channels as color features.

$$M = \frac{\text{Total insensity value of } r^{\text{th}} \text{ channel of the image pixels}}{\text{Total intensity value of the image}} \quad (12)$$

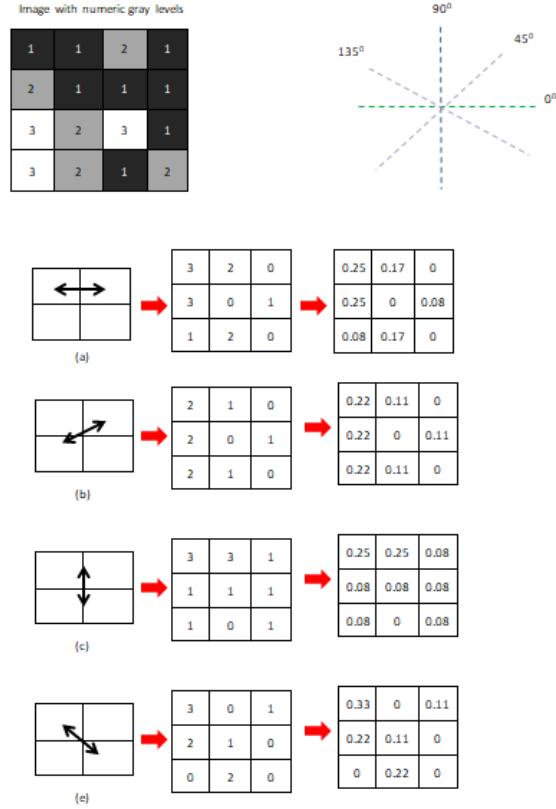


Figure 24: Computing the Haralick texture features from a 4×4 example image step by step

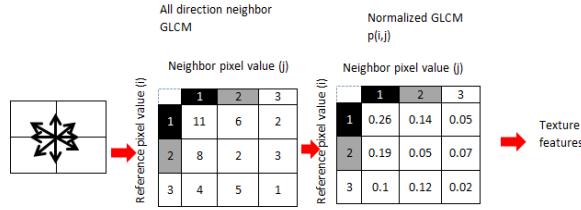


Figure 25: Computing the Haralick texture features from a 4×4 example image with all direction



Figure 26

$$SD = \frac{\sqrt{\sum_{j=0}^h (r^{th} \text{channel intensity}_j - r^{th} \text{mean value})^2}}{\text{Total intensity value of the image}} \quad (13)$$

where h is the number of pixels of the image and r is the channel type which can be red, green, or blue

3.14 Scagnostic features

Scagnostic features (Wilkinson, Anand, and Grossman 2005; Wilkinson and Wills 2008; Dang and Wilkinson 2014; Dang, Anand, and Wilkinson 2013) describe the characteristics of 2D scatterplot. Various types of measures are calculated based on the appearance of scatterplot. All the scagnostics features are calculated by using the R package called binostics. Scagnostic features has the range of [0,1]. There are 9 measures which are classified in to three categories as shown in figure 27. Based on binary images, scagnostic features are extracted.

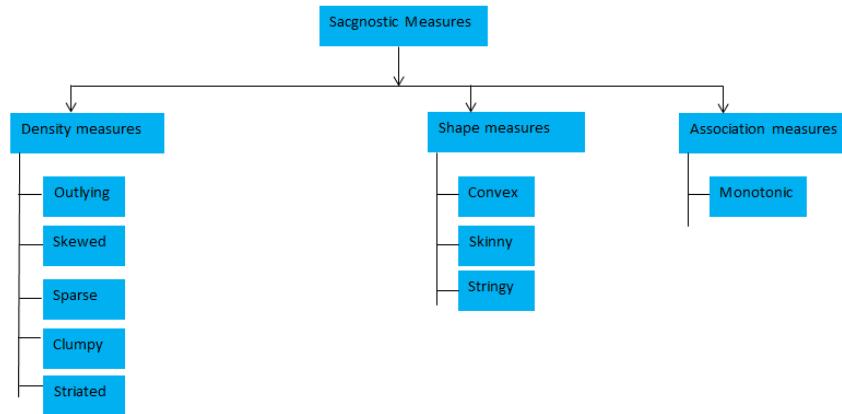


Figure 27: Hierarchy of Scagnostics

We measure the scagnostic features for cartesian and polar coordinate (see figure 28) separately.

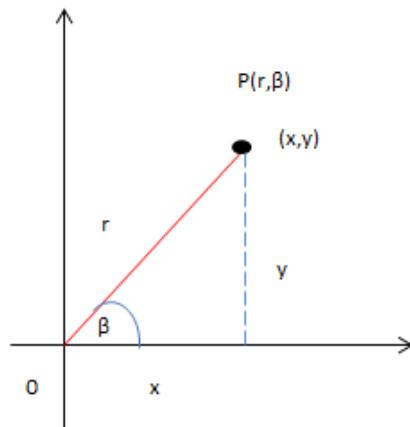


Figure 28: Polar coordinate

As the first step, we have to extract the contour of the leaf image (see figure 29). Then find the x and y coordinate values of the cartesian and polar separately. The x and y coordinate value is used to calculate the scagnostic features.

The following definitions can be useful in understanding scagnostics features.

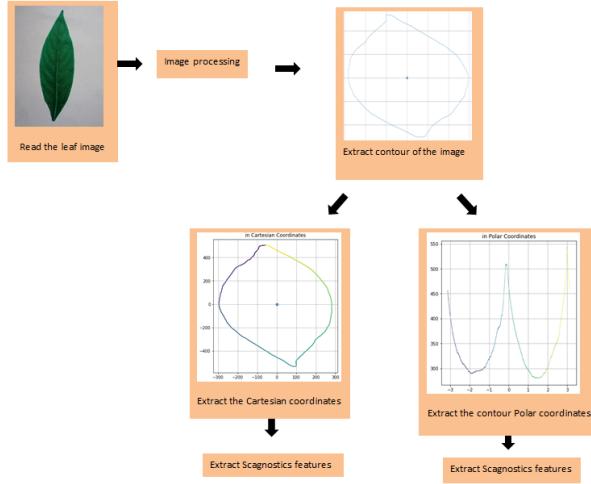


Figure 29: Preprocessing for Scagnostics

3.14.1 Geometric Graphs

- Graph

A graph $Gr = (Ve, Ed)$ is defined as a set Ve (called vertices) together with a relation on Ve induced by a set Ed (called edges). A pair of vertices is defined as an edge $e(\nu, \omega)$, with $e \in Ed$ and $\nu, \omega \in Ve$.

- Geometric Graph

An embedding of a graph in a metric space S that maps vertices to points and edges to straight line segments connecting pairs of points is defined as a geometric graph $G^* = [f(Ve), g(Ed), S]$.

From several features of 2D Euclidean geometric graphs, Scagnostic measures are derived.

The Euclidean distance between vertices that connected to edge is defined as the length of an edge, $\text{length}(e)$.

The sum of the lengths of edges in graph is known as the length of a graph, $\text{length}(Gr)$.

A list of successively adjacent, distinct edges are known as a path. If first and last vertex are the same of the path, then the path is closed.

A region bounded by a closed path is known as a polygon (P). A polygon bounded by exactly one closed path that has no intersecting edges is known as a simple polygon.

The length of boundary of a simple polygon is known as the perimeter of a simple polygon. The area of interior of a simple polygon is known as the area of a simple polygon.

3.14.2 Minimum Spanning Tree (MST)

- Tree

A graph in which any two nodes are connected by exactly one path is known as a *tree*.

- Spanning Tree

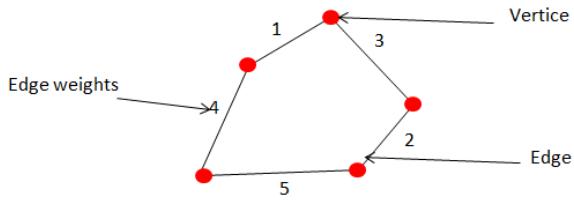


Figure 30: Graph with 5 vertices and 5 edges

An undirected graph whose edges are structured as a tree is defined as a *Spanning Tree*.

Spanning Tree of Graph Gr is: $G'(V', E')$

$$V' = Ve$$

$$E' \subset Ed$$

$$E' = |Ve| - 1$$

The graph can have more than one spanning tree.

Spanning tree should not be disconnected and not contain any cycle. By removing one edge from the Spanning tree will make it disconnected. By adding one edge to the Spanning tree will create a loop. A complete (Each vertices connected with each other) undirected graph can have n^{n-2} number of spanning trees where n is the number of vertices. Every connected and undirected graph has at least one Spanning Tree. Disconnected graph doesn't have any spanning tree. From a complete graph by removing $\max(\text{edges} - n + 1)$ edges we can construct a spanning tree.

- Minimum Spanning Tree

A spanning tree whose total length is least of all spanning trees on a given set of points is known as a Minimum Spanning Tree (MST).

If each edge has distinct weights then there will be only one and unique MST.

- Remark

The geometric MST computed from Euclidean distances between points in a 2D Euclidean geometric graph is the restriction.

3.14.3 Convex Hull

A collection of the boundaries of one or more simple polygons that have a subset of the points for their vertices and that collectively contain all the points, is defined as a hull of a set of points embedded in 2D Euclidean space.

If a hull contains all the straight line segments connecting any pair of points in its interior, is known as a convex hull. The convex hull bounds a single polygon. After deleting the points on the convex hull, a convex hull called peeled convex hull is computed.

3.14.4 Alpha Hull

Most of proximity graphs (neighborhood graph) represent the nonconvex shape of a set of points on the plane. A geometric graph whose edges are determined by an indicator function based on distances between a given set of points in a metric space, is known as a proximity graph. An open disk D is used to define the indicator function.

If a point is on the boundary of D then D *touches* a point and if a point is in D then D *contains* a point. An open disk of radius r is defined as $D(r)$.

An alpha shape (Dang and Wilkinson 2014) is a collection of one or more simple polygons (Wilkinson and Wills 2008; Wilkinson, Anand, and Grossman 2005). An edge exists between any pair of points that can be touched by an open disk $D(\alpha)$ containing no points, is defined as an alpha shape graph.

A value of α to be the average value of the edge lengths in the MST (Wilkinson and Wills 2008; Wilkinson, Anand, and Grossman 2005). The large values like 90th percentile of the MST edge lengths are used, because to reduce noise. If the percentile exceeds a tenth, clamp the value at one-tenth the width of a frame, because it prevents in including sparse or striated point sets in a single alpha graph.

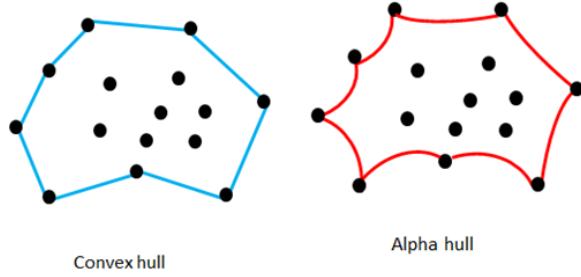


Figure 31: Convex hull and alpha hull

3.14.5 Preprocessing

To improve the performance of the algorithm and robustness of the measures, preprocessing techniques as binning and deleting outliers are used before computing geometric graphs.

- Binning

As the first step of binning, the data are normalized to the unit interval. Then use a 40 by 40 hexagonal grid to aggregate the points in each scatterplot. Reduce the bin size by half and rebin until no more than 250 non empty cells, if there are more than 250 non empty cells. By efficiency (too many bins slow down calculations of the geometric graphs) and sensitivity (too few bins obscure features in the scatterplots), the choice of bin size is constrained.

To improve the performance, hexagon binning is used. To manage the problem of having to many points that start to overlap, hexagon binning is used. The plots of hexagonal binning are density rather than points. To use hexagons instead of squares for binning a 2D surface as a plane, there are many reasons. Hexagons are more similar to circle than square.

To keep scagnostics orientation-independent this bias reduction is important. To attenuate the influence of binning, stabilizing transformation is used when computing scagnostics from binned data.

The weight function is defined as;

$$\text{weight} = 0.7 + \frac{0.3}{1 + t^2} \quad (14)$$

where $t = \frac{n}{500}$. (n is the number of vertex)

If $n > 2000$ then this function is fairly constant. By using hex binning the shape and the parameters of the function is determined. In computing Sparse, Skewed and Convex scagnostics this weight function is used to adjust for bias.

- Deleting Outliers

To improve robustness of the scagnostics, deleting outliers can be used. A vertex whose adjacent edges in the MST all have a weight (length) greater than ω is defined as an outlier in this context. By considering nonparametric criterion for the simplicity and Tukey's idea choose the following weight calculation.

$$\text{weight} = qu_{75} + 1.5(qu_{75} - qu_{25}) \quad (15)$$

where qu_{75} is the 75th percentile of the MST edge lengths and $(qu_{75} - qu_{25})$ is the interquartile range of the edge lengths.

3.14.6 Degree of a Vertex

The degree of a vertex in an undirected graph is known as the number of edges associated with the vertex.

Eg:- Vertices of degree 2 There are 2 edges associated with each vertex.

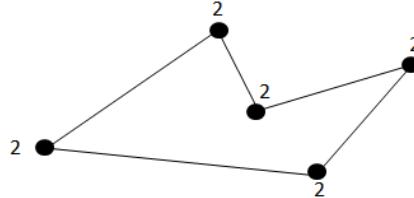


Figure 32: Vertices of degree 2

Geometric Graphs	Notation
Convex Hull	CH
Alpha Hull	Al
Minimum Spanning Tree	T

Table 4: Notations of Geometric Graphs

The definitions of scagnostic features are defined as follows.

3.14.7 Density Measures

Detect different distributions of scattered points in density measures.

- Outlying

$$F_{sc1} = \frac{\text{Total length of edges adjacent to outlying points}}{\text{Total edge length of } T} \quad (16)$$

The outlying measure calculate before deleting the outliers for the other measures.

- Skewed

$$qu_{skew} = \frac{qu_{90} - qu_{50}}{qu_{90} - qu_{10}} \quad (17)$$

$$F_{sc2} = 1 - \text{weight} * (1 - qu_{skew}) \quad (18)$$

where the weight function is equation 14.

The skewed measure is the first measure of relative density which is a relatively robust measure of skewness in the distribution of edge lengths. After adaptive binning skewed tends to decrease with n .

- Sparse

$$F_{sc3} = \text{weight} * qu_{90} \quad (19)$$

where the weight function is equation 14 and qu_{90} is the 90th percentile of the distribution of edge lengths in the T .

The second relative density measure is sparse measure that measures whether points in a 2D scatterplot are confined to a lattice or a small number of locations on the plane.

If the number of points is extremely small or tuples are produced by the product of categorical variables, then sparse can be happen.

$$qu_{90} = \alpha \text{statistic} \quad (20)$$

The α statistic exceeds unity (e.g., when all points fall on either of the two diagonally opposing vertices of a square), clamp the value to 1 in the extremely rare event (Wilkinson and Wills 2008,@inproceedings44).

- Clumpy

$$F_{sc4} = \max_j [1 - \frac{\max_k [\text{length}(e_k)]}{\text{length}(e_j)}] \quad (21)$$

Clustering points are not indicated by an extreme distribution of T edge lengths. Therefore RUNT statistic (Wilkinson and Wills 2008; Wilkinson, Anand, and Grossman 2005) which is another measure based on the T , is introduced. The smaller of the number of leaves of each of the two subtrees joined at that node isdefined as the runt size of a dendrogram node. There is an association between runt size (r_j) each edge (e_j) in the T because there is an isomorphism between a single-linkage dendrogram and the T .

The smaller of the two subsets of edges that are still connected to each of the two vertices in e_j after deleting edges in the MST with lengths less than $\text{length}(e_j)$, is known as the RUNT graph (R_j) (Wilkinson and Wills 2008; Wilkinson, Anand, and Grossman 2005).

The RUNT-based measure responds to clusters with small maximum introcluster distance relative to the length of their nearest-neighbor inter-cluster distance (Wilkinson and Wills 2008,@inproceedings44). In the formula j runs over all edges in T and k runs over all edges in RUNT graph.

- Striated

$$F_{sc5} = \frac{1}{|Ve|} \sum_{\nu \in Ve^{(2)}} I(\cos \theta_{e(\nu,a)e(\nu,b)} < -0.75) \quad (22)$$

where $Ve^{(2)} \subseteq Ve$ and $I()$ be an indicator function.

Striated define the coherence in a set of points as the presence of relatively smooth paths in the minimum spanning tree.

The measure is based on the number of adjacent edges whose cosine is less than minus 0.75.

3.14.8 Shape Measures

Both topological and geometric aspects of shape of a set of scattered points is considered. As an example, a set of scattered points on the plane appeared to be connected, convex and so forth, want to know under the shape measures. By definition scattered points are not like this. Therefore to make inferences additional machinery (based on geometric graphs) is needed. By measuring the aspects of the convex hull, the alpha hull, and the minimum spanning tree is determined.

- Convex

$$F_{sc6} = \text{weight} * \frac{\text{Area of alpha hull}}{\text{Area of convex hull}} \quad (23)$$

where the weight function is equation 14.

The ratio of the area of the alpha hall(Al) and the area of the convex hull(CH) is the base of measuring convexity.

$$\text{Ratio} = \frac{\text{area}(A)}{\text{area}(H)} \begin{cases} (=1); \text{ if the nonconvex hull and convex hull have identical areas} \\ (\neq 1); \text{ otherwise} \end{cases}$$

- Skinny

$$F_{sc7} = 1 - \frac{\sqrt{4 * \pi * \text{Area of alpha hull}}}{\text{Perimeter of alpha hull}} \quad (24)$$

Roughly, the skinny is measured by using the corrected and normalized ratio of perimeter to area of a polygon measures.

$$F_{sc7} = \begin{cases} 0; \text{ if circle} \\ \text{Near 1; if skinny} \end{cases}$$

- Stringy

$$F_{sc8} = \frac{|Ve^{(2)}|}{|Ve| - |Ve^{(1)}|} \quad (25)$$

where Ve is the number of vertices.

A skinny shape with no branches is known as a stringy shape. By counting the vertices of degree 2 in the minimum spanning tree and comparing them to the overall number of vertices minus the number of single-degree vertices, skinny measure is calculated.

To adjust for negative skew in its conditional distribution of n , cube the stringy measure.

3.14.9 Association Measure

Symmetric and relatively robust measure of association are interested.

- Monotonic

$$F_{sc9} = r_{Spearman}^2 \quad (26)$$

To assess the monotonicity in a scatter plot, the squared Spearman correlation coefficient is used. This is the only coefficient not based on a subset of the Delaunay graph (Wilkinson and Wills 2008).

In calculating monotonicity, squared the coefficient because to consider the large values and to remove the distinction between positive and negative coefficients (Because assume that the investigators are more interested in strong relationships rather than negative or positive).

We introduced number of minimum and maximum points, correlation of cartesian contour as new features under scagnostics.

3.15 Number of Minimum (F_8) and Maximum Points (F_9)

Number of minimum, and maximum points are new measures which are obtained from the polar coordinate of leaf contour. Number of global maximum points are defined as number of maximum points. Number of global minimum points are defined as number of minimum points.

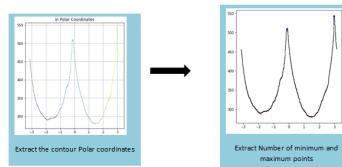


Figure 33: Minimum and Maximum Points

$$F_8 = \text{Number of global minimum points} \quad (27)$$

$$F_9 = \text{Number of global maximum points} \quad (28)$$

3.16 Correlation of Cartesian Contour (F_{10})

Correlation is another new feature which is obtained from the cartesian contour.

$$F_{10} = \frac{\sum_{i=0}^m (x_i - \bar{x})(y_i - \bar{y})}{\sqrt{\sum_{i=0}^m (x_i - \bar{x})^2 (y_i - \bar{y})^2}} \quad (29)$$

where (x_i, y_i) is the coordinate of cartesian contour and m is the number of points in the cartesian contour

4 Example

There are two color image leaf datasets (Flavia ,Swedish) are used. After passing through the required image processing steps, binary image is extracted which has a white foreground and black background.

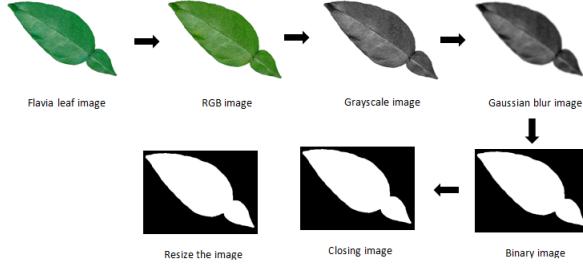


Figure 34: Image processing steps of Flavia dataset

The leaf images are taken as the closest ones. Therefore to find the best contour among several contours, can use the contour which contains the center of leaf image. Identify the best contour is really important when extracting shape features.

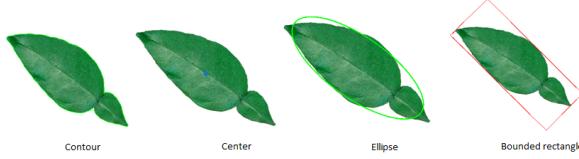


Figure 35: Example feature extraction of Flavia dataset

5 Application of features to classify images

5.1 Data sets

We use two publicly available datasets for demonstrate the applications of features.

5.1.1 Flavia Leaf Image Dataset

The Flavia dataset contains 1907 leaf images. There are 32 different species and each have 50-77 images. Scanners and digital cameras are used to acquire the leaf images on plain background. The isolated

leaf images contain blades only, without petiole. These leaf images are collected from the most common plants in Yangtze, Delta, China (Waldchen and Mader 2018). Those leaves were sampled on the campus of the Nanjing University and the Sun Yat-Sen arboretum, Nanking, China (Waldchen and Mader 2018). (<https://sourceforge.net/projects/flavia/files/Leaf%2520Image%2520Dataset/>)



Figure 36: Sample of Flavia dataset

5.1.2 Swedish Leaf Image Dataset

The Swedish dataset contains 1125 images. The images of isolated leaf scans on a plain background of 15 Swedish tree species, with 75 leaves per species. This dataset has been captured as part of a joined leaf classification project between the Linkoping University and the Swedish Museum of Natural History (Waldchen and Mader 2018). (<https://www.cvl.isy.liu.se/en/research/datasets/swedish-leaf/>)



Figure 37: Sample of Swedish leaf dataset

5.2 Visualization of Leaf Images in the Feature Space

We used LDA, and PCA to visualize leaf images in feature space. LDA is a supervised dimensionality reduction technique, and PCA is unsupervised dimensionality reduction technique. In this section, we visualize, and compare the results obtained using LDA, and PCA on flavia and swedish datasets. To visualize LDA projection shape label is taken as the response variable. There are mainly 5 shape categories as diamond, simple round, round, needle, and heart shape. More details about the shape categories are discussed in our next paper.

5.2.1 Swedish Dataset

PCA Projection

The results of the PCA1 and PCA2, and PCA1 and PCA3 projection on swedish dataset shows clear separation among the shapes.

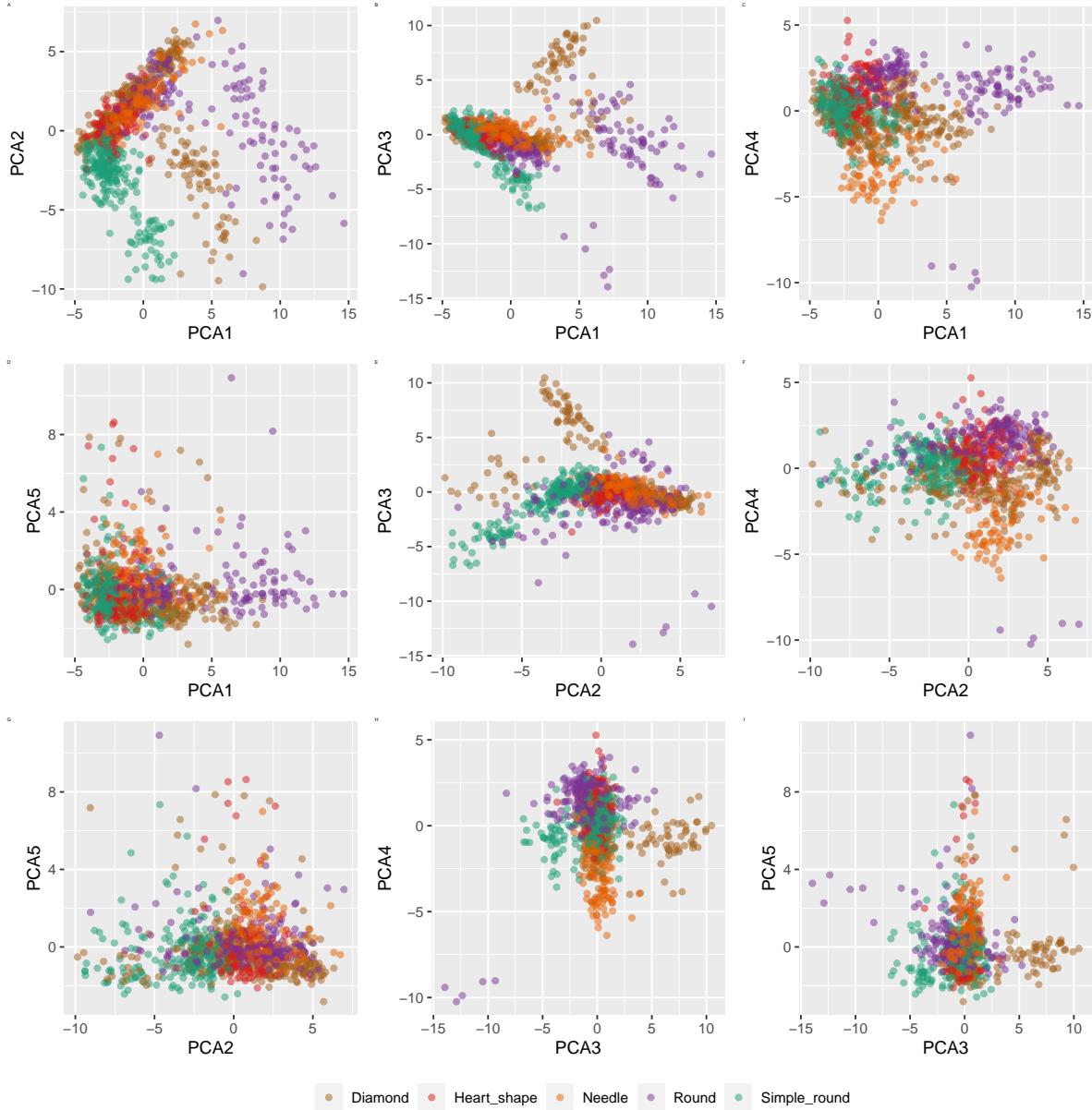


Figure 38: Distribution of Swedish leaf images on the projection space created based on pincipal component analysis. All projected points are coloured according to their shape labels.

LDA Projection

When consider the LDA results on swedish dataset, LDA1, LDA2, and LDA3 shows the separation of shapes of leaf images.

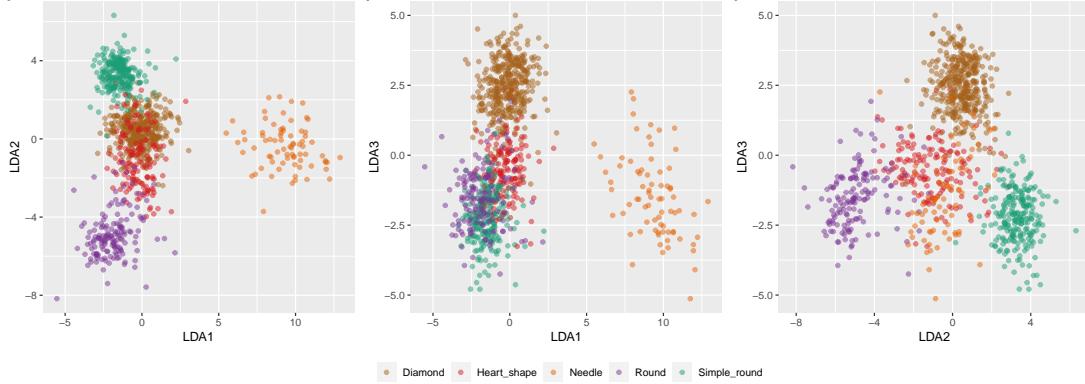


Figure 39: Distribution of Swedish leaf images on the projection space created based on linear discriminant analysis. All projected points are coloured according to their shape labels.

5.2.2 Flavia Dataset

PCA projection

LDA Projection

The projected results of LDA1 and LDA2 on flavia dataset shows clear classification of leaf shapes than PCAs.

6 Discussion and Conclusions

There are mainly four categories of features that are used to classify leaf images. Many research were based on shape, color, and texture features. In this research paper, we introduced new feature category called scagnostics. Other than that correlation of cartesian coordinate, number of convex points, number of minimum and maximum points are introduced as new shape features. To visualize the leaf images on feature space LDA, and PCA are used. The results are obtained based on flavia and swedish datasets. LDA is performed better than PCA when classifying leaf shapes. More details about the classification of leaf images are described in our next paper.

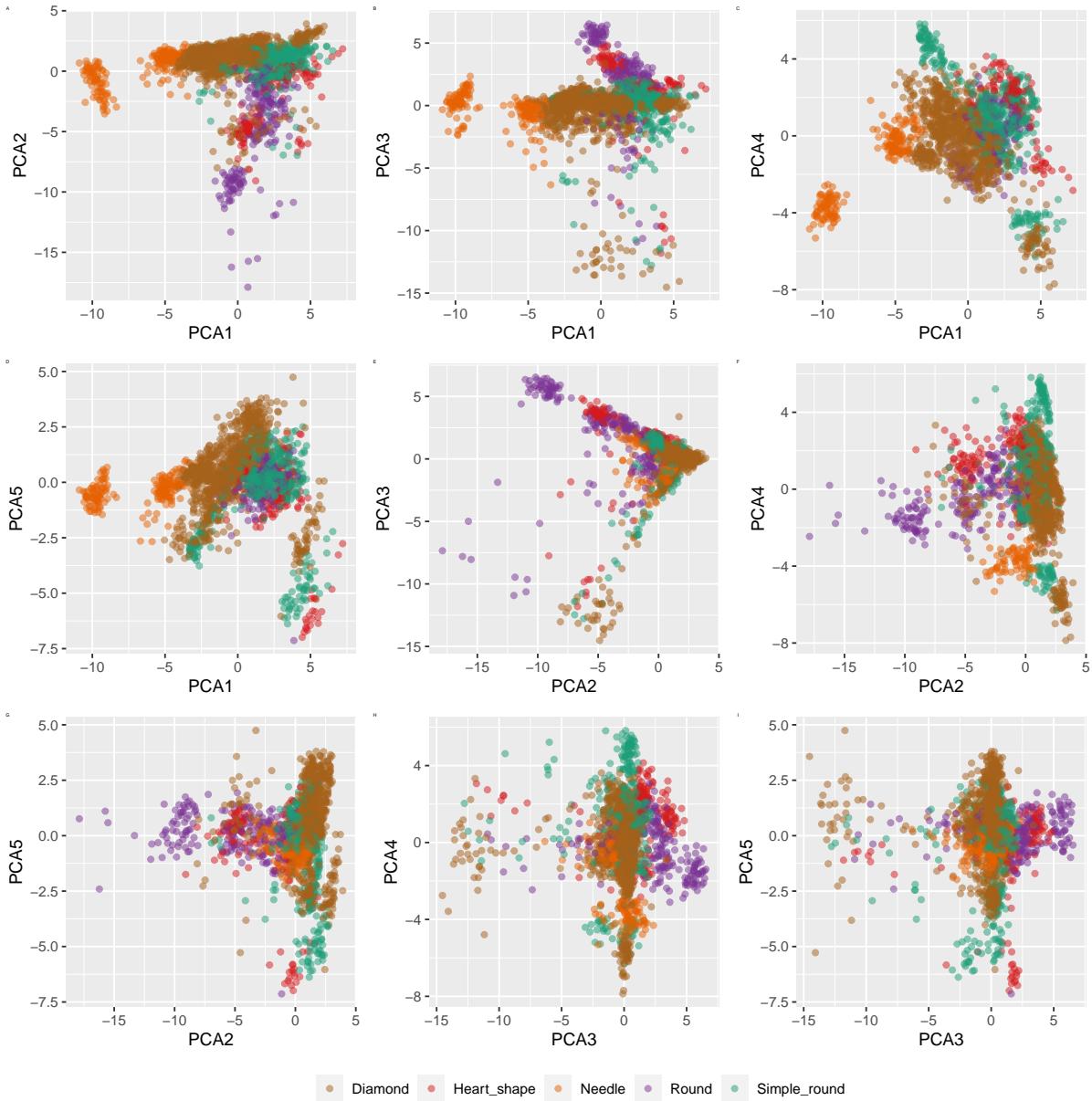


Figure 40: Distribution of Flavia leaf images on the projection space created based on principal component analysis. All projected points are coloured according to their shape labels.

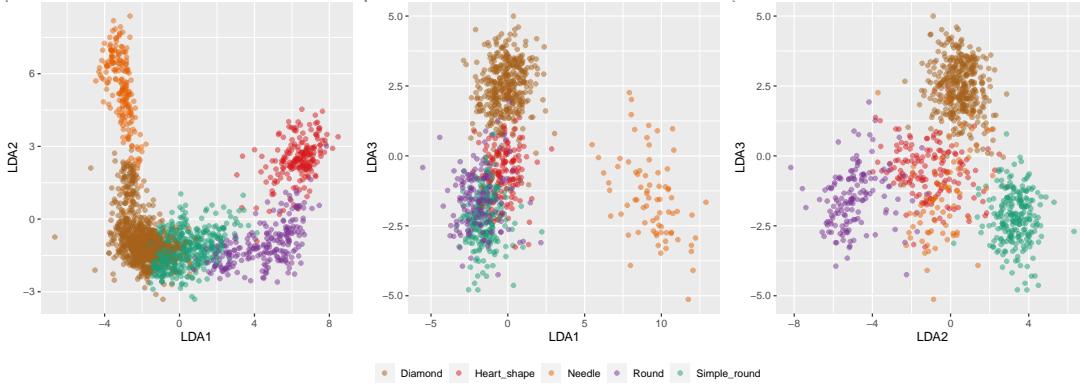


Figure 41: Distribution of Flavia leaf images on the projection space created based on linear discriminant analysis. All projected points are coloured according to their shape labels.

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