Deadlock

Unit-II

Lecture -5



- To develop a description of deadlocks, which prevent sets of concurrent processes from completing their tasks
- To present a number of different methods for preventing or avoiding deadlocks in a computer system

At the end of this session, participants will be able to

- Discuss System Model and Deadlock Characterization
- Describe methods for Handling Deadlocks, Deadlock Prevention, Deadlock Avoidance
- Discuss deadlock Detection and Recovery from Deadlock



- 1 System Model
- 2 Deadlock Characterization
- 3 Methods for Handling Deadlocks
- 4 Deadlock Prevention
- 5 Deadlock Detection



Presentation Outline

- 1 System Model



System Model

- System consists of resources
- Resource types $R_1, R_2, ..., R_m$
- CPU cycles, memory space, I/O devices
- Each resource type Ri has Wi instances.
- Each process utilizes a resource as follows:
 - request
 - IISe
 - release

Presentation Outline

- Deadlock Characterization



Deadlock can arise if four conditions hold simultaneously

- Mutual exclusion: only one process at a time can use a resource
- Hold and wait: a process holding at least one resource is waiting to acquire additional resources held by other processes
- No preemption: a resource can be released only voluntarily by the process holding it, after that process has completed its task
- **Circular wait**: there exists a set $\{P_0, P_1, P_n\}$ of waiting processes such that P_0 is waiting for a resource that is held by P_1, P_1 is waiting for a resource that is held by P_2, P_{n1} is waiting for a resource that is held by P_n , and P_n is waiting for a resource that is held by P_0 . 4 D > 4 A > 4 B > 4 B >

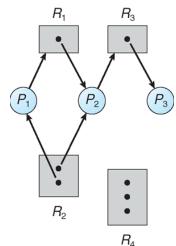
A set of vertices V and a set of edges E.

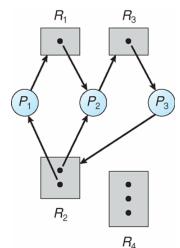
- V is partitioned into two types:
- $P = \{P_1, P_2, P_n\}$, the set consisting of all the processes in the system
- $R = \{R_1, R_2, R_m\}$, the set consisting of all resource types in the system
 - **request edge** directed edge $P_i \rightarrow R_i$
 - **assignment edge** directed edge $R_i \rightarrow P_i$



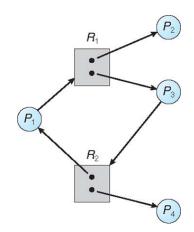
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Example of a Resource Allocation Graph





Graph With A Cycle But No Deadlock



- If graph contains no cycles → no deadlock
- \blacksquare If graph contains a cycle \rightarrow
 - if only one instance per resource type, then deadlock
 - if several instances per resource type, possibility of deadlock

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Presentation Outline

- 3 Methods for Handling Deadlocks



- Ensure that the system will never enter a deadlock state:
 - Deadlock prevention
 - Deadlock avoidance
- Allow the system to enter a deadlock state and then recover
- Ignore the problem and pretend that deadlocks never occur in the system; used by most operating systems, including UNIX

Presentation Outline

- Deadlock Prevention



Deadlock Prevention

Restrain the ways request can be made

- Mutual Exclusion not required for sharable resources (e.g., read-only files); must hold for non-sharable resources
- Hold and Wait must guarantee that whenever a process requests a resource, it does not hold any other resources
 - Require process to request and be allocated all its resources before it begins execution, or allow process to request resources only when the process has none allocated to it.
 - Low resource utilization; starvation possible



No Preemption

- If a process that is holding some resources requests another resource that cannot be immediately allocated to it, then all resources currently being held are released
- Preempted resources are added to the list of resources for which the process is waiting
- Process will be restarted only when it can regain its old resources, as well as the new ones that it is requesting
- **Circular Wait** impose a total ordering of all resource types, and require that each process requests resources in an increasing order of enumeration



Requires that the system has some additional a priori information available

- Simplest and most useful model requires that each process declare the maximum number of resources of each type that it may need
- The deadlock-avoidance algorithm dynamically examines the resource-allocation state to ensure that there can never be a circular-wait condition
- Resource-allocation state is defined by the number of available and allocated resources, and the maximum demands of the processes

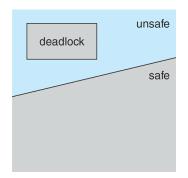


- When a process requests an available resource, system must decide if immediate allocation leaves the system in a safe state
- System is in safe state if there exists a sequence $\langle P_1, P_2, P_n \rangle$ of ALL the processes in the systems such that for each P_i , the resources that P_i can still request can be satisfied by currently available resources + resources held by all the P_i , with J < I; That is:
 - If P_i resource needs are not immediately available, then P_i can wait until all P_i have finished
 - When P_i is finished, P_i can obtain needed resources, execute, return allocated resources, and terminate
 - When P_i terminates, P_{i+1} can obtain its needed resources, and so on



- If a system is in safe state \rightarrow no deadlocks
- $lue{}$ If a system is in unsafe state ightarrow possibility of deadlock
- \blacksquare Avoidance \rightarrow ensure that a system will never enter an unsafe state.

Safe, Unsafe, Deadlock State



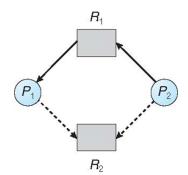
- Single instance of a resource type
 - Use a resource-allocation graph
- Multiple instances of a resource type
 - Use the bankers algorithm



- Claim edge $P_i \rightarrow R_i$ indicated that process P_i may request resource R_i ; represented by a dashed line
- Claim edge converts to request edge when a process requests a resource
- Request edge converted to an assignment edge when the resource is allocated to the process
- When a resource is released by a process, assignment edge reconverts to a claim edge
- Resources must be claimed a priori in the system



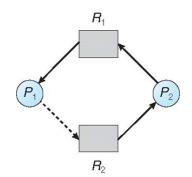
Resource-Allocation Graph





Deadlock Prevention

Unsafe State In Resource-Allocation Graph



- Suppose that process P_i requests a resource R_i
- The request can be granted only if converting the request edge to an assignment edge does not result in the formation of a cycle in the resource allocation graph

Bankers Algorithm

- Multiple instances
- Each process must a priori claim maximum use
- When a process requests a resource it may have to wait
- When a process gets all its resources it must return them in a finite amount of time



Let n = number of processes, and m = number of resources types

- **Available**: Vector of length m. If **available** [j] = k, there are k instances of resource type R_i available
- Max: $n \times m$ matrix. If Max [i,j] = k, then process P_i may request at most k instances of resource type R_i
- **Allocation**: $n \times m$ matrix. If **Allocation[i,j] = k** then P_i is currently allocated k instances of R_i
- **Need**: $n \times m$ matrix. If **Need[i,i]** = **k**, then P_i may need kmore instances of R_i to complete its task Need [i,j] = Max[i,j] Allocation [i,j]



Safety Algorithm

Let Work and Finish be vectors of length m and n, respectively. Initialize:

Work = Available Finish [i] = false for i = 0, 1, n - 1

- **2** Find an *i* such that both:
 - (a) Finish [i] = false
 - (b) $Need_i \leq Work$ If no such i exists, go to step 4
- Work = Work + Allocation;
 Finish[i] = true
 go to step 2
- 4 If **Finish** [i] == **true** for all *i*, then the system is in a safe state

 $Request_i = request$ vector for process P_i . If $Request_i[j] = k$ then process P_i wants k instances of resource type R_i

- 1 If $Request_i < Need_i$ go to step 2. Otherwise, raise error condition, since process has exceeded its maximum claim
- 2 If **Request**; < **Available**, go to step 3. Otherwise P_i must wait, since resources are not available
- 3 Pretend to allocate requested resources to Pi by modifying the state as follows:

```
Available = Available Request_i;
Allocation_i = Allocation_i + Request_i;
Need_i = Need_i Reguest_i:
```

- 4 If safe \rightarrow the resources are allocated to P_i
- If unsafe $\rightarrow P_i$ must wait, and the old resource-allocation state is restored 4 D > 4 A > 4 B > 4 B >



- 5 processes P_0 through P_4 ;
 - 3 resource types:

A (10 instances), B (5instances), and C (7 instances)

Snapshot at time T_0 :

	<u>Allocation</u>	<u>Max</u>	<u>Available</u>
	ABC	ABC	ABC
P_0	0 1 0	753	3 3 2
P_1	200	3 2 2	
P_2	302	902	
P_3	2 1 1	222	
P_4	002	4 3 3	

The content of the matrix **Need** is defined to be **Max – Allocation**

The system is in a safe state since the sequence $\langle P_1, P_3, P_4, P_2, P_0 \rangle$ satisfies safety criteria

Check that Request \leq Available (that is, $(1,0,2) \leq (3,3,2) \Rightarrow$ true

	<u>Allocation</u>	<u>Need</u>	<u>Available</u>
	ABC	ABC	ABC
P_0	0 1 0	7 4 3	230
P_1	302	020	
P_2	302	600	
P_3	2 1 1	0 1 1	
P_4	002	4 3 1	

- Executing safety algorithm shows that sequence $\langle P_1, P_3, P_4, P_0, P_2 \rangle$ satisfies safety requirement
- Can request for (3,3,0) by P_4 be granted?
- Can request for (0,2,0) by P_0 be granted?



- 5 Deadlock Detection

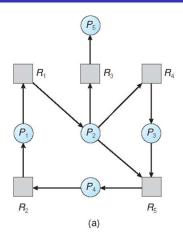


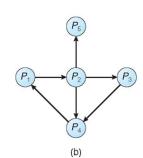
- Allow system to enter deadlock state
- Detection algorithm
- Recovery scheme



- Maintain wait-for graph
 - Nodes are processes
 - $P_i \rightarrow P_i$ if P_i is waiting for P_i
- Periodically invoke an algorithm that searches for a cycle in the graph. If there is a cycle, there exists a deadlock
- An algorithm to detect a cycle in a graph requires an order of n^2 operations, where n is the number of vertices in the graph







Resource-Allocation Graph

Corresponding wait-for graph



- **Available**: A vector of length **m** indicates the number of available resources of each type
- Allocation: An n x m matrix defines the number of resources of each type currently allocated to each process
- **Request**: An **n** x m matrix indicates the current request of each process. If **Request** [i][j] = k, then process P_i is requesting **k** more instances of resource type R_i .

- 1 Let Work and Finish be vectors of length m and n, respectively Initialize: (a) Work = Available (b) For i = 1,2, n, if **Allocation**; $\neq 0$, then Finish[i] = false; otherwise, Finish[i] = true
- Find an index i such that both:
 - (a) Finish[i] == false
 - (b) $Reguest_i < Work$ If no such i exists, go to step 4



go to step 2

3 Work = Work + Allocation; Finish[i] = true

4 If Finish[i] == false, for some i, 1 < i < n, then the system is in deadlock state. Moreover, if **Finish[i]** == **false**, then P_i is deadlocked

Algorithm requires an order of $O(m \times n^2)$ operations to detect whether the system is in deadlocked state

Example of Detection Algorithm

P₂ requests an additional instance of type C

Request

ABC

 P_0 000

202 P_1

 P_2 001

 P_3 100

 P_{A} 002

- State of system?
 - Can reclaim resources held by process P_0 , but insufficient resources to fulfill other processes; requests
 - Deadlock exists, consisting of processes P_1 , P_2 , P_3 , and P_4



Example

- Five processes P₀ through P₄; three resource types
 A (7 instances), B (2 instances), and C (6 instances)
- □ Snapshot at time T₀:

	<u>Allocation</u>	<u>Request</u>	<u>Available</u>
	ABC	ABC	ABC
P_0	010	000	000
P_1	200	202	
P_2	303	000	
P_3	2 1 1	100	
P_4	002	002	

□ Sequence $\langle P_0, P_2, P_3, P_1, P_4 \rangle$ will result in **Finish[i] = true** for all **i**



Detection-Algorithm Usage

- When, and how often, to invoke depends on:
 - How often a deadlock is likely to occur?
 - How many processes will need to be rolled back? one for each disjoint cycle
- If detection algorithm is invoked arbitrarily, there may be many cycles in the resource graph and so we would not be able to tell which of the many deadlocked processes caused the deadlock

Recovery from Deadlock: Process Termination

- Abort all deadlocked processes
- Abort one process at a time until the deadlock cycle is eliminated
- In which order should we choose to abort?
 - 1 Priority of the process
 - How long process has computed, and how much longer to completion
 - Resources the process has used
 - Resources process needs to complete
 - How many processes will need to be terminated
 - Is process interactive or batch?



Recovery from Deadlock: Resource Preemption

- Selecting a victim minimize cost
- Rollback return to some safe state, restart process for that state
- Starvation same process may always be picked as victim, include number of rollback in cost factor



Summary

- A deadlocked state occurs when two or more processes are waiting indefinitely for an event that can be caused only by one of thewaiting processes.
- Deadlock Characterization
- Methods for Handling Deadlocks
- Deadlock Prevention and Deadlock Avoidance
- Deadlock Detection and Recovery from Deadlock

- List three examples of deadlocks that are not related to a computer system environment
- How deadlock can be prevented?
- How can it be detected?