#### COURSE: UCS1502 - MICROPROCESSORS AND INTERFACING

### Addressing modes of 8086

Dr. K. R. Sarath Chandran Assistant Professor, Dept. of CSE

#### This presentation covers

Addressing modes of 8086

#### **Learning Outcome of this module**

To understand various addressing modes of 8086



# Do you know ??

- What is addressing mode?
- What are the different addressing modes of 8086?



Different ways of representing source operands in instructions are known as addressing modes. There are 8 different addressing modes in 8086.

#### 1. Immediate addressing mode:

Data operand is a part of the instruction itself.

Eg:

MOV AX, 543FH MOV CH, 00H

### 2. Direct addressing mode:

The address of the memory location is written directly in the instruction.

MOV AX, [5000]

Physical address calculation for above instruction is 10H x DS + 5000H

Eg: if DS = 1000, DS: Offset = 1000:5000

Physical address =  $10H \times 1000 + 5000 = 10000 + 5000 = 15000H$ 



### 3. Register addressing mode:

In this, operands are mentioned in registers. MOV AX, BX MOV CH, AH

### 4. Register indirect addressing mode:

This addressing mode allows data to be addressed at any memory location through an offset address held in any of the following registers: BP, BX, DI & SI.

MOV AX, [BX]

Physical address calculation for above instruction is 10H x DS + BX

Eg: if DS = 1000, BX = 2000

Physical address =  $10H \times 1000 + 2000 = 10000 + 2000 = 12000H$ 



### 5. Indexed addressing mode:

Here offset of the operand is stored in one of the index registers. DS is the default segment for SI, and ES is the default segment for DI.

MOV AX, [SI]

Physical address =  $10H \times DS + SI$ 

### 6. Register relative addressing mode:

In this, data is available at an effective address formed by adding an 8 bit or 16-bit displacement value with content of any one of the registers BX, BP, SI, DI.

MOV AX, [BX+04]

MOV AX, [BX+5000]

Physical address calculation for above instruction is  $10H \times DS + BX + 5000$ 

Eg: if DS = 1000, BX = 2000

Physical address =  $10H \times 1000 + 2000 + 5000 = 10000 + 7000 = 17000H$ 



### 7. Based Indexed addressing mode:

The effective address of data is formed by adding content of base register BX or BP to the content of index register.

MOV AX, [BX+SI]

Physical address =  $10H \times DS + BX + SI$ 

#### 8. Relative Based Indexed addressing mode:

In this addressing mode, the operand's offset is computed by adding the base register contents, an index registers contents and 8 or 16-bit displacement.

MOV AX, [BX+SI+5000]

Physical address calculation for above instruction is 10H x DS + BX + SI + 5000

Eg: if DS = 1000, BX = 2000 and SI = 3000

Physical address =  $10H \times 1000 + 2000 + 3000 + 5000 = 1A000H$ 



### **Summary**

- 1. Immediate addressing mode
- 2. Direct addressing mode
- 3. Register addressing mode
- 4. Register indirect addressing mode
- 5. Indexed addressing mode
- 6. Register relative addressing mode
- 7. Based Indexed addressing mode
- 8. Relative Based Indexed addressing mode

### References

• Doughlas V. Hall, "Microprocessors and Interfacing, Programming and Hardware", Second Edition, TMH, 2012.



# Thank you

