

Simulated Annealing



Simulated Annealing

Use a more complex Evaluation Function:

- Do sometimes accept candidates with higher cost to escape from local optimum
- Adapt the parameters of this Evaluation Function during execution
- Based upon the analogy with the simulation of the annealing of solids

Other Names

- Monte Carlo Annealing
- Statistical Cooling
- Probabilistic Hill Climbing
- Stochastic Relaxation
- Probabilistic Exchange Algorithm

Simulated Annealing

- Word comes from **metallurgy**
- In metallurgy – to make really strong objects, we follow slow and controlled cooling procedure known as annealing
- Same can be applied to Computer Science Algorithms
- SN algorithms are applied in
 - Travelling Sales Person problem
 - Designing printed circuit boards
 - Planning for a path for a Robot
 - Designing 3d structures of protein molecules in Bio-Informatics
- **Intuition behind SN:** At the beginning, we don't care about actually moving towards the good solution and accept bad moves as well and bad configurations as well.
 - But as we progress towards the solution, we become more careful and try to get closer to the solution and selecting only good moves

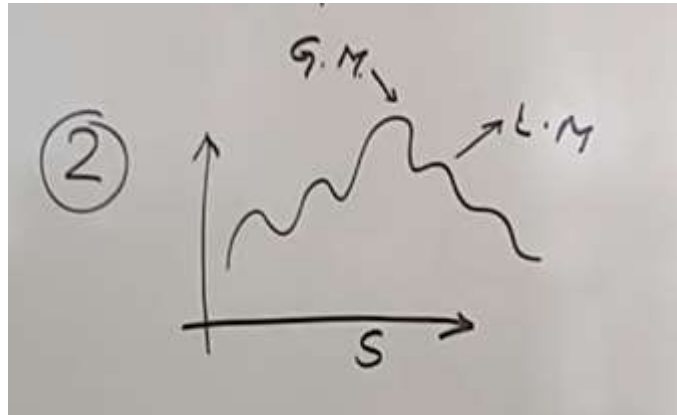
Simulated Annealing

- To formulate any problem in order to apply algorithms like SN, every problem needs to have a way to define how good a given configuration is.
- Every problem or every solution that we are solving needs to have a way to describe the goodness or fitness of the solution of the problem.
- In other words, in optimization problems, it is known as **Energy** of the solution
- Define the ENERGY of the solution as E and CHANGE in Energy as ΔE
 - Every time the system goes through a change of configuration, we can compute Energy
- **Example: Water bubble Game:**
 - One can focus in just one of the hooks and continue to play the game that he/she can get as many rings as possible in one of the holes, forgetting about the remaining hooks
 - After certain time, We will end up in a **DEADLOCK** where we have lot of rings hooked in one of the hooks but the other hooks are empty
 - If we play vigorously, remove lot of rings that are already solved
 - If we play very slow, it will take really a long time to get to the final solution



Simulated Annealing

- Deadlock Situations are known as LOCAL MAXIMA or LOCAL MINIMA
- Can plot all possible configurations of a given system on X axis and on Y axis, we were to compute the corresponding ENERGY of all the configurations, then ENERGY LANDSCAPE will be



- Once Energy is defined and comes to know about the GLOBAL MINIMA / MAXIMA, we also need a way in which we can change the configuration of the system every time
- In Water bubble game, we can change the CONFIGURATION, by pressing the button – it **randomly** alters the configuration of the system to get a new configuration

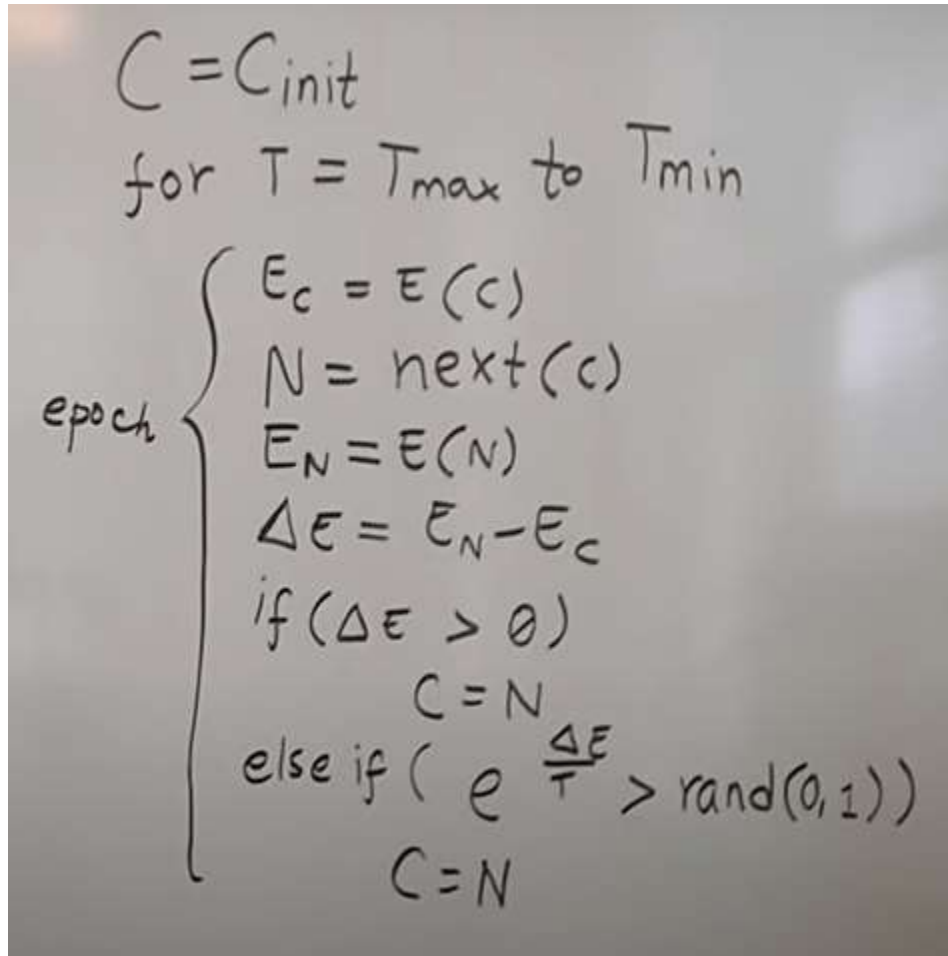
Simulated Annealing

- Where we can apply this ?



- With these definitions, Let us get into **SIMULATED ANNEALING** Algorithm

Simulated Annealing Algorithm



Handwritten code for the Simulated Annealing Algorithm:

```
C = Cinit
for T = Tmax to Tmin
  epoch {
    Ec = E(C)
    N = next(C)
    EN = E(N)
    ΔE = EN - Ec
    if (ΔE > 0)
      C = N
    else if ( e-ΔE/T > rand(0,1))
      C = N
```

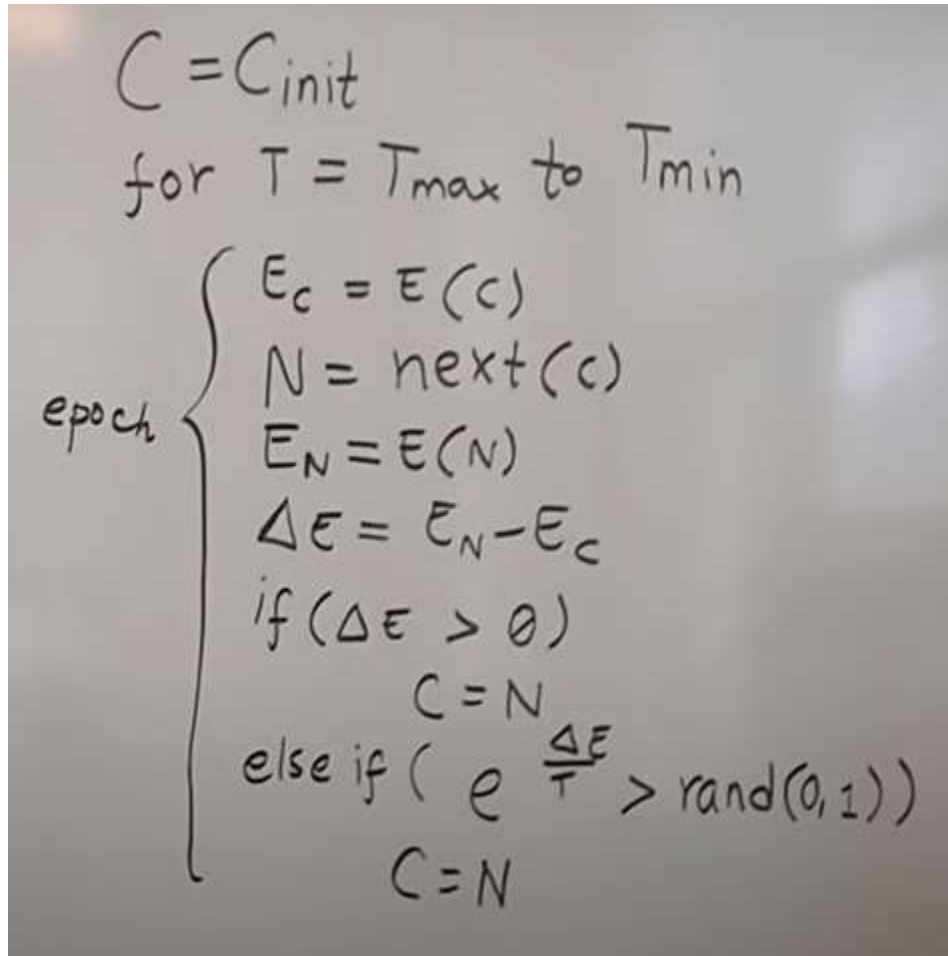
C_{init} – Initial Configuration

T – Temperature (Monotonically decreasing function)

In annealing, start with very high temperature, we slowly controlled to cool the material

- For every value of temperature, compute the current energy of the system for the current configuration (E_c)
- Alter/Change the configuration
- Compute Energy for this New config (E_N)
- Compute Change in Energy

Simulated Annealing Algorithm



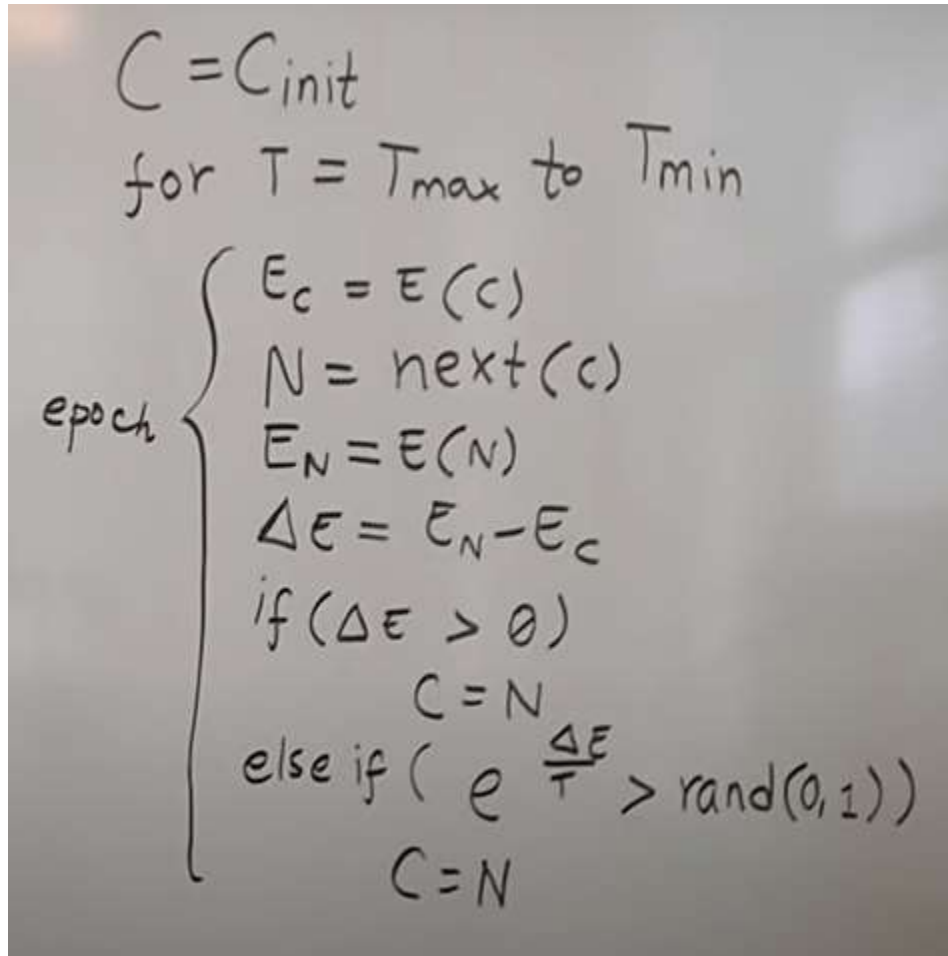
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```

IF we are working on
MAXIMIZATION problem

- $\Delta E > 0$, Change in Energy is a good move. So accepts the move
 - Set the NEW config as the CURRENT config
 - Repeat the Process and getting a better solution and move close to the FINAL solution
- $\Delta E < 0$, (Negative) Change in Energy is a bad move. So compute the probability as shown
 - If probability is very high, then accept the move even if it is a bad move
 - If probability is very low, then accept the move even with low probability

Simulated Annealing Algorithm



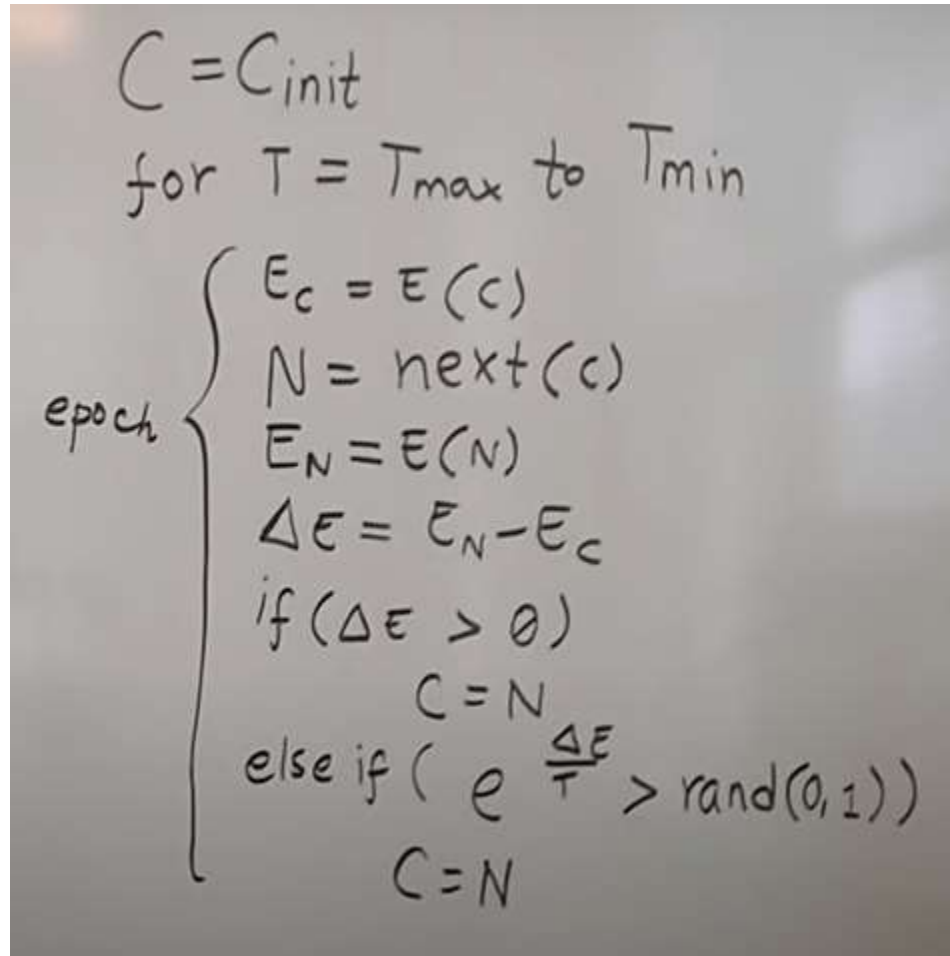
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for T = T_max to T_min
    epoch {
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        N = next(C)
        E_N = E(N)
        ΔE = E_N - E_c
        if (ΔE > 0)
            C = N
        else if ( eΔE/T > rand(0,1) )
            C = N
```

Probability depends on 2 terms, ΔE and T

- When T is very high, then probability for accepting the bad move becomes very high
 - In other words, at HIGH T , we are exploring the solution space or we are exploring the configurations and accepting the bad moves as well
- When T is very low, then we have very low probability to accept the bad moves
- Eg. $T = 10,000$ and $\Delta E = 10$, then
$$e^{0.001} = 1.0010005001667$$

Means, has a very high probability to become greater than $\text{rand}(0,1)$. So accepts the move

Simulated Annealing Algorithm



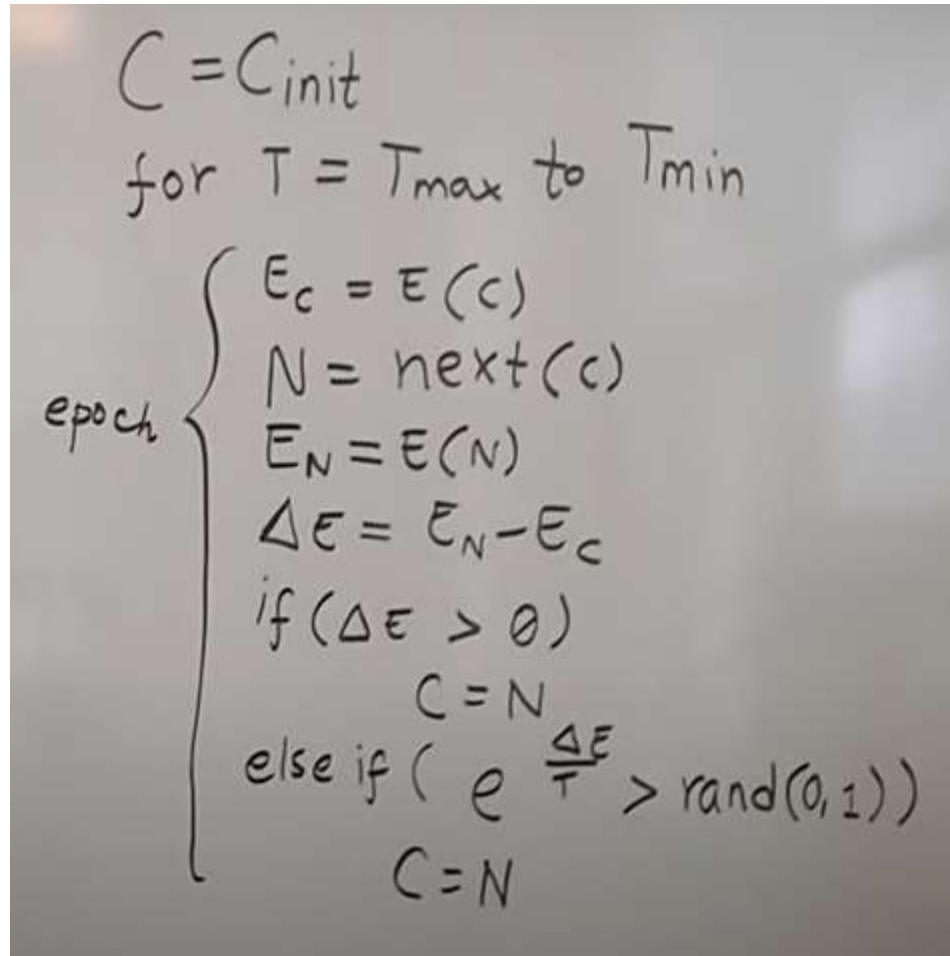
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Probability depends on 2 terms, ΔE and T

- When T is very high, then probability for accepting the **bad move** becomes **very high**
 - In other words, at HIGH T , we are exploring the solution space or we are exploring the configurations and accepting the bad moves as well
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Simulated Annealing Algorithm



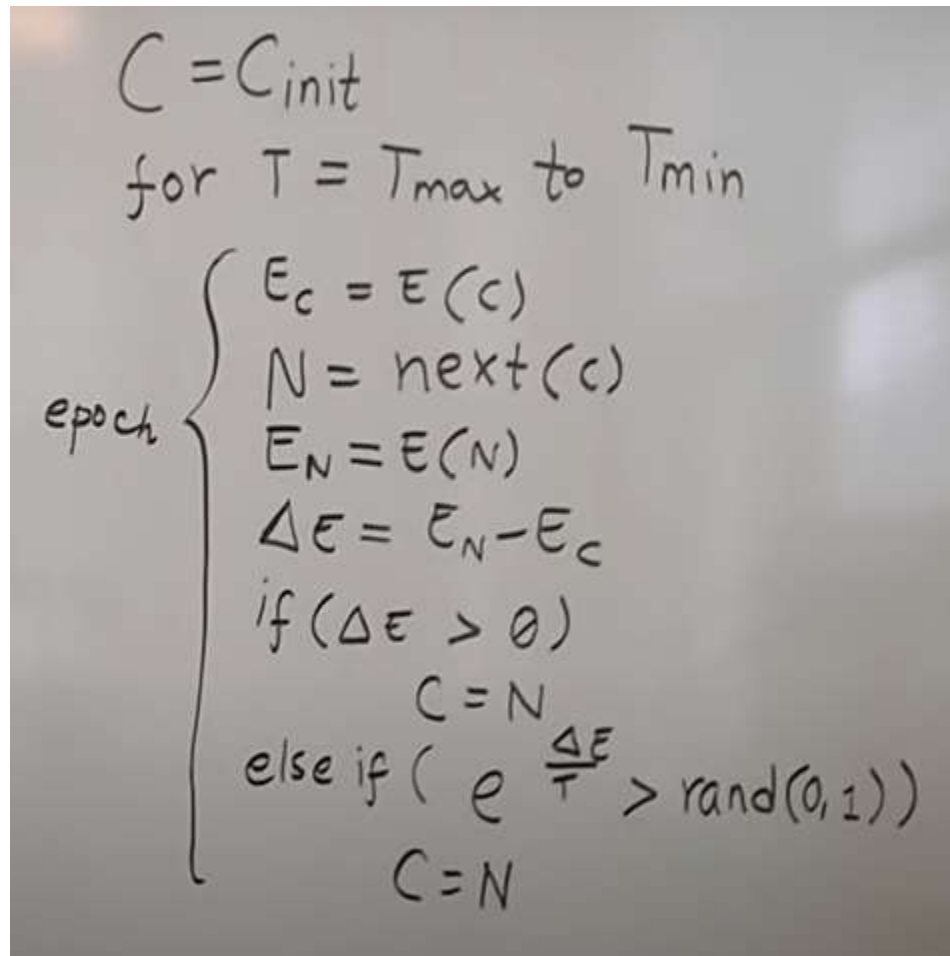
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```

ΔE also influences

- When ΔE is very high, then we have very low probability to accept the **bad move**
- When ΔE is very low, then we have very high probability to accept the bad move
- Repeat the process for certain no. of times. Epochs = 100 or 200
- Finally, expecting the solution to converge towards the GLOBAL MAXIMUM (/ MINIMUM)

Simulated Annealing Algorithm



Handwritten code for the Simulated Annealing Algorithm:

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    Ec = E(c)
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```

1. **Remove the Probability factor** or the Temperature factor and always **accept the good moves only** – **HILL CLIMBING / Greedy algorithm** which always move towards a better solution
 - Such algorithms are prone to easily be stuck in LOCAL MINIMA
2. **Random Walk** – We don't care about how good a move we are making every time, but we just explore, continue to explore the space.
 - Such algorithms never converge and will probably never give you the best optimal solution

Simulated annealing search

- Idea: escape local maxima by allowing some "bad" moves but **gradually decrease** their frequency

```
function SIMULATED-ANNEALING(problem, schedule) returns a solution state
  inputs: problem, a problem
           schedule, a mapping from time to "temperature"
  local variables: current, a node
                   next, a node
                   T, a "temperature" controlling prob. of downward steps

  current ← MAKE-NODE(INITIAL-STATE[problem])
  for t ← 1 to ∞ do
    T ← schedule[t]
    if T = 0 then return current
    next ← a randomly selected successor of current
     $\Delta E \leftarrow \text{VALUE}[\textit{next}] - \text{VALUE}[\textit{current}]$ 
    if  $\Delta E > 0$  then current ← next
    else current ← next only with probability  $e^{\Delta E/T}$ 
```

Properties of simulated annealing search

- One can prove: If T decreases slowly enough, then simulated annealing search will find a global optimum with probability approaching 1
- Widely used in VLSI layout, airline scheduling, etc

Simulation of cooling (Metropolis 1953)

Minimization Problem

- At a fixed temperature T :
- Perturb (randomly) the current state to a new state
- ΔE is the difference in energy between current and new state
- If $\Delta E < 0$ (new state is lower), accept new state as current state
- If $\Delta E \geq 0$, accept new state with probability
$$Pr(\text{accepted}) = \exp(-\Delta E / k_B \cdot T)$$
- Eventually the system evolves into thermal equilibrium at temperature T ; then the formula mentioned before holds
- When equilibrium is reached, temperature T can be lowered and the process can be repeated

Performance

- SA is a **general solution** method that is **easily applicable** to a large number of problems
- "**Tuning**" of the parameters (initial **c** , decrement of **c** , stop criterion) is relatively easy
- Generally the **quality** of the results of SA is **good**, although it can take **a lot of time**
- Results are generally **not reproducible**: another run can give a different result
- SA can leave an optimal solution and not find it again (so try to remember the **best solution found so far**)
- Proven to find the **optimum** under certain conditions; one of these conditions is that you must **run forever**

Conclusions

- It is very easy to implement.
- It can be generally applied to a wide range of problems.
- SA can provide high quality solutions to many problems.
- Care is needed to devise an appropriate neighborhood structure and cooling scheduler to obtain an efficient algorithm.