# MAEKAWA'S DISTRIBUTED MUTEX ALGORITHM

Reference: 1. Mukesh Singhal & N.G. Shivaratri, Advanced Concepts in Operating Systems,

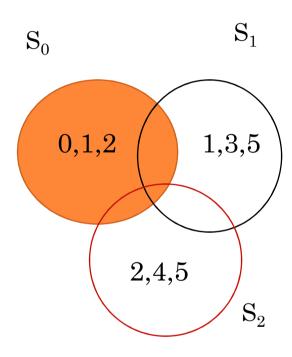
2. George Coulouris, Jean Dollimore and Tim Kindberg, "Distributed Systems Concepts and Design", Fifth Edition, Pearson Education, 2012

### MAEKAWA'S ALGORITHM

• With each process i, associate a subset  $S_i$ . Divide the set of processes into subsets that satisfy the following two conditions:

$$\begin{aligned} &\mathbf{i} \in S_i \\ &\forall i,j: \ 0 {\leq} i,j \leq n\text{-}1 \ | \quad S_i \cap S_j \ \neq \ \emptyset \end{aligned}$$

• Main idea. Each process i is required to receive permission from S<sub>i</sub> only. Correctness requires that multiple processes will never receive permission from all members of their respective subsets.



## MAEKAWA'S ALGORITHM

**Example**. Let there be seven processes 0, 1, 2, 3, 4, 5, 6

$$S_0 = \{0, 1, 2\}$$
 $S_1 = \{1, 3, 5\}$ 
 $S_2 = \{2, 4, 5\}$ 
 $S_3 = \{0, 3, 4\}$ 
 $S_4 = \{1, 4, 6\}$ 
 $S_5 = \{0, 5, 6\}$ 
 $S_6 = \{2, 3, 6\}$ 

## MAEKAWA'S ALGORITHM

#### Version 1 {Life of process I}

- 1. Send timestamped request to each process in  $S_i$ .
- Request received → send reply to process with the lowest timestamp. Thereafter, "lock" (i.e. commit) yourself to that process, and keep others waiting.
- 3. Enter CS if you receive an reply from each member in  $S_i$ .
- 4. To exit CS, send *release* to every process in S<sub>i</sub>.
- 5. Release received → unlock yourself. Then send reply to the next process with the lowest timestamp.

$$S_0 = \{0, 1, 2\}$$

$$S_1 = \{1, 3, 5\}$$

$$S_2 = \{2, 4, 5\}$$

$$S_3 = \{0, 3, 4\}$$

$$S_4 = \{1, 4, 6\}$$

$$S_5 = \{0, 5, 6\}$$

$$S_6 = \{2, 3, 6\}$$

ME1. At most one process can enter its critical section at any time.

Let **i** and **j** attempt to enter their Critical Sections

 $S_i \cap S_j \neq \emptyset$  implies there is a process  $k \in S_i \cap S_j$ 

Process k will never send reply to both.

So it will act as the arbitrator and establishes ME1

$$S_0 = \{0, 1, 2\}$$

$$S_1 = \{1, 3, 5\}$$

$$S_2 = \{2, 4, 5\}$$

$$S_3 = \{0, 3, 4\}$$

$$S_4 = \{1, 4, 6\}$$

$$S_5 = \{0, 5, 6\}$$

$$S_6 = \{2, 3, 6\}$$

#### ME2. No deadlock. Unfortunately deadlock is

possible! Assume 0, 1, 2 want to enter their critical sections.

From 
$$S_0 = \{0,1,2\}$$
,  $0,2$  send  $reply$  to  $0$ , but  $1$  sends  $reply$  to  $1$ ;

From 
$$S_1$$
= {1,3,5}, 1,3 send  $reply$  to 1, but 5 sends  $reply$  to 2;

From 
$$S_2$$
= {2,4,5}, 4,5 send  $reply$  to 2, but 2 sends  $reply$  to 0;

$$S_0 = \{0, 1, 2\}$$

$$S_1 = \{1, 3, 5\}$$

$$S_2 = \{2, 4, 5\}$$

$$S_3 = \{0, 3, 4\}$$

$$S_4 = \{1, 4, 6\}$$

$$S_5 = \{0, 5, 6\}$$

$$S_6 = \{2, 3, 6\}$$

#### Avoiding deadlock

If processes always receive messages in increasing order of timestamp, then deadlock "could be" avoided. But this is too strong an assumption.

Version 2 uses three *additional* messages:

- failed
- inquire
- yield

$$S_0 = \{0, 1, 2\}$$

$$S_1 = \{1, 3, 5\}$$

$$S_2 = \{2, 4, 5\}$$

$$S_3 = \{0, 3, 4\}$$

$$S_4 = \{1, 4, 6\}$$

$$S_5 = \{0, 5, 6\}$$

$$S_6 = \{2, 3, 6\}$$

## New features in version 2

- Send *reply* and set lock as usual.
- If lock is set and a request with a larger timestamp arrives, send failed (you have no chance). If the incoming request has a lower timestamp, then send inquire (are you in CS?) to the locked process.
- Receive *inquire* and at least one *failed* message → send *yield*. The recipient resets the lock.

$$S_0 = \{0, 1, 2\}$$

$$S_1 = \{1, 3, 5\}$$

$$S_2 = \{2, 4, 5\}$$

$$S_3 = \{0, 3, 4\}$$

$$S_4 = \{1, 4, 6\}$$

$$S_5 = \{0, 5, 6\}$$

$$S_6 = \{2, 3, 6\}$$

### RESOLVING DEADLOCK

P0 has lower timestamp so gets

higher priority. P1 has timestamp higher than P0, P0 P1 so gets lower priority. Waiting Queue P0 waits for reply from P1 P0P1 waits for reply from P0 P1 waits for reply from P2 P0P2P2 P2 waits for release from P0 P1 Waits for Release → Waits for Reply

ME2. No deadlock. Unfortunately deadlock is possible! Assume 0, 1, 2 want to enter their critical sections.

Now, 0 waits for 1 (to send a release), 1 waits for 2 (to send a release), , and 2 waits for 0 (to send a release), . So deadlock is possible!

S<sub>1</sub>= {1, 3, 5}

low priority high priority 
$$S_2$$
= {2, 4, 5}

i j k  $S_3$ = {0, 3, 4}

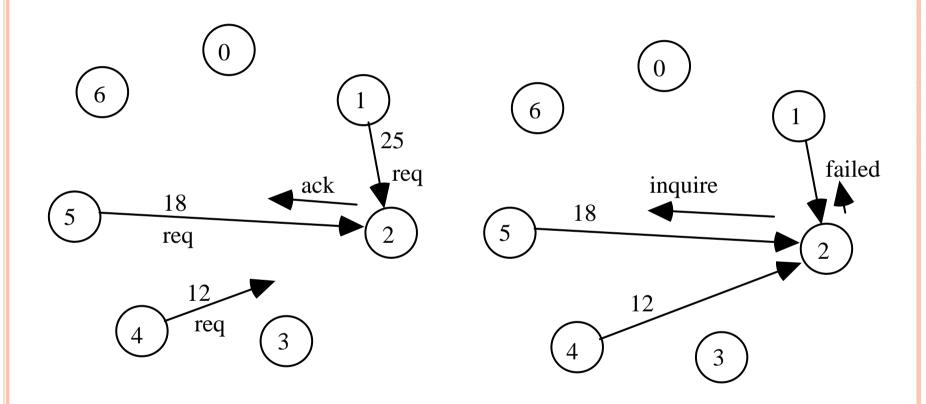
P1 blocks  $\Rightarrow$  P2 blocks  $\Rightarrow$  P0 (P0 locked by P1)  $S_4$ = {1, 4, 6}

P2 sends failed to P1 P2 sends Inquire to P0  $S_5$ = {0, 5, 6}

P0 sends yield to P2  $S_6$ = {2, 3, 6}

P2 sends Grant to P0

(P0 after receiving grant from P2, P0 replies to its waiting set of process with high priority, say here it is to P1)



## Maekawa's Algorithm

- state = <u>Released</u>, voted = false
- enter() at process Pi:
  - state = Wanted
  - Multicast Request message to all processes in Vi
  - Wait for Reply (vote) messages from all processes in Vi (including vote from self)
  - state = Held
- exit() at process Pi:
  - state = Released
  - Multicast Release to all processes in Vi

### Maekawa's Algorithm

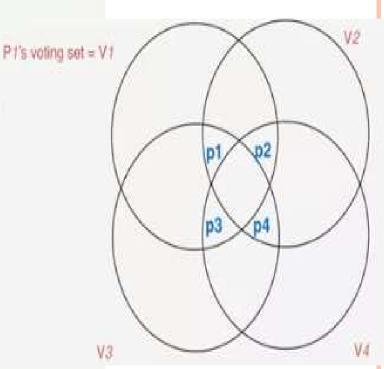
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When Pi receives a Request from Pj:
if (state == Held OR voted = true)
           queue Request
else
           send Reply to P_i and set voted = true
    When Pi receives a Release from Pj:
if (queue empty)
           voted = false
else
           dequeue head of queue, say Pk
           Send Reply only to Pk
           voted = true
```

#### SAFETY

- When a process Pi receives replies from all its voting set Vi members, no other process Pj could have received replies from all its voting set members Vj
  - Vi and Vj intersect in at least one process say Pk
  - But Pk sends only one Reply (vote) at a time, so it could not have voted for both Pi and Pj

### LIVENESS

- A process needs to wait for at most (N-1) other processes to finish CS
- But does not guarantee liveness
- Since can have a deadlock
- Example: all 4 processes need access
  - P1 is waiting for P3
  - P3 is waiting for P4
  - P4 is waiting for P2
  - P2 is waiting for P1
  - No progress in the system!
- There are deadlock-free versions



#### Performance of Maekawa's Algorithm

- Bandwidth
  - 2√N messages per enter()
  - √N messages per exit()
  - Better than Ricart and Agrawala's (2\*(N-1) and N-1 messages)
  - $\sqrt{N}$  quite small. N ~ 1 million =>  $\sqrt{N}$  = 1K
- Client delay: One round trip time
- Synchronization delay: 2 message transmission times