

Toy Car as AI Bot



Raktim Gautam Goswami¹, Abhishek Bairagi², Alok Ranjan Kesari³ & G V V Sharma⁴

1

1

CONTENTS

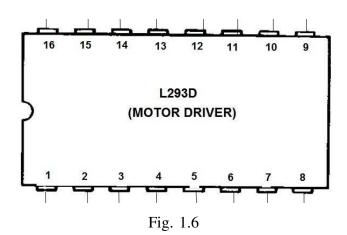
1 Hardware Setup

2 Implementation

Abstract—A Toycar is controlled using bluetooth and google voice recognition software.

1 HARDWARE SETUP

- 1.1 Assemble the motors, chassis and wheels to build the toycar.
- 1.2 Stick the breadboard to the chassis of the toycar.
- 1.3 Stick a 9V battery to the breadboard and connect the positive and negative terminals to extreme ends of the breadboard.
- 1.4 Stick a 9V battery to the breadboard and connect the positive and negative terminals to extreme ends of the breadboard.
- 1.5 Provide 9V to the supply pin of the Arduino.
- 1.6 Plug the L293D motor driver IC in Fig. 1.6 on the breadboard.



The authors are with the Department of Electrical Engineering, Indian Institute of Technology, Hyderabad 502285 India . e-mail: 1. ee17btech11004@iith.ac.in, 2. ee17btech11051@iith.ac.in, 3. arke-sari@iith.ac.in, 4. gadepall@iith.ac.in

Power	L293D			
9V	1	8	9	16
GND	4	5	12	13

Arduino	D2	D3	D4	D5
L293D	2	7	10	15

Motor	+		-	
L293D	3	11	6	14

TABLE 1.7

Arduino	D0	$\frac{2}{3}$ D1	5V	GND
HC05	TX	RX	Vcc	GND

TABLE 1.8

- 1.7 Connect the L293D pins according to Table 1.7.
- 1.8 Connect the HC05 pins according to Table 1.8.

2 Implementation

2.1 Dump the following code in Arduino using its IDE.

wget https://raw.githubusercontent.com/gadepall/EE1390/master/bot/codes/vcb.cpp

- 2.2 Install Google API "Arduino Bluetooth Controller" using google play-store
- 2.3 Open the app and connect to HC-05.
- 2.4 Open voice control section in the app and tap to give following commands.

Left, Right, Forward, Back & Stop

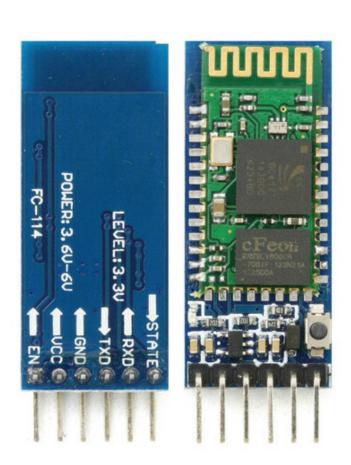


Fig. 1.8: HC05 Bluetooth module

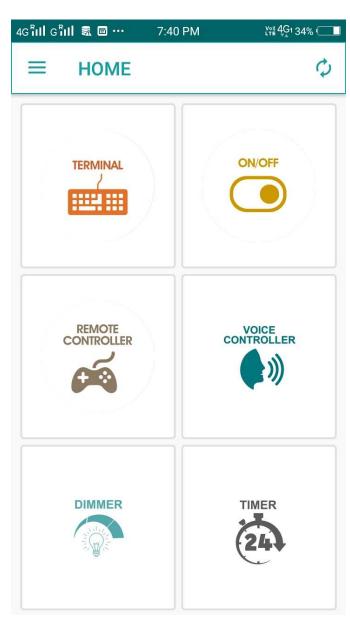


Fig. 2.2