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*Abstract—This manual provides an introduction to SVM.*

### 1 REFLECTION

1.1 Find the distance of  $\mathbf{x}_1 = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$  from the line

$$(3 \ 4)\mathbf{x} + 5 = 0 \quad (1.1)$$

1.2 Show that the distance of the point  $\mathbf{x}_1$  from the line

$$\mathbf{n}^T \mathbf{x} + c = 0, \quad \|\mathbf{n}\| = 1 \quad (1.2)$$

is

$$M = |\mathbf{n}^T \mathbf{x}_1 + c| \quad (1.3)$$

1.3 Find the reflection  $\mathbf{x}_2$  of  $\mathbf{x}_1$ .

1.4 Define

$$f(\mathbf{x}) = \mathbf{n}^T \mathbf{x} + c \quad (1.4)$$

1.5 Compute  $f(\mathbf{x}_1)$  and  $f(\mathbf{x}_2)$ . Comment.

### 2 OPTIMIZATION PROBLEM

2.1 Suppose  $(\mathbf{x}_1, y_1)$  and  $(\mathbf{x}_2, y_2)$  where  $y_1, y_2 \in \{1, -1\}$ . If you want to find  $\mathbf{n}, c$  from the given dataset, how will formulate the equivalent op-

timization problem?

**Solution:** Consider the optimization problem

$$\max_{\mathbf{n}, c} M \quad (2.1)$$

$$\text{s.t. } y_1 (\mathbf{x}_1^T \mathbf{n} + c) \geq M \quad (2.2)$$

$$y_2 (\mathbf{x}_2^T \mathbf{n} + c) \geq M \quad (2.3)$$

$$\|\mathbf{n}\| = 1 \quad (2.4)$$

2.2 The *signum* function is defined as

$$\text{sgn}(z) = \begin{cases} 1 & z > 0 \\ 0 & z = 0 \\ -1 & z < 0 \end{cases} \quad (2.5)$$

Show that

$$\text{sgn}(\mathbf{x}^T \mathbf{n} + c) = \text{sgn}(\mathbf{x}^T \mathbf{w} + d) \quad (2.6)$$

where

$$\mathbf{w} = \frac{\mathbf{n}}{M}, d = \frac{c}{M}, M > 0 \quad (2.7)$$

2.3 Show that (2.1)-(2.4) can be reformulated as

$$\min_{\mathbf{w}, d} \frac{1}{2} \|\mathbf{w}\|^2 \quad (2.8)$$

$$\text{s.t. } y_i (\mathbf{x}_i^T \mathbf{w} + d) \geq 1 \quad (2.9)$$

**Solution:** From (2.7),

$$\mathbf{w} = \frac{\mathbf{n}}{M} \implies \|\mathbf{w}\| = \frac{\|\mathbf{n}\|}{M} \quad (2.10)$$

$$\implies M = \frac{1}{\|\mathbf{w}\|} \because \|\mathbf{n}\| = 1 \quad (2.11)$$

Thus,

$$\max_{\mathbf{n}, c} M = \max_{\mathbf{w}, d} \frac{1}{\|\mathbf{w}\|} = \min_{\mathbf{w}, d} \|\mathbf{w}\|. \quad (2.12)$$

Also, (2.2)-(2.3) become

$$y_i (\mathbf{x}_i^T \mathbf{w} + d) \geq 1 \quad (2.13)$$

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- 2.4 Solve (2.8) for  $\mathbf{x}_1 = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$ ,  $y_1 = 1$  and  $\mathbf{x}_2 = \begin{pmatrix} 0.8 \\ -0.6 \end{pmatrix}$ ,  $y_2 = -1$  graphically.
- 2.5 Repeat the above exercise using KKT conditions.
- 2.6 Repeat the above exercise using *cvxpy/cvxopt*.

### 3 SVM

- 3.1 If  $\alpha_i$  be the Lagrange multiplier, obtain the Lagrange primal function for (2.8).  
**Solution:** The desired function is given by

$$L_p(\mathbf{w}, \alpha_i) = \frac{1}{2} \|\mathbf{w}\|^2 - \sum_{i=1}^N \alpha_i \{y_i (\mathbf{x}_i^T \mathbf{w} + d - 1)\} \quad (3.1)$$

- 3.2 Show that stationarity condition yields

$$\mathbf{w} = \sum_{i=1}^N \alpha_i y_i \mathbf{w}_i \quad (3.2)$$

$$0 = \sum_{i=1}^N \alpha_i y_i \quad (3.3)$$

**Solution:** From the stationarity condition,

$$\nabla_{\mathbf{w}} L_p(\mathbf{w}, d, \alpha_i) = \frac{\partial L_p(\mathbf{w}, \alpha_i)}{\partial \mathbf{w}} = 0 \quad (3.4)$$

$$\implies \mathbf{w}^T - \sum_{i=1}^N \alpha_i y_i \mathbf{x}_i^T = 0 \quad (3.5)$$

$$\text{or, } \mathbf{w} = \sum_{i=1}^N \alpha_i y_i \mathbf{x}_i \quad (3.6)$$

and

$$\nabla_d L_p(\mathbf{w}, d, \alpha_i) = \frac{\partial L_p(\mathbf{w}, \alpha_i)}{\partial d} = 0 \quad (3.7)$$

$$\implies \sum_{i=1}^N \alpha_i y_i = 0 \quad (3.8)$$

- 3.3 Substitute (3.21)-(3.23) in the primal function to obtain the Lagrangian (Wolfe) dual objective function  $L_D$ .
- 3.4 Repeat the above exercises for

$$\min_{\mathbf{w}} \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_{i=1}^N \xi_i \quad (3.9)$$

$$\text{s.t } \xi_i \geq 0 \quad (3.10)$$

$$y_i \mathbf{x}_i^T \mathbf{w} \geq 1 - \xi_i \quad (3.11)$$

$$\mathbf{w} = \sum_{i=1}^N \alpha_i y_i \mathbf{w}_i \quad (3.12)$$

$$0 = \sum_{i=1}^N \alpha_i y_i \quad (3.13)$$

$$\alpha_i = C - \mu_i \quad (3.14)$$

- 3.5 Show that the KKT conditions are

$$\alpha_i [y_i (\mathbf{x}_i^T \mathbf{w}) - (1 - \xi_i)] = 0 \quad (3.15)$$

$$\mu_i \xi_i = 0 \quad (3.16)$$

$$y_i (\mathbf{x}_i^T \mathbf{w}) - (1 - \xi_i) = 0 \quad (3.17)$$

- 3.6

$$P = \{\mathbf{x} : f(\mathbf{x}) = \mathbf{n}^T \mathbf{x} + c = 0\}, \quad \|\mathbf{n}\| = 1 \quad (3.18)$$

be a hyperplane where  $\mathbf{n}$  is a unit normal vector to the plane.

- 3.7 Let

$$P = \{\mathbf{x} : f(\mathbf{x}) = \mathbf{n}^T \mathbf{x} + c = 0\}, \quad \|\mathbf{n}\| = 1 \quad (3.19)$$

be a hyperplane where  $\mathbf{n}$  is a unit normal vector to the plane.

- 3.8 Consider the quadratic programming problem

$$\min_{\mathbf{w}} \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_{i=1}^N \xi_i \quad (3.20)$$

$$\text{s.t } \xi_i \geq 0 \quad (3.21)$$

$$y_i (\mathbf{x}_i^T \mathbf{w}) \geq 1 - \xi_i \quad (3.22)$$

- 3.9 If  $\alpha_i, \mu_i$  be the Lagrange multipliers, obtain the Lagrange primal function.

- 3.10 Show that stationarity condition yields

$$\mathbf{w} = \sum_{i=1}^N \alpha_i y_i \mathbf{w}_i \quad (3.23)$$

$$0 = \sum_{i=1}^N \alpha_i y_i \quad (3.24)$$

$$\alpha_i = C - \mu_i \quad (3.25)$$

3.11 Show that the KKT conditions are

$$\alpha_i \left[ y_i (\mathbf{x}_i^T \mathbf{w}) - (1 - \xi_i) \right] = 0 \quad (3.26)$$

$$\mu_i \xi_i = 0 \quad (3.27)$$

$$y_i (\mathbf{x}_i^T \mathbf{w}) - (1 - \xi_i) = 0 \quad (3.28)$$

3.12 Substitute (3.21)-(3.23) in the primal function to obtain the Lagrangian (Wolfe) dual objective function  $L_D$ .