

# Voice Recognition through Machine Learing



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Abstract—This manual shows how to develop a voice recognition algorithm and use it to control a toycar.

### 1 Dataset

1.1 Draw the block diagram of the AI-ML system for the toycar.

**Solution:** See Fig. 1.1

- 1.2 Record 'forward' 80 times using you phone and save as 'forwardi.wav' for i = 1, ..., 80. The recording duration should be between 1-3 seconds.
- 1.3 Repeat by recording 'left', 'right', 'back' and 'stop'. Make sure that the audio files for each command are in separate directories. Download the following directory for reference

svn checkout https://github.com/gadepall/ EE1390/trunk/AI-ML/audio\_dataset

1.4 Use the following script to generate a dataset for 'back' command. Explain through a block diagram.

https://raw.githubusercontent.com/gadepall/ EE1390/master/AI-ML/codes/250files.py

**Solution:** The datasets are generated through zero padding. The diagram in Fig. 1.4 explains how this is done for the back command.

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- 1.5 Suitably modify the above script to generate similar datasets for 'left', 'right', 'stop' and 'forward'.
- 1.6 Summarize the datasets generated through a table.

**Solution:** See Table 1.6

## 2 Linear Regression: Least Squares

- 2.1 Draw the block diagram for the ML algorithm **Solution:** See Fig. 2.1
- 2.2 List the reference vectors for all the voice commands.

**Solution:** See Table 2.2.

2.3 The sigmoid function is defined as

$$s(x) = \frac{1}{1 + e^{-x}} \tag{2.1}$$

Sketch s(x).

**Solution:** The following code plots s(x) in Fig. 2.3.

2.4 Show that 0 < s(x) < 1.

**Solution:** s(x) is useful for transforming large values to a value between 0 and 1.

2.5 Formulate a regression model for the voice recognition system.

**Solution:** Let  $\mathbf{x}$  be the voice command. The model used is

$$\mathbf{v} = \mathbf{W}\mathbf{x} + \mathbf{b} \tag{2.2}$$

where W is the weight matrix and b is the bias vector. Ideally, the output y should be one of the reference vectors in Table 2.2.

2.6 Frame an optimization problem for estimatingW and b.

**Solution:** This is done by considering the cost function

$$\min_{\mathbf{W}, \mathbf{b}} J(\mathbf{W}, \mathbf{b}) = \frac{1}{2} ||\mathbf{y} - \hat{\mathbf{y}}||^2$$
 (2.3)

Commands	Input	Output /	Conditioned	Training	Testing
		Input file			
Back	80	250	20000	16000	4000
Forward	80	250	20000	16000	4000
Left	80	250	20000	16000	4000
Right	80	250	20000	16000	4000
Stop	80	250	20000	16000	4000
	Total		100000		

TABLE 1.6: File calculus

Command	Reference vector						
Forward	(1	0	0	0	$0)^T$		
Back	(0	1	0	0	$0)^T$		
Left	(0	0	1	0	$0)^T$		
Right	(0	0	0	1	$0)^T$		
Stop	(0	0	0	0	$1)^T$		

TABLE 2.2: Reference vectors

where

$$\hat{\mathbf{y}} = \mathbf{W}\mathbf{x} + \mathbf{b} \tag{2.4}$$

3 Gradient Descent

3.1 Let W be  $2 \times 2$  and x, y be  $2 \times 1$ . Show that

$$\frac{\partial \left( \mathbf{y}^T \mathbf{W} \mathbf{x} \right)}{\partial \mathbf{W}} = \mathbf{y} \mathbf{x}^T \tag{3.1}$$

3.2 Given that **b** is  $2 \times 1$ , show that

$$\frac{\partial ||\mathbf{W}\mathbf{x} + \mathbf{b}||^2}{\partial \mathbf{W}} = 2(\mathbf{W}\mathbf{x} + \mathbf{b})\mathbf{x}^T$$

(3.2)

3.3 Find

$$\frac{\partial ||\mathbf{y} - \hat{\mathbf{y}}||^2}{\partial \mathbf{W}}$$
 (3.3) 3.10 Suppose

**Solution:** 

$$\|\mathbf{y} - \hat{\mathbf{y}}\|^2 = \|y\|^2 - 2\mathbf{y}^T (\mathbf{W}\mathbf{x} + \mathbf{b}) + \|\mathbf{W}\mathbf{x} + \mathbf{b}\|^2$$
(3.4)

From (3.1) and (3.2)

$$\frac{\partial ||\mathbf{y} - \hat{\mathbf{y}}||^2}{\partial \mathbf{W}} = -2(\mathbf{y} - \hat{\mathbf{y}})\mathbf{x}^T$$
 (3.5)

3.4 Show that

$$\frac{\partial \mathbf{y}^T \mathbf{b}}{\partial \mathbf{h}} = \mathbf{y} \tag{3.6}$$

3.5 Show that

$$\frac{\partial ||\mathbf{b}||^2}{\partial \mathbf{b}} = 2\mathbf{b} \tag{3.7}$$

3.6 Show that

$$\frac{\partial ||\mathbf{W}\mathbf{x} + \mathbf{b}||^2}{\partial \mathbf{b}} = 2(\mathbf{W}\mathbf{x} + \mathbf{b})$$
 (3.8)

3.7 Show that

3.9 Show that

$$\frac{\partial ||\mathbf{y} - \hat{\mathbf{y}}||^2}{\partial \mathbf{h}} = -2(\mathbf{y} - \hat{\mathbf{y}}) \tag{3.9}$$

3.8 W and b can be estimated from (2.3) using

$$\mathbf{W}(n+1) = \mathbf{W}(n) - \frac{\alpha}{2} \frac{\partial J(\mathbf{W}, \mathbf{b})}{\partial \mathbf{W}}$$
(3.10)

$$\mathbf{b}(n+1) = \mathbf{b}(n) - \frac{\alpha}{2} \frac{\partial J(\mathbf{W}, \mathbf{b})}{\partial \mathbf{b}}$$
(3.11)

Show that (3.10) can be expressed as

$$\mathbf{W}(n+1) = \mathbf{W}(n) + \alpha (\mathbf{y} - \hat{\mathbf{y}}) \mathbf{x}^{T}$$
 (3.12)

$$\mathbf{b}(n+1) = \mathbf{b}(n) + \alpha (\mathbf{y} - \hat{\mathbf{y}})$$
 (3.13)

$$s'(x) = (1 - s(x)) s(x)$$
 (3.14)

$$s(x) = (1 - s(x)) s(x)$$
 (3.14)

$$J(\mathbf{W}, \mathbf{b}) = \frac{1}{2} ||\mathbf{y} - s(\hat{\mathbf{y}})||^2$$
 (3.15)

where the  $s(\cdot)$  function operates elementwise.

Show that

$$\mathbf{W}(n+1) = \mathbf{W}(n) + \alpha \left[ (\mathbf{y} - s(\hat{\mathbf{y}})) \odot s'(\hat{\mathbf{y}}) \right] \mathbf{x}^{T}$$
(3.16)

$$\mathbf{b}(n+1) = \mathbf{b}(n) + \alpha (\mathbf{y} - s(\hat{\mathbf{y}})) \odot s'(\hat{\mathbf{y}})$$
(3.17)

where  $\odot$  is the Hadamard product, or elementwise multiplication of vectors.

3.11 Store the complete dataset in a directory and execute

https://raw.githubusercontent.com/gadepall/ EE1390/master/AI-ML/codes/code.py

from within the directory. Note that this should be done on a powerful workstation. This will generate two files **W1.out** and **b.out**. This is the full code that is used for training.

#### 4 Prediction

4.1 For the test input  $\mathbf{x}$ , compute  $s(\hat{\mathbf{y}})$  using the estimated  $\mathbf{W}$  and  $\mathbf{b}$ . If

$$\hat{y}_i = \max_j \hat{y}_j \tag{4.1}$$

define

$$y_i = 1, y_i = 0, i \neq j$$
 (4.2)

Match this vector the entries in Table 2.2.

4.2 Execute

https://raw.githubusercontent.com/gadepall/ EE1390/master/AI-ML/codes/record.py

to predict the output.

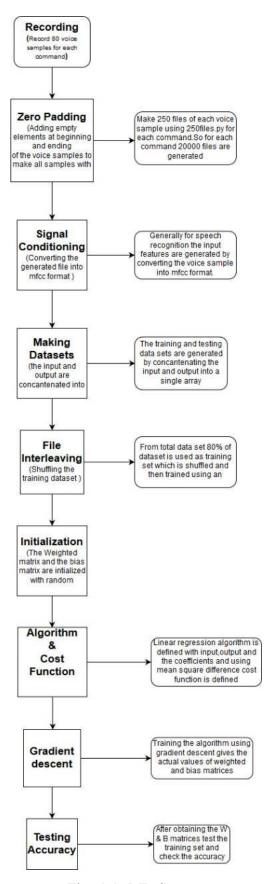


Fig. 1.1: ML System

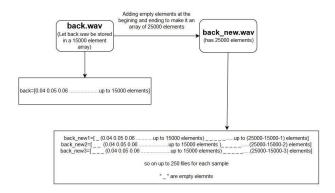


Fig. 1.4: Zero padding

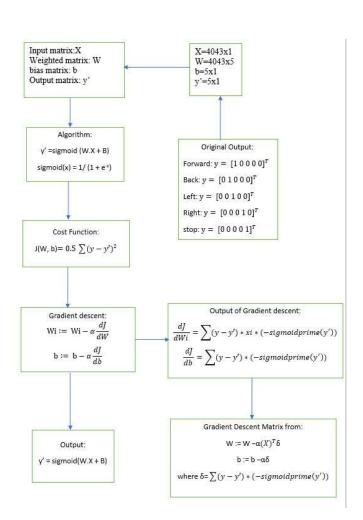


Fig. 2.1: Least squares and gradient descent

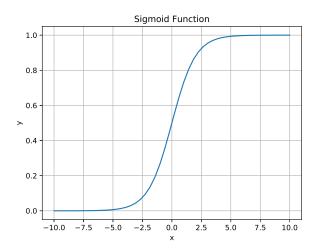


Fig. 2.3: Sigmoid function