#### 1

# Assignment 11

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Abstract—This is a simple document explaining how to form a basis of a vector space and how to get the coordinates of the vector.

Download all and latex-tikz codes from

svn co https://github.com/gadepall/school/trunk/ncert/geometry/figs

## 1 Problem

In  $C^3$ , let  $\alpha_1 = (1, 0, -i)$ ,  $\alpha_2 = (1 + i, 1 - i, 1)$ ,  $\alpha_3 = (i, i, i)$ . Prove that these vectors form a basis for  $C^3$ . What are the coordinates of the vector (a,b,c) in the basis?

### 2 EXPLANATION

Now,

$$C_1\alpha_1 + C_2\alpha_2 + C_3\alpha_3 = \mathbf{0}$$
 (2.0.1)

$$\implies C_1 \begin{pmatrix} 1\\0\\-i \end{pmatrix} + C_2 \begin{pmatrix} 1+i\\1-i\\1 \end{pmatrix} + C_3 \begin{pmatrix} i\\i\\i \end{pmatrix} = \mathbf{0} \qquad (2.0.2)$$

So,

$$\begin{pmatrix} 1 & 1+i & i \\ 0 & 1-i & i \\ -i & 1 & i \end{pmatrix} \begin{pmatrix} C_1 \\ C_2 \\ C_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$
 (2.0.3)

Considering the co-efficient matrix *A*:

$$\begin{pmatrix}
1 & 1+i & i \\
0 & 1-i & i \\
-i & 1 & i
\end{pmatrix} 
\xrightarrow{R_3 \leftarrow R_3 / i} 
\begin{pmatrix}
1 & 1+i & i \\
0 & 1-i & i \\
0 & i & i-1
\end{pmatrix}$$

$$\xrightarrow{R_3 \leftarrow R_3 / i} 
\begin{pmatrix}
1 & 1+i & i \\
0 & 1-i & i \\
0 & 1 & 1+i
\end{pmatrix} 
\xrightarrow{R_3 \leftarrow (1-i)R_3}$$

$$\begin{pmatrix}
1 & 1+i & i \\
0 & 1-i & i \\
0 & 1-i & 2
\end{pmatrix} 
\xrightarrow{R_3 \leftarrow R_3 - R_2} 
\begin{pmatrix}
1 & 1+i & i \\
0 & 1-i & i \\
0 & 0 & 2-i
\end{pmatrix}$$

$$\xrightarrow{R_2 \leftarrow \frac{1+i}{1-i}R_2} 
\xrightarrow{R_3 \leftarrow R_3 - R_2} 
\begin{pmatrix}
1 & 1+i & i \\
0 & 1-i & i \\
0 & 0 & 2-i
\end{pmatrix}
\xrightarrow{R_1 \leftarrow R_1 - R_2}$$

$$\begin{pmatrix}
1 & 0 & i+1 \\
0 & 1+i & -1 \\
0 & 0 & 2-i
\end{pmatrix}$$

$$\begin{pmatrix}
1 & 0 & i+1 \\
0 & 1+i & -1 \\
0 & 0 & 2-i
\end{pmatrix} 
\xrightarrow{R_1 \leftarrow R_1 - R_2} 
\xrightarrow{R_1 \leftarrow R_1 - R_2}$$

Now let

$$R = \begin{pmatrix} 1 & 0 & i+1 \\ 0 & 1+i & -1 \\ 0 & 0 & 2-i \end{pmatrix}$$
 (2.0.5)

Where R is the row reduced form of matrix A. So  $\alpha_1,\alpha_2$  and  $\alpha_3$  are linearly independent which implies that these 3 vectors form a basis of vector space  $C^3$ .

Now, consider a vector  $\beta = \begin{pmatrix} a \\ b \\ c \end{pmatrix}$  and let the

coordinates are 
$$x = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$$
 such that

$$Ax = \begin{pmatrix} a \\ b \\ c \end{pmatrix} \tag{2.0.6}$$

$$\implies x = A^{-1} \begin{pmatrix} a \\ b \\ c \end{pmatrix} \tag{2.0.7}$$

Let us consider a matrix (A|I) where I is a 3x3 identity matrix. Now, applying the Gauss-Jordon

theorem we can get  $A^{-1}$ 

$$\begin{pmatrix} 1 & 0 & 0 & \frac{1-4i}{5} & \frac{1-2i}{5} & \frac{-2+4i}{5} \\ 0 & 1 & 0 & \frac{1-2i}{5} & \frac{1+3i}{5} & -\frac{2+i}{5} \\ 0 & 0 & 1 & \frac{3-i}{5} & -\frac{2+i}{5} & -\frac{3i+1}{5} \end{pmatrix}$$

$$(2.0.9)$$

$$\implies (I|A^{-1}) = \begin{pmatrix} 1 & 0 & 0 & \frac{1-4i}{5} & \frac{1-2i}{5} & \frac{-2+4i}{5} \\ 0 & 1 & 0 & \frac{1-2i}{5} & \frac{1+3i}{5} & -\frac{2+i}{5} \\ 0 & 0 & 1 & \frac{3-i}{5} & -\frac{2+i}{5} & -\frac{3i+1}{5} \end{pmatrix}$$

$$(2.0.10)$$

$$\implies A^{-1} = \begin{pmatrix} \frac{1-4i}{5} & \frac{1-2i}{5} & \frac{-2+4i}{5} \\ \frac{1-2i}{5} & \frac{1+3i}{5} & -\frac{2+i}{5} \\ \frac{3-i}{5} & -\frac{2+i}{5} & -\frac{3i+1}{5} \end{pmatrix}$$

$$(2.0.11)$$

So,

$$x = A^{-1} \begin{pmatrix} a \\ b \\ c \end{pmatrix}$$

$$(2.0.12)$$

$$\implies x = \frac{1}{5} \begin{pmatrix} (1 - 4i)a + (1 - 2i)b + (-2 + 4i)c \\ (1 - 2i)a + (1 + 3i)b - (2 + i)c \\ (3 - i)a - (2 + i)b - (3i + 1)c \end{pmatrix}$$

$$(2.0.13)$$

$$\implies \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \frac{1}{5} \begin{pmatrix} (1 - 4i)a + (1 - 2i)b + (-2 + 4i)c \\ (1 - 2i)a + (1 + 3i)b - (2 + i)c \\ (3 - i)a - (2 + i)b - (3i + 1)c \end{pmatrix}$$

$$(2.0.14)$$