

# Assignment 11

Jayati Dutta

**Abstract**—This is a simple document explaining how to form a basis of a vector space and how to get the coordinates of the vector.

Download all and latex-tikz codes from

svn co <https://github.com/gadepall/school/trunk/ncert/geometry/figs>

## 1 PROBLEM

In  $C^3$ , let  $\alpha_1 = (1, 0, -i)$ ,  $\alpha_2 = (1 + i, 1 - i, 1)$ ,  $\alpha_3 = (i, i, i)$ . Prove that these vectors form a basis for  $C^3$ . What are the coordinates of the vector (a,b,c) in the basis?

## 2 EXPLANATION

Now,

$$C_1\alpha_1 + C_2\alpha_2 + C_3\alpha_3 = \mathbf{0} \quad (2.0.1)$$

$$\Rightarrow C_1(1, 0, -i) + C_2(1 + i, 1 - i, 1) + C_3(i, i, i) = \mathbf{0} \quad (2.0.2)$$

So,

$$\begin{pmatrix} 1 & 1+i & i \\ 0 & 1-i & i \\ -i & 1 & i \end{pmatrix} \begin{pmatrix} C_1 \\ C_2 \\ C_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \quad (2.0.3)$$

Considering the co-efficient matrix A:

$$\begin{aligned} \begin{pmatrix} 1 & 1+i & i \\ 0 & 1-i & i \\ -i & 1 & i \end{pmatrix} &\xrightarrow{R_3 \leftarrow R_3 + iR_1} \begin{pmatrix} 1 & 1+i & i \\ 0 & 1-i & i \\ 0 & i & i-1 \end{pmatrix} \\ &\xrightarrow{R_3 \leftarrow R_3/i} \begin{pmatrix} 1 & 1+i & i \\ 0 & 1-i & i \\ 0 & 1 & 1+i \end{pmatrix} \xrightarrow{R_3 \leftarrow (1-i)R_3} \\ &\begin{pmatrix} 1 & 1+i & i \\ 0 & 1-i & i \\ 0 & 1-i & 2 \end{pmatrix} \xrightarrow{R_3 \leftarrow R_3 - R_2} \begin{pmatrix} 1 & 1+i & i \\ 0 & 1-i & i \\ 0 & 0 & 2-i \end{pmatrix} \\ &\xrightarrow{R_2 \leftarrow \frac{1+i}{1-i}R_2} \begin{pmatrix} 1 & 1+i & i \\ 0 & 1+i & -1 \\ 0 & 0 & 2-i \end{pmatrix} \xrightarrow{R_1 \leftarrow R_1 - R_2} \\ &\begin{pmatrix} 1 & 0 & i+1 \\ 0 & 1+i & -1 \\ 0 & 0 & 2-i \end{pmatrix} \quad (2.0.4) \end{aligned}$$

Now let

$$R = \begin{pmatrix} 1 & 0 & i+1 \\ 0 & 1+i & -1 \\ 0 & 0 & 2-i \end{pmatrix} \quad (2.0.5)$$

Where  $R$  is the row reduced form of matrix  $A$ . Now,

$$\begin{pmatrix} 1 & 0 & i+1 \\ 0 & 1+i & -1 \\ 0 & 0 & 2-i \end{pmatrix} \begin{pmatrix} C_1 \\ C_2 \\ C_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \quad (2.0.6)$$

$$\Rightarrow (2-i)C_3 = 0 \quad (2.0.7)$$

$$\Rightarrow C_3 = 0 \quad (2.0.8)$$

$$C_1 + (i-1)C_3 = 0 \quad (2.0.9)$$

$$\Rightarrow C_1 = 0 \quad (2.0.10)$$

$$C_2 = 0 \quad (2.0.11)$$

As  $C_1, C_2, C_3 \neq 0$ , so  $\alpha_1, \alpha_2$  and  $\alpha_3$  are linearly independent and as the dimension of the vector space  $C^3$  is 3. So we can say that these 3 vectors span the vector space  $C^3$  which implies that these 3 vectors form a basis of vector space  $C^3$ .

Now, consider a vector  $\beta = (a, b, c)$  such that

$$\beta R = (a \ b \ c) \begin{pmatrix} \rho_1 \\ \rho_2 \\ \rho_3 \end{pmatrix} \quad (2.0.12)$$

Where  $\rho_1 = (1 \ 0 \ i - 1)$ ,  $\rho_2 = (0 \ 1 + i \ -1)$  and  $\rho_3 = (0 \ 0 \ 2 - i)$  are the rows of the matrix  $R$ .

Now,

$$\beta R = (a \ b \ c) Q A \quad (2.0.13)$$

When matrix  $A$  is row reduced to the matrix  $R$ , if same operations are simultaneously operated on the Identity matrix  $I$ , then we can get matrix  $Q$ . So,

$$Q = \begin{pmatrix} 1 & -i & 0 \\ 0 & i & 0 \\ 1 - i & -1 & -i - 1 \end{pmatrix} \quad (2.0.14)$$

Now,

$$x_i = (a \ b \ c) Q_i \quad (2.0.15)$$

where  $x_i$  represents the coordinate of  $i^{th}$  vector. So,

$$x_1 = (a \ b \ c) Q_1 \quad (2.0.16)$$

$$\Rightarrow x_1 = (a \ b \ c) \begin{pmatrix} 1 \\ 0 \\ 1 - i \end{pmatrix} \quad (2.0.17)$$

$$\Rightarrow x_1 = a + c(1 - i) \quad (2.0.18)$$

$$\Rightarrow x_1 = (a + c) - ic \quad (2.0.19)$$

Similarly,

$$x_2 = (a \ b \ c) Q_2 \quad (2.0.20)$$

$$\Rightarrow x_2 = (a \ b \ c) \begin{pmatrix} -i \\ i \\ -1 \end{pmatrix} \quad (2.0.21)$$

$$\Rightarrow x_2 = -c + i(b - a) \quad (2.0.22)$$

$$x_3 = (a \ b \ c) Q_3 \quad (2.0.23)$$

$$\Rightarrow x_3 = (a \ b \ c) \begin{pmatrix} 0 \\ 0 \\ -i - 1 \end{pmatrix} \quad (2.0.24)$$

$$\Rightarrow x_3 = -c - ic \quad (2.0.25)$$