

# Assignment 14

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**Abstract**—This is a simple document explaining how to describe a linear functional on a vector space for certain conditions.

Download all and latex-tikz codes from

svn co <https://github.com/gadepall/school/trunk/ncert/geometry/figs>

## 1 PROBLEM

In  $R^3$ , let  $\alpha_1 = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$ ,  $\alpha_2 = \begin{pmatrix} 0 \\ 1 \\ -2 \end{pmatrix}$  and  $\alpha_3 = \begin{pmatrix} -1 \\ -1 \\ 0 \end{pmatrix}$ .

Describe explicitly a linear functional  $f$  on  $R^3$  such that  $f(\alpha_1) = f(\alpha_2) = 0$  but  $f(\alpha_3) \neq 0$

## 2 EXPLANATION

Let us consider  $\alpha = \begin{pmatrix} a \\ b \\ c \end{pmatrix}$  such that

$$\alpha_1 x_1 + \alpha_2 x_2 + \alpha_3 x_3 = \alpha \quad (2.0.1)$$

$$\alpha_1 x_1 + \alpha_2 x_2 + \alpha_3 x_3 = \begin{pmatrix} a \\ b \\ c \end{pmatrix} \quad (2.0.2)$$

The coefficient matrix is :

$$A = \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & -1 \\ 1 & -2 & 0 \end{pmatrix} \quad (2.0.3)$$

So,

$$A\mathbf{x} = \alpha \quad (2.0.4)$$

$$\Rightarrow \mathbf{x} = A^{-1}\alpha \quad (2.0.5)$$

$$(2.0.6)$$

Now to get  $A^{-1}$ , we will consider Gauss-Jordan theorem. So, we will take  $(A|I)$ , where  $I$  is a  $3 \times 3$

identity matrix.

$$\begin{pmatrix} 1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & -1 & 0 & 1 & 0 \\ 1 & -2 & 0 & 0 & 0 & 1 \end{pmatrix} \xrightarrow{R_3 \leftarrow R_3 - R_1} \begin{pmatrix} 1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & -1 & 0 & 1 & 0 \\ 0 & -2 & 1 & -1 & 0 & 1 \end{pmatrix} \xrightarrow{R_3 \leftarrow R_3 + 2R_2} \begin{pmatrix} 1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & -1 & 0 & 1 & 0 \\ 0 & 0 & -1 & -1 & 2 & 1 \end{pmatrix} \xrightarrow{R_3 \leftarrow R_3 / (-1)} \begin{pmatrix} 1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & -1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 & -2 & -1 \end{pmatrix} \xrightarrow{\begin{matrix} R_2 \leftarrow R_2 + R_3 \\ R_1 \leftarrow R_1 + R_3 \end{matrix}} \begin{pmatrix} 1 & 0 & 0 & 2 & -2 & -1 \\ 0 & 1 & 0 & 1 & -1 & -1 \\ 0 & 0 & 1 & 1 & -2 & -1 \end{pmatrix} \quad (2.0.7)$$

Now, we can say that

$$A^{-1} = \begin{pmatrix} 2 & -2 & -1 \\ 1 & -1 & -1 \\ 1 & -2 & -1 \end{pmatrix} \quad (2.0.8)$$

As

$$\mathbf{x} = A^{-1}\alpha \quad (2.0.9)$$

$$\Rightarrow \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = A^{-1} \begin{pmatrix} a \\ b \\ c \end{pmatrix} \quad (2.0.10)$$

$$\Rightarrow \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 2 & -2 & -1 \\ 1 & -1 & -1 \\ 1 & -2 & -1 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} \quad (2.0.11)$$

Now, let us consider  $B_1 = \begin{pmatrix} 2 \\ -2 \\ -1 \end{pmatrix}$ ,  $B_2 = \begin{pmatrix} 1 \\ -1 \\ -1 \end{pmatrix}$  and  $B_3 = \begin{pmatrix} 1 \\ -2 \\ -1 \end{pmatrix}$  and  $\alpha = \begin{pmatrix} a \\ b \\ c \end{pmatrix}$ . So,

$$x_1 = \mathbf{B}_1^T \alpha \quad (2.0.12)$$

$$x_2 = \mathbf{B}_2^T \alpha \quad (2.0.13)$$

$$x_3 = \mathbf{B}_3^T \alpha \quad (2.0.14)$$

Now, as  $f$  is a linear functional on  $R^3$ ,

$$\alpha = \alpha_1 x_1 + \alpha_2 x_2 + \alpha_2 x_2 \quad (2.0.15)$$

$$\Rightarrow f(\alpha) = f(\alpha_1 x_1 + \alpha_2 x_2 + \alpha_2 x_2) \quad (2.0.16)$$

$$\Rightarrow f(\alpha) = x_1 f(\alpha_1) + x_2 f(\alpha_2) + x_3 f(\alpha_3) \quad (2.0.17)$$

$$\Rightarrow f(\alpha) = \begin{pmatrix} x_1 & x_2 & x_3 \end{pmatrix} \begin{pmatrix} f(\alpha_1) \\ f(\alpha_2) \\ f(\alpha_3) \end{pmatrix} \quad (2.0.18)$$

$$\Rightarrow f(\alpha) = \mathbf{x}^T \begin{pmatrix} f(\alpha_1) \\ f(\alpha_2) \\ f(\alpha_3) \end{pmatrix} \quad (2.0.19)$$

As mentioned in the problem statement,  $f(\alpha_1) = f(\alpha_2) = 0$  and  $f(\alpha_3) \neq 0$ .

Now,

$$f(\alpha) = \mathbf{x}^T \begin{pmatrix} f(\alpha_1) \\ f(\alpha_2) \\ f(\alpha_3) \end{pmatrix} \quad (2.0.20)$$

$$\Rightarrow f(\alpha) = \begin{pmatrix} x_1 & x_2 & x_3 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \\ f(\alpha_3) \end{pmatrix} \quad (2.0.21)$$

$$\Rightarrow f(\alpha) = x_3 f(\alpha_3) \quad (2.0.22)$$

$$\Rightarrow f(\alpha) = f(\alpha_3) \mathbf{B}_3^T \alpha \quad (2.0.23)$$

$$\Rightarrow f(a, b, c) = f(\alpha_3) \begin{pmatrix} 1 & -2 & -1 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} \quad (2.0.24)$$

So, the function can be defined as:

$$f(x, y, z) = f(\alpha_3) \begin{pmatrix} 1 & -2 & -1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} \quad (2.0.25)$$

$$\text{or, } f(\mathbf{x}) = f(\alpha_3) \mathbf{B}_3^T \mathbf{x} \quad (2.0.26)$$

Using this defined function, it can be verified that:

$$f(\alpha_1) = f(\alpha_3) \begin{pmatrix} 1 & -2 & -1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} \quad (2.0.27)$$

$$\Rightarrow f(1, 0, 1) = f(\alpha_3) \begin{pmatrix} 1 & -2 & -1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} \quad (2.0.28)$$

$$\Rightarrow f(1, 0, 1) = 0 \quad (2.0.29)$$

Similarly,

$$f(\alpha_2) = f(\alpha_3) \begin{pmatrix} 1 & -2 & -1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} \quad (2.0.30)$$

$$\Rightarrow f(0, 1, -2) = f(\alpha_3) \begin{pmatrix} 1 & -2 & -1 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \\ -2 \end{pmatrix} \quad (2.0.31)$$

$$\Rightarrow f(0, 1, -2) = 0 \quad (2.0.32)$$

and

$$f(\alpha_3) = f(\alpha_3) \begin{pmatrix} 1 & -2 & -1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} \quad (2.0.33)$$

$$\Rightarrow f(-1, -1, 0) = f(\alpha_3) \begin{pmatrix} 1 & -2 & -1 \end{pmatrix} \begin{pmatrix} -1 \\ -1 \\ 0 \end{pmatrix} \quad (2.0.34)$$

$$\Rightarrow f(-1, -1, 0) \neq 0 \quad (2.0.35)$$

Hence, the above problem statement is verified.