Analysis Report

Nodecentric(int const *, int const *, int const *, int const *, float const *, float*, int, float, int)

Duration	8.42911 ms (8,429,112 ns)	
Grid Size	[1024,1,1]	
Block Size	[256,1,1]	
Registers/Thread	23	
Shared Memory/Block	0 B	
Shared Memory Requested	96 KiB	
Shared Memory Executed	96 KiB	
Shared Memory Bank Size	4 B	

[0] GeForce GTX 1080 Ti

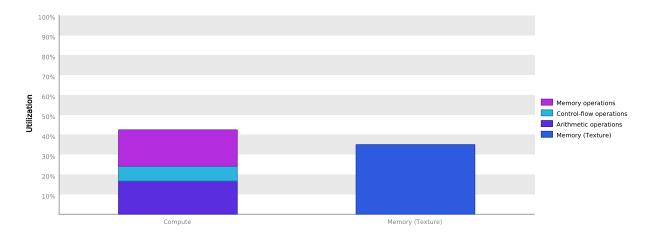
GPU UUID	GPU-51a10016-cec5-22dd-3021-19cfb1344de6
Compute Capability	6.1
Max. Threads per Block	1024
Max. Threads per Multiprocessor	2048
Max. Shared Memory per Block	48 KiB
Max. Shared Memory per Multiprocessor	96 KiB
Max. Registers per Block	65536
Max. Registers per Multiprocessor	65536
Max. Grid Dimensions	[2147483647, 65535, 65535]
Max. Block Dimensions	[1024, 1024, 64]
Max. Warps per Multiprocessor	64
Max. Blocks per Multiprocessor	32
Half Precision FLOP/s	88.592 GigaFLOP/s
Single Precision FLOP/s	11.34 TeraFLOP/s
Double Precision FLOP/s	354.368 GigaFLOP/s
Number of Multiprocessors	28
Multiprocessor Clock Rate	1.582 GHz
Concurrent Kernel	true
Max IPC	6
Threads per Warp	32
Global Memory Bandwidth	484.44 GB/s
Global Memory Size	10.915 GiB
Constant Memory Size	64 KiB
L2 Cache Size	2.75 MiB
Memcpy Engines	2
PCIe Generation	3
PCIe Link Rate	8 Gbit/s
PCIe Link Width	16

1. Compute, Bandwidth, or Latency Bound

The first step in analyzing an individual kernel is to determine if the performance of the kernel is bounded by computation, memory bandwidth, or instruction/memory latency. The results below indicate that the performance of kernel "Nodecentric" is most likely limited by instruction and memory latency. You should first examine the information in the "Instruction And Memory Latency" section to determine how it is limiting performance.

1.1. Kernel Performance Is Bound By Instruction And Memory Latency

This kernel exhibits low compute throughput and memory bandwidth utilization relative to the peak performance of "GeForce GTX 1080 Ti". These utilization levels indicate that the performance of the kernel is most likely limited by the latency of arithmetic or memory operations. Achieved compute throughput and/or memory bandwidth below 60% of peak typically indicates latency issues.



2. Instruction and Memory Latency

Instruction and memory latency limit the performance of a kernel when the GPU does not have enough work to keep busy. The results below indicate that the GPU does not have enough work because instruction execution is stalling excessively.

2.1. Kernel Profile - PC Sampling

The Kernel Profile - PC Sampling gives the number of samples for each source and assembly line with various stall reasons. The samples are collected at a period of 256 [2^8] cycles. You can change the period under Settings->Analysis tab. The allowed values are from 5 to 31. Increasing the period would reduce the number of samples collected.

Using this information you can pinpoint portions of your kernel that are introducing latencies and the reason for the latency. Samples are taken in round robin order for all active warps at a fixed number of cycles regardless of whether the warp is issuing an instruction or not.

Instruction Issued - Warp was issued

Instruction Fetch - The next assembly instruction has not yet been fetched.

Execution Dependency - An input required by the instruction is not yet available. Execution dependency stalls can potentially be reduced by increasing instruction-level parallelism.

Memory Dependency - A load/store cannot be made because the required resources are not available or are fully utilized, or too many requests of a given type are outstanding. Data request stalls can potentially be reduced by optimizing memory alignment and access patterns.

Texture - The texture sub-system is fully utilized or has too many outstanding requests.

Synchronization - The warp is blocked at a __syncthreads() call.

Constant - A constant load is blocked due to a miss in the constants cache.

Pipe Busy - The compute resource(s) required by the instruction is not yet available.

Memory Throttle - Large number of pending memory operations prevent further forward progress. These can be reduced by combining several memory transactions into one.

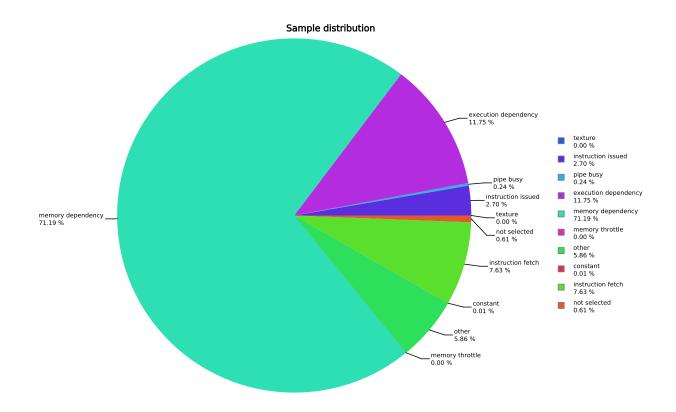
Not Selected - Warp was ready to issue, but some other warp issued instead. You may be able to sacrifice occupancy without impacting latency hiding and doing so may help improve cache hit rates.

Other - The warp is blocked for an uncommon reason.

Sleeping -The warp is blocked, yielded or sleeping.

Examine portions of the kernel that have high number of samples to know where the maximum time was spent and observe the latency reasons for those samples to identify optimization opportunities.

Cuda Functions	Sample Count	% of Kernel Samples
Nodecentric(int const *, int const *, int const *, int const *, float const *, float*, int, float, int)	1211718	100.0



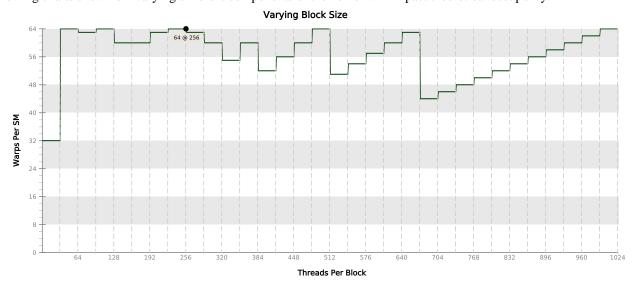
2.2. Occupancy Is Not Limiting Kernel Performance

The kernel's block size, register usage, and shared memory usage allow it to fully utilize all warps on the GPU.

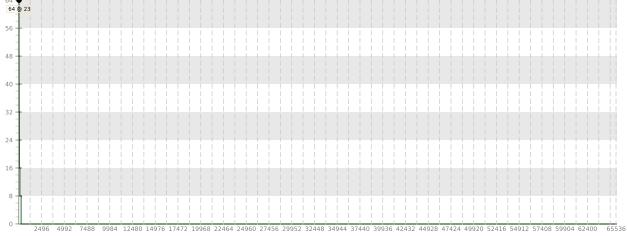
Variable	Achieved	Theoretical	Device Limit	Grid Si	ze: [1	.024,1	,1](1024	block	(s) Bl	ock S	ize: [2	256,1,	1] (256 th
Occupancy Per SM														
Active Blocks		8	32	0	3	6	9	12	15	18	21	24	27	30 32
Active Warps	62.54	64	64	0	7	14	21	. 2	28	35	42	49	56	664
Active Threads		2048	2048	0	256	51	2	768	102	24 1	.280	1536	179	2 2048
Occupancy	97.7%	100%	100%	0%		25	5%		50)%		75%	, 0	100%
Warps														
Threads/Block		256	1024	0	128	25	6	384	51	2	640	768	89	6 1024
Warps/Block		8	32	0	3	6	9	12	15	18	21	24	27	30 32
Block Limit		8	32	0	3	6	9	12	15	18	21	24	27	30 32
Registers														
Registers/Thread		23	65536	0	8192	2 163	84 2	4576	327	68 4	0960	49152	2 573	44 65536
Registers/Block		6144	65536	0		16	5k		32	?k		48k		64k
Block Limit		10	32	0	3	6	9	12	15	18	21	24	27	30 32
Shared Memory														
Shared Memory/Block		0	98304	0			32	2k			64	k		96k
Block Limit		0	32	0	3	6	9	12	15	18	21	24	27	30 32

2.3. Occupancy Charts

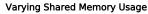
The following charts show how varying different components of the kernel will impact theoretical occupancy.

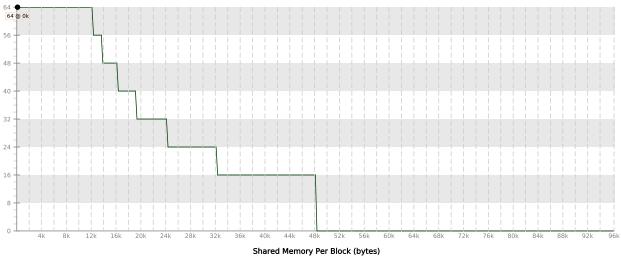






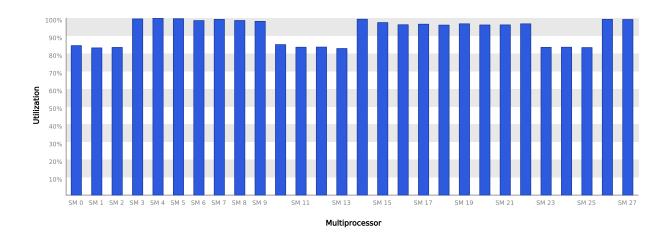
Registers Per Thread





2.4. Multiprocessor Utilization

The kernel's blocks are distributed across the GPU's multiprocessors for execution. Depending on the number of blocks and the execution duration of each block some multiprocessors may be more highly utilized than others during execution of the kernel. The following chart shows the utilization of each multiprocessor during execution of the kernel.



3. Compute Resources

GPU compute resources limit the performance of a kernel when those resources are insufficient or poorly utilized. Compute resources are used most efficiently when all threads in a warp have the same branching and predication behavior. The results below indicate that a significant fraction of the available compute performance is being wasted because branch and predication behavior is differing for threads within a warp.

3.1. Kernel Profile - Instruction Execution

The Kernel Profile - Instruction Execution shows the execution count, inactive threads, and predicated threads for each source and assembly line of the kernel. Using this information you can pinpoint portions of your kernel that are making inefficient use of compute resource due to divergence and predication.

Examine portions of the kernel that have high execution counts and inactive or predicated threads to identify optimization opportunities.

Cuda Fuctions :

Nodecentric(int const *, int const *, int const *, int const *, float const *, float*, int, float, int)

Maximum instruction execution count in assembly: 37355528

Average instruction execution count in assembly: 2856060

Instructions executed for the kernel: 805408945

Thread instructions executed for the kernel: 25650830715

Non-predicated thread instructions executed for the kernel: 24455755911

Warp non-predicated execution efficiency of the kernel: 94.9%

Warp execution efficiency of the kernel: 99.5%

3.2. Divergent Branches

Compute resource are used most efficiently when all threads in a warp have the same branching behavior. When this does not occur the branch is said to be divergent. Divergent branches lower warp execution efficiency which leads to inefficient use of the GPU's compute resources.

Optimization: Each entry below points to a divergent branch within the kernel. For each branch reduce the amount of intra-warp divergence.

3.3. Function Unit Utilization

Different types of instructions are executed on different function units within each SM. Performance can be limited if a function unit is over-used by the instructions executed by the kernel. The following results show that the kernel's performance is not limited by overuse of any function unit.

Load/Store - Load and store instructions for shared and constant memory.

Texture - Load and store instructions for local, global, and texture memory.

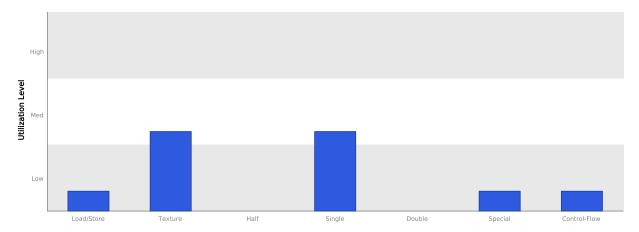
Half - Half-precision floating-point arithmetic instructions.

Single - Single-precision integer and floating-point arithmetic instructions.

Double - Double-precision floating-point arithmetic instructions.

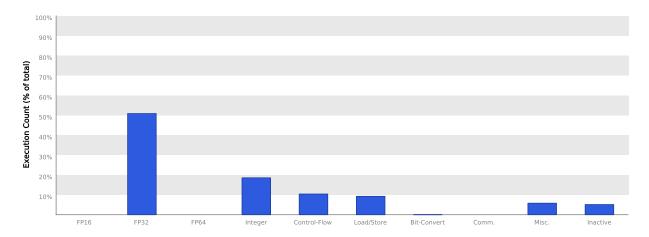
Special - Special arithmetic instructions such as sin, cos, popc, etc.

Control-Flow - Direct and indirect branches, jumps, and calls.



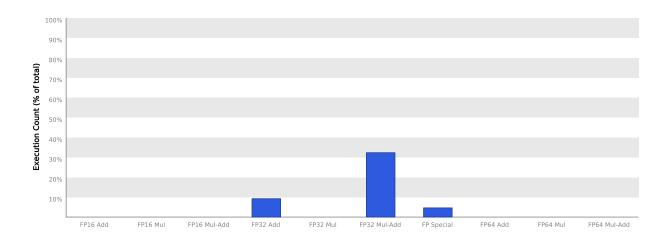
3.4. Instruction Execution Counts

The following chart shows the mix of instructions executed by the kernel. The instructions are grouped into classes and for each class the chart shows the percentage of thread execution cycles that were devoted to executing instructions in that class. The "Inactive" result shows the thread executions that did not execute any instruction because the thread was predicated or inactive due to divergence.



3.5. Floating-Point Operation Counts

The following chart shows the mix of floating-point operations executed by the kernel. The operations are grouped into classes and for each class the chart shows the percentage of thread execution cycles that were devoted to executing operations in that class. The results do not sum to 100% because non-floating-point operations executed by the kernel are not shown in this chart.

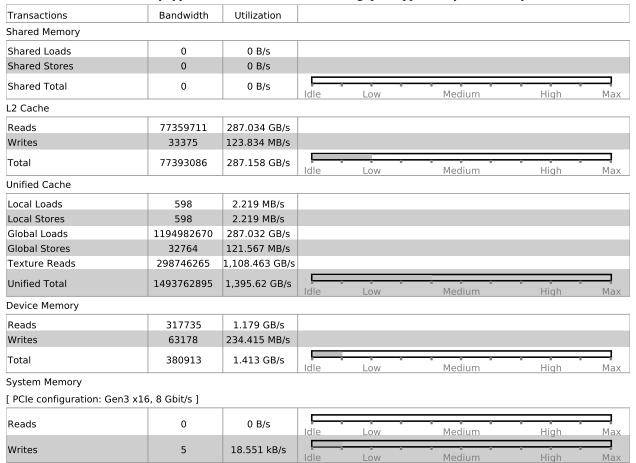


4. Memory Bandwidth

Memory bandwidth limits the performance of a kernel when one or more memories in the GPU cannot provide data at the rate requested by the kernel.

4.1. Memory Bandwidth And Utilization

The following table shows the memory bandwidth used by this kernel for the various types of memory on the device. The table also shows the utilization of each memory type relative to the maximum throughput supported by the memory.



4.2. Memory Statistics

The following chart shows a summary view of the memory hierarchy of the CUDA programming model. The green nodes in the diagram depict logical memory space whereas blue nodes depicts actual hardware unit on the chip. For the various caches the reported percentage number states the cache hit rate; that is the ratio of requests that could be served with data locally available to the cache over all requests made.

The links between the nodes in the diagram depict the data paths between the SMs to the memory spaces into the memory system. Different metrics are shown per data path. The data paths from the SMs to the memory spaces report the total number of memory instructions executed, it includes both read and write operations. The data path between memory spaces and "Unified Cache" or "Shared Memory" reports the total amount of memory requests made (read or write). All other data paths report the total amount of transferred memory in bytes.