

InPO: Inversion Preference Optimization with Reparametrized DDIM for Efficient Diffusion Model Alignment



Project Page:

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Motivation:

• Efficiency: How to Mitigate the Impact of Long-Chain Markov Processes in Diffusion Models Alignment?

| DPO | Diffusion-DPO | DDIM-InPO | | | |
|------------|-------------------------------------------------------------------------------|-----------------------------------------------------------------------|--|--|--|
| $p(x_0 c)$ | $p(x_0 c)$ | $p(x_0 c)$ | | | |
| LLM | Denoiser $)\times T$ | Denoiser | | | |
| † c prompt | $ \begin{array}{c} \uparrow \\ c \\ \hline c \\ prompt \\ noise \end{array} $ | $ \begin{array}{c} \uparrow \\ c \\ x_t\\ prompt latent \end{array} $ | | | |

Solution:

• **Step-1**: Diffusion Model Reparameterization for One-Step Generation.

$$x_0(t) = \frac{x_t}{\sqrt{\bar{\alpha}_t}} - \frac{\sqrt{1 - \bar{\alpha}_t}}{\sqrt{\bar{\alpha}_t}} \epsilon_{\theta}^t(x_t)$$

• Step-2: Finding Appropriate Latent Variables x_t at any timestep t via DDIM Inversion.

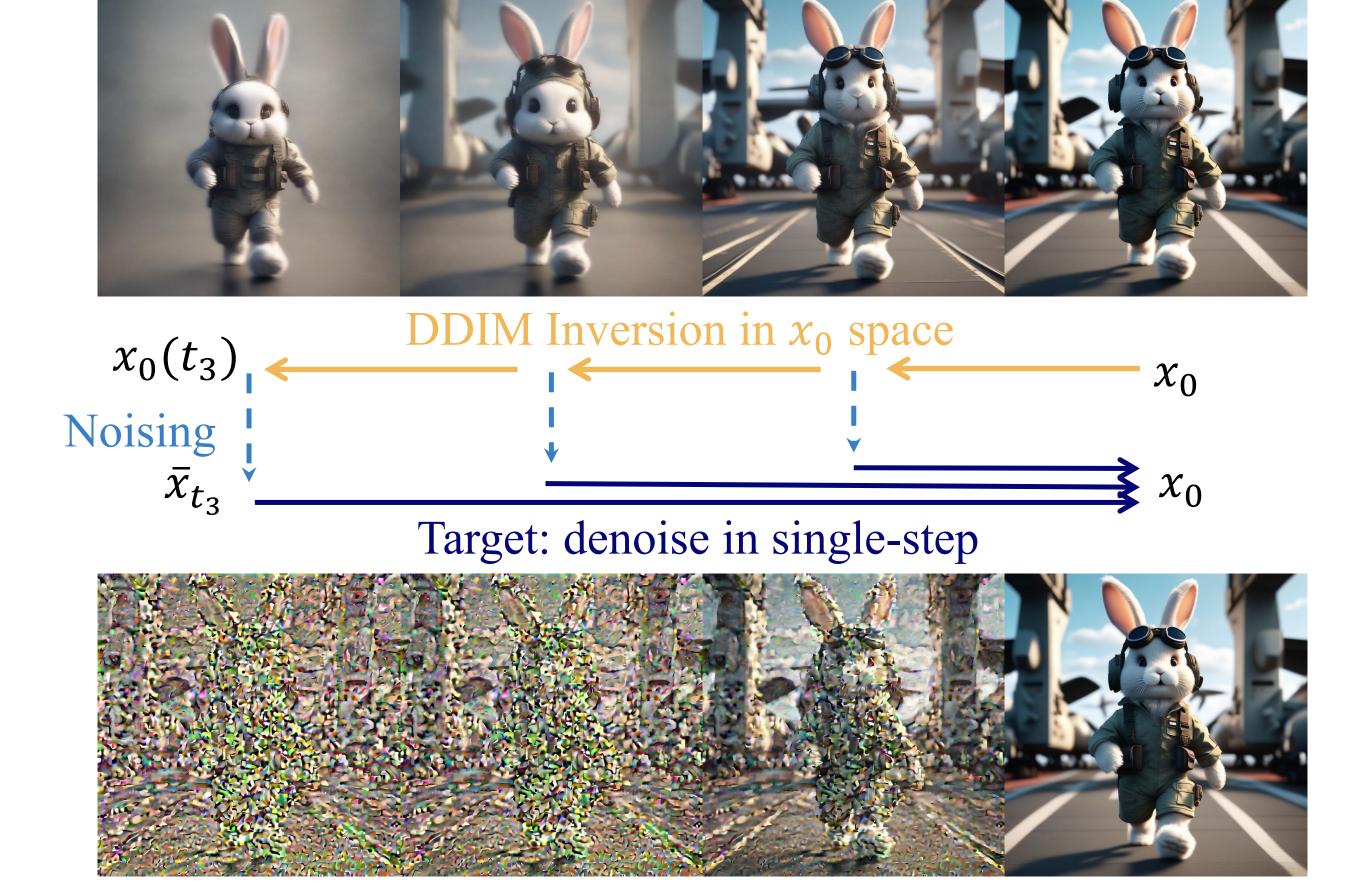
$$x_{t} = \sqrt{\frac{\alpha_{t}}{\alpha_{t+1}}} x_{t+1} + (\sqrt{\frac{1 - \alpha_{t}}{\alpha_{t}}} - \sqrt{\frac{1 - \alpha_{t+1}}{\alpha_{t+1}}}) \epsilon_{\theta}^{t+1} (x_{t+1})$$

• Step-3: Joint Distribution DPO Training Framework.

$$\mathcal{L}(\theta) := -\mathbb{E}_{t,(\boldsymbol{x}_0^w, \boldsymbol{x}_0^l, \boldsymbol{c}) \sim \mathcal{D}} \log \sigma$$

$$\left(\beta \mathbb{E}_{\boldsymbol{x}_t^w \sim p_{\theta}^{\boldsymbol{c}}(\boldsymbol{x}_t^w | \boldsymbol{x}_0^w)} \left[\log \frac{p_{\theta}^{\boldsymbol{c}}(\boldsymbol{x}_0^w, \boldsymbol{x}_t^w)}{p_{\text{ref}}^{\boldsymbol{c}}(\boldsymbol{x}_0^w, \boldsymbol{x}_t^w)} - \log \frac{p_{\theta}^{\boldsymbol{c}}(\boldsymbol{x}_0^l, \boldsymbol{x}_t^l)}{p_{\text{ref}}^{\boldsymbol{c}}(\boldsymbol{x}_0^l, \boldsymbol{x}_t^l)} \right] \right)$$

DDIM-InPO Framework:



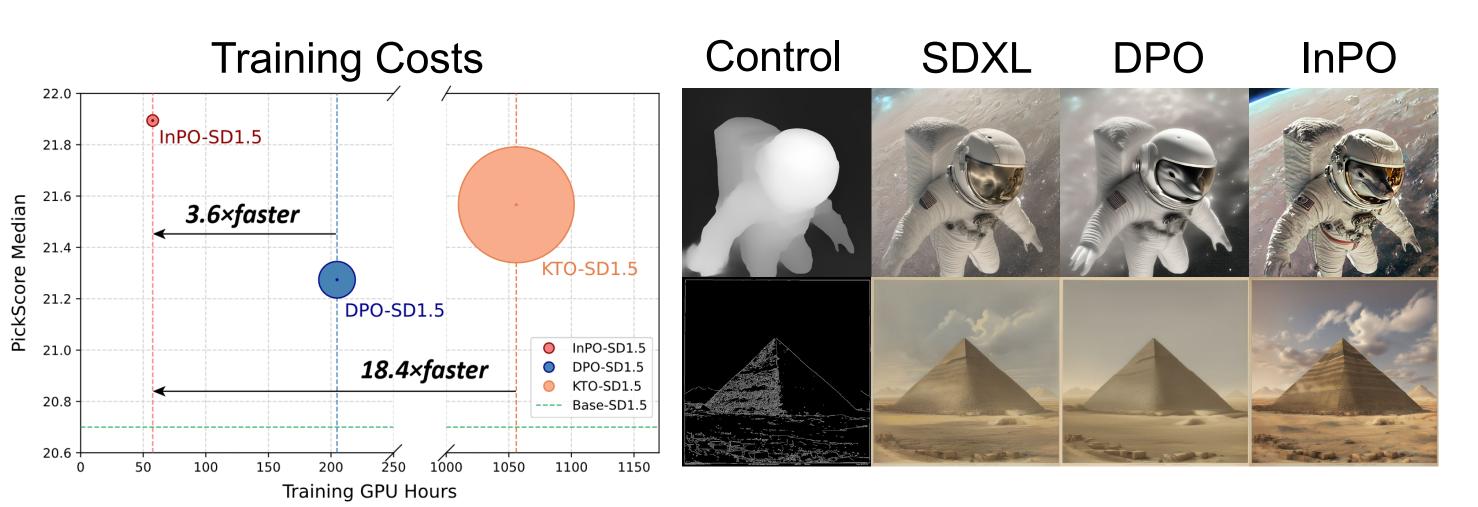
Perceptual Superiority:



Experiments:

Win-rate Comparison with Baselines

| Model | Baselines | Win-rate (HPDv2) | | | Win-rate (Parti-Prompts) | | | | |
|------------|----------------|------------------|-----------|-------|--------------------------|-----------|-----------|--------------|--------------|
| | | Aesthetic | PickScore | HPS | CLIP | Aesthetic | PickScore | HPS | CLIP |
| InPO-SDXL | vs. Base-SDXL | 56.37 | 79.25 | 85.38 | 53.37 | 61.70 | 72.89 | 78.31 | 50.55 |
| | vs. SFT-SDXL | 66.66 | 88.31 | 89.91 | 59.00 | 69.70 | 88.54 | 88.91 | 56.99 |
| | vs. DPO-SDXL | 55.87 | 59.28 | 65.81 | 46.91 | 57.17 | 56.92 | 60.11 | 42.28 |
| InPO-SD1.5 | vs. Base-SD1.5 | 80.19 | 85.84 | 90.22 | 66.44 | 74.63 | 73.16 | 81.86 | 61.89 |
| | vs. SFT-SD1.5 | 56.63 | 66.84 | 58.91 | 57.87 | 52.27 | 62.50 | 58.03 | 57.54 |
| | vs. DPO-SD1.5 | 70.50 | 74.94 | 84.06 | 61.09 | 68.01 | 63.54 | 75.31 | 57.54 |
| | vs. KTO-SD1.5 | 59.81 | 67.41 | 60.94 | 60.03 | 59.01 | 62.25 | 58.76 | 57.60 |



Conclusion:

Advantages of Fine-Tuning Data-Dependent Latent Variables in Pre-Trained Diffusion Models:

- Preservation of Pre-Trained Knowledge
- Targeted Performance Improvement
- Optimized Computational Efficiency
- Interpretability and Parametric Control
- Cross-Domain Broader Applicability

Future Work: Targeted fine-tuning of specific latent variables (via controlled noise injection) may establish a universal paradigm for future post-training adaptation.