

EE 675: Microprocessor Applications in Power Electronics - Assignment 3

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1 Question 1

Write a C program to print data from the blocks of a TMS320F28379D bootstrappable .bin binary file.

For this question, a simple C program is given named 'rbin_170070038.c'. To read the binary data `fread()` and `fseek()` functions are used. The invocation for this program is given as `./rbin impy.bin` where the argument is the .bin file that we want to read and if 1 argument is not given or file is not found, an error message is displayed saying "File not found".

1.1 Algorithm

- First we check if the invocation is correct or not i.e. if only 1 argument is there and if it could be opened or not.
- Then we read the first 2 bytes which tell us about the width of the instruction. If the bytes are `0x08aa`, then the width is 8 bits otherwise 16 bits. Typically it is 8 bits for our microprocessor.
- Then we move to the 23rd byte or `byte[22]` to read the block-size of the block that follows.
- Block information starts from 23rd byte. First 2 bytes tell us the block-size. If it is `0x0000`, then it means we have reached the end of the file. We use this as the stopping condition for the while loop.
- Next 4 bytes store the address of the first block entry.
- From next byte on, data entries start. We then print these data entries in a for loop using `printf()` statement and using the iterator to get the address of the block entries.
- Once we read `0x0000` as the block size, we break the while loop and close the file.

2 Question 2

Write a C program to read upto 8 words from the TMS320F28379D processor using the firmware of the ccm interface

For this question, a simple C program is given named 'rcom_170070038.c'. To open and close the ports, `open_port()` and `close_port()` of the `sportf.c` file were used. For reading and writing from the SPI port, `read()` and `write()` functions were used. The invocation for this program is given as `./rcom 1 8a00 6` where the argument 1 represents the port being used ('/dev/ttyUSB1'), the second argument 8a00 represents the address from where we have to read the data and argument 6 represents how many words are being read.

2.1 Algorithm

- First we check if the invocation is correct or not and if the port could be opened or not.
- We concatenate the first argument with the string "/dev/ttyUSB" to get the port-Number which will be used as argument to open the port. We then open the port with the baud rate specified as 115200
- We take the address as the second argument and left pad it with zeros to get 8 byte character array `memoryAddress`.
- We then initialize the 14 byte command header with first 2 bytes as 0x00, next 4 bytes with the address and the 7th byte or `byte[6]` with argument 3 i.e. read size or how many words are being read. Here each character of the `memoryAddress` represents 4 bits of the address and so we extract the byte information for the command header by concatenating 2 characters and then converting it to 1 byte char value which is then fed to the command header.
- After that, we write the command header in the port byte-wise using `write()` function
- After that we read the values byte-wise and store it in an array named `recieved`.
- Then we concatenate 2 bytes to get a word since a word is of 2 bytes and then print the value using `printf()` function.
- Finally we close the port with `close_port()` function